Commute Time:

$$CT(i,j) = H(i,j) + H(j,i)$$

- The Commute time CT(i,j) on a graph is the expected time it takes a random walk to visit node j starting from node i and return.
- The hitting time H(i,j) of a random walk on a graph is the expected time it takes to visit node j starting from node i.

The *commute time distance* can be expressed in terms of the *unnormalized* and *normalized* Laplacian.

■ In terms of the eigen-system of the *unnormalized* Laplacian *L*:

$$CT(i,j) = \text{vol}(V) \sum_{\alpha=2}^{|V|} \frac{1}{\lambda_{\alpha}} \left(v_{\alpha j} - v_{\alpha i} \right)^2$$
 (1)

■ In terms of the eigen-system of the *normalized* Laplacian L_{sym} :

$$CT(i,j) = \text{vol}(V) \sum_{\alpha=2}^{|V|} \frac{1}{\lambda_{\alpha}^{\text{sym}}} \left(\frac{v_{\alpha j}^{\text{sym}}}{\sqrt{D_{jj}}} - \frac{v_{\alpha i}^{\text{sym}}}{\sqrt{D_{ii}}} \right)^{2}$$
(2)

Where $vol(V) = \sum_i D_{ii}$ and |V| denotes the cardinality of the set of nodes.

We can rewrite (1) and (2) in the following form:

$$CT(i,j) = \sum_{\alpha=2}^{|V|} \left(\sqrt{\frac{\mathsf{vol}(V)}{\lambda_{\alpha}}} v_{\alpha j} - \sqrt{\frac{\mathsf{vol}(V)}{\lambda_{\alpha}}} v_{\alpha i} \right)^{2}$$

$$CT(i,j) = \sum_{\alpha=2}^{|V|} \left(\sqrt{\frac{\text{vol}(V)}{\lambda_{\alpha}^{\text{sym}} D_{jj}}} v_{\alpha j}^{\text{sym}} - \sqrt{\frac{\text{vol}(V)}{\lambda_{\alpha}^{\text{sym}} D_{ji}}} v_{\alpha i}^{\text{sym}} \right)^{2}$$

The previous form express the CTD as Euclidean distances.

Commute time embedding:

Let Θ denote the new vector space that preserves the commute time distance of the nodes of the graph. The new coordinate matrix can be written:

■ In terms of the *unnormalized* Laplacian *L*:

$$\Theta = \sqrt{\operatorname{vol}(V)} \mathbf{\Lambda}^{-1/2} \mathbf{V}^T$$

■ In terms of the *normalized* Laplacian L_{sym} :

$$\Theta_{sym} = \sqrt{vol(V)} \mathbf{\Lambda}_{L_{sym}}^{-1/2} \mathbf{V}_{L_{sym}}^T \mathbf{D}^{-1/2}$$

Let m denote the new dimension in the embedded space and n the dimension in the original space (m < n).

 \Rightarrow Θ and Θ_{sym} are $m \times n$ matrices, Λ and Λ_{sym} are $m \times m$ matrices and \mathbf{V} and \mathbf{V}_{sym} are $n \times m$ matrices.

Notice that the columns of Θ and Θ_{sym} are vectors of Cartesian co-ordinates.

Optimal embedding problem in terms of the unnormalized Laplacian (as defined in the paper)

The objective function:

$$\sum_{ij} (y_i - y_j)^2 W_{ij} \tag{3}$$

Which relates to the quadratic form of L:

$$\frac{1}{2}\sum_{ij}(y_i-y_j)^2W_{ij}=\mathbf{y}'(D-W)\mathbf{y}=\mathbf{y}'L\mathbf{y}$$

The minimization problem can be reduced to finding a solution to:

$$\arg\min_{\mathbf{y}\in\mathbb{R}^n} \ \mathbf{y}' L \mathbf{y} \tag{4a}$$

subject to
$$\mathbf{y}'D\mathbf{y} = 1$$
 (4b)

$$\mathbf{p}'D\mathbb{1} = 0 \tag{4c}$$



The vector **y** that minimizes the objective function (4a) is given by the smallest eigenvalue solution of the generalized eigenvalue problem:

$$L\mathbf{y} = \lambda D\mathbf{y}$$

Recall:

