Air Condition Design

TEAM 8 (RETURN BRAIN)

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Table of contents

Contents

Firstly: Project Description:	2
Description	2
Hardware Requirements	2
Software Requirements	2
Secondly: Layered architecture:	3
Thirdly : System modules:	3
Fourthly: APIs:	3
DIO APIs:	3
TIMER APIs:	4
ADC APIs:	4
LCD APIs:	5
KEYPAD APIs:	5
SENSOR APIs:	6
BUZZER APIs:	6
INTERRUPT SERVICE APIs:	6
DELAY APIs:	7
TIME OUT APIs:	7
APPLICATION APIs:	7
Fifthly: Flowcharts APIs:	7
ECUAL FLOWCHARTS:	8
SERVICES FLOWCHARTS:	16
ADDITION FLOWCHARTS:	17



Firstly: Project Description:

Description

Hardware Requirements

LCD

KEYPAD

TEMPERATURE SENSOR

BUZZER

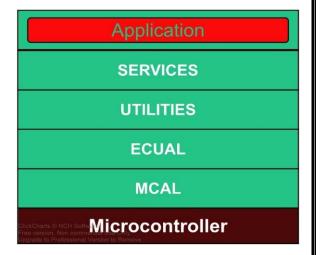
Software Requirements

- 1. The user set temperature $(20 \sim 35 \text{ Celsius})$
- 2. KEYPAD 1 INCREAMENT BUTTON for incrementing input range
- 3. KEYPAD 2 DECCREAMENT BUTTON for decrementing input range
- 4. KEYPAD 3 SET BUZZER BUTTON for choosing the setting temperature
- 5. When temperature exceed set temperature, BUZZER ON
- 6. Display the current reading of temperature sensor
- 7. KEYPAD 4 STOP BUZZER BUTTON for stop BUZZER
- 8. KEYPAD 5 RESET BUTTON for resetting temperature to 20 Celsius
- 9. This will be repeated forever
- 10. The sequence is described below
 - 1. LCD display "Welcome Message" for one second
 - 2. LCD clear
 - 3. LCD display "Default Temp is 20" for one second
 - 4. LCD clear
 - 5. LCD display "Please Choose The Required Temp" for half second
 - 6. Press KEYPAD 1 OR 2 for in/decrement temperature
 - 7. Press KEYPAD 3 for set temperature
 - 8. After step 7, any Press for KEYPAD 1,2 OR 3:
 - 1. display "This Operation Is Not Allowed" for half second time out
 - 9. LCD display current temperature
 - 10. LCD display bell-shape if the current temperature exceed setting temperature



Secondly: Layered architecture:

- 1- Microcontroller
- 2- MCAL
- 3- ECUAL
- 4- UTILITIES
- 5- SERVICES
- 6- Application



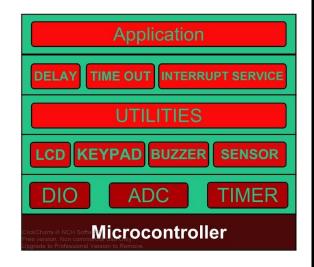
Thirdly: System modules:

1- Specify system modules/drivers:

- DIO, TIMER, ADC
- LCD, KEYPAD, SENSOR, BUZZER,
- DELAY, TIME OUT, INTERRUPT SERVICE
- APPLICATION

2- Assign each module to its related layer:

- By drawing



Fourthly: APIs:

DIO APIs:

```
void DIO_InitPin (PIn_name pin ,PIN_Status status );
void DIO_init (void);
void DIO_WRitePin (PIn_name pin ,Voltage_type s);
Voltage_type DIO_ReadPin(PIn_name pin);
void DIO_WritePort(PORT_Type Port,u8 data);
```



TIMER APIs:

```
void TIMER_init (uint8_t Mode,uint8_t intial_value);
  void TIMER_start (uint8_t prescaler_value);
  void TIMER_set(uint8_t intial_value);
  void TIMER_getStatus(uint8_t *value);
  void TIMER_Stop (void);

void TIMER2_init (u8 Mode,u8 intial_value);
  void TIMER2_start (u8 prescaler_value);
  void TIMER2_set(u8 intial_value);
  void TIMER2_getStatus(u8 *value);
  void TIMER2_Stop (void);
```

