

Third in a 3-part series:

- Workshop 1: What is a graph and what can we do with it?
- Workshop 2: Graph algorithms: Traversing the tree and beyond
- Workshop 3: Graphs in the real world

Previous workshops are available on the WiDS YouTube channel

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Code for today:

https://github.com/juliaolivieri/WiDS graph examples

A graph is a structure to represent relationships between things

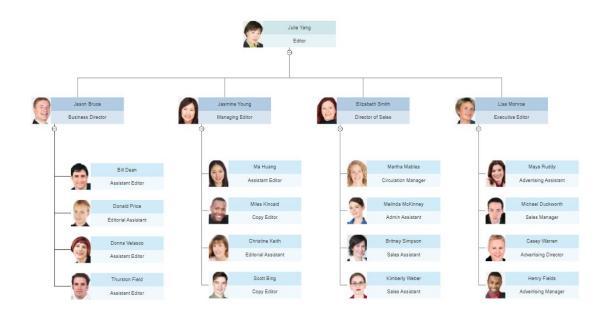


Image from https://www.smartdraw.com/organizational-chart/online-organizational-charts.htm

A graph is a structure to represent relationships between things

Image from https://chem.libretexts.org/Bookshelves/Organic_Chemistry/Supplemental_Modules_(Organic_Chemistry)/F undamentals/Structure_of_Organic_Molecules

A graph is a structure to represent relationships between things

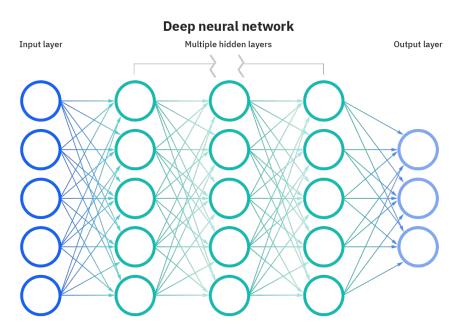


Image from https://www.ibm.com/cloud/learn/neural-networks

A graph is a structure to represent relationships between things



Image from

https://gatton.uky.edu/about-us/stay-connected/news/2020/links-center-social-network-analysis-workshop-success

A graph is a structure to represent relationships between things

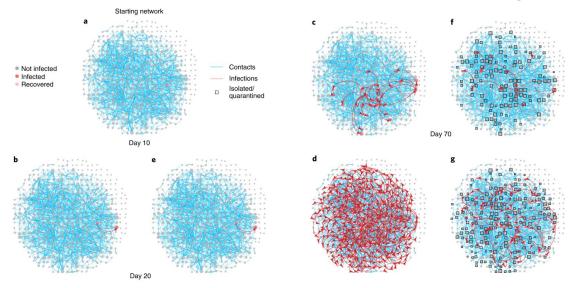


Image from https://www.nature.com/articles/s41591-020-1036-8

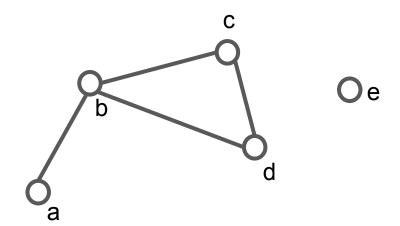
A graph **G** is a pair of sets (**V**, **E**) satisfying the following two conditions:

- 1. **V** is finite and non-empty
- 2. Each element of **E** is a 2-element subset of **V**

Example:

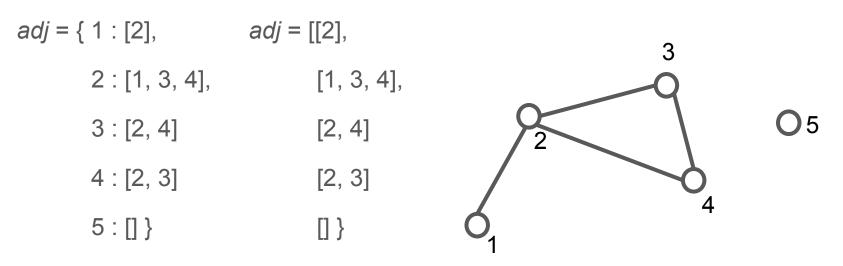
$$V = \{1, 2, 3, 4, 5\}$$

$$E = \{(1, 2), (2, 4), (2, 3), (3, 4)\}$$



Data structures to store graphs: Adjacency list

Adjacency list/adjacency dictionary: For each vertex, we store a list of all the neighbors of that vertex