 λ is is an eigenvalue of L_{rw} with eigenvector y iff λ is an eigenvalue of L_{sym} with eigenvector $w = D^{1/2}y$.

$$L_{sym} w = \lambda w$$

$$(D^{1/2} - D^{-1/2}W)y = \lambda D^{1/2}y$$

$$(I - D^{-1}W)y = \lambda y$$

$$L_{rw} y = \lambda y$$

$$(D^{-1}L)y = \lambda y$$

$$Ly = \lambda Dy$$

$$(5)$$

Optimal embedding problem in terms of the unnormalized Laplacian

The unnormalized version of the optimal embedding problem is given by minimizing the following objective function:

subject to
$$\mathbf{y}'\mathbf{y} = 1$$
 (6b)

$$\mathbf{y}'\mathbb{1} = 0 \tag{6c}$$

Notice that this formulation is not the Laplacian eigenmap. The solution to (6a) is associated to the standard eigenvalue problem:

$$L\mathbf{y} = \lambda \mathbf{y}$$



Optimal embedding problem in terms of the normalized Laplacian

Let $\mathbf{u} = D^{1/2}\mathbf{y}$. We can rewrite the objective function (3):

$$\sum_{ij} (y_i - y_j)^2 W_{ij} = \sum_{ij} \left(\frac{u_i}{\sqrt{D_{ii}}} - \frac{u_j}{\sqrt{D_{jj}}} \right)^2 W_{ij}$$

Which relates to the quadratic form of L_{sym} :

$$\frac{1}{2}\sum_{ij}\left(\frac{u_i}{\sqrt{D_{ii}}}-\frac{u_j}{\sqrt{D_{jj}}}\right)^2W_{ij}=\mathbf{u}'L_{sym}\mathbf{u}$$

$$\arg\min_{u\in\mathbb{R}^n} \quad \mathbf{u}' L_{sym} \mathbf{u} \tag{7a}$$

subject to
$$\mathbf{u}'\mathbf{u} = 1$$
 (7b)

$$\mathbf{u}'(D^{1/2}\mathbb{1}) = 0 \tag{7c}$$

The vector \mathbf{u} that minimizes the objective function in (7a) is given by the smallest eigenvalue solution of the standard eigenvalue problem:

$$L_{sym}\mathbf{u}=\lambda\mathbf{u}$$

Notice that

$$\mathop{\mathsf{arg\,min}}_{\mathbf{y},\ \mathbf{y}'D\mathbf{y}=\mathbf{1};\ D\mathbf{y}\perp\mathbb{1}}\mathbf{y}'L\mathbf{y}=\mathop{\mathsf{arg\,min}}_{\mathbf{u},\ \mathbf{u}'\mathbf{u}=\mathbf{1};\ \mathbf{u}\perp D^{1/2}\mathbb{1}}\mathbf{u}'L_{\mathit{sym}}\mathbf{u}$$

Commute time embedding for the Normalized Laplacian L_{sym} The new Cartesian coordinate of the i:th data points:

$$\mathbf{x}_i = \sqrt{\operatorname{vol}(V)/\lambda_{\alpha}D_{ii}} \cdot [v_{2i}, v_{3i}, ..., v_{mi}]$$

and:

$$x_{i\alpha} = v_{\alpha i} \frac{\sqrt{\text{vol}(V)}}{\sqrt{\lambda_{\alpha} D_{ii}}}, \quad \alpha > 1$$

 $v_{\alpha i}$ refers to the *i*:th component of the α eigenvector of L_{sym} . The first eigenvector of L_{sym} :

$$v_{1i} = \frac{\sqrt{D_{ii}}}{vol(V)}$$
 $\lambda_1 = 0$

Statistical properties of the data point $x_{i\alpha}$

From the constraints (7b), (7c):

$$\begin{cases} \sum_{i} v_{\alpha i} \sqrt{D_{ii}} = 0, & \text{for } \alpha > 1 \\ \sum_{i} v_{\alpha i}^{2} = 1, & \text{for all } \alpha \end{cases}$$

