

# Migration\_Demigration\_CGLS

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```
[4]: using SeisPlot,PyPlot, Printf
```

## 0.1 1) Test CGLS with EXPLICIT OPERATOR

```
[5]: function cglsl(A, y, x0, tol, max_iter)
      # min_x ||A x-y||_2^2

      m, n = size(A)
      x = x0
      r = A' * (y - A * x)
      p = r
      rsold = r' * r

      for i in 1:max_iter
          Ap = A * p
          alpha = rsold / (Ap' * Ap)
          x = x + alpha * p
          r = r - alpha * A' * Ap
          rsnew = r' * r
          if sqrt(rsnew) < tol
              break
          end
          p = r + (rsnew / rsold) * p
          rsold = rsnew
      end

      return x
end
```

```
[5]: cglsl (generic function with 1 method)
```

```
[6]: # Testing CGLS with Explicit A.

A = randn(20,3)
x = randn(3)
y = A*x+0.001*randn(20)
x0 = zeros(3)
```

```

tol = 0.0001
max_iter = 3

x1 = cgls(A, y, x0, tol, 20)

x2 = (A'*A)\(A'y)
k=1
@printf("    True      Estimated\n")
for k in 1:3
@printf("    %7.4f      %7.4f \n", x1[k],x2[k])
end

```

True	Estimated
1.7556	1.7556
-0.8735	-0.8735
0.7247	0.7247

### 0.1.1 2) CGLS Implicit for demigration and migration Opertors

```

[7]: function cgls_Implicit(y, x0, tol, max_iter, ntraces, s, rec, nx, nz, dx, dz, nt, dt, v)
    # min_x ||A x-y||_2^2 Implicit. This code is not recyclable because it is
    # designed for the specific operators used in PSTM with demigra and migra
    # operators.

    x = x0
    tmp = y .- demigra(ntraces,s,rec,nx,nz,dx,dz,nt,dt,v,x)
    r = migra(ntraces,s,rec,nx,nz,dx,dz,nt,dt,v,tmp)
    p = r
    rsold = sum(r.*r)

    for i in 1:max_iter
        Ap = demigra(ntraces,s,rec,nx,nz,dx,dz,nt,dt,v,p)
        alpha = rsold / sum(Ap.* Ap)
        x = x + alpha * p
        r = r - alpha * migra(ntraces,s,rec,nx,nz,dx,dz,nt,dt,v,Ap) #
        rsnew = sum(r.*r)
        if sqrt(rsnew) < tol
            break
        end
        p = r + (rsnew / rsold) * p
        rsold = rsnew
    end

    return x

```

```
end
```

[7]: `cglb_Implicit` (generic function with 1 method)

### 0.1.2 3) Dot product test to ensure migration and demigration functions behave like $L'$ and $L$

Born / Kirchoff PSTM Example

- $L$  Demigration (modelling) operator
- $L'$ : Migration (imaging) operator

Test numerically that

$$\langle Lx, y \rangle = \langle L'y, x \rangle$$

```
[8]: nx = 200; nz = 200
dx = 10.; dz = 10.
nt = 1200; dt = 0.002

Lx = (nx-1)*dx
Lz = (nz-1)*dz

# Prepare a simple geometry by computing sources and receiver positions
ns = 10
nr = 20
ntraces = nr*ns
s = zeros(ntraces)
r = zeros(ntraces)

k = 1
for is = 1:ns
    for ir = 1:nr
        s[k] = 10.0 + (0.8*Lx-10.0)*(is-1)/(ns-1)
        r[k] = 14.0 + (0.9*Lx-14.0)*(ir-1)/(nr-1)
        k = k + 1
    end
end
v = ones(nz,nx)*1000;

m1 = randn(nz,nx);          d1 = demigra(ntraces,s,r,nx,nz,dx,dz,nt,dt,v,m1) # L
↪ m1
d2 = randn(nt,ntraces); m2 = migra(ntraces,s,r,nx,nz,dx,dz,nt,dt,v,d2) #
↪ L' d2

aux1 = d1.*d2;
aux2 = m1.*m2;
dot1 = sum(aux1[:])
dot2 = sum(aux2[:])
```

```
println("True if we pass the dot product test --> ", abs(dot1-dot2)<1.0e-10)
```

True if we pass the dot product test --> true

#### 0.1.3 4) Test code with inverse problem crime.

- First we use a model to generate data via the demigration operator. Then, we add noise to data and then we use the adjoint to recover the image. Finally, we use LS migration to find the image that fits the data. The LS migration is iteratively computed via CGLS.

