Mathematical Optimization (Linear programming)

XER"; CER"; AER"; bER"

•canonical form LP: max c^Tx subj.to: Ax≤b and x≥0

general LP can be reconstructed with:

minimgation: $\min c^Tx \rightarrow \max c^Tx$ max. $x_i \in 0 \rightarrow \text{substit}(x_i)$ with $x_i = -x_i^+$ lower bound: $A_i \times b_i \rightarrow -A_i \times b_i$ mox constr.: $x_i \in \mathbb{R} \rightarrow \text{substit}(x_i)$ with $x_i = x_i^+ - x_i^-$ equality: $A_i \times b_i \rightarrow A_i \times b_i$; $-A_i \times b_i$

• shandard form LP: $\max C^T x = b$ and $x \ge 0$

y: slack variables appended to x canonical LP from standard LP: $A_i \times b_i \rightarrow y_i + A_i \times b_i$; $y_i \ge 0$

Y1 Y2 Y3 X4 X2 example: $x_1+4x_2 \leq 40$ 100191 $2x_1 + x_2 \le 42$ 01021 42 1.5x1+3x2≤36 0 0 1 1.5 3 À β=(1,2,3) ←

allowed operations (beep same solution)

· change row order

· multiply row with non-zero number

· add multiple of one row to an other

•basis: B=(β(1),...,β(m)); β(i)∈{1,...,n+m}, i=1,...,m

(β(i): column# of A where column=e;)

• basis exchange: modify A,b to change basis without changing solution

10014 | 40 > 0=40 01021

1/4 0 0 1/4 1 10 -1/4 1 0 7/4 0 32 2=2-1/41 -3/4 0 1 3/4 0 | 6

 $4B=(1,2,3) \Rightarrow exchange i=1, k=5$ $\Rightarrow \beta = (5,2,3)$

• basic solution: set non-basic var. to 0

1/4 0 0 1/4 1 10 -1/4 1 0 7/4 0 32 -3/4 0 1 3/4 0 6

 $X_2 = 10 - \frac{1}{4}y_1 - \frac{1}{4}X_A$ $y_4^* = 0$, $x_4^* = 0$ y=32+1/4y, -3/4x, $x_2^* = 10, y_2^* = 32, y_3^* = 6$ $y_3 = 6 + 3/4y_1 - 3/4x_1$

• basic feasible solution:

basic solution that is also feasible \(\Limin \text{all } \times \(\text{x*, y*} ≥ \)

Y3=0

• short tableau: (= compact notation)

i= → 23 1 K= → 1 2 3 4 5 Y1 /2 /3 X1 X2 1/4 0 0 1/4 1 10 -1/4 1 0 7/4 0 - 401340 6

 $i=k=\longrightarrow 1$ 4 1 1 / X basic solution 1 5 x₂ \(\gamma_4 \\ \gamma_4 \\ \gamma_4 \\ \gamma_2 \\ \gamma_4 \\ \gamma_4 \\ \gamma_4 \\ \gamma_2 \\ \gamma_4 \\ \gamma X2, Y2, Y3 for x=0, y=0 3 3 /3 -3/4 3/4 6

⇒ basis exchange formula:

aik = 1/aik (pivot) ajk = - ajk/aik (pivot col.) ail = ail/aik (pivot row)

ajl = ajl - ajk ail aik b; = bi/aik bj=bj-ajk-bi/aik

esechange Y₄ X₄ Yn Y3 i=3,k=4: y3 -3/4 3/4 6 X4 -1 4/3 8 Y2=0 1×2 I new basic

cond. for feasible basic solution to stay feasible • $a_{ik} > 0$ (pivot nonnegalive) b_j/a_{jk} ≥ b_i/a_{ik} ∀_j (quotient rule)

%=0 **↓** • short fableau with cost: append variable z to x to track objective of basic solution ($z = c^T x$)

X, ... Xn Z /1... /m X1... Xn Z -C, --Cn 1 0 .. 0 - C2 0 ya an .. an ym am - am | bm

conditor increasing objective after exchange: $a_{ok} < 0$

Solution

basis exchange formula same for objective towas for other rows.

