```
# This Python 3 environment comes with many helpful analytics
libraries installed
# It is defined by the kaggle/python Docker image:
https://github.com/kaggle/docker-python
# For example, here's several helpful packages to load
import numpy as np # linear algebra
import pandas as pd # data processing, CSV file I/O (e.g. pd.read csv)
# Input data files are available in the read-only "../input/"
directory
# For example, running this (by clicking run or pressing Shift+Enter)
will list all files under the input directory
import os
for dirname, _, filenames in os.walk('/kaggle/input'):
    for filename in filenames:
        print(os.path.join(dirname, filename))
# You can write up to 20GB to the current directory (/kaggle/working/)
that gets preserved as output when you create a version using "Save &
Run All"
# You can also write temporary files to /kaggle/temp/, but they won't
be saved outside of the current session
```

# Smart Farming System and Crop Health Monitoring

```
# Handle missing values using forward fill (updated method)
soil df.ffill(inplace=True)
weather df.ffill(inplace=True)
# ----- Merge Datasets
# Merge based on nearest timestamps with a 30-minute tolerance
merged df = pd.merge asof(
   soil df.sort values('time'),
   weather df.sort values('observation time'),
   left on='time',
   right on='observation time',
   direction='nearest',
   tolerance=pd.Timedelta('30min')
)
# Drop rows with NaNs after merging
merged df.dropna(inplace=True)
print("□ Merge successful. Data is ready for EDA.")
☐ Merge successful. Data is ready for EDA.
# Display basic information about the dataset
print("Dataset Information:")
merged df.info()
# Display summary statistics for numerical columns
print("\nSummary Statistics:")
display(merged df.describe())
# Display the first five rows of the dataset
print("\nSample Data:")
display(merged df.head())
Dataset Information:
<class 'pandas.core.frame.DataFrame'>
Index: 2398 entries, 16 to 2413
Data columns (total 32 columns):
#
                                Non-Null Count Dtype
    Column
- - -
   -----
 0
                                2398 non-null
    time
                                               datetime64[ns]
1
    batt vol
                                2398 non-null float64
2
    temperature x
                                2398 non-null float64
3
                               2398 non-null float64
    humidity x
 4
                               2398 non-null float64
    soil sensor1 temp
 5
    soil_sensor2_temp
                               2398 non-null
                                               float64
 6
    soil sensor1 vwc
                               2398 non-null float64
    7
 8
```

## Summary Statistics:

,							
		time	batt_vol	temperature_x			
humidity	′ × \		_	_			
count	_	2398	2398.000000	2398.000000			
2398.000	0000						
mean 2	2021-06-30 17:57:5	3.401584640	7.681004	68.057018			
83.247615							
min	2021-04-	26 03:49:57	0.402363	-557.608000			
2.140000							
25% 2	2021-05-10 03:51:1	6.249999872	5.895580	57.348500			
64.42000	10						
50%	2021-05-22 20:0	8:27.500000	5.922404	67.127000			
74.60500	10						
75%	2021-08-23 05:0	9:44.500000	6.094846	80.793500			
83.270000							
max	2021-09-	20 19:14:21	122.465971	579.434000			
606.4900	000						
std		NaN	9.793480	86.494632			
60.83363	32						
S	oil_sensor1_temp	soil_sensor	2_temp soil_	sensor1_vwc \			
count	2398.000000	2398.	000000	2398.000000			
mean	425.058148	469.	790550	0.331324			

min 25% 50% 75% max std	32.000000 57.560000 68.360000 71.780000 11647.220000 1492.836986	32.0000 58.4600 68.5400 73.3550 11798.7800 1519.5850	00 00 00 00	-0.696000 0.309000 0.334000 0.342000 1.831000 0.210239	
	_sensor2_vwc 2_conductivity 2398.000000		ductivity 98.000000		
mean 1.687299	0.146607		2.802931		
min 0.000000 25%	-0.696000 0.240000		0.000000		
0.209000 50%	0.284000		0.258000		
0.250000 75%	0.309000		0.278000		
0.280000 max	1.843000		65.422000		
64.202000 std	0.424960		9.043069		
6.932954	4	1	1	والمراجعة المراجعة المراجعة المراجعة	
temperature_count	soil_temp_4 _y \ _2398.000000	solar_radiation 2398.000000	solar_rad	liation_high 2398.000000	
2398.000000 mean	63.399917	226.962052		265.864053	
65.912427 min	49.000000	0.000000		0.000000	
34.000000 25%	55.000000	0.000000		0.000000	
58.000000 50%	62.000000	49.000000		65.000000	
68.000000 75%	73.000000	416.000000		520.000000	
75.000000 max 92.000000	77.000000	1097.000000		1322.000000	
std 12.484911	9.340486	296.844174		340.075365	
tempe count mean min 25%	erature_high 2398.000000 66.243953 34.000000 58.000000	temperature_low 2398.000000 65.583820 34.000000 58.000000	wind_dire	2398.000000 153.465388 0.000000 90.000000	\

50% 75% max std	68.000000 75.000000 92.000000 12.532116	75.6 92.6	000000 000000 000000 153077		157.500000 202.500000 337.500000 91.631290			
<pre>wind_gust_direction_degrees wind_gust_speed_mph wind_speed_mph</pre>								
count 2398.000000		2398.000000		2398.0000	00			
mean		157.265430		11.2256	05			
6.792327 min		0.000000		0.0000	00			
0.000000 25%		90.000000		6.0000	00			
3.000000 50%		157.500000		10.0000	00			
5.000000 75%		225.000000		15.0000	00			
9.000000 max		337.500000		39.0000	00			
27.000000 std		92.102406		7.1505				
4.946210		321102400		7.1505	<b>5</b> 4			
[8 rows x 32 columns]								
Sample Data:								
16 2021-04-26 17 2021-04-26 18 2021-04-26 19 2021-04-26 20 2021-04-26	04:19:15 04:48:33 05:17:50		35.	528 114 258 230	dity_x \ 71.50 71.24 71.24 71.44 71.71			
<pre>soil_sensor1_temp soil_sensor2_temp soil_sensor1_vwc soil sensor2 vwc \</pre>								
16 -0.696	51.08		32.00		0.333			
17 -0.696	51.08		32.00		0.334			
10	F0 00		22.00		0 000			

soil\_sensor1\_conductivity soil\_sensor2\_conductivity ...