```
[9]: ns = 4           # 4 sources
     nr = 100        # 100 receivers
     ntraces = ns*nr  # Total number of traces to model
     nt = 1000
     dt = 2/1000.0
     nx = 200; dx = 10; Lx = (nx-1)*dx
     nz = 300; dz = 10; Lz = (nz-1)*dz;
     v = ones(nz,nx)*1900

     # Prepare a simple geometry by computing sources and receiver positions

     s = zeros(ntraces)
     r = zeros(ntraces)

     k = 1
     for is = 1:ns
         for ir = 1:nr
             s[k] = 10.0 + (0.8*Lx-10.0)*(is-1)/(ns-1)
             r[k] = 14.0 + (0.9*Lx-14.0)*(ir-1)/(nr-1)
             k = k + 1
         end
     end

     m_true = zeros(nz,nx)
     n1=100
     m_true[100,1:n1]      .=1.0;      m_true[110,n1:end]  .=1.0
     m_true[120,1:n1+20]  .=-1.0;      m_true[130,n1+20:end] .=-1.0
     m_true[140,1:n1+40]  .=1.0;      m_true[150,n1+40:end] .=1.0

     d      = demigra(ntraces,s,r,nx,nz,dx,dz,nt,dt,v,m_true)
     m_adj  = migra(ntraces,s,r,nx,nz,dx,dz,nt,dt,v,d)
     m_adj  = m_adj/maximum(m_adj)
     m_cgls = cgls_Implicit(d, zeros(size(m_true)), 0.
         ↪001,10,ntraces,s,r,nx,nz,dx,dz,nt,dt,v);
```

## 0.2 Now plot results obtained via test with inverse problem crime

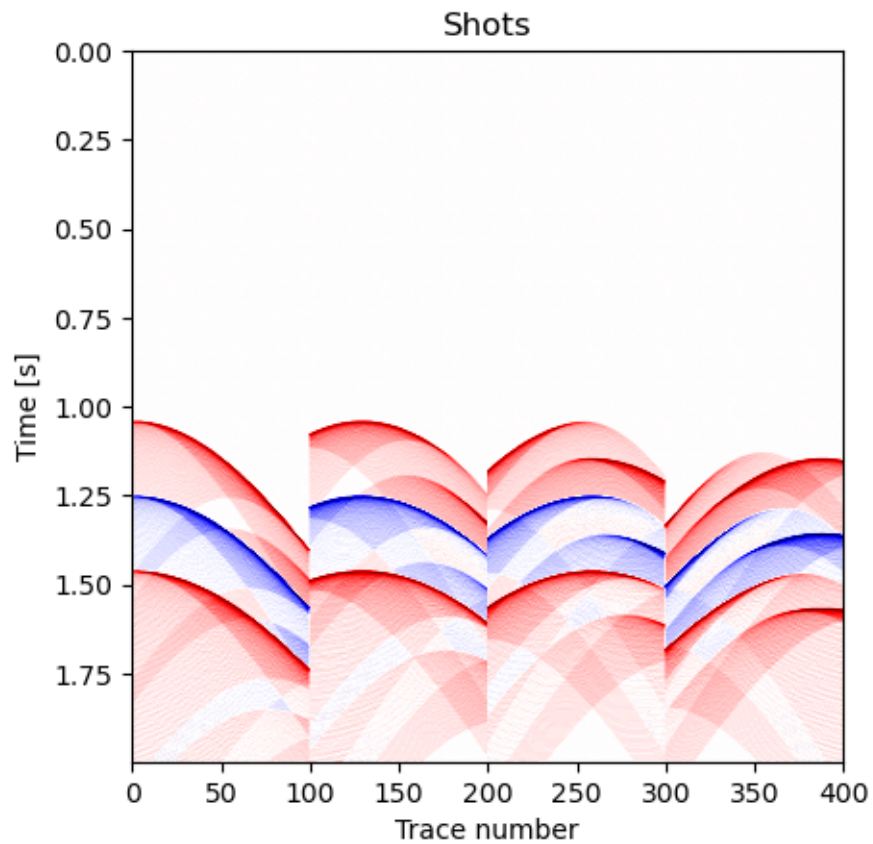
```
[10]: dmax = 0.4*maximum(d)
figure(1)
tmax = dt*(nt-1)
imshow(d,vmin=-dmax,vmax=dmax,extent=[0,ntraces,tmax,0],aspect=200,cmap="seismic")
xlabel("Trace number"); ylabel("Time [s]");title("Shots")
figure(2)
E = [0,(nx-1)*dx,(nz-1)*dz,0]