simplex method

- 1) start with a feasible tableau ⇔ b, ,.., b, ≥0
- 2) perform exchange step with a pivot aik that satisfies:
 - $a_{ik} > 0$ and $b_j / a_{ik} > b_i / a_{ik} \forall j \rightarrow \text{will remain feasible}$
 - $a_{ok} < 0 \rightarrow will increase objective$
- 3) repeal @ until:
 - a_{ok}>0 ∀k > basic solution is optimal solution!
 - ∃k s.t a_{ok}<0 & a_{ik}≤0∀i → solution is unbounded!

multiple pivots could satisfy these cond. additional rules that improve efficiency:

- · pick column with most negative and
- · pick viable column with smallest index k "Blade's rule": guaranteed to terminate

finding a feasible basic solution (for when initial tableou is unfeasible)

original problem: $\max c^T x$ subj.to: y + Ax = b and $x \ge 0, y \ge 0$ auxiliary problem: $\max -x_0$ subj.to: $y + Ax - (1,...,1)^T \cdot x_0 = b$ and $x \ge 0, y \ge 0, x_0 \ge 0$

> problem always feasible (with large x_0)! if $x_0^*=0$, then x^*,y^* feasible solutions of original problem!

<u>dual problem</u>

subj.to: $Ax \le b$, $x \ge 0$ \rightarrow dual problem: $Ax \le b$, $x \ge 0$ \rightarrow dual problem: $Ax \le b$, $Ax \ge b$, Axprimal problem: max cTX

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4x_1+x_2+5x_3+3x_4=Cx_4
max 4x_4 + x_2 + 5x_3 + 3x_4
                                                                                                                                 Min y_4 + 55y_2 + 3y_3
                                            find linear comb. of constr.
                                             at every x coeff dominales (X1-X2-X3+3X441). y
s.t.: x_4 - x_2 - x_3 + 3x_4 \le 1
                                                                                                                                 st: y_4 + 5y_2 - y_3 \ge 4
                                            its coeff in ct and resulting
        5x_4 + x_2 + 3x_3 + 8x_4 \le 55
                                                                                                                                       -y_1 + y_2 + 2y_3 \ge 1
                                                                                      5x+x2+3x3+8x4=551.72
                                            constraint is minimal
       -x_1+2x_2+3x_3-5x_4 \le 3
                                                                                                                                       -y<sub>4</sub> +3y<sub>2</sub>+3y<sub>3</sub>≥5
                                                                                   (-x_1+2x_1+3x_1-5x_4+3)\cdot y_3
                                                                                                                                      -3y_1 + 8y_2 - 5y_3 \ge 3
       X<sub>1</sub>,X<sub>2</sub>,X<sub>3</sub>,X<sub>4</sub>≥0
                                                                                                                                       y<sub>4</sub>,y<sub>2</sub>,y<sub>3</sub>≥0
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 rel. foslandard LP: primal slack var. x^s = y dual opkim.var. $max c^{T}x subj.to: x^{S} + Ax = b ; x^{S}, x \ge 0$ dual slack var. ys = x primal ophim.car. $\{\max -b^Ty \text{ subj.to: } y^S - A^Ty = -c ; y^S, y \ge 0\}$

• weak duality theorem: $z = c^Tx \le b^Ty = w$ feasible x objective \le feasible x objective • strong duality theorem: $z^* = c^T x^* = b^T y^* = w^*$ optimum of primal = optimum of dual

pd OPT INF UNB OPT V X INF X V UNB X V X

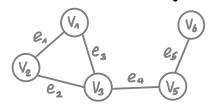
(usefull e.g. if some non-optimal z, w are found that are close - can stop, since optimum is between)

• complementary slackness theorem: necessary and sufficient cond. for x* and x* useful to compute x*ify* $((A)_i x^* = b_i \text{ or } y_i^* = 0 \quad \forall_{i=1,..,m}) \text{ AND } ((A^T)_j y^* = C_j \text{ or } x_j^* = 0 \quad \forall_{j=1,..,n})$ (is known and the opposite)

