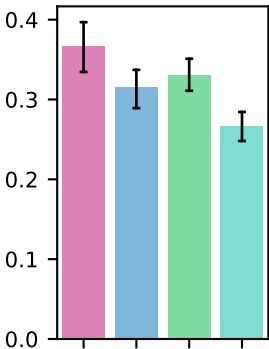


norm_bestpath



Waypoint
User
shared
Fully
Autonomous