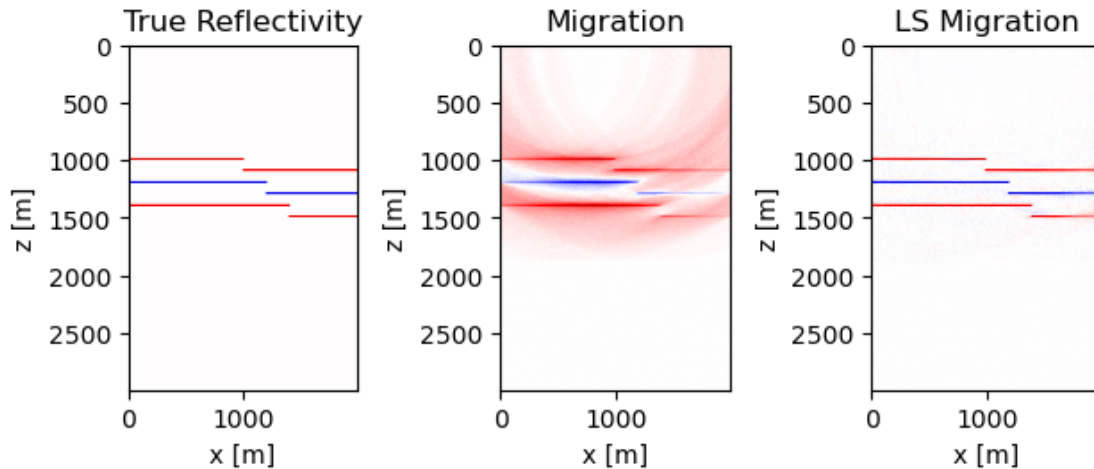
subplot(131);imshow(m_true,vmin=-1,vmax=1,cmap="seismic",extent=E )
title("True Reflectivity");xlabel("x [m]");ylabel("z [m]")

subplot(132);imshow(m_adj, vmin=-1,vmax=1,cmap="seismic",extent=E)
title("Migration");xlabel("x [m]");ylabel("z [m]")

subplot(133);imshow(m_cgls,vmin=-1,vmax=1,cmap="seismic",extent=E)
title("LS Migration");xlabel("x [m]");ylabel("z [m]")

tight_layout()
```





### 0.2.1 Functions for migration and demigration

```
[11]: function demigra(ntraces,s,r,nx,nz,dx,dz,nt,dt,v,m)
# Program for simple demigration d = L m
    d = zeros(nt,ntraces)
    for k = 1:ntraces
        for ix = 1:nx
            for iz = 1:nz
                dr = ((ix-1)*dx-r[k])^2+((iz-1)*dz)^2; dr =sqrt(dr)
                ds = ((ix-1)*dx-s[k])^2+((iz-1)*dz)^2; ds =sqrt(ds)
                time = (dr+ds)/v[iz,ix]
                it = floor(Int,time/dt+1)
                if ( it<nt )
                    d[it,k] = d[it,k] + m[iz,ix]
                end
            end
        end
    end
end
return d
end
```

[11]: demigra (generic function with 1 method)

```
[12]: function migra(ntraces,s,r,nx,nz,dx,dz,nt,dt,v,d)
# Program for simple migration ma = L' m
    ma = zeros(nz,nx)
    for k = 1:ntraces
        for ix = 1:nx
            for iz = 1:nz
                dr = ((ix-1)*dx-r[k])^2+((iz-1)*dz)^2; dr =sqrt(dr)
```

```

        ds = ((ix-1)*dx-s[k])^2+((iz-1)*dz)^2; ds =sqrt(ds)
        time = (dr+ds)/v[iz,ix]
        it = floor(Int,time/dt+1)  # Assigned nearest integer

        if ( it<nt )

            ma[iz,ix] = ma[iz,ix] + d[it,k]
            end
        end
    end
end
return ma
end

```

[12]: migra (generic function with 1 method)