

Advantech – USB 4750 Documentation

Specifications of device: :

Isolated Digital Input

Isolated Digital Input

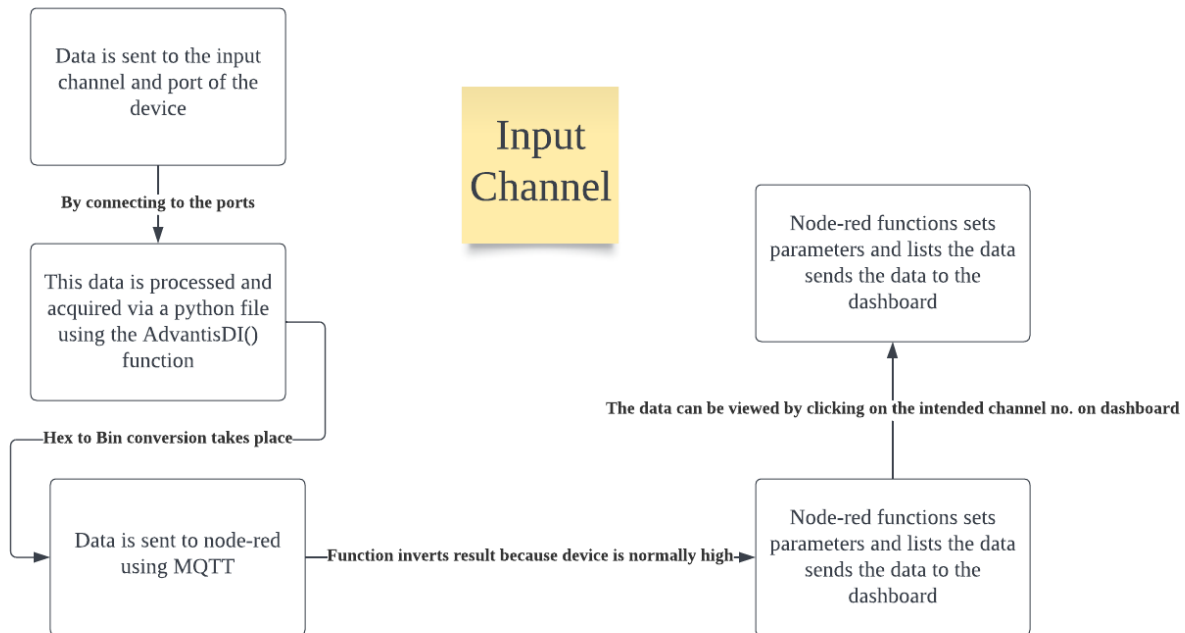
Number of Input Channels	16
Interrupt Inputs	2 (IDI0,IDI8)
Optical Isolation	2500 V _{DC}
Optical Isolator response time	50 us
Input Voltage	V _{IH} (max.) = 60 V _{DC} V _{IH} (min.) = 5 V _{DC} V _{IL} (max.) = 2 V _{DC}

Isolated Digital Output

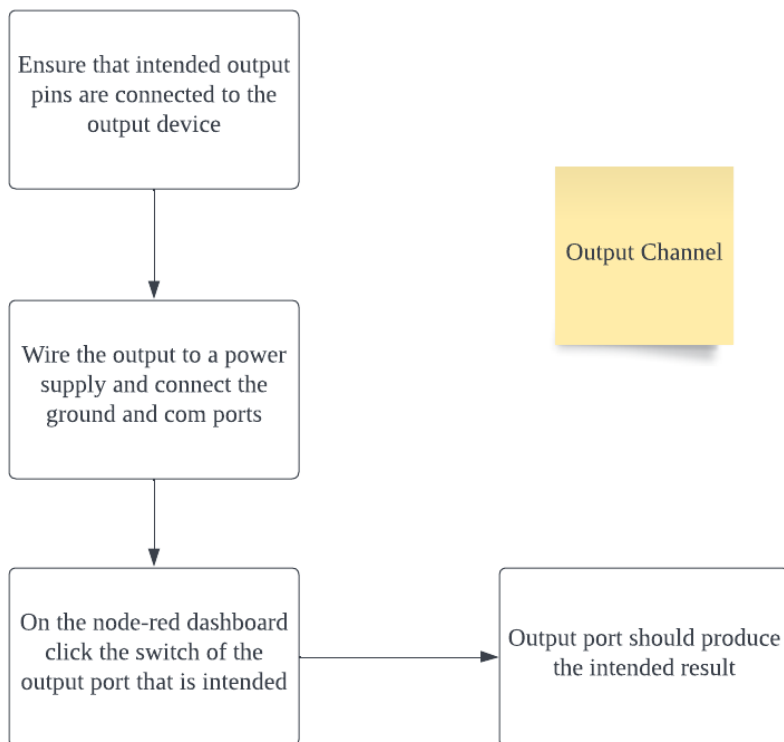
Isolated Digital Output

Number of Output Channels	16
Optical Isolation	2500 V _{DC}
Optical Isolator response time	50 us
Supply Voltage	5~40 V _{DC}
Sink Current	200 mA max. /channel

