

Position Error (cartesian) & Orientation Error (yaw ψ , pitch θ , roll ϕ) vs. Time & Trajectory Step

Step

$+\psi$

$+\theta$

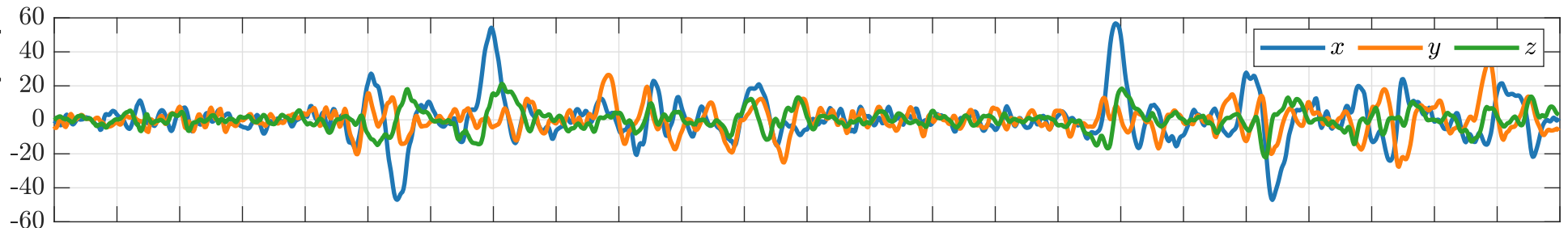
$+\phi$

$-\psi$

$-\theta$

$-\phi$

Pos. Error [mm]



Orient. Error [°]