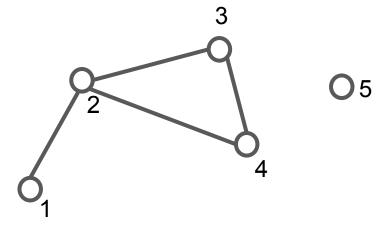
O(|V| + |E|) space complexity, good for traversal algorithms

Data structures to store graphs: Adjacency matrix

Adjacency matrix: Matrix A of dimension |V| x |V| defined by:

$$a_{ij} = \begin{cases} \mathbf{1} & \text{if } (i,j) \in E \\ \mathbf{0} & \text{otherwise} \end{cases}$$

	1	2	3	4	5
1	0	1	0	0	0
2	1	0	1	1	0
3	0	1	0	1	0
4	0	1	1	0	0
5	0	0	0	0	0



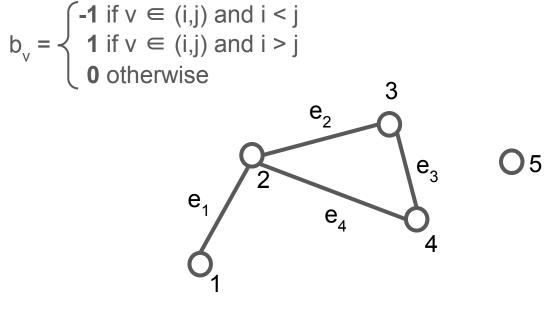
 $O(|V|^2)$ space complexity, good for finding if edges exist

Data structures to store graphs: Incidence matrix

Incidence matrix: Matrix B of dimension $|V| \times |E|$, with column for edge E = (i,j), i < j

defined by:

	e ₁	e ₂	e_3	e ₄
1	-1	0	0	0
2	1	-1	0	-1
3	0	1	-1	0
4	0	0	1	1
5	0	0	0	0



O(|V||E|) space complexity

Graph data structure comparison

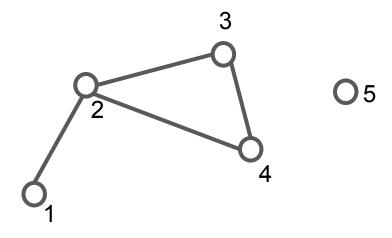
	Adjacency list
Storage	O(V + E)
Add vertex	O(1)
Add edge	O(1)
Remove vertex	O(E)
Remove edge	O(V)
Are i and j adjacent?	O(V)

The data structure we choose depends on the application

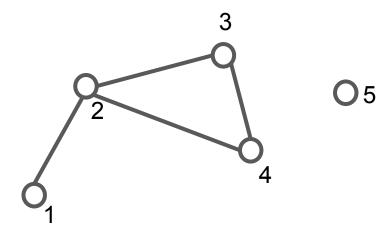
Why would we use an incidence matrix?

Table from https://en.wikipedia.org/wiki/Graph_(abstract_data_type)

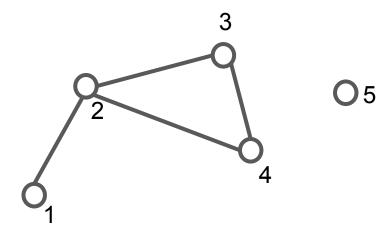
	1	2	3	4	5
1	0	1	0	0	0
2	1	0	1	1	0
3	0	1	0	1	0
4	0	1	1	0	0
5	0	0	0	0	0



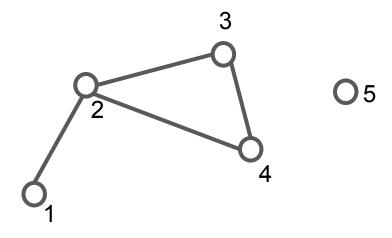
	1	2	3	4	5
1	1	0	1	1	0
2	0	3	1	1	0
3	1	1	2	1	0
4	1	1	1	2	0
5	0	0	0	0	0



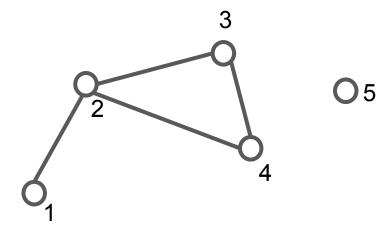
	1	2	3	4	5
1	0	3	1	1	3
2	3	2	4	4	0
3	1	4	2	3	0
4	1	4	3	2	0
5	0	0	0	0	0