32.00

72.32

32.00

0.333

0.337

0.333

50.90

51.62

50.54

18 -0.696

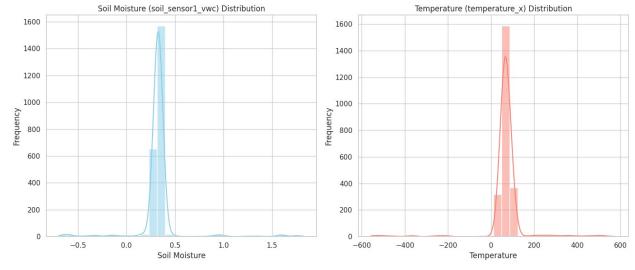
19 -0.693

20

-0.696

```
soil temp 4 \
                        0.250
                                                     0.000 ...
16
49.0
17
                        0.252
                                                     0.000 ...
49.0
                        0.249
18
                                                     0.000
49.0
                                                     0.048 ...
19
                        33.017
49.0
                        0.249
                                                     0.000 ...
20
49.0
    solar radiation
                     solar radiation high temperature y
temperature high \
                                       0.0
                                                      42.0
16
                0.0
42.0
17
                0.0
                                       0.0
                                                      42.0
42.0
18
                0.0
                                       0.0
                                                      42.0
42.0
19
                0.0
                                       0.0
                                                      42.0
42.0
20
                0.0
                                       0.0
                                                      41.0
42.0
    temperature low wind direction degrees
wind gust direction degrees \
                                        90.0
16
               42.0
90.0
               42.0
                                        90.0
17
90.0
18
               42.0
                                        90.0
90.0
19
               42.0
                                        90.0
90.0
20
               41.0
                                        90.0
90.0
    wind gust speed mph
                         wind speed mph
16
                   10.0
                                     6.0
17
                   10.0
                                     7.0
18
                   10.0
                                     7.0
19
                                     6.0
                    9.0
20
                    7.0
                                     4.0
[5 rows x 32 columns]
# Check for missing values in the dataset
missing values = merged df.isnull().sum().sort values(ascending=False)
```

```
print("Missing Values Per Column:")
display(missing values[missing values > 0])
Missing Values Per Column:
Series([], dtype: int64)
import matplotlib.pyplot as plt
import seaborn as sns
# Set plot style
sns.set(style="whitegrid")
# Plot distributions of target variables
fig, axes = plt.subplots(1, 2, figsize=(14, 6))
# Soil moisture distribution
sns.histplot(merged df['soil sensor1 vwc'], bins=30, kde=True,
ax=axes[0], color='skyblue')
axes[0].set title('Soil Moisture (soil sensor1 vwc) Distribution')
axes[0].set xlabel('Soil Moisture')
axes[0].set ylabel('Frequency')
# Temperature distribution
sns.histplot(merged df['temperature x'], bins=30, kde=True,
ax=axes[1], color='salmon')
axes[1].set title('Temperature (temperature x) Distribution')
axes[1].set xlabel('Temperature')
axes[1].set ylabel('Frequency')
plt.tight layout()
plt.show()
/usr/local/lib/python3.10/dist-packages/seaborn/ oldcore.py:1119:
FutureWarning: use inf as na option is deprecated and will be removed
in a future version. Convert inf values to NaN before operating
instead.
 with pd.option context('mode.use inf as na', True):
/usr/local/lib/python3.10/dist-packages/seaborn/ oldcore.py:1119:
FutureWarning: use inf as na option is deprecated and will be removed
in a future version. Convert inf values to NaN before operating
instead.
 with pd.option context('mode.use inf as na', True):
```

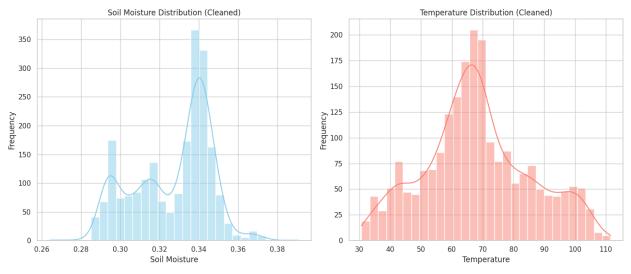


```
def remove outliers iqr(df, column):
    Q1 = df[column].quantile(0.25)
    03 = df[column].quantile(0.75)
    IQR = Q3 - Q1
    lower bound = Q1 - 1.5 * IQR
    upper bound = 03 + 1.5 * IQR
    cleaned df = df[(df[column] >= lower bound) & (df[column] <=</pre>
upper bound)]
    return cleaned df
# Remove outliers from both target variables
cleaned_df = remove_outliers_iqr(merged_df, 'soil_sensorl_vwc')
cleaned_df = remove_outliers_iqr(cleaned_df, 'temperature_x')
# Plot distributions after outlier removal
fig, axes = plt.subplots(1, 2, figsize=(14, 6))
sns.histplot(cleaned df['soil sensor1 vwc'], bins=30, kde=True,
ax=axes[0], color='skyblue')
axes[0].set title('Soil Moisture Distribution (Cleaned)')
axes[0].set xlabel('Soil Moisture')
axes[0].set ylabel('Frequency')
sns.histplot(cleaned_df['temperature x'], bins=30, kde=True,
ax=axes[1], color='salmon')
axes[1].set title('Temperature Distribution (Cleaned)')
axes[1].set xlabel('Temperature')
axes[1].set ylabel('Frequency')
plt.tight layout()
plt.show()
/usr/local/lib/python3.10/dist-packages/seaborn/ oldcore.py:1119:
FutureWarning: use inf as na option is deprecated and will be removed
```

```
in a future version. Convert inf values to NaN before operating instead.
```

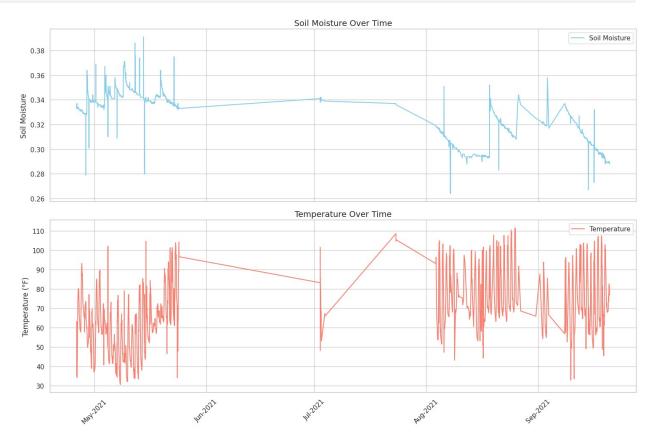
with pd.option\_context('mode.use\_inf\_as\_na', True):
/usr/local/lib/python3.10/dist-packages/seaborn/\_oldcore.py:1119:
FutureWarning: use\_inf\_as\_na option is deprecated and will be removed in a future version. Convert inf values to NaN before operating instead.

with pd.option\_context('mode.use\_inf\_as\_na', True):



```
import matplotlib.dates as mdates
# Set 'time' as index for plotting
cleaned df = cleaned df.sort values('time').set index('time')
# Plot time series for soil moisture and temperature
fig, axes = plt.subplots(2, 1, figsize=(15, 10), sharex=True)
# Soil Moisture Trend
axes[0].plot(cleaned df.index, cleaned df['soil sensor1 vwc'],
color='skyblue', label='Soil Moisture')
axes[0].set title('Soil Moisture Over Time', fontsize=14)
axes[0].set ylabel('Soil Moisture')
axes[0].legend()
# Temperature Trend
axes[1].plot(cleaned df.index, cleaned df['temperature x'],
color='salmon', label='Temperature')
axes[1].set title('Temperature Over Time', fontsize=14)
axes[1].set ylabel('Temperature (°F)')
axes[1].legend()
# Formatting x-axis
axes[1].xaxis.set major locator(mdates.MonthLocator())
```

```
axes[1].xaxis.set_major_formatter(mdates.DateFormatter('%b-%Y'))
plt.xticks(rotation=45)
plt.tight_layout()
plt.show()
```



#### **Observations from Time Series Trends:**

#### Soil Moisture:

Gradual decline over time with noticeable drops. Possible irrigation or weather-induced changes. Temperature:

Clear seasonal pattern with fluctuations. Sharp changes indicate external influences (e.g., rainfall, cloud cover).

```
# Create lag features (1, 3, and 6 time steps)
lags = [1, 3, 6]
for lag in lags:
    cleaned_df[f'soil_moisture_lag_{lag}'] =
cleaned_df['soil_sensorl_vwc'].shift(lag)
    cleaned_df[f'temperature_lag_{lag}'] =
cleaned_df['temperature_x'].shift(lag)

# Create rolling mean features (3, 6, and 12 time steps)
windows = [3, 6, 12]
```

```
for window in windows:
    cleaned df[f'soil moisture roll mean {window}'] =
cleaned df['soil sensor1 vwc'].rolling(window=window).mean()
    cleaned df[f'temperature roll mean {window}'] =
cleaned df['temperature x'].rolling(window=window).mean()
# Drop rows with NaN from feature creation
cleaned df = cleaned df.dropna()
# Check new features
cleaned df.head()
                     batt vol temperature x humidity x
soil sensor1_temp \
time
2021-04-26 09:41:29 5.960725
                                      56.660
                                                    66.18
49.46
2021-04-26 10:40:04
                     5.941564
                                      64.202
                                                    57.19
49.28
2021-04-26 11:09:22 5.941564
                                      68.000
                                                    53.25
49.10
2021-04-26 11:38:39 5.935816
                                      71.114
                                                    50.03
49.10
                                                    47.38
2021-04-26 12:07:57 5.935816
                                      73.778
49.10
                     soil_sensor2_temp soil_sensor1_vwc
soil sensor2 vwc \
time
2021-04-26 09:41:29
                                  32.0
                                                    0.333
0.696
2021-04-26 10:40:04
                                  32.0
                                                    0.333
0.696
2021-04-26 11:09:22
                                  32.0
                                                    0.334
0.696
2021-04-26 11:38:39
                                  32.0
                                                    0.334
0.696
2021-04-26 12:07:57
                                  32.0
                                                    0.334
0.696
                     soil sensor1 conductivity
soil sensor2 conductivity \
time
2021-04-26 09:41:29
                                         0.249
0.0
2021-04-26 10:40:04
                                         0.253
0.0
```

