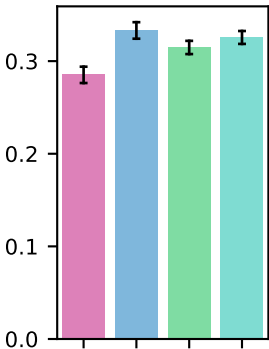


## norm\_bestpath



Waypoint  
User  
shared  
Fully  
Autonomous