• sensitivity theorem: for relaxed constr. $A_x = b + t$ (t:small!) $\Rightarrow z^*_{new} = z^* + t^T \cdot y^*$ > if y=0: constri is inactive > relaxing it with t; >0 won't raise objective \Rightarrow if $\gamma_i>0$: relaxing constr. i with $t_i>0$ will raise objective. larger $\gamma_i \Rightarrow$ larger increase in z^*

combinatorial optimization

undirected, unweighted graph:



 e_{s} vertices: $V = \{v_{1}...v_{n}\}$ e_{s} edges: $E = \{e_{n}...e_{m}\}$ $-(v_{5})$ graph: $G = (v_{i}E)$

edge representation in memory:

- Breadth-Einst search (for shortest path): find smallest # of edges connecting V_n to $U \in V := d(V_{n,U})$

 $\overline{d}(V_{A},U) = \begin{cases} 0 : U = V_{A} \\ \infty : U \neq V_{A} \end{cases}$ k=1 ; L={v,} while L # {} do: Lnew= {}

for all ue N(L)= {ueV|] weL, Eu, wfeEf do: if d(v,v)=00 then d(v,v)=k, Lnew~U kek+1, LeLnew

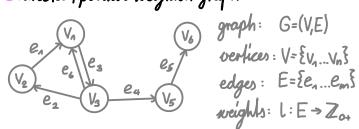
proof: show $D_{k} = \overline{D}_{k}$ by induction $\left(D_{k} = \{ u \in V \mid o(v_{*}, u) = k \} \right)$ $D_o = \{v_i\} = D_o \quad \checkmark$

assume $D_r = \overline{D}_r \forall r \leq k$, proce $D_{k+n} = \overline{D}_{k+n}$:

 $\overline{D}_{k+a} \subseteq D_{k+a}$: let $U \in \overline{D}_{k+a}$. since $U \in N(D_k) \to cl(v_a, u) \le k+1$ and with $d(v_{a,0})>k \Rightarrow d(v_{a,0})=k+1 \Rightarrow \overline{D}_{k+1} \leq D_{k+1}$

 $D_{k+1} \subseteq \overline{D}_{k+1}$: let $U \in D_{k+1} \Rightarrow \exists path (v_1,...,w_iU) \Rightarrow w \in D_k$ $\Rightarrow \cup \in \mathbb{N}(\mathbb{O}_{k}) \Rightarrow \cup \in \overline{\mathbb{O}}_{k+n} \Rightarrow \mathbb{O}_{k+n} \subseteq \mathbb{O}_{k+n}$

directed, positive weighted graph:



path: P= {ea,eb,...} path length: L(P)= \(\int_{eep} \) L(e) shortest path: d(s,v)= min (IP) s.t Piss-v path comments:

·if path ((s~w~t)=d(s,t) then Us~w)=d(s,w)

· all edges used by shortest paths form a free

-Diskrtras algorithm (for shortest path):

while M#V:

U= argmin dv M←M v {v}

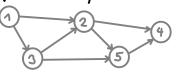
for all $e=(u,w) \in S_{+}(u)$, $w \in V \setminus M$:

if dw>du+l(e) then dw←du+l(e)

proof: show dy=d(s,v) \v \iv by induction at iter. 1: ds=d(s,s)=0 1 assume at iter i: $d_x = d(s,x) \ \forall x \in M \rightarrow \text{show at } i+1: \ d_u = d(s,u)$ du < d(s,v): can't happen, as du always some path or co $d_{\nu}>d(s,\nu):$ $d_{\nu}>d(s,\nu)=d(s,\nu)< d_{\nu}$

- longest path problem: can be built by filipping all weights to negative and searching shortest path. problem is that subpath of longest path is itself not longest. Dijkshas alg. breaks... very hard problem?

special case for directed acyclic graphs DAG:

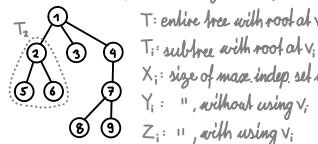


verlices sorted, so all edges point right.

in this case a subpath of the longest path is also the longest subpath?