ADC APIs:

```
void ADC_init(PIn_name channel, uint8_t V_ref_type ,
    uint8_t Diff_OR_Single , uint8_t ADCH_OR_ADCL ,
    uint8t uint8_t prescaler , uint8_t INT_init);
    uint8_t ADC_Read(PIn_name channel);
```



LCD APIs:

```
void LCD_init (void);
void LCD _sendcommand (uint8_t cmnd);
void LCD_sendchar (uint8_t char_data);
void LCD _sendstring(uint8_t *str);
void LCD_setcursor (uint8_t row, uint8_t column);
void LCD_clear (void);
void LCD_customchar(uint8_t *pattern, uint8_t location);
LCD_floattostring (f32_t float_value);
```

KEYPAD APIs:

```
Keypad_Status_en KEYPAD_Init(PIn_name First_Output,PIn_name Firs_Input);

unit8_t KEYPAD_GetNum_time(unit8_t timeout);

static unit8_t KEYPAD_GetKey(void);
```



SENSOR APIs:

```
void Temp_init(PIn_name channel);
   uint8_t Temp_Read(PIn_name channel);
```

BUZZER APIs:

```
void buzz_init(PIn_name pin_num);
     void buzz_ON();
     void buzz_OFF();
```

INTERRUPT SERVICE APIs:

```
# define ISR(vector,...)
void vector (void) __attribute__
((signal,used))__VA_ARGS__ ; \
void vector (void)
```



DELAY APIs:

```
void Delay (uint8_t milliseconds);
```

TIMEOUT APIs:

```
Static void TIMER_out_Stop (void);
Static void TIME_out_init (void);
void TIMER_out (uint8_t milliseconds);
static void TIMER_ISR(void);
static void Timer0_Ovf_CALLBACK (void (*copyFuncptr) (void));
```

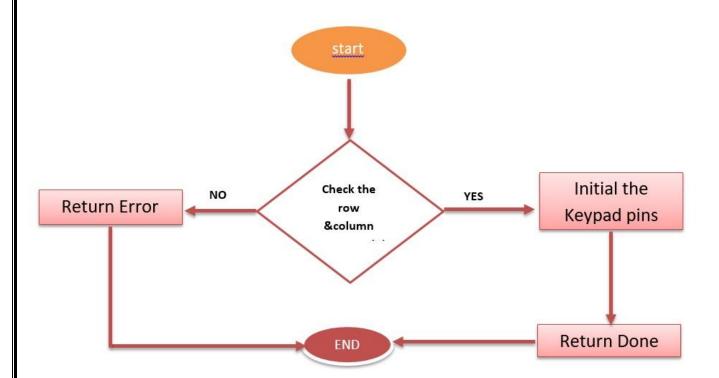
APPLICATION APIs:

```
void APP_Init(void);
void APP_Start(void);
```

Fifthly: Flowcharts APIs:

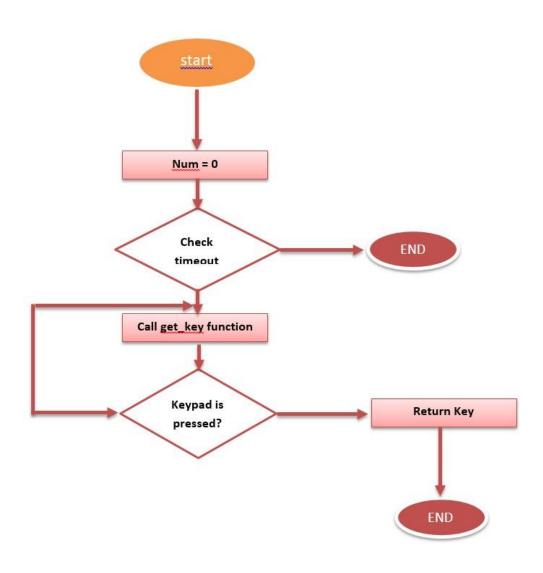
ECUAL FLOWCHARTS:

Keypad APIs Keypad_Status_en KEYPAD_Init(PIn_name First_Output,PIn_name Firs_Input);



