

Com S 576 - Motion Planning: HW2

Solutions by: Mohammad Hashemi

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Task 1 P3.1

$$H_i = \{(x, y) \in \mathbb{R}^2 \mid f_i(x, y) \leq 0\}$$

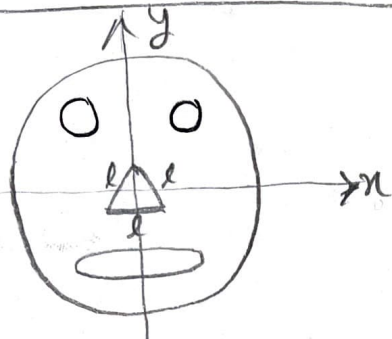
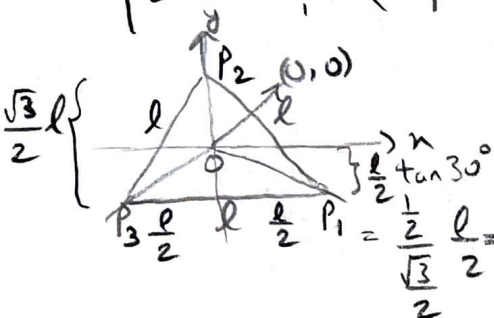


Fig. 3.4 → Amended by a triangle inscribed @ the center

The requested task of the question can be done by adding another algebraic primitive to O ;

$$O \supseteq H_1 \wedge H_2 \wedge H_3 \wedge H_4 \wedge H_5$$

The new one

$$H_5 = H_{51} \wedge H_{52} \wedge H_{53}$$

$$P_1 = \left(\frac{l}{2}, -\frac{\sqrt{3}}{6}l\right); P_2 = \left(0, \frac{\sqrt{3}}{3}l\right); P_3 = \left(-\frac{l}{2}, -\frac{\sqrt{3}}{6}l\right) \Rightarrow \begin{cases} H_{51} \rightarrow P_1 P_2 \rightarrow f_{51} \\ H_{52} \rightarrow P_2 P_3 \rightarrow f_{52} \\ H_{53} \rightarrow P_3 P_1 \rightarrow f_{53} \end{cases}$$

$$P_1 P_2 : ax + by + c = 0 \Rightarrow \begin{cases} \frac{l}{2}a - \frac{\sqrt{3}}{6}lb + c = 0 \\ \frac{\sqrt{3}}{3}lb + c = 0 \Rightarrow c = -\frac{\sqrt{3}}{3}lb \end{cases} \xRightarrow{a=1} \frac{l}{2} = \frac{\sqrt{3}}{2}lb \Rightarrow b = \frac{1}{\sqrt{3}} = \frac{\sqrt{3}}{3} \Rightarrow c = -\frac{l}{3}$$

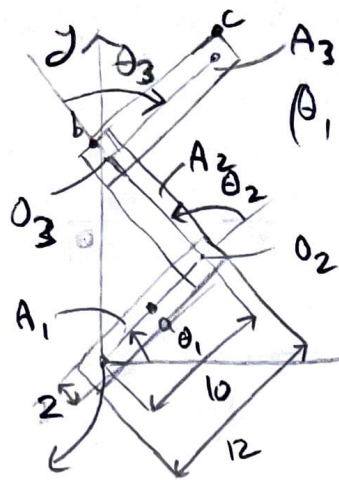
$$\Rightarrow x + \frac{\sqrt{3}}{3}y - \frac{l}{3} = 0 \xRightarrow{(0,0)} f(0,0) = -\frac{l}{3} < 0 \Rightarrow f_{51}(x,y) = -\left(x + \frac{\sqrt{3}}{3}y - \frac{l}{3}\right)$$

$$P_2 P_3 : a=1 \Rightarrow \begin{cases} \frac{\sqrt{3}}{3}lb + c = 0 \Rightarrow c = -\frac{\sqrt{3}}{3}lb \\ -\frac{l}{2} - \frac{\sqrt{3}}{6}lb + c = 0 \end{cases} \Rightarrow -\frac{\sqrt{3}}{2}lb = \frac{l}{2} \Rightarrow b = -\frac{1}{\sqrt{3}} = -\frac{\sqrt{3}}{3} \Rightarrow c = \frac{l}{3}$$

$$\Rightarrow x - \frac{\sqrt{3}}{3}y + \frac{l}{3} = 0 \xRightarrow{(0,0)} f(0,0) = \frac{l}{3} > 0 \Rightarrow f_{52}(x,y) = x - \frac{\sqrt{3}}{3}y + \frac{l}{3}$$

$$P_3 P_1 : y + \frac{\sqrt{3}}{6}l = 0 \xRightarrow{(0,0)} f(x,y) = \frac{\sqrt{3}}{6}l > 0 \Rightarrow f_{53}(x,y) = y + \frac{\sqrt{3}}{6}l$$

Task 2 P 3.7



$$(\theta_1, \theta_2, \theta_3) = \left(\frac{\pi}{4}, \frac{\pi}{2}, -\frac{\pi}{4}\right)$$

$$a \in A_1 \xrightarrow[\text{frame}]{\text{Body}} a = (5, 0)$$

$$b \in A_2 \xrightarrow{\sim} b = (11, 0)$$

$$c \in A_3 \xrightarrow{\sim} c = (11, 1)$$

a)

$$\Rightarrow a \in W: T_1 a = \begin{bmatrix} \cos \theta_1 & -\sin \theta_1 & 0 \\ \sin \theta_1 & \cos \theta_1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 5\frac{\sqrt{2}}{2} \\ 5\frac{\sqrt{2}}{2} \\ 1 \end{bmatrix}$$

\downarrow
 $a \in A_1$

$$b \in W: T_1 T_2 b = T_1 \begin{bmatrix} \cos \theta_2 & -\sin \theta_2 & 0 \\ \sin \theta_2 & \cos \theta_2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 11 \\ 0 \\ 1 \end{bmatrix} = T_1 \begin{bmatrix} 10 \\ 11 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 10 \\ 11 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{-\sqrt{2}}{2} \\ \frac{21\sqrt{2}}{2} \\ 1 \end{bmatrix}$$

$$c \in W: T_1 T_2 T_3 c = T_1 T_2 \begin{bmatrix} \cos \theta_3 & -\sin \theta_3 & 0 \\ \sin \theta_3 & \cos \theta_3 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 11 \\ 1 \\ 1 \end{bmatrix} = T_1 T_2 \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 11 \\ 11 \\ 1 \end{bmatrix} = T_1 T_2 \begin{bmatrix} 6\sqrt{2}+10 \\ -5\sqrt{2} \\ 1 \end{bmatrix}$$

$$= T_1 \begin{bmatrix} 0 & -1 & 10 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 6\sqrt{2}+10 \\ -5\sqrt{2} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5\sqrt{2}+10 \\ 6\sqrt{2}+10 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 11+10\sqrt{2} \\ 1 \end{bmatrix}$$

\downarrow
 c

b) All such configs should form an equilateral triangle:



$$\text{So } \theta_1 \in [0, 2\pi]; \theta_2 \in \left\{\frac{\pi}{3}\right\}; \theta_3 \in \left\{\frac{\pi}{3}\right\}$$