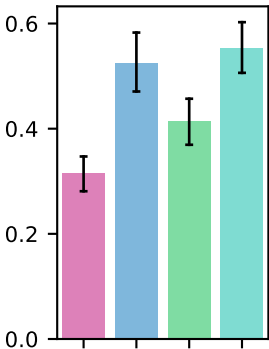


norm_userpath_cum



Waypoint
User
shared
Fully
Autonomous