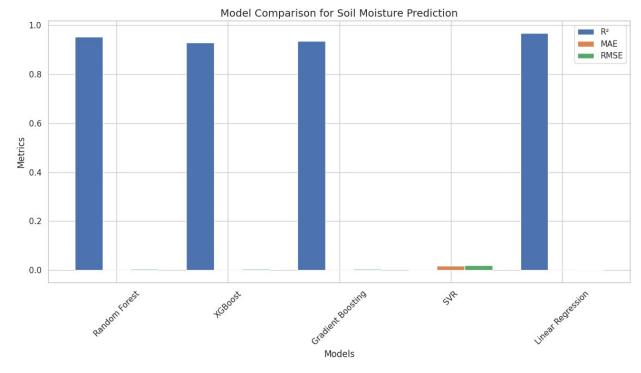
```
2021-04-26 11:09:22
                                          0.251
0.0
2021-04-26 11:38:39
                                          0.253
0.0
2021-04-26 12:07:57
                                          0.252
0.0
                        observation time
                                                soil moisture lag 3 \
time
                                           . . .
2021-04-26 09:41:29 2021-04-26 09:45:00
                                                              0.334
                                           . . .
2021-04-26 10:40:04 2021-04-26 10:45:00
                                                              0.334
                                           . . .
2021-04-26 11:09:22 2021-04-26 11:15:00
                                                              0.333
                                           . . .
2021-04-26 11:38:39 2021-04-26 11:45:00
                                                              0.333
2021-04-26 12:07:57 2021-04-26 12:15:00
                                                              0.333
                     temperature lag 3 soil moisture lag 6 \
time
2021-04-26 09:41:29
                                 39.362
                                                        0.333
2021-04-26 10:40:04
                                 43.322
                                                        0.333
                                 52.520
2021-04-26 11:09:22
                                                        0.333
2021-04-26 11:38:39
                                 56,660
                                                        0.334
2021-04-26 12:07:57
                                 64.202
                                                        0.334
                      temperature lag 6
                                         soil moisture roll mean 3 \
time
                                 34.574
2021-04-26 09:41:29
                                                           0.333333
2021-04-26 10:40:04
                                 34.142
                                                           0.333000
2021-04-26 11:09:22
                                 34.376
                                                           0.333333
2021-04-26 11:38:39
                                 39.362
                                                           0.333667
2021-04-26 12:07:57
                                 43.322
                                                           0.334000
                      temperature roll mean 3
soil moisture roll mean 6 \
time
2021-04-26 09:41:29
                                       50.834
0.333333
2021-04-26 10:40:04
                                       57.794
0.333333
2021-04-26 11:09:22
                                       62.954
0.333500
2021-04-26 11:38:39
                                       67.772
0.333500
2021-04-26 12:07:57
                                       70.964
0.333500
                      temperature roll mean 6
soil moisture roll mean 12 \
time
```

```
2021-04-26 09:41:29
                                      43.397
0.333583
2021-04-26 10:40:04
                                       48.407
0.333583
2021-04-26 11:09:22
                                       54.011
0.333583
2021-04-26 11:38:39
                                       59.303
0.333667
2021-04-26 12:07:57
                                       64.379
0.333417
                     temperature roll mean 12
time
2021-04-26 09:41:29
                                      41.6105
2021-04-26 10:40:04
                                       44.0000
2021-04-26 11:09:22
                                      46.7405
2021-04-26 11:38:39
                                      49.7285
2021-04-26 12:07:57
                                      50,6075
[5 rows x 43 columns]
from sklearn.model selection import train test split
# Target variables
target soil moisture = 'soil sensor1 vwc'
target temperature = 'temperature x'
# Features (excluding targets and datetime columns)
features = [col for col in cleaned df.columns if col not in [
    target soil moisture, target temperature, 'observation time'
] and not col.startswith('soil sensor') and not
col.startswith('temperature')]
# Prepare data for soil moisture prediction
X soil = cleaned df[features]
y soil = cleaned_df[target_soil_moisture]
# Prepare data for temperature prediction
X temp = cleaned df[features]
y temp = cleaned df[target temperature]
# Train-test split (80-20 split)
X train soil, X test soil, y train soil, y test soil =
train_test_split(X_soil, y_soil, test_size=0.2, random_state=42)
X_train_temp, X_test_temp, y_train_temp, y_test_temp =
train test split(X_temp, y_temp, test_size=0.2, random_state=42)
# Confirm shapes
print(f"Soil Moisture - Train: {X_train_soil.shape}, Test:
{X test soil.shape}")
```

```
print(f"Temperature - Train: {X train temp.shape}, Test:
{X test temp.shape}")
Soil Moisture - Train: (1717, 26), Test: (430, 26)
Temperature - Train: (1717, 26), Test: (430, 26)
from sklearn.ensemble import RandomForestRegressor
from sklearn.metrics import r2 score, mean absolute error,
mean squared error
# Initialize the Random Forest Regressor with hyperparameters
rf soil = RandomForestRegressor(
    n estimators=200,
    \max depth=10,
    min samples split=4,
    min_samples_leaf=2,
    random state=42,
    n_jobs=-1
)
# Train the model
rf_soil.fit(X_train_soil, y_train_soil)
# Make predictions
y pred soil = rf soil.predict(X test soil)
# Evaluate performance
r2 soil = r2 score(y test soil, y pred soil)
mae_soil = mean_absolute_error(y_test_soil, y_pred_soil)
rmse soil = mean squared error(y test soil, y pred soil,
squared=False)
print(f"Random Forest - Soil Moisture Prediction:")
print(f"R2: {r2 soil:.4f}, MAE: {mae soil:.4f}, RMSE:
{rmse soil:.4f}")
Random Forest - Soil Moisture Prediction:
R<sup>2</sup>: 0.9579, MAE: 0.0011, RMSE: 0.0040
# Initialize the Random Forest Regressor with similar hyperparameters
rf temp = RandomForestRegressor(
    n estimators=200,
    max depth=10,
    min samples split=4,
    min samples leaf=2,
    random state=42,
    n jobs=-1
)
# Train the model
rf temp.fit(X train temp, y train temp)
```