	1	2	3	4	5
1	3	2	4	4	0
2	2	11	6	6	0
3	4	6	7	6	0
4	4	6	6	7	0
5	0	0	0	0	0



	1	2	3	4	5
1	2	11	6	6	0
2	11	14	17	17	0
3	6	17	12	13	0
4	6	17	13	12	0
5	0	0	0	0	0



The graph Laplacian

The graph Laplacian can be used to easily solve many graph theory problems

- Number of spanning trees
- Number of components
- Construction of low-dimensional embeddings

$$L = D - A$$
 $L = B^T B$

Where *D* is a diagonal matrix with the degree of each vertex

The graph Laplacian

The graph Laplacian can be used to easily solve many graph theory problems

- Number of spanning trees
- Number of components
- Construction of low-dimensional embeddings

	1	2	3	4	5
1	1	-1	0	0	0
2	-1	3	-1	-1	0
3	0	-1	2	-1	0
4	0	-1	-1	2	0
5	0	0	0	0	0

Many graph datasets are available online

Many are available to download as simple text files with one line per edge

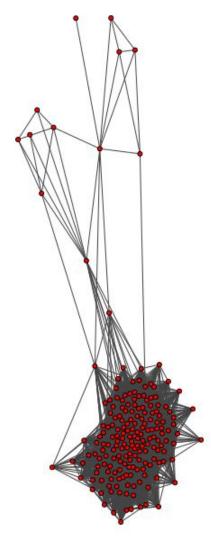
All analysis performed with the python igraph package

https://github.com/juliaolivieri/WiDS_graph_examples

```
# Berkely-Stanford web graph from 2002
# Nodes: 685230 Edges: 7600595
# FromNodeId
                ToNodeId
        11
        17
        254913
        438238
254913
       255378
254913
       255379
254913
       255383
254913
       255384
254913
       255392
254913
       255393
254913 255394
254913 255396
254913 255399
254913 255401
254913
       255402
254913 255561
254913 255562
254913
       255637
254913
       255638
254913
        255662
```



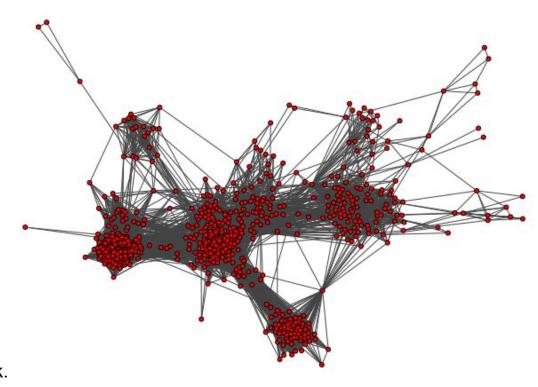
Includes the relationships between all friends of a single user (not plotted)



Downloaded from https://snap.stanford.edu/data/ego-Twitter.html



Includes the relationships between all friends of a single user (not plotted)



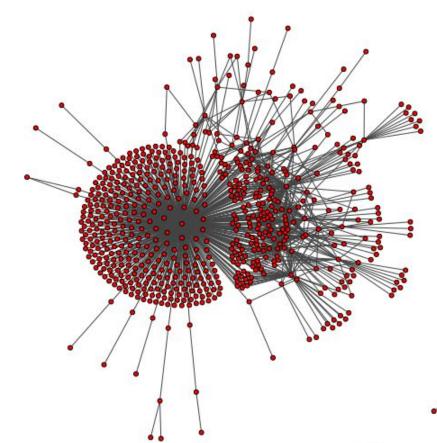
Downloaded from https://snap.stanford.edu/data/ego-Facebook.



Movielens

Vertices are either movies or users, and an edge means that the user has watched that movie.

Only 2000 vertices are plotted for clarity



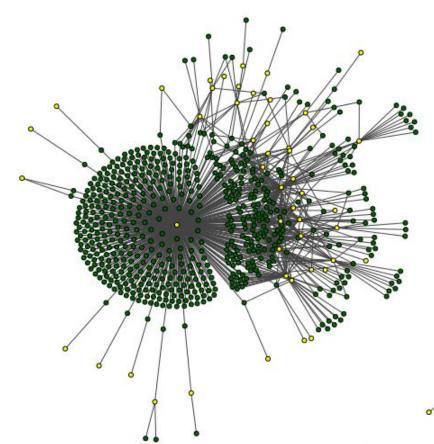
Downloaded from https://www.kaggle.com/grouplens/movielens-20m-dataset



Movielens

Vertices are either movies or users, and an edge means that the user has watched that movie.

