

# GENERATIVE ADVERSARIAL NETWORKS With PyTorch:

### Introduction to GANs

#### What are GANs?

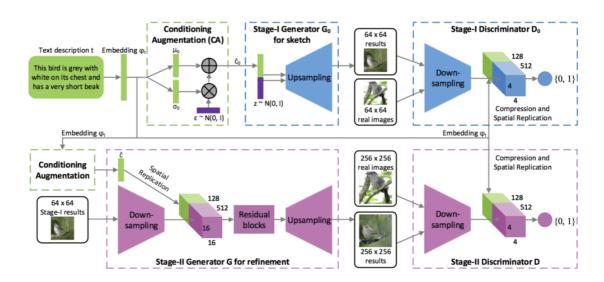
Generative Adversarial Networks (GANs) are a type of machine learning framework where two neural networks, the Generator and the Discriminator, are trained simultaneously through adversarial processes. The Generator creates fake data samples, while the Discriminator evaluates them against real data samples to distinguish the fake from the real.

#### **Applications of GANs**

GANs have a wide range of applications including, but not limited to:

- **Image Generation**: Creating realistic images, enhancing image resolution, and generating art.
- **Image-to-Image Translation**: Tasks like image colorization, super-resolution, and style transfer.
- Video Generation: Creating realistic video sequences from images or text.
- Data Augmentation: Generating synthetic data to augment training datasets.
- Healthcare: Enhancing medical imaging and aiding in drug discovery.
- **Entertainment**: Generating realistic textures and environments in video games, and creating virtual reality content.

## THE GAN ARCHITECTURE



The architecture of a Generative Adversarial Network (GAN) consists of two primary components: the Generator and the Discriminator. These two neural networks are trained simultaneously through an adversarial process, where the Generator aims to produce realistic data, and the Discriminator aims to distinguish between real and fake data.

#### Generator

The Generator is a neural network that takes random noise as input and generates data that mimics the real data. The goal of the Generator is to create outputs that are indistinguishable from real data samples to the Discriminator. The Generator's architecture typically includes:

- **Input Layer**: Takes a random noise vector (e.g., sampled from a normal distribution) as input.
- Hidden Layers: Series of fully connected (or sometimes convolutional) layers with
  activation functions such as ReLU. These layers learn to transform the noise into a more
  structured output.
- **Output Layer**: Produces data of the same shape as the real data, often using a Tanh activation function to ensure the output values are in a specific range.

Example of Generator network class in Pytorch:

```
def forward(self, x):
    return self.main(x).view(-1, 1, 28, 28)
```

#### Discriminator

The Discriminator is a neural network that takes both real data and fake data (generated by the Generator) as input and tries to classify them as real or fake. The goal of the Discriminator is to correctly identify real versus fake data samples. The Discriminator's architecture typically includes:

- Input Layer: Takes a data sample (e.g., an image) as input.
- **Hidden Layers**: Series of fully connected (or sometimes convolutional) layers with activation functions such as Leaky ReLU. These layers learn to extract features that help in distinguishing real data from fake data.
- **Output Layer**: Produces a single value (often using a Sigmoid activation function) representing the probability that the input data is real.

Example of the Discriminator network in Pytorch:

#### **Adversarial Training**

The training process of GANs is adversarial in nature, where the Generator and Discriminator compete against each other:

- **Generator's Objective**: Generate data that is realistic enough to fool the Discriminator. It aims to minimize the Discriminator's ability to correctly classify fake data as fake.
- **Discriminator's Objective**: Correctly classify real data as real and fake data as fake. It aims to maximize its classification accuracy.

This adversarial process can be summarized by the following loss functions:

- **Generator Loss**: Measures how well the Generator is able to fool the Discriminator. It is typically the negative log probability of the Discriminator predicting the fake data as real.
- **Discriminator Loss**: Measures how well the Discriminator is able to distinguish between real and fake data. It is the sum of the log probabilities of correctly classifying real data and fake data.

The following code snippets define the loss functions and optimizers used for training the GAN:

```
criterion = nn.BCELoss()

optimizer_g = optim.Adam(generator.parameters(), 1r=0.0002)
optimizer_d = optim.Adam(discriminator.parameters(), 1r=0.0002)
```

During training, both networks are updated in a loop until the Generator produces realistic data that the Discriminator cannot easily distinguish from real data. This adversarial process leads to the Generator learning to produce increasingly realistic data samples over time.

This architecture and training process form the foundation of Generative Adversarial Networks, enabling them to generate high-quality synthetic data across various applications.