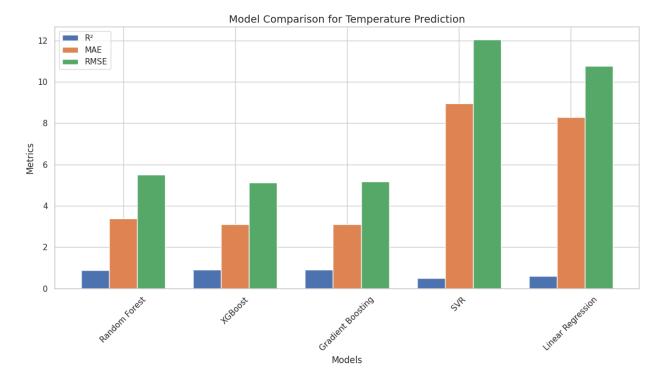
```
# Make predictions
y pred temp = rf temp.predict(X test temp)
# Evaluate performance
r2 temp = r2 score(y test temp, y pred temp)
mae_temp = mean_absolute_error(y_test_temp, y_pred_temp)
rmse temp = mean squared error(y test temp, y pred temp,
squared=False)
print(f"Random Forest - Temperature Prediction:")
print(f"R2: {r2_temp:.4f}, MAE: {mae_temp:.4f}, RMSE:
{rmse temp:.4f}")
Random Forest - Temperature Prediction:
R<sup>2</sup>: 0.8962, MAE: 3.3712, RMSE: 5.4506
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.ensemble import RandomForestRegressor,
GradientBoostingRegressor
from sklearn.svm import SVR
from sklearn.linear model import LinearRegression
from xgboost import XGBRegressor
from sklearn.metrics import mean squared error, mean absolute error,
r2 score
# Replace these variables with your actual data variables
X train = X train soil # Training features
X test = X test soil # Testing features
y train = y train soil # Training target
y_test = y_test_soil # Testing target
# Models for comparison
models = {
    'Random Forest': RandomForestRegressor(n estimators=200,
max depth=10, random state=42),
    'XGBoost': XGBRegressor(n estimators=200, max depth=6,
learning rate=0.05, random state=42),
    'Gradient Boosting': GradientBoostingRegressor(n estimators=200,
max depth=6, learning rate=0.05, random state=42),
    'SVR': SVR(C=10, kernel='rbf'),
    'Linear Regression': LinearRegression()
}
results = []
# Train and evaluate models
for name, model in models.items():
```

```
model.fit(X train, y train)
    y pred = model.predict(X test)
    r2 = r2_score(y_test, y_pred)
    mae = mean absolute error(y test, y pred)
    rmse = np.sqrt(mean_squared_error(y_test, y_pred))
    results.append({'Model': name, 'R2': r2, 'MAE': mae, 'RMSE':
rmse})
    print(f"{name}: R<sup>2</sup>={r2:.4f}, MAE={mae:.4f}, RMSE={rmse:.4f}")
# Results DataFrame
results df = pd.DataFrame(results)
# Plot comparison
fig, ax = plt.subplots(figsize=(12, 7))
x = np.arange(len(results df['Model']))
width = 0.25
ax.bar(x - width, results df['R2'], width, label='R2')
ax.bar(x, results df['MAE'], width, label='MAE')
ax.bar(x + width, results df['RMSE'], width, label='RMSE')
ax.set xlabel('Models', fontsize=12)
ax.set ylabel('Metrics', fontsize=12)
ax.set title('Model Comparison for Soil Moisture Prediction',
fontsize=14)
ax.set xticks(x)
ax.set xticklabels(results df['Model'], rotation=45)
ax.legend()
plt.tight_layout()
plt.show()
Random Forest: R<sup>2</sup>=0.9541, MAE=0.0011, RMSE=0.0042
XGBoost: R<sup>2</sup>=0.9304, MAE=0.0014, RMSE=0.0051
Gradient Boosting: R<sup>2</sup>=0.9372, MAE=0.0012, RMSE=0.0049
SVR: R^2 = -0.0022, MAE=0.0168, RMSE=0.0195
Linear Regression: R<sup>2</sup>=0.9688, MAE=0.0010, RMSE=0.0034
```



```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.ensemble import RandomForestRegressor,
GradientBoostingRegressor
from sklearn.svm import SVR
from sklearn.linear model import LinearRegression
from xgboost import XGBRegressor
from sklearn.metrics import mean squared error, mean absolute error,
r2 score
# Replace these variables with your actual temperature dataset
variables
X train = X train temp # Training features for temperature
X test = X test temp  # Testing features for temperature
y_train = y_train_temp # Training target (temperature)
y test = y_test_temp
                     # Testing target (temperature)
# Models for comparison
models = {
    'Random Forest': RandomForestRegressor(n estimators=200,
max depth=10, random state=42),
    'XGBoost': XGBRegressor(n estimators=200, max depth=6,
learning rate=0.05, random state=42),
    'Gradient Boosting': GradientBoostingRegressor(n estimators=200,
max depth=6, learning rate=0.05, random state=42),
    'SVR': SVR(C=10, kernel='rbf'),
    'Linear Regression': LinearRegression()
```

```
}
results = []
# Train and evaluate models
for name, model in models.items():
    model.fit(X_train, y_train)
    y pred = model.predict(X test)
    r2 = r2_score(y_test, y_pred)
    mae = mean absolute error(y test, y pred)
    rmse = np.sqrt(mean squared error(y test, y pred))
    results.append({'Model': name, 'R<sup>2</sup>': r2, 'MAE': mae, 'RMSE':
rmse})
    print(f"{name}: R^2 = \{r2:.4f\}, MAE={mae:.4f}, RMSE={rmse:.4f}")
# Results DataFrame
results df = pd.DataFrame(results)
# Plot comparison
fig, ax = plt.subplots(figsize=(12, 7))
x = np.arange(len(results df['Model']))
width = 0.25
ax.bar(x - width, results_df['R2'], width, label='R2')
ax.bar(x, results_df['MAE'], width, label='MAE')
ax.bar(x + width, results df['RMSE'], width, label='RMSE')
ax.set_xlabel('Models', fontsize=12)
ax.set ylabel('Metrics', fontsize=12)
ax.set title('Model Comparison for Temperature Prediction',
fontsize=14)
ax.set xticks(x)
ax.set xticklabels(results df['Model'], rotation=45)
ax.legend()
plt.tight_layout()
plt.show()
Random Forest: R<sup>2</sup>=0.8945, MAE=3.3946, RMSE=5.4962
XGBoost: R<sup>2</sup>=0.9086, MAE=3.1183, RMSE=5.1161
Gradient Boosting: R<sup>2</sup>=0.9063, MAE=3.1018, RMSE=5.1788
SVR: R<sup>2</sup>=0.4933, MAE=8.9472, RMSE=12.0446
Linear Regression: R<sup>2</sup>=0.5948, MAE=8.2830, RMSE=10.7710
```



```
import numpy as np
from sklearn.preprocessing import MinMaxScaler
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout
from tensorflow.keras.callbacks import EarlyStopping
from sklearn.metrics import r2 score, mean absolute error,
mean squared error
     ----- Data Preparation
# Scale features and target
scaler X = MinMaxScaler()
scaler y = MinMaxScaler()
X_train_scaled = scaler X.fit transform(X train soil)
X_test_scaled = scaler_X.transform(X_test_soil)
y_train_scaled = scaler_y.fit_transform(y_train_soil.values.reshape(-
1, 1))
y test scaled = scaler y.transform(y test soil.values.reshape(-1, 1))
# Reshape features for LSTM input: (samples, timesteps, features)
X train scaled = X train scaled.reshape((X train scaled.shape[0], 1,
X train scaled.shape[1]))
X test scaled = X test scaled.reshape((X test scaled.shape[0], 1,
X test scaled.shape[1]))
             ----- LSTM Model Building
```

```
model = Sequential()
model.add(LSTM(128, return sequences=True,
input shape=(X train scaled.shape[1], X train scaled.shape[2]),
