
homework sheet 02

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Problem 1

Consider the Voronoi diagram generated by the given points. Color every Voronoi region which was generated around a point labeled a in white and otherwise in black. Then the problem of finding a decision tree, which correctly labels all n points is (clearly) equivalent to the problem of determining the color at a random position inside the unit square.

We will work the second formulation.

Problem 1

Claim: the worst case scenario, demanding most splits in the decision tree, is when we have a “checkerboard” coloring - when no two Voronoi regions of the same colour share an edge (see Fig. 1). Any other scenario is easier or not-more-difficult to solve.

(informal) Proof: consider a Voronoi tessellation in which there exist two regions of the same color, which share an edge. Then if we merge those two regions, we can remove one of the points. This reduces the number of regions to search for by one, which cannot make the problem more complicated, i.e. no scenario is more complicated than the “checkerboard” coloring.

With this statement, it is enough to consider the “checkerboard” coloring and it’s solution tree:

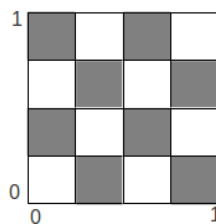


Figure 1: Checkerboard colouring for $n=16$

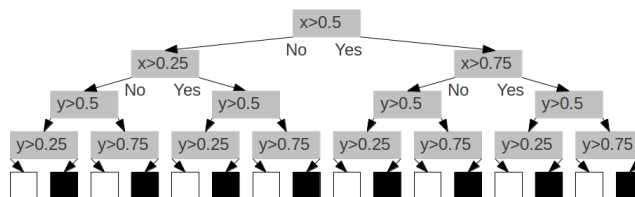


Figure 2: Decision tree for the scheme from Fig.1

Alternative argument - “quadtree”-like approach:

Suppose that the domain contains n points. Then we can always split it in two s.t. each subdomain contains approximately the same number of points (to be precise, each subdomain contains at most $\frac{2^{\lceil \log_2 n \rceil}}{2}$ points). Apply this recursively to each subdomain. We get a tree of depth at most $\lceil \log_2 n \rceil$.

Problem 2

Our worst case scenario in the solution of Problem 1 fulfills the requirements as the tree is of depth $n - 1$.

Problem 3

TODO

Problem 3

Problem 7

Consider the 1D situation. Then there are only two possible cases:

- the vectors \mathbf{u} and \mathbf{v} are parallel
Then $h_r(\mathbf{u}) = h_r(\mathbf{v})$ is always fulfilled and

$$p(h_r(\mathbf{u}) = h_r(\mathbf{v})) = 1 - \frac{0}{\pi} = 1$$

- the vectors \mathbf{u} and \mathbf{v} are antiparallel
Then $h_r(\mathbf{u}) = -h_r(\mathbf{v})$ and

$$p(h_r(\mathbf{u}) = h_r(\mathbf{v})) = 1 - \frac{\pi}{\pi} = 0$$

Now suppose we are in 2D. It is sufficient to show that

$$p(h_r(\mathbf{u}) \neq h_r(\mathbf{v})) = \frac{\theta(\mathbf{u}, \mathbf{v})}{\pi}.$$

Then

$$p(h_r(\mathbf{u}) = h_r(\mathbf{v})) = 1 - p(h_r(\mathbf{u}) \neq h_r(\mathbf{v})) = 1 - \frac{\theta(\mathbf{u}, \mathbf{v})}{\pi}.$$

Let u_\perp , v_\perp be the lines, perpendicular to \mathbf{u} and \mathbf{v} , respectively. Then the probability that $h_r(\mathbf{u})$ is not equal to $h_r(\mathbf{v})$ is the same as the probability of choosing any point in the plane, which falls in the shaded region in Fig. 3. From simple geometry, the angle between \mathbf{u}_\perp and \mathbf{v}_\perp is equal to $\theta(\mathbf{u}, \mathbf{v})$. Thus the probability that a randomly chosen point in the plane falls in the shaded region is equal to $\frac{2\theta}{2\pi} = \frac{\theta}{\pi}$, which we wanted to show.

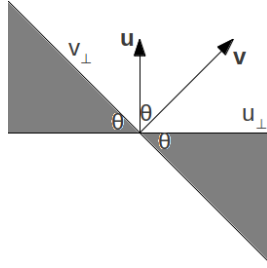


Figure 3: 2D diagram

Now suppose that we are in a higher dimensional space. Then if \mathbf{u} and \mathbf{v} are not parallel or antiparallel (in which case we come down to the same calculation as in 1D, which we already showed), they define a unique plane that contains both of them. It is sufficient to consider the projection of \mathbf{r} onto that plane and whether it lies in the same shaded region as in 2D, hence the problem is reduced to the 2D case.