A basic flowchart summarizing the entire process is being shown below:-



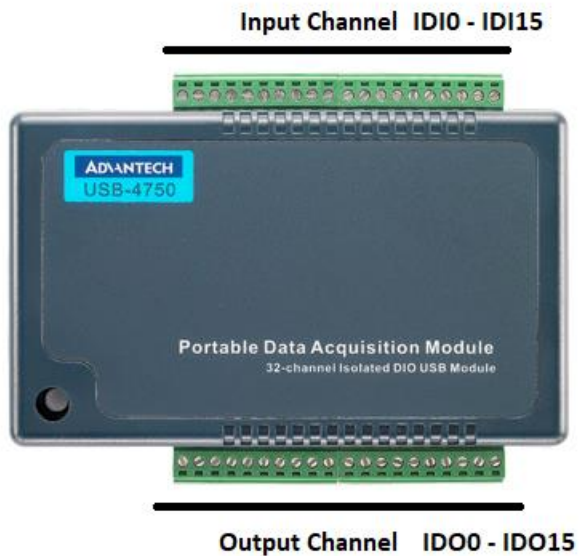
Output Channel:-



Step by Step process of extracting data from Inputs

Each input channel will accept a 5 V- 60 V Direct Current

It is important to note that the numbering of the ports is as follows



Each channel is separated into 2 ports

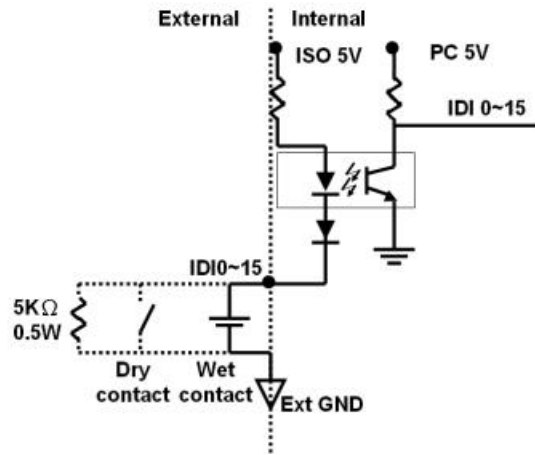
For the input channel :- Port 1 (IDI0 – IDI7)

Port 2 (IDI8 – IDI15)

For the output channel :- Port 1 (IDO0 – IDO7)

Port 2 (IDO8 – IDO15)

Step 1 :- Connect ground of input pin to the GND channel in the device and connect the other pin to the desired channel



Step 2 :- Connect the device to the computer with all the drivers installed and run the python program provided

On successful connection with the device the terminal should give an output of

‘Connected to MQTT broker’ as shown below:-

```
19  $nokeyworus:  $
20  */
21  /*****
22  *
23  * Windows Example:
24  *   StaticDI.py
```

PROBLEMS 5 OUTPUT DEBUG CONSOLE TERMINAL

```
PS C:\Advantech\DAQNavi\Examples\Python\DI_StaticDI> & "C:/Program Files/Pyth
.py
Reading ports status is in progress, any key to quit!
Connected to MQTT Broker!
DI port 0 status is 0x0
DI port 1 status is 0x0
<class 'list'>
Send `00000000` to topic `PORT1`
Send `00000000` to topic `PORT2`
Send `00000000` to topic `PORT3`
```

Step 4:- Once connected, proceed to the node-red dashboard and toggle the switch on the channel number of the port that you have inserted the input to and the result should be displayed on the screen

Important - The input being triggered through a channel will only be displayed and shown by toggling the switch linked that channel and port number

Advantech USB-4750

Input Channel

ID0	<input type="checkbox"/>	ID1	<input type="checkbox"/>	ID2	<input type="checkbox"/>	ID3	<input type="checkbox"/>	ID4	<input type="checkbox"/>	ID5	<input checked="" type="checkbox"/>
ID6	<input type="checkbox"/>	ID7	<input type="checkbox"/>	ID8	<input type="checkbox"/>	ID9	<input type="checkbox"/>	ID10	<input type="checkbox"/>	ID11	<input type="checkbox"/>
ID12	<input type="checkbox"/>	ID13	<input type="checkbox"/>	ID14	<input type="checkbox"/>	ID15	<input type="checkbox"/>				