activation='tanh'))
model.add(Dropout(0.2))
model.add(LSTM(64, activation='tanh'))
model.add(Dense(32, activation='relu'))
model.add(Dense(1))
model.compile(optimizer='adam', loss='mse')
# Early stopping to prevent overfitting
early stop = EarlyStopping(monitor='val loss', patience=15,
restore best weights=True)
# ----- Model Training
_____
history = model.fit(
   X_train_scaled, y_train_scaled,
   epochs=100, # Increase epochs if needed
   batch size=32,
   validation_split=0.1,
   callbacks=[early stop],
   verbose=1
)
# ----- Evaluation
# Predict on test set
y pred scaled = model.predict(X test scaled)
y pred = scaler y.inverse transform(y pred scaled)
y actual = scaler y.inverse transform(y test scaled)
# Calculate metrics
r2 = r2 score(y actual, y pred)
mae = mean absolute error(y actual, y pred)
rmse = mean squared error(y actual, y pred, squared=False)
print(f"\nLSTM Soil Moisture Prediction:")
print(f"R2: {r2:.4f}")
print(f"MAE: {mae:.4f}")
print(f"RMSE: {rmse:.4f}")
/usr/local/lib/python3.10/dist-packages/keras/src/layers/rnn/
rnn.py:204: UserWarning: Do not pass an `input_shape`/`input_dim`
argument to a layer. When using Sequential models, prefer using an
```

```
`Input(shape)` object as the first layer in the model instead.
  super(). init (**kwargs)
Epoch 1/100
49/49 —
                         -- 5s 21ms/step - loss: 0.1244 - val loss:
0.0041
Epoch 2/100
                           0s 5ms/step - loss: 0.0034 - val_loss:
49/49 -
0.0015
Epoch 3/100
                          - Os 5ms/step - loss: 0.0020 - val loss:
49/49 -
0.0015
Epoch 4/100
49/49
                           0s 5ms/step - loss: 0.0021 - val_loss:
0.0014
Epoch 5/100
49/49 -
                          Os 5ms/step - loss: 0.0020 - val loss:
0.0013
Epoch 6/100
49/49 —
                          - 0s 5ms/step - loss: 0.0017 - val loss:
0.0013
Epoch 7/100
49/49 —
                          - 0s 5ms/step - loss: 0.0020 - val_loss:
0.0012
Epoch 8/100
49/49 -
                           Os 5ms/step - loss: 0.0016 - val_loss:
0.0013
Epoch 9/100
49/49 —
                          - 0s 5ms/step - loss: 0.0014 - val_loss:
0.0013
Epoch 10/100
49/49 -
                           Os 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 11/100
49/49 -
                          - 0s 5ms/step - loss: 0.0017 - val loss:
0.0012
Epoch 12/100
49/49 —
                          - 0s 5ms/step - loss: 0.0015 - val_loss:
0.0012
Epoch 13/100
49/49 -
                           0s 5ms/step - loss: 0.0016 - val_loss:
0.0012
Epoch 14/100
49/49 -
                          - 0s 5ms/step - loss: 0.0015 - val_loss:
0.0012
Epoch 15/100
49/49 -
                           Os 5ms/step - loss: 0.0016 - val loss:
0.0012
Epoch 16/100
49/49 -
                          Os 5ms/step - loss: 0.0020 - val loss:
```

```
0.0012
Epoch 17/100
49/49 -
                          - 0s 5ms/step - loss: 0.0014 - val_loss:
0.0011
Epoch 18/100
49/49 -
                            Os 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 19/100
                            Os 5ms/step - loss: 0.0013 - val loss:
49/49 -
0.0011
Epoch 20/100
49/49 -
                           Os 5ms/step - loss: 0.0011 - val_loss:
0.0011
Epoch 21/100
49/49 -
                          - 0s 5ms/step - loss: 0.0010 - val_loss:
0.0012
Epoch 22/100
49/49 —
                          Os 5ms/step - loss: 0.0012 - val_loss:
0.0011
Epoch 23/100
49/49 -
                           Os 5ms/step - loss: 0.0013 - val loss:
0.0011
Epoch 24/100
49/49 -
                           Os 5ms/step - loss: 0.0017 - val loss:
0.0011
Epoch 25/100
49/49 -
                           Os 5ms/step - loss: 0.0013 - val_loss:
0.0012
Epoch 26/100
49/49 -
                           Os 5ms/step - loss: 0.0013 - val loss:
0.0011
Epoch 27/100
49/49 —
                          - 0s 5ms/step - loss: 0.0010 - val loss:
0.0011
Epoch 28/100
                          - 0s 5ms/step - loss: 0.0010 - val loss:
49/49 -
0.0011
Epoch 29/100
49/49 -
                            Os 5ms/step - loss: 0.0012 - val loss:
0.0012
Epoch 30/100
49/49 -
                          Os 5ms/step - loss: 0.0011 - val loss:
0.0010
Epoch 31/100
                           Os 5ms/step - loss: 0.0012 - val loss:
49/49 -
0.0012
Epoch 32/100
49/49 -
                          - 0s 5ms/step - loss: 0.0011 - val loss:
0.0013
```

```
Epoch 33/100
49/49 -
                          - 0s 5ms/step - loss: 0.0010 - val loss:
0.0012
Epoch 34/100
49/49 -
                          - 0s 5ms/step - loss: 0.0011 - val loss:
0.0011
Epoch 35/100
49/49 -
                           Os 6ms/step - loss: 0.0012 - val loss:
9.6613e-04
Epoch 36/100
49/49 -
                          Os 5ms/step - loss: 0.0010 - val loss:
9.6707e-04
Epoch 37/100
49/49 -
                          Os 5ms/step - loss: 9.2884e-04 - val loss:
0.0011
Epoch 38/100
49/49 -
                          Os 5ms/step - loss: 0.0011 - val loss:
0.0011
Epoch 39/100
49/49 -
                           Os 5ms/step - loss: 0.0011 - val loss:
0.0011
Epoch 40/100
49/49 -
                          - 0s 5ms/step - loss: 9.8471e-04 - val loss:
0.0011
Epoch 41/100
49/49 -
                           Os 6ms/step - loss: 0.0012 - val loss:
9.0919e-04
Epoch 42/100
49/49 -
                           Os 5ms/step - loss: 9.8771e-04 - val loss:
9.5793e-04
Epoch 43/100
49/49 -
                           Os 5ms/step - loss: 9.3493e-04 - val loss:
9.5066e-04
Epoch 44/100
49/49 -
                           Os 5ms/step - loss: 8.5005e-04 - val loss:
9.3353e-04
Epoch 45/100
49/49 —
                          - 0s 5ms/step - loss: 8.0594e-04 - val loss:
9.3290e-04
Epoch 46/100
49/49 —
                          - 0s 5ms/step - loss: 9.0323e-04 - val loss:
0.0010
Epoch 47/100
49/49 -
                          Os 5ms/step - loss: 9.9698e-04 - val loss:
0.0012
Epoch 48/100
49/49 -
                          - 0s 5ms/step - loss: 0.0010 - val loss:
9.0885e-04
Epoch 49/100
```

```
49/49 -
                          - 0s 5ms/step - loss: 7.4111e-04 - val loss:
8.9675e-04
Epoch 50/100
49/49 -
                          Os 5ms/step - loss: 8.2347e-04 - val loss:
8.5886e-04
Epoch 51/100
49/49 -
                           Os 5ms/step - loss: 8.2262e-04 - val loss:
9.4252e-04
Epoch 52/100