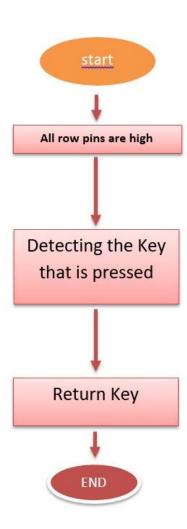
Keypad APIs

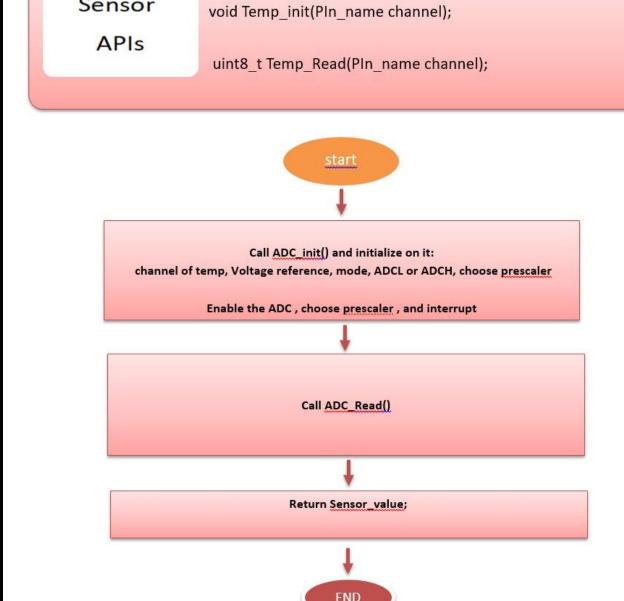
unit8_t KEYPAD_GetNum_time(unit8_t timeout);



Keypad APIs

static unit8_t KEYPAD_GetKey(void);

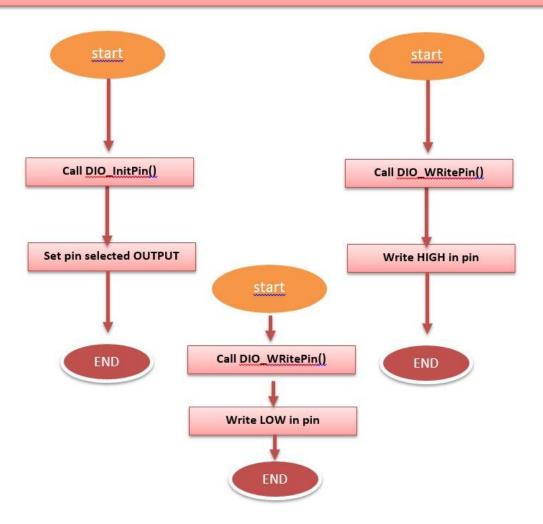


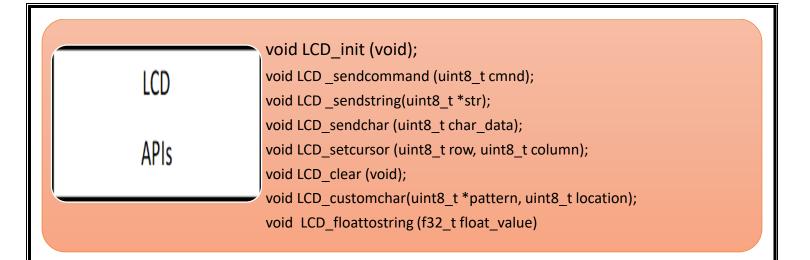


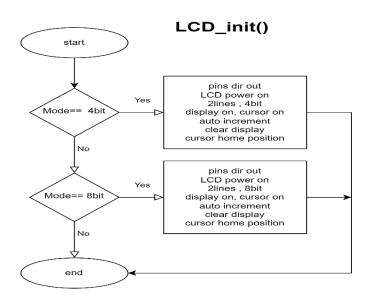
Sensor

Buzzer void bazz_init(Pln_name pin_num);

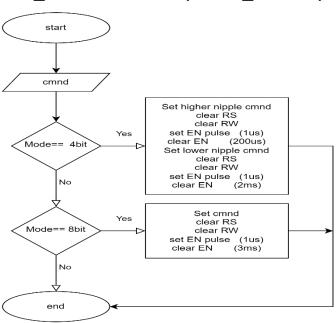
APIs void bazz_ON();
void bazz_OFF();