## PROJECT WORKSPACE

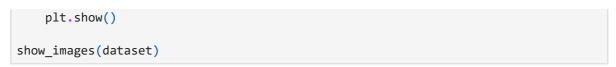
```
In []: #Installing some dependencies
!pip install torch torchvision matplotlib

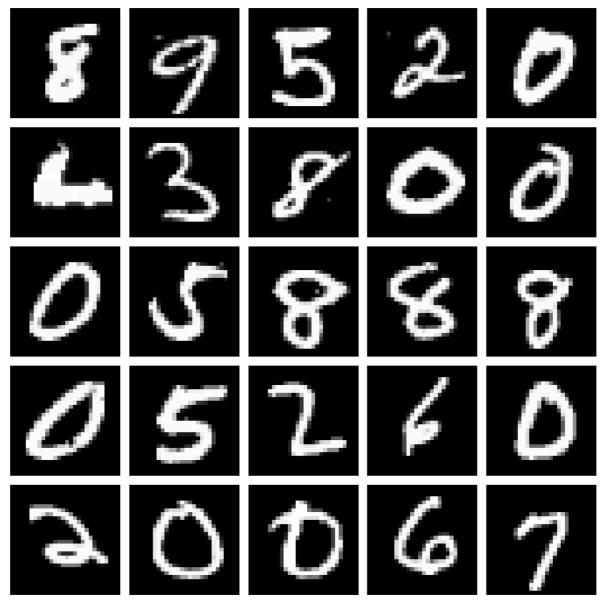
In [7]: # Doing some basic imports
import torch
import torch.nn as nn
import torch.optim as optim
import torchvision.transforms as transforms
import torchvision.datasets as datasets # torchvision for computervision ,
from torch.utils.data import DataLoader
import matplotlib.pyplot as plt # For data visualization
```

## DATA PREPARATION

For this project, I'll use the MNIST dataset, a collection of 70,000 images of handwritten digits.

```
In [8]: transform = transforms.Compose([
             transforms.ToTensor(),
             transforms.Normalize((0.5,), (0.5,))
         ])
         dataset = datasets.MNIST(root='data', train=True, transform=transform, download=Tru
         dataloader = DataLoader(dataset, batch_size=64, shuffle=True)
In [11]:
         import numpy as np
         # Plotting some images from the dataset
         def show_images(dataset, num_images=25):
             data_loader = DataLoader(dataset, batch_size=num_images, shuffle=True)
             images, labels = next(iter(data_loader))
             images = images.numpy()
             fig, axes = plt.subplots(5, 5, figsize=(10, 10))
             axes = axes.flatten()
             for img, ax in zip(images, axes):
                 ax.imshow(np.squeeze(img), cmap='gray')
                 ax.axis('off')
             plt.tight_layout()
```





# PYTORCH CODE IMPLEMENTATION

# **MODEL BUILDING**

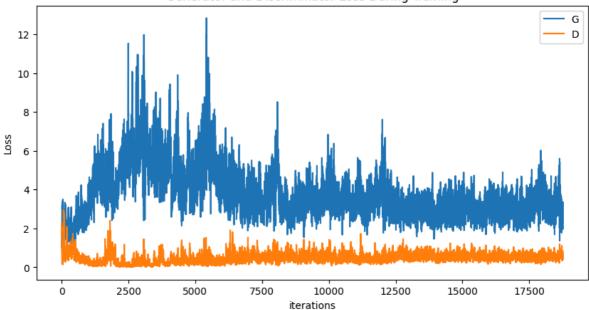
```
nn.Tanh()
    def forward(self, x):
        return self.main(x).view(-1, 1, 28, 28)
class Discriminator(nn.Module):
   def __init__(self):
        super(Discriminator, self).__init__()
        self.main = nn.Sequential(
            nn.Linear(28*28, 512),
            nn.LeakyReLU(0.2, inplace=True),
            nn.Linear(512, 256),
            nn.LeakyReLU(0.2, inplace=True),
            nn.Linear(256, 1),
            nn.Sigmoid()
        )
    def forward(self, x):
        return self.main(x.view(-1, 28*28))
```