49/49 —
                          - Os 5ms/step - loss: 8.1923e-04 - val loss:
0.0010
Epoch 53/100
49/49 -
                          Os 5ms/step - loss: 7.4869e-04 - val loss:
8.3887e-04
Epoch 54/100
49/49 -
                          Os 5ms/step - loss: 8.3411e-04 - val loss:
8.1377e-04
Epoch 55/100
                          - 0s 5ms/step - loss: 8.2660e-04 - val loss:
49/49 —
8.4227e-04
Epoch 56/100
49/49 -
                           Os 5ms/step - loss: 8.2114e-04 - val loss:
9.2412e-04
Epoch 57/100
                          Os 5ms/step - loss: 9.0165e-04 - val loss:
49/49 –
8.2181e-04
Epoch 58/100
49/49 —
                          Os 5ms/step - loss: 9.6983e-04 - val loss:
8.0119e-04
Epoch 59/100
49/49 —
                          - 0s 5ms/step - loss: 5.4996e-04 - val loss:
8.6148e-04
Epoch 60/100
49/49 -
                           Os 5ms/step - loss: 6.4023e-04 - val loss:
8.2391e-04
Epoch 61/100
49/49 -
                          Os 6ms/step - loss: 8.0509e-04 - val loss:
9.5268e-04
Epoch 62/100
49/49 -
                           Os 6ms/step - loss: 6.5777e-04 - val loss:
8.7869e-04
Epoch 63/100
49/49 —
                          - 0s 6ms/step - loss: 7.5793e-04 - val_loss:
9.0717e-04
Epoch 64/100
49/49 -
                          - 0s 6ms/step - loss: 7.5255e-04 - val_loss:
7.9705e-04
Epoch 65/100
49/49 -
                          Os 6ms/step - loss: 6.5361e-04 - val loss:
```

```
8.0717e-04
Epoch 66/100
49/49 —
                          - 0s 6ms/step - loss: 5.7245e-04 - val loss:
7.9702e-04
Epoch 67/100
49/49 -
                           Os 5ms/step - loss: 6.6197e-04 - val loss:
7.9605e-04
Epoch 68/100
49/49 -
                           Os 5ms/step - loss: 7.3985e-04 - val loss:
8.5354e-04
Epoch 69/100
49/49 -
                          Os 5ms/step - loss: 5.8290e-04 - val_loss:
8.1516e-04
Epoch 70/100
49/49 -
                          - 0s 6ms/step - loss: 6.7305e-04 - val_loss:
8.3063e-04
Epoch 71/100
                          - Os 5ms/step - loss: 6.2010e-04 - val loss:
49/49 —
8.3220e-04
Epoch 72/100
49/49 —
                          - 0s 5ms/step - loss: 7.2935e-04 - val loss:
8.0709e-04
Epoch 73/100
49/49 —
                          Os 5ms/step - loss: 6.8442e-04 - val loss:
9.5191e-04
Epoch 74/100
49/49 -
                           Os 5ms/step - loss: 6.5706e-04 - val loss:
0.0012
Epoch 75/100
49/49 -
                          Os 5ms/step - loss: 9.2737e-04 - val loss:
7.8402e-04
Epoch 76/100
49/49 ---
                          - 0s 5ms/step - loss: 6.0804e-04 - val loss:
8.0880e-04
Epoch 77/100
                          - 0s 5ms/step - loss: 5.1126e-04 - val loss:
49/49 —
8.8189e-04
Epoch 78/100
49/49 -
                           Os 5ms/step - loss: 5.9505e-04 - val loss:
8.5408e-04
Epoch 79/100
49/49 -
                          Os 5ms/step - loss: 5.0134e-04 - val loss:
7.6749e-04
Epoch 80/100
49/49 -
                           Os 5ms/step - loss: 5.9038e-04 - val loss:
0.0012
Epoch 81/100
49/49 -
                          - 0s 5ms/step - loss: 6.6264e-04 - val loss:
7.9149e-04
```

```
Epoch 82/100
49/49 -
                          Os 5ms/step - loss: 5.8645e-04 - val loss:
8.4414e-04
Epoch 83/100
49/49 —
                          - 0s 5ms/step - loss: 6.2872e-04 - val loss:
9.4964e-04
Epoch 84/100
49/49 —
                          Os 5ms/step - loss: 6.4185e-04 - val loss:
9.0546e-04
Epoch 85/100
49/49 -
                          Os 5ms/step - loss: 7.7181e-04 - val loss:
8.1869e-04
Epoch 86/100
49/49 -
                          Os 5ms/step - loss: 6.7574e-04 - val loss:
8.4343e-04
Epoch 87/100
49/49 —
                          Os 5ms/step - loss: 7.1999e-04 - val loss:
8.6342e-04
Epoch 88/100
49/49 -
                          Os 5ms/step - loss: 6.5257e-04 - val loss:
8.6155e-04
Epoch 89/100
49/49 ---
                          - 0s 5ms/step - loss: 5.3856e-04 - val loss:
0.0011
Epoch 90/100
49/49 -
                           Os 5ms/step - loss: 6.5667e-04 - val loss:
7.9449e-04
Epoch 91/100
49/49 —
                           Os 5ms/step - loss: 6.2982e-04 - val loss:
7.9337e-04
Epoch 92/100
49/49 -
                           Os 5ms/step - loss: 5.5737e-04 - val loss:
9.2164e-04
Epoch 93/100
49/49 -
                           Os 5ms/step - loss: 6.4128e-04 - val loss:
9.5718e-04
Epoch 94/100
                          Os 5ms/step - loss: 6.5177e-04 - val loss:
49/49 —
8.3452e-04
14/14 -
                          - 0s 14ms/step
LSTM Soil Moisture Prediction:
R^2: 0.9695
MAE: 0.0013
RMSE: 0.0034
import keras tuner as kt
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout
from tensorflow.keras.callbacks import EarlyStopping
```

```
def build lstm model(hp):
    model = Sequential()
    model.add(
        LSTM(
            units=hp.Choice('units 1', [32, 64, 96]),
            return sequences=True,
            input shape=(X train scaled.shape[1],
X train_scaled.shape[2]),
            activation='tanh'
    )
    model.add(Dropout(rate=hp.Choice('dropout 1', [0.1, 0.2, 0.3])))
    model.add(
        LSTM(
            units=hp.Choice('units_2', [32, 64]),
            activation='tanh'
        )
    model.add(Dense(units=hp.Choice('dense units', [16, 32, 48]),
activation='relu'))
    model.add(Dense(1))
    model.compile(
        optimizer='adam',
        loss='mse'
    return model
# Setup Bayesian Optimization with fewer trials for efficiency
tuner = kt.BayesianOptimization(
    build lstm model,
    objective='val loss',
    max trials=5,
    executions per trial=1,
    directory='tuning results',
    project_name='soil_moisture lstm optimized'
)
# Perform tuning
tuner.search(
    X_train_scaled, y_train_scaled,
    epochs=30,
    validation split=0.1,
    callbacks=[EarlyStopping(monitor='val_loss', patience=5,
restore best weights=True)],
    verbose=1
)
# Retrieve the best hyperparameters
```

```
best_hp = tuner.get_best_hyperparameters(num_trials=1)[0]
print("Best Hyperparameters:")
for param, value in best_hp.values.items():
    print(f"{param}: {value}")

Trial 5 Complete [00h 00m 11s]
val_loss: 0.0011297814780846238

Best val_loss So Far: 0.001028774306178093
Total elapsed time: 00h 00m 56s
Best Hyperparameters:
units_1: 64
dropout_1: 0.1
units_2: 32
dense_units: 32
```

