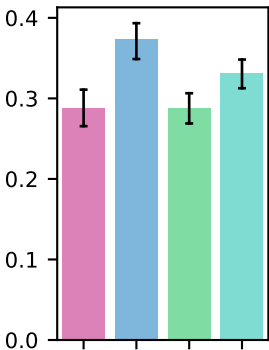


norm_userpath



Waypoint
User
Shared
Control
Fully
Autonomous