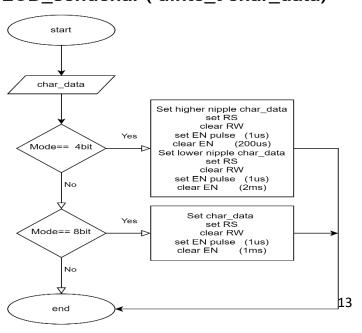


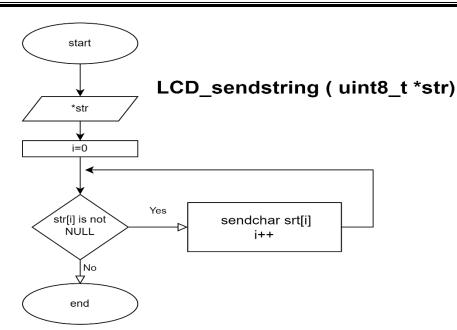


LCD_sendcommand(uint8_t cmnd)

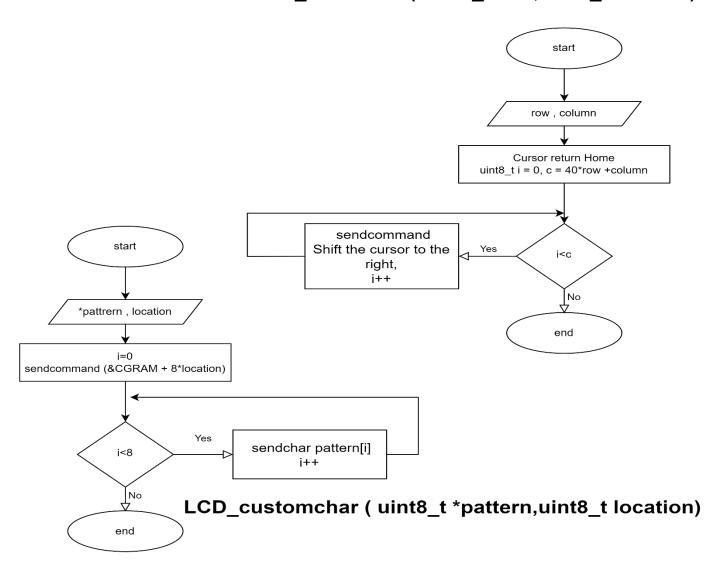


LCD_sendchar (uint8_t char_data)

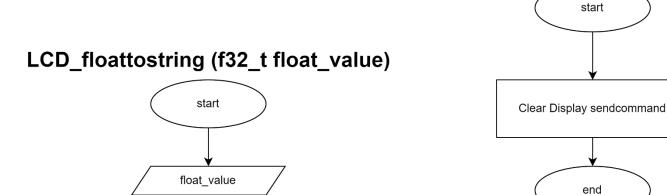




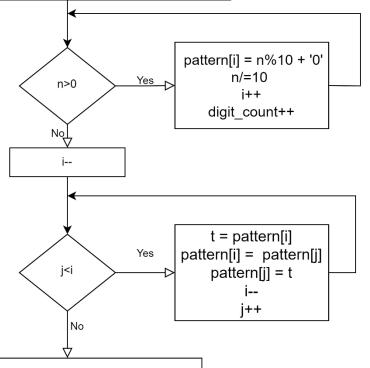
LCD_setcursor (uint8_t row,uint8_t column)







int n,i=0,j=0,temp_integer, digitcount=0 char t, pattern[10] temp_float = float_value*10 n = temp_float



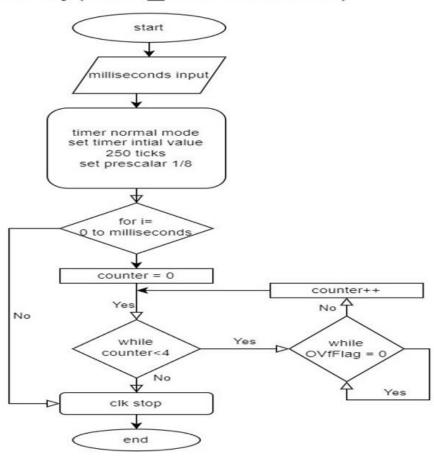
SERVICES FLOWCHARTS:

Delay

APIS

void Delay(uint32_t milliseconds);

Delay(uint8_t milliseconds)



APPLICATION FLOWCHARTS:

Application

APIs

void APP_Init(void);
void APP_Start(void);