**Optimized LSTM Architecture:** Layer 1: 64 units, 10% dropout Layer 2: 32 units Dense Layer: 32 units Best Validation Loss: 0.0010

```
# Include 'time' column before splitting
X soil with time = cleaned df[['time'] + [col for col in
cleaned df.columns if col not in ['soil sensor1 vwc', 'temperature x',
'observation time']]]
# Train-test split with 'time' column
from sklearn.model selection import train test split
X_train_soil_with_time, X_test_soil_with_time, y_train_soil,
v test soil = train_test_split(
    X_soil_with_time, cleaned df['soil sensor1 vwc'], test size=0.2,
random state=42, shuffle=False
# Extract 'time' after split
time_test = X_test_soil_with_time['time'].reset_index(drop=True)
# Remove 'time' column from features before LSTM training
X train soil = X train soil with time.drop(columns=['time'])
X test soil = X test soil with time.drop(columns=['time'])
# Build and train the optimized LSTM model
best model = Sequential()
best model.add(LSTM(64, return sequences=True,
input shape=(X train scaled.shape[1], X train scaled.shape[2]),
activation='tanh'))
best model.add(Dropout(0.1))
best model.add(LSTM(32, activation='tanh'))
best model.add(Dense(32, activation='relu'))
best model.add(Dense(1))
```

```
best model.compile(optimizer='adam', loss='mse')
# Train the model with early stopping
history = best model.fit(
    X train scaled, y train_scaled,
    epochs=100,
    validation split=0.1,
    callbacks=[EarlyStopping(monitor='val loss', patience=10,
restore_best weights=True)],
    verbose=1
)
# Predict on test data
y pred scaled = best model.predict(X test scaled)
y pred = scaler y.inverse transform(y pred scaled)
y actual = scaler y.inverse transform(y test scaled)
# Evaluate performance
r2 = r2 score(y actual, y pred)
mae = mean absolute error(y actual, y pred)
rmse = mean squared error(y actual, y pred, squared=False)
print(f"\nOptimized LSTM Soil Moisture Prediction:")
print(f"R2: {r2:.4f}")
print(f"MAE: {mae:.4f}")
print(f"RMSE: {rmse:.4f}")
# Export predictions to CSV
import pandas as pd
time test = cleaned df.loc[X test soil.index, 'time']
predictions df = pd.DataFrame({
    'time': time test,
    'Actual Soil Moisture': y actual.flatten(),
    'Predicted Soil Moisture': y pred.flatten()
})
csv filename = 'optimized lstm soil moisture predictions.csv'
predictions df.to csv(csv filename, index=False)
print(f"\nPredictions exported to '{csv filename}'")
Epoch 1/100
/usr/local/lib/python3.10/dist-packages/keras/src/layers/rnn/
rnn.py:204: UserWarning: Do not pass an `input shape`/`input dim`
argument to a layer. When using Sequential models, prefer using an
`Input(shape)` object as the first layer in the model instead.
  super().__init__(**kwargs)
```

```
49/49 -
                          - 2s 10ms/step - loss: 0.1430 - val loss:
0.0131
Epoch 2/100
49/49 -
                          Os 5ms/step - loss: 0.0079 - val loss:
0.0022
Epoch 3/100
49/49 -
                           Os 5ms/step - loss: 0.0023 - val loss:
0.0016
Epoch 4/100
49/49 -
                          - 0s 5ms/step - loss: 0.0020 - val loss:
0.0015
Epoch 5/100
49/49 -
                           Os 5ms/step - loss: 0.0017 - val loss:
0.0014
Epoch 6/100
                           Os 5ms/step - loss: 0.0016 - val loss:
49/49 -
0.0013
Epoch 7/100
49/49 -
                          Os 5ms/step - loss: 0.0020 - val loss:
0.0014
Epoch 8/100
49/49 -
                           Os 5ms/step - loss: 0.0017 - val loss:
0.0013
Epoch 9/100
                           Os 5ms/step - loss: 0.0015 - val loss:
49/49 -
0.0013
Epoch 10/100
49/49 —
                          Os 5ms/step - loss: 0.0018 - val loss:
0.0013
Epoch 11/100
49/49 -
                          Os 5ms/step - loss: 0.0013 - val loss:
0.0013
Epoch 12/100
49/49 -
                           Os 5ms/step - loss: 0.0021 - val loss:
0.0013
Epoch 13/100
49/49 -
                          Os 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 14/100
49/49 -
                           Os 5ms/step - loss: 0.0017 - val loss:
0.0013
Epoch 15/100
49/49 -
                          - 0s 5ms/step - loss: 0.0013 - val_loss:
0.0012
Epoch 16/100
49/49 -
                           Os 5ms/step - loss: 0.0016 - val_loss:
0.0013
Epoch 17/100
49/49 -
                           Os 5ms/step - loss: 0.0014 - val loss:
0.0012
```

```
Epoch 18/100
49/49 -
                           Os 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 19/100
49/49 -
                          - 0s 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 20/100
49/49 -
                           Os 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 21/100
49/49 -
                           Os 5ms/step - loss: 0.0012 - val loss:
0.0012
Epoch 22/100
49/49 -
                           Os 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 23/100
49/49 -
                          Os 5ms/step - loss: 0.0016 - val loss:
0.0011
Epoch 24/100
49/49 -
                           Os 5ms/step - loss: 0.0015 - val loss:
0.0011
Epoch 25/100
49/49 -
                          - 0s 5ms/step - loss: 0.0014 - val loss:
0.0012
Epoch 26/100
49/49 -
                           Os 5ms/step - loss: 0.0012 - val loss:
0.0011
Epoch 27/100
49/49 -
                           Os 5ms/step - loss: 0.0012 - val loss:
0.0012
Epoch 28/100
49/49 -
                           Os 5ms/step - loss: 0.0012 - val loss:
0.0012
Epoch 29/100
49/49 -
                            Os 5ms/step - loss: 0.0015 - val loss:
0.0011
Epoch 30/100
49/49 -
                          - 0s 5ms/step - loss: 0.0012 - val loss:
0.0011
Epoch 31/100
49/49 -
                          Os 5ms/step - loss: 0.0011 - val loss:
0.0011
Epoch 32/100
49/49 -
                           Os 5ms/step - loss: 7.6865e-04 - val loss:
0.0012
Epoch 33/100
49/49 -
                          Os 5ms/step - loss: 0.0011 - val loss:
0.0012
Epoch 34/100
49/49 -
                        — 0s 5ms/step - loss: 0.0011 - val loss:
```

```
0.0011
Epoch 35/100
49/49 -
                          - 0s 5ms/step - loss: 0.0010 - val loss:
0.0010
Epoch 36/100
49/49 -
                           Os 5ms/step - loss: 0.0010 - val loss:
0.0010
Epoch 37/100
49/49
                           Os 5ms/step - loss: 0.0011 - val loss:
0.0011
Epoch 38/100
49/49 -
                           Os 5ms/step - loss: 9.8344e-04 - val_loss:
0.0010
Epoch 39/100
49/49 -
                          - 0s 5ms/step - loss: 9.8548e-04 - val_loss:
0.0010
Epoch 40/100
49/49 -
                          - 0s 5ms/step - loss: 9.6210e-04 - val_loss:
9.9045e-04
Epoch 41/100
49/49 –
                           Os 5ms/step - loss: 9.6122e-04 - val loss:
9.5256e-04
Epoch 42/100
49/49 —
                          Os 5ms/step - loss: 0.0011 - val loss:
9.4177e-04
Epoch 43/100
49/49 -
                           Os 5ms/step - loss: 9.9557e-04 - val loss:
9.7558e-04
Epoch 44/100
49/49 -
                          Os 5ms/step - loss: 0.0012 - val loss:
0.0010
Epoch 45/100
49/49 —
                          - 0s 5ms/step - loss: 7.9283e-04 - val loss:
9.4284e-04
Epoch 46/100
49/49 —
                          - 0s 5ms/step - loss: 0.0011 - val loss:
8.9989e-04
Epoch 47/100
49/49 -
                           Os 5ms/step - loss: 8.3998e-04 - val loss:
9.1411e-04
Epoch 48/100
49/49 -
                          Os 5ms/step - loss: 7.3031e-04 - val loss:
0.0010
Epoch 49/100
                           Os 5ms/step - loss: 9.8973e-04 - val loss:
49/49 -
9.2088e-04
Epoch 50/100
49/49 -
                          - 0s 5ms/step - loss: 0.0010 - val loss:
8.9280e-04
Epoch 51/100
```

```
49/49 —
                          - 0s 5ms/step - loss: 9.2893e-04 - val loss:
9.6542e-04
Epoch 52/100
49/49 -
                          Os 5ms/step - loss: 7.3750e-04 - val loss:
0.0011
Epoch 53/100
49/49 -
                           Os 5ms/step - loss: 0.0011 - val loss:
9.2179e-04
Epoch 54/100
49/49 ---
                          - 0s 5ms/step - loss: 0.0010 - val loss:
8.5230e-04
Epoch 55/100
49/49 -
                          - 0s 5ms/step - loss: 7.6633e-04 - val loss:
8.9811e-04
Epoch 56/100
49/49 -
                          Os 5ms/step - loss: 7.4045e-04 - val loss:
8.2944e-04
Epoch 57/100
49/49 -
                          - 0s 5ms/step - loss: 8.5877e-04 - val loss:
0.0012
Epoch 58/100
49/49 -
                           Os 5ms/step - loss: 8.7852e-04 - val loss:
8.0960e-04
Epoch 59/100
                          Os 5ms/step - loss: 6.7738e-04 - val loss:
49/49 -
8.7944e-04
Epoch 60/100
                          - Os 5ms/step - loss: 7.3774e-04 - val_loss:
49/49 ---
8.4623e-04
Epoch 61/100
49/49 —
                          - 0s 5ms/step - loss: 8.7161e-04 - val loss:
8.0983e-04
Epoch 62/100
49/49 -
                           Os 5ms/step - loss: 7.7314e-04 - val loss:
8.1408e-04
Epoch 63/100
49/49 —
                          Os 5ms/step - loss: 6.7787e-04 - val loss:
9.5302e-04
Epoch 64/100
49/49 -
                           Os 5ms/step - loss: 8.9996e-04 - val loss:
8.4075e-04
Epoch 65/100
49/49 -
                          - 0s 5ms/step - loss: 7.1966e-04 - val_loss:
8.1605e-04
Epoch 66/100
49/49 -
                          - 0s 5ms/step - loss: 8.9343e-04 - val_loss:
8.3107e-04
Epoch 67/100
49/49 -
                          Os 5ms/step - loss: 0.0010 - val loss:
8.0109e-04
```

```
Epoch 68/100
49/49 -
                          Os 5ms/step - loss: 6.6712e-04 - val loss:
7.9880e-04
Epoch 69/100
49/49 —
                          - 0s 5ms/step - loss: 7.6178e-04 - val loss:
8.2178e-04
Epoch 70/100
49/49 —
                          Os 5ms/step - loss: 8.3550e-04 - val loss:
7.9554e-04
Epoch 71/100
49/49 -
                          Os 5ms/step - loss: 8.4450e-04 - val loss:
7.8760e-04
Epoch 72/100
49/49 -
                          Os 5ms/step - loss: 5.1509e-04 - val loss:
8.1037e-04
Epoch 73/100
49/49 —
                          Os 5ms/step - loss: 6.4173e-04 - val loss:
7.7087e-04
Epoch 74/100
49/49 -
                          Os 5ms/step - loss: 6.7356e-04 - val loss:
8.1911e-04
Epoch 75/100
49/49 ---
                          - 0s 5ms/step - loss: 5.8627e-04 - val loss:
0.0011
Epoch 76/100
49/49 -
                           Os 5ms/step - loss: 7.6399e-04 - val loss:
7.8335e-04
Epoch 77/100
49/49 -
                           Os 5ms/step - loss: 5.6180e-04 - val loss:
8.0175e-04
Epoch 78/100
49/49 -
                           Os 5ms/step - loss: 5.7542e-04 - val loss:
8.3024e-04
Epoch 79/100
49/49 -
                           Os 6ms/step - loss: 6.1975e-04 - val loss:
0.0010
Epoch 80/100
49/49 —
                          - 0s 6ms/step - loss: 6.0013e-04 - val loss:
8.7626e-04
Epoch 81/100
49/49 —
                          - 0s 5ms/step - loss: 6.5410e-04 - val loss:
7.9885e-04
Epoch 82/100
49/49 —
                          Os 6ms/step - loss: 7.3326e-04 - val loss:
7.8032e-04
Epoch 83/100
                           Os 5ms/step - loss: 8.2310e-04 - val loss:
49/49 -
9.6384e-04
14/14 -
                          0s 13ms/step
```

```
Optimized LSTM Soil Moisture Prediction:
R2: 0.9688
MAE: 0.0015
RMSE: 0.0034
Predictions exported to 'optimized_lstm_soil_moisture_predictions.csv'
```

