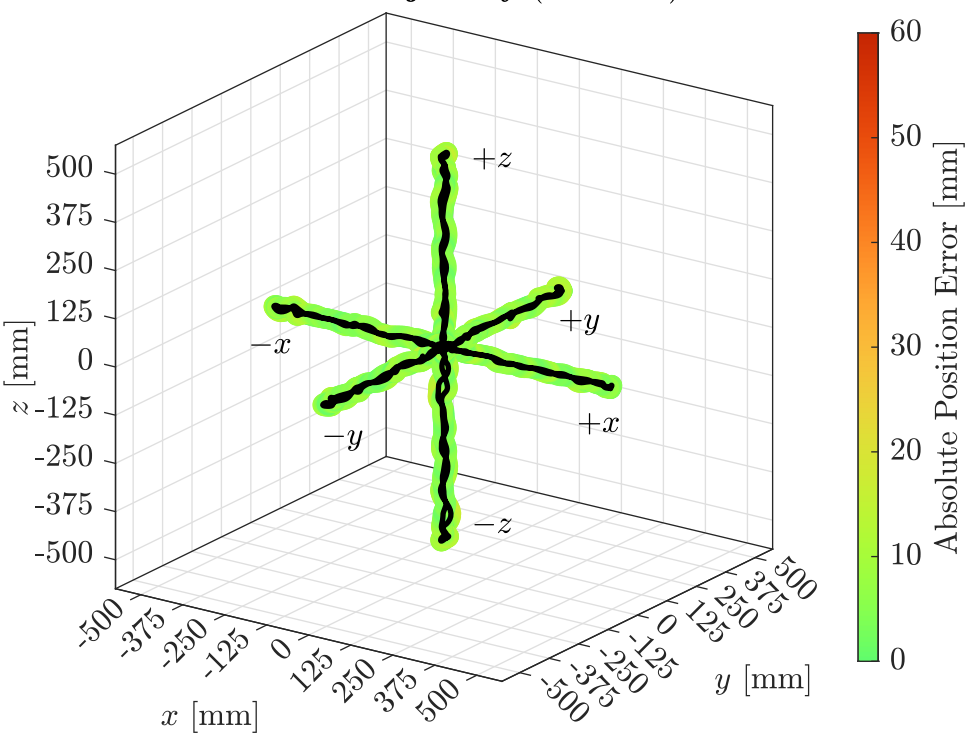
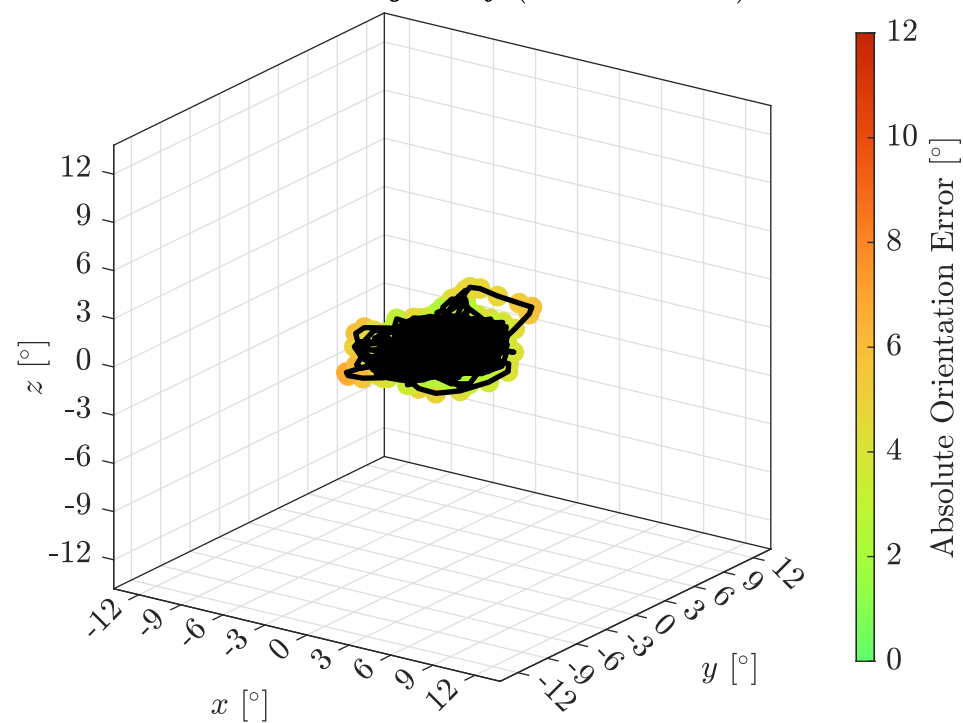


Position Trajectory (cartesian)**Orientation Trajectory (rotation vector)****Position Error (cartesian) & Orientation Error (yaw ψ , pitch θ , roll ϕ) vs. Time & Trajectory Step**