

# **Part 1**

# **Preliminaries, Notation and Linear Algebra**

M D Sacchi

Problemas Inversos - UNLP

- <https://github.com/msacchi/UNLP-2024-Inversion>
- Email: msacchi@ualberta.ca

# Preliminaries: Notation

$f(\mathbf{x})$  : scalar function of a vector

$\mathbf{x}$  : a vector

$x$  : a scalar

$\alpha$  : a scalar

$\mathbf{M}$  : a matrix

$M_{i,j}$  : element of the matrix

$J$  : scalar cost function

In general, we will use upper case bold fonts for matrices, and lower case bold fonts for vectors.

Lower case non-bold are scalars. Operators are denoted by calligraphic fonts. All the above is true unless we indicate there is an exception.

# Preliminaries: Notation

- $J = f(\mathbf{x})$
- $\mathbf{u} = f(\mathbf{x})$
- $\alpha = \mathbf{M}$
- $\mathbf{AB} = \mathbf{C}$
- $\alpha + \mathbf{M} = \mathbf{v}$
- $\|\mathbf{v}\|_2^2 = \alpha$
- $\|\mathbf{v}\|_2^2 = \mathbf{u}$

# Preliminaries: Notation

- $J = f(\mathbf{x})$  ok
- $\mathbf{u} = f(\mathbf{x})$  X
- $\alpha = \mathbf{M}$  X
- $\mathbf{AB} = \mathbf{C}$  ok
- $\alpha + \mathbf{M} = \mathbf{v}$  X
- $\|\mathbf{v}\|_2^2 = \alpha$  ok
- $\|\mathbf{v}\|_2^2 = \mathbf{u}$  X

# Preliminaries: ell-2 norm

$$\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ \vdots \\ u_N \end{pmatrix}$$

- Real vector

$$\mathbf{u} : N \times 1 \longrightarrow \|\mathbf{u}\|_2^2 = \mathbf{u}^T \mathbf{u} = \sum_{i=1}^N u_i^2$$

- Complex vector

$$\mathbf{u} : N \times 1 \longrightarrow \|\mathbf{u}\|_2^2 = \mathbf{u}^H \mathbf{u} = \sum_{i=1}^N u_i u_i^* = \sum_{i=1}^N |u_i|^2$$

- The ell-2 norm

$$l_2 = \|\mathbf{u}\|_2 = \sqrt{\|\mathbf{u}\|_2^2}$$

# Preliminaries: ell-2 norm

$$\|\mathbf{u}\|_2^2 = \mathbf{u}^T \mathbf{u} = (u_1 \quad u_2 \quad u_3 \quad u_4) \begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{pmatrix} = \sum_{k=1}^4 u_k^2$$

$$\|\mathbf{u}\|_2^2 = \mathbf{u}^H \mathbf{u} = (u_1^* \quad u_2^* \quad u_3^* \quad u_4^*) \begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{pmatrix} = \sum_{k=1}^4 |u_k|^2$$

# Preliminaries: Matrix-times-vector

$\mathbf{A}$  : Matrix  
 $\mathbf{x}$  : Vector  
 $\mathbf{y}$  : Vector  
 $\alpha$  : scalar

$A_{ij}$  : Element of the Matrix  $\mathbf{A}$

$x_i$  : Element of Vector  $\mathbf{x}$

$y_i$  : Element of Vector  $\mathbf{y}$

## Matrix Multiplication

$$\mathbf{y} = \mathbf{A} \mathbf{x}$$
$$N \times 1 \quad N \times M \quad M \times 1$$



# Preliminaries: Matrix-times-vector

$$\mathbf{y} = \mathbf{A} \mathbf{x}$$

$N \times 1$        $N \times M$        $M \times 1$

Outer Loop      Inner Loop

$$y_i = \sum_{j=1}^M A_{ij} x_j \quad i = 1 \dots N$$

Output index      Input index

# Notation and Review of Linear Algebra

$$\mathbf{y} = \mathbf{A} \mathbf{x}$$

## Matrix-times-vector multiplication

```
In [1]: 1 N = 4
        2 M = 5
        3 A = randn(Float32,N,M)
        4 x = randn(Float32,M)
        5
        6 y = A*x
```

```
Out[1]: 4-element Vector{Float32}:
        -0.48016113
         3.7603946
         4.958347
         0.91909456
```

## My own code...

```
In [2]: 1 y= zeros(Float32,N)
        2 for i = 1:N                                # Outer loop over data parameters
        3     for j=1:M                                # Inner loop over model parameters
        4         y[i]+=A[i,j]*x[j]
        5     end
        6 end
        7 y
```

```
Out[2]: 4-element Vector{Float32}:
        -0.48016113
         3.7603943
         4.9583473
         0.91909456
```

# Preliminaries: Matrix-times-vector

$$\underset{N \times 1}{\mathbf{y}} = \underset{N \times M}{\mathbf{A}} \underset{M \times 1}{\mathbf{x}}$$

$$y_i = \sum_{j=1}^M A_{ij} x_j \quad i = 1 \dots N$$

**Forward mode**

$$\underset{M \times 1}{\mathbf{x}'} = \underset{M \times N}{\mathbf{A}^T} \underset{N \times 1}{\mathbf{y}}$$

$$x'_j = \sum_{i=1}^N A_{ij} y_i \quad j = 1 \dots M$$

**Transpose mode**

# Preliminaries: Matrix-times-vector

$$\underset{N \times 1}{\mathbf{y}} = \underset{N \times M}{\mathbf{A}} \underset{M \times 1}{\mathbf{x}}$$

$$y_i = \sum_{j=1}^M A_{ij} x_j \quad i = 1 \dots N$$

**Forward mode**

$$\underset{M \times 1}{\mathbf{x}'} = \underset{M \times N}{\mathbf{A}^H} \underset{N \times 1}{\mathbf{y}}$$

$$x'_j = \sum_{i=1}^N A_{ij}^* y_i \quad j = 1 \dots M$$

**Conjugate mode**