Ireus: any 2 vertices are connected by exactly one path.

- independent set problem: largest set of vertices that don't share edges S⊆V s.t. Yu,v ∈S: {u,v}&E



T: enlire free with root at v,

comments:

· if v; & S then |S∩Y[T;]|=X; ∀v; children of v;

X; size of max indep. set in T;

· if v; ∈ S then |S∩V[T;]|=Y; ∀v; children of v;

 $Y_i : "$, without using V_i

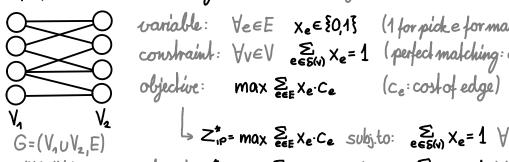
(8) (9) Z;: 11, with using V;

algorithm: traverse tree bottom up, updating Y; Z; for each node:

 $Y_i = \sum_{j=1}^{n} \max(Y_j, Z_j)$; $Z_i = 1 + \sum_{j=1}^{n} \min_{j=1}^{n} \sum_{j=1}^{n} \max(Y_i, Z_j)$

combinatorial optimization via LP

• perfect bipartite matching problem: find largest set $M \subseteq E$ s.t. $\forall e_1 \neq e_2, e_4, e_2 \in M$: $e_1 \cap e_2 = \emptyset$



variable: $\forall e \in E \quad x_e \in \{0,1\} \quad (1 \text{ for picke for matching } M)$

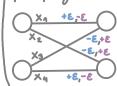
constraint: $\forall v \in V$ $\underset{e \in S(v)}{\succeq} x_e = 1$ (perfect matching: one edge out of every vertex)

> Z*p= max ≥ Xe·Ce subj.to: ≥ Xe=1 \ \veV; Xe>0 \ \ \ e E; Xe \ \ \ Z

|V_1 = |V_2| = n relaxed: Z_10 = max \(\frac{\x_{e}}{\x_{e}} \text{X}_{e} \cdot C_e \) subject: \(\frac{\x_{e}}{\x_{e}} \text{X}_{e} = 1 \) \(\frac{\x_{e}}{\x_{e}} \text{> 0 } \) \(\frac{\x_{e}}{\x_{e}} \text{|R} \)

in this problem if x^* is any extreme point (basic feasible solution) of the relaxed problem, then $x^* \in \mathbb{Z}$. since LP solutions are always extreme points it follows that $Z_{ip}^* = Z_{Lp}^*$

proof by contradiction: assume x extreme point and tractional



for \times to be fractional and feasible it has to contain loops of even length. In one peasible solutions y, z can be built by adding/subtracting a sufficiently small ε to edges of x as shown.

masimum matching/minimum vertex cover:

max.matching:

Z = max EEE Xe subj.to: EES(N) Xe=1 YVEV, Xe>0 YeEE, XeEZ

relaxed max. matching: $Z_{LP}^* = \max \sum_{e \in E} x_e \text{ subj.to: } \sum_{e \in S(v)} x_e \le 1 \ \forall v \in V, \ x_e \ge 0 \ \forall e \in E, \ x_e \in \mathbb{R}$] dual! relaxed min vertex cover: $W_{LP}^* = \min \sum_{v \in V} y_v \text{ subj.to: } y_v + y_v \ge 1 \ \forall \xi v, v \le E, \chi \ge 0 \ \forall v \in V, \ \chi_e \in \mathbb{R}$

min vertex cover:

wip = min for y, subj.to: y,+y, >1 Y \underline{\underl

 $Z_{IP}^* \stackrel{\checkmark}{\leftarrow} Z_{LP}^* = W_{LP}^* \stackrel{\checkmark}{\leftarrow} W_{IP}^* \rightarrow \text{weak duality holds for mase.matching} = \min. \text{vertex cover}.$

— for bipartife graps these can be shown to be equalities (similar to above proof)