### **Predict Temperature**

```
# Include 'time' column before splitting
X temp with time = cleaned df[['time'] + [col for col in
cleaned df.columns if col not in ['temperature_x', 'soil_sensor1_vwc',
'observation time']]]
# Train-test split with 'time' column
from sklearn.model selection import train test split
X train temp with time, X test temp with time, y train temp,
y test temp = train test split(
    X temp with time, cleaned df['temperature x'], test size=0.2,
random state=42, shuffle=False
# Extract 'time' from test set
time test temp = X test temp with time['time'].reset index(drop=True)
# Remove 'time' column from features
X_train_temp = X_train_temp with time.drop(columns=['time'])
X test temp = X test temp with time.drop(columns=['time'])
from xgboost import XGBRegressor
from sklearn.metrics import r2 score, mean absolute error,
mean squared error
import pandas as pd
# Train XGBoost model
xgb temp = XGBRegressor(
    n estimators=200,
    \max depth=6,
    learning rate=0.05,
    subsample=0.8,
    colsample bytree=0.8,
    random state=42
)
xgb temp.fit(X train temp, y train temp)
# Predict
y_pred_temp = xgb_temp.predict(X_test_temp)
```

```
# Evaluate
r2 temp = r2 score(y test temp, y pred temp)
mae_temp = mean_absolute_error(y_test_temp, y_pred_temp)
rmse temp = mean squared error(y test temp, y pred temp,
squared=False)
print(f"\nXGBoost Temperature Prediction:")
print(f"R2: {r2 temp:.4f}")
print(f"MAE: {mae temp:.4f}")
print(f"RMSE: {rmse temp:.4f}")
XGBoost Temperature Prediction:
R^2: 0.8619
MAE: 4.0121
RMSE: 5.8602
# Step 1: Extract only the 'time' column as a 1D Series
if 'time' in X test temp with time.columns:
    time test temp = X test temp with time['time'].iloc[:, 0] if
X test temp with time['time'].ndim > \frac{1}{1} else
X test temp with time['time']
else:
    raise KeyError("The 'time' column was not found in
X test temp with time.")
# Step 2: Flatten actual and predicted arrays
y actual temp flat = np.ravel(y test temp)
y pred temp flat = np.ravel(y pred temp)
# Step 3: Check lengths for consistency
assert len(time test temp) == len(y actual temp flat) ==
len(y_pred_temp_flat), \
    f"Length mismatch: time={len(time test temp)},
actual={len(y actual temp flat)}, predicted={len(y pred temp flat)}"
# Step 4: Create DataFrame with predictions
predictions temp df = pd.DataFrame({
    'time': time_test_temp.reset_index(drop=True),
    'Actual Temperature': y_actual_temp_flat,
    'Predicted Temperature': y pred temp flat
})
# Step 5: Export to CSV
csv filename = 'xgboost temperature predictions.csv'
predictions_temp_df.to_csv(csv_filename, index=False)
print(f"\n Predictions exported to '{csv filename}' successfully.")
```

```
Predictions exported to 'xgboost_temperature_predictions.csv'
successfully.
import shutil

# Path to the folder you want to download
folder_path = '/kaggle/working/tuning_results'
output_zip_path = '/kaggle/working/tuning_results.zip'

# Zip the folder
shutil.make_archive(base_name=output_zip_path.replace('.zip', ''),
format='zip', root_dir=folder_path)
print(f" Folder zipped successfully at: {output_zip_path}")

Folder zipped successfully at: /kaggle/working/tuning_results.zip
csv_filename = 'weather_sensor_farmer_data.csv'
cleaned_df.to_csv(csv_filename, index=False)
print(f"\n file exported to '{csv_filename}' successfully.")
```