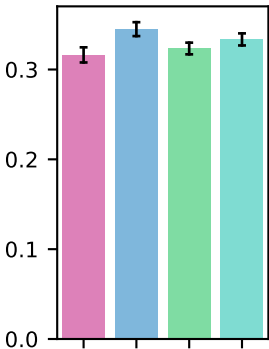


norm_userpath



Waypoint
User
Shared Control
Fully Autonomous