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Mouse gene regulatory network ...

Vertices are genes and edges between them represent regulatory relationships.

Only 500 vertices are plotted for clarity

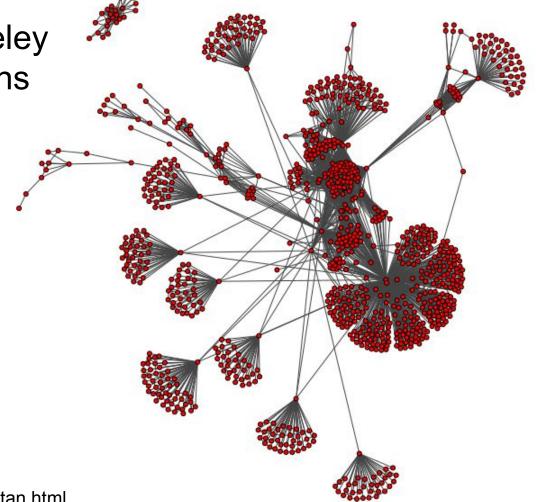
Downloaded from https://networkrepository.com/bio-mouse-gene.php



Stanford-Berkeley web connections

Vertices are Berkeley or Stanford webpages and edges are links between them

Only 1000 vertices are plotted for clarity



Downloaded from https://snap.stanford.edu/data/web-BerkStan.html











V			











V	193	747	26,232	43,126	685,230











V	193	747	26,232	43,126	685,230
E					





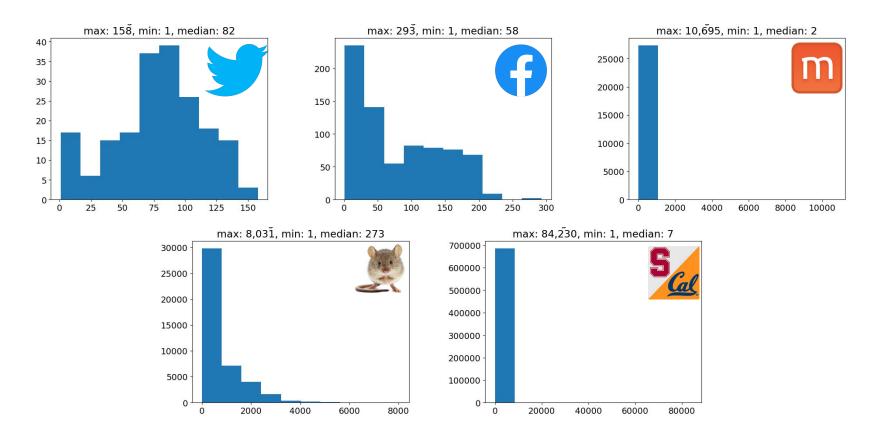






V	193	747	26,232	43,126	685,230
ΙΕΙ	7,597	30,025	174,844	14,461,095	6,649,470

How does the distribution of degrees differ?







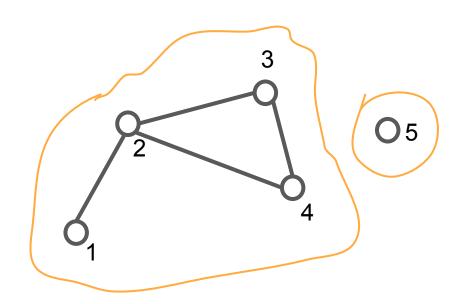






V	193	747	26,232	43,126	685,230
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Components					

Component of a graph: subgraph within which every pair of vertices is connected by a path