It follows that:

$$\sum_{i} v_{\alpha i} \sqrt{D_{ii}} = 0 \Rightarrow \sum_{i} x_{i\alpha} \left(\frac{D_{ii}}{\text{vol}(V)} \right) = 0 = E[x_{i\alpha}] = \mu_{\alpha}$$
 (8)

$$\sum_{i} v_{\alpha i}^{2} = 1 \Rightarrow E[X_{i\alpha}^{2}] - E[X_{i\alpha}]^{2} = \sum_{i=1}^{n} x_{i\alpha}^{2} \left(\frac{D_{ii}}{\text{vol}(V)}\right) = \frac{1}{\lambda_{\alpha}}$$
 (9)

Covariance Matrix

$$\Lambda_{\alpha\alpha'} = \sum_{i} x_{i\alpha} x_{i\alpha'} \left(\frac{D_{ii}}{\text{vol}(V)} \right) = \sum_{i=1}^{n} \frac{v_{i\alpha} v_{i\alpha'}}{\sqrt{\lambda_{\alpha} \lambda_{\alpha'}}} = \frac{1}{\lambda_{\alpha}} \gamma_{\alpha\alpha'} \qquad (10)$$

$$\sum_{i} v_{\alpha i} v_{\alpha' i} = \gamma_{\alpha\alpha'} \quad \text{(orthonormal)}$$

$$\begin{cases}
\gamma_{\alpha\alpha'} = 0, & \alpha \neq \alpha' \\
\gamma_{\alpha\alpha'} = 1, & \alpha = \alpha'
\end{cases}$$

Points are weighted by their degree.

Some questions to think about

- What is the meaning of the eigenvalues λ_{α} ?
- What does it mean that the covariance matrix is diagonalized?
- How can we relate to Principal Component Analysis?

- The inverse of the eigenvalues correspond to the variance of the data points when we project to one of the axis.
- The variance is the inverse of the eigenvalues only if we are using Cartesian coordinates.
- From (10) it is clear that Λ is diagonalized given the orthogonality of the eigenvectors.
- The new Cartesian coordinates are uncorrelated and linearly independent (but not independent).
- The eigenvector space coincides with the Principal Components in the projected space.



Commute time embedding for the unnormalized Laplacian L

$$\mathbf{x}_i = \sqrt{\operatorname{vol}(V)/\lambda_{\alpha}} \ [v_{2i}, v_{3i}, ..., v_{mi}]$$

Meaning that for the α dimension

$$x_{i\alpha} = v_{i\alpha} \frac{\sqrt{\text{vol}(V)}}{\sqrt{\lambda_{\alpha}}}, \quad \alpha > 1$$

The first eigenvector of *L*:

$$v_{1i}=rac{1}{\sqrt{|V|}}, \quad \lambda_1=0$$

Statistical properties of the data point $x_{i\alpha}$

From the constraints (6b), (6c):

$$\begin{cases} \sum_{i} v_{i\alpha} = 0, & \text{for } \alpha > 1 \\ \sum_{i} v_{i\alpha}^{2} = 1, & \text{for all } \alpha \end{cases}$$

it follows that:

$$\sum_{i} v_{i\alpha} = 0 \Rightarrow \sum_{i} x_{i\alpha} \left(\frac{1}{|V|} \right) = 0 = E[X_{\alpha}] = \mu_{\alpha}$$

$$\sum_{i} v_{i\alpha}^{2} = 1 \Rightarrow E[X_{\alpha}^{2}] - E[X_{\alpha}]^{2} = \sum_{i=1}^{n} x_{i\alpha}^{2} \left(\frac{1}{|V|} \right) = \frac{1}{\lambda_{\alpha}} \frac{\text{Vol}(V)}{|V|}$$
(11)

Covariance Matrix

$$\Lambda_{\alpha\alpha'} = \sum_{i} x_{i\alpha} x_{i\alpha'} \left(\frac{1}{|V|} \right) = \sum_{i=1}^{n} \frac{v_{i\alpha} v_{i\alpha'}}{\sqrt{\lambda_{\alpha} \lambda_{\alpha'}}} \frac{\mathsf{Vol}(\mathsf{V})}{|V|} = \frac{1}{\lambda_{\alpha}} \frac{\mathsf{Vol}(\mathsf{V})}{|V|} \gamma_{\alpha\alpha'}$$

- Each data point contributes equally, regardless of the degree distribution.
- The spread of the points non trivially depend on the number of nodes and volume.
- \blacksquare L_{sym} is much simpler.