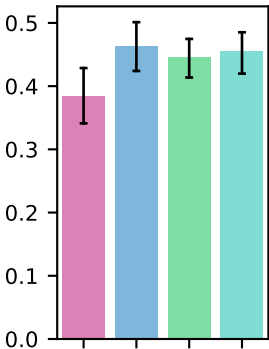


norm_bestpath_cum



Waypoint
User
shared
Fully
Autonomous