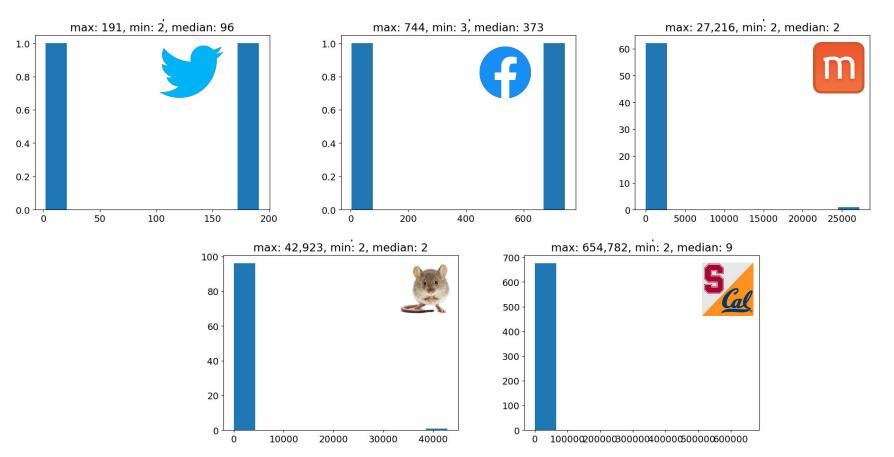






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ΙΕΙ	7,597	30,025	174,844	14,461,095	6,649,470
Components	2	2	63	97	676

How many vertices are in each component?











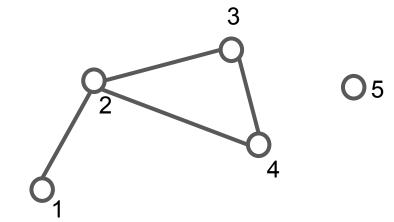


V	193	747	26,232	43,126	685,230
E	7,597	30,025	174,844	14,461,095	6,649,470
Components	2	2	63	97	676
Density					

Density of a graph: The fraction of possible edges that are present

$$D = rac{|E|}{inom{|V|}{2}} = rac{2|E|}{|V|(|V|-1)}$$

$$D = \frac{2 \times 4}{5 \times 4} = 0.4$$













V	193	747	26,232	43,126	685,230
ΙΕΙ	7,597	30,025	174,844	14,461,095	6,649,470
Components	2	2	63	97	676
Density	0.410	0.108	0.000	0.016	0.000





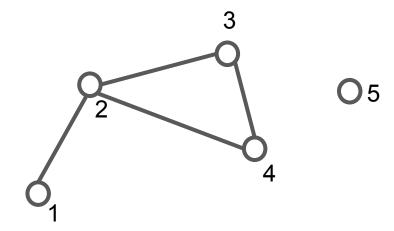




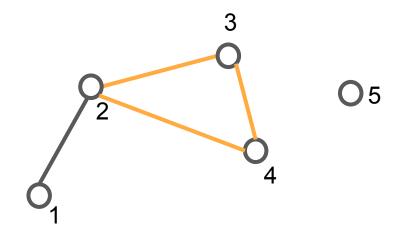


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Girth					

Girth of a graph: The length of the shortest cycle



Girth of a graph: The length of the shortest cycle













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Density	0.410	0.108	0.000	0.016	0.000
Girth	3	3	4	3	3









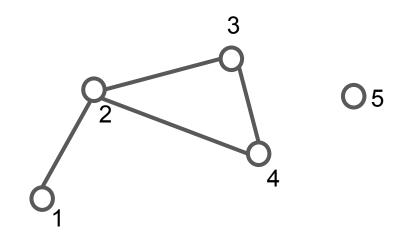


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Density	0.410	0.108	0.000	0.016	0.000
Girth	3	3	4	3	3
Assortativity					

Assortativity coefficient: The Pearson correlation coefficient of degree between vertices that share an edge

Correlation coefficient = -0.87

i	j	d(i)	d(j)
1	2	1	3
2	3	3	2
2	4	3	2
3	4	2	2



Assortativity coefficient: The Pearson correlation coefficient of degree between vertices that share an edge

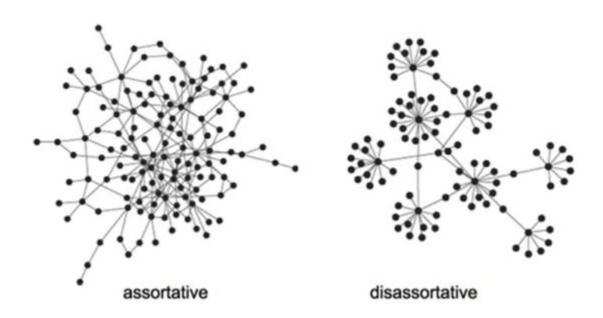


Image from https://www.quora.com/What-is-the-difference-between-modularity-and-assortativity-in-network-science











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Density	0.410	0.108	0.000	0.016	0.000
Girth	3	3	4	3	3
Assortativity	-0.034	0.503	-0.111	0.002	-0.113

Thank you!

Email me with questions: jolivier@stanford.edu