# **MODEL TRAINING**

```
In [ ]: generator = Generator()
         discriminator = Discriminator()
         # Using Adam Optimizer and BinaryCrossEntropy Loss
         criterion = nn.BCELoss()
         optimizer g = optim.Adam(generator.parameters(), lr=0.0002)
         optimizer_d = optim.Adam(discriminator.parameters(), 1r=0.0002)
In [14]:
        # Initialize lists to store the loss values
         # This will enable us plot the losses later on
         d_losses = []
         g_losses = []
         num_epochs = 20
         for epoch in range(num epochs):
             for i, (real_images, _) in enumerate(dataloader):
                 batch_size = real_images.size(0)
                 # Train Discriminator
                 real_labels = torch.ones(batch_size, 1)
                 fake_labels = torch.zeros(batch_size, 1)
                 outputs = discriminator(real_images)
                 d_loss_real = criterion(outputs, real_labels)
                 real score = outputs
                 z = torch.randn(batch_size, 100)
                 fake_images = generator(z)
                 outputs = discriminator(fake_images.detach())
                 d_loss_fake = criterion(outputs, fake_labels)
                 fake_score = outputs
                 d loss = d loss real + d loss fake
                 optimizer_d.zero_grad()
                 d_loss.backward()
                 optimizer_d.step()
                 # Train Generator
```

```
outputs = discriminator(fake images)
                 g_loss = criterion(outputs, real_labels)
                 optimizer_g.zero_grad()
                 g loss.backward()
                 optimizer g.step()
                 # Record the Losses
                 d losses.append(d loss.item())
                 g_losses.append(g_loss.item())
             print(f'Epoch [{epoch}/{num_epochs}], d_loss: {d_loss.item():.4f}, g_loss: {g_l
                   f'D(x): {real_score.mean().item():.2f}, D(G(z)): {fake_score.mean().item()
         Epoch [0/20], d_loss: 0.2938, g_loss: 3.2088, D(x): 0.87, D(G(z)): 0.11
         Epoch [1/20], d_loss: 0.6490, g_loss: 4.5835, D(x): 0.86, D(G(z)): 0.19
         Epoch [2/20], d_loss: 0.5929, g_loss: 9.6355, D(x): 0.88, D(G(z)): 0.01
         Epoch [3/20], d_loss: 0.3569, g_loss: 5.7651, D(x): 0.87, D(G(z)): 0.08
         Epoch [4/20], d loss: 0.2780, g loss: 5.4575, D(x): 0.93, D(G(z)): 0.09
         Epoch [5/20], d_loss: 0.2873, g_loss: 5.6587, D(x): 0.91, D(G(z)): 0.12
         Epoch [6/20], d_loss: 0.4554, g_loss: 3.9616, D(x): 0.86, D(G(z)): 0.09
         Epoch [7/20], d_loss: 0.7824, g_loss: 2.8026, D(x): 0.75, D(G(z)): 0.11
         Epoch [8/20], d_loss: 1.2747, g_loss: 1.8294, D(x): 0.70, D(G(z)): 0.24
         Epoch [9/20], d_loss: 0.7637, g_loss: 3.2661, D(x): 0.72, D(G(z)): 0.10
         Epoch [10/20], d_loss: 0.2501, g_loss: 3.2513, D(x): 0.92, D(G(z)): 0.12
         Epoch [11/20], d_loss: 0.3131, g_loss: 2.6590, D(x): 0.91, D(G(z)): 0.17
         Epoch [12/20], d_loss: 0.2366, g_loss: 2.9754, D(x): 0.96, D(G(z)): 0.16
         Epoch [13/20], d_loss: 0.4572, g_loss: 3.3137, D(x): 0.85, D(G(z)): 0.12
         Epoch [14/20], d_loss: 0.4166, g_loss: 3.7680, D(x): 0.84, D(G(z)): 0.08
         Epoch [15/20], d_loss: 0.4858, g_loss: 2.6184, D(x): 0.84, D(G(z)): 0.15
         Epoch [16/20], d_loss: 0.2739, g_loss: 3.0489, D(x): 0.90, D(G(z)): 0.11
         Epoch [17/20], d_loss: 0.7272, g_loss: 2.8237, D(x): 0.81, D(G(z)): 0.22
         Epoch [18/20], d_loss: 0.2626, g_loss: 3.0699, D(x): 0.96, D(G(z)): 0.17
         Epoch [19/20], d_loss: 0.8250, g_loss: 2.1163, D(x): 0.91, D(G(z)): 0.43
In [15]: # Plotting the loss curves
         def plot losses(d losses, g losses):
             plt.figure(figsize=(10, 5))
             plt.title("Generator and Discriminator Loss During Training")
             plt.plot(g_losses, label="G")
             plt.plot(d_losses, label="D")
             plt.xlabel("iterations")
             plt.ylabel("Loss")
             plt.legend()
             plt.show()
         plot_losses(d_losses, g_losses)
```





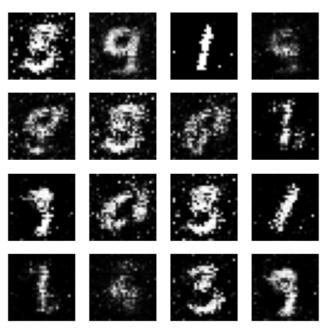
## **MODEL EVALUATION**

```
In [18]: # Here I get images at random from my testing set
def generate_and_save_images(model, epoch, test_input):
    predictions = model(test_input).detach().cpu().numpy()
    fig = plt.figure(figsize=(4, 4))

    for i in range(predictions.shape[0]):
        plt.subplot(4, 4, i+1)
        plt.imshow(predictions[i, 0], cmap='gray')
        plt.axis('off')

    plt.savefig('image_at_epoch_{:04d}.png'.format(epoch))
        plt.show()

test_input = torch.randn(16, 100)
    generate_and_save_images(generator, num_epochs, test_input)
```



# SAVING AND LOADING THE MODEL

```
In [19]: torch.save(generator.state_dict(), 'generator.pth')
    torch.save(discriminator.state_dict(), 'discriminator.pth')

# Loading the modeLs
    generator.load_state_dict(torch.load('generator.pth'))
    discriminator.load_state_dict(torch.load('discriminator.pth'))

Out[19]: <All keys matched successfully>
In []:
```