Output Channel

ID0	<input type="checkbox"/>	ID1	<input type="checkbox"/>	ID2	<input type="checkbox"/>	ID3	<input type="checkbox"/>	ID4	<input type="checkbox"/>	ID5	<input type="checkbox"/>
ID6	<input type="checkbox"/>	ID7	<input type="checkbox"/>	ID8	<input type="checkbox"/>	ID9	<input type="checkbox"/>	ID10	<input type="checkbox"/>	ID11	<input type="checkbox"/>
ID12	<input type="checkbox"/>	ID13	<input type="checkbox"/>	ID14	<input type="checkbox"/>	ID15	<input type="checkbox"/>				

Input Readings

Click the switch to display value of ID0

Click the switch to display value of ID2

Click the switch to display value of ID4

Click the switch to display value of ID6

Click the switch to display value of ID8

Click the switch to display value of ID10

Click the switch to display value of ID1

Click the switch to display value of ID3

Click the switch to display value of ID5

Click the switch to display value of ID7

Click the switch to display value of ID9

Click the switch to display value of ID11

To connect multiple inputs and display the results on node-red dashboard:-

To connect multiple inputs, connect the input pins and the grounds to their respective channel number in the device and toggle the switch on the node-red dashboard and the result will be displayed for a result showing multiple inputs

Input Channel

ID0

☐

ID1

☐

ID2

☐

ID3

☐

ID4

☐

ID5

☒

ID6

☐

ID7

☐

ID8

☐

ID9

☐

ID10

☐

ID11

☐

ID12

☐

ID13

☒

ID14

☐

ID15

☐

Output Channel

ID0

☐

ID1

☐

ID2

☐

ID3

☐

ID4

☐

ID5

☐

ID6

☐

ID7

☐

ID8

☐

ID9

☐

ID10

☐

ID11

☐

ID12

☐

ID13

☐

ID14

☐

ID15

☐

Input Readings

Click the switch to display value of ID0

Click the switch to display value of ID1

Click the switch to display value of ID2

Click the switch to display value of ID3

Click the switch to display value of ID4

Click the switch to display value of ID5

Click the switch to display value of ID6

Click the switch to display value of ID7

Click the switch to display value of ID8

Click the switch to display value of ID9

Click the switch to display value of ID10

Click the switch to display value of ID11

Click the switch to display value of ID12

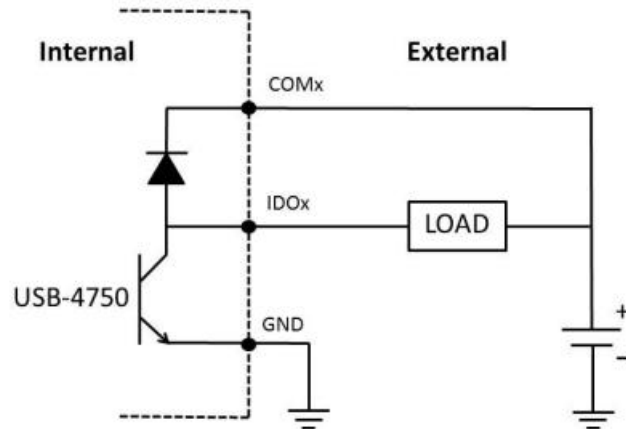
Click the switch to display value of ID13

0

1

Step by step process of writing data to output:-

Step 1:- Please make sure that connecting the output devices to the device should be done by following the wiring schematic of the circuit given below



Step 2 :- Connect the device to the computer with all the drivers installed and run the python program provided

On successful connection with the device the terminal should give an output of ‘Connected to MQTT broker’ as shown below:-

```
129         instantDoCtrl.dispose()
130
131         # If something wrong in this execution, print the error code on screen for track
132         if BioFailed(ret):
133             enumStr = AdxEnumToString("ErrorCode", ret.value, 256)
134             print("Some error occurred. And the last error code is %#x. [%s]" % (ret.value, enumStr))
135
136         return 0
137
138
139 if __name__ == "__main__":
140     AdvInstantDO(deviceDescription)
141
```

PROBLEMS 4 OUTPUT DEBUG CONSOLE TERMINAL

```
PS C:\Advantech\DAQNAvi\Examples\Python\DO_StaticDO> & "C:/Program Files/Python37/python.exe" c:/Use
Connected to MQTT Broker!
```

Step 3 :- Go to the node-red dashboard and the port and channel number needed to be activated can be activated by pushing the switch and toggling the switch to enable the output to be sent for a single input or any number of input

ID0	<input type="checkbox"/>	ID1	<input type="checkbox"/>	ID2	<input type="checkbox"/>	ID3	<input type="checkbox"/>	ID4	<input type="checkbox"/>	ID5	<input type="checkbox"/>
ID6	<input type="checkbox"/>	ID7	<input type="checkbox"/>	ID8	<input type="checkbox"/>	ID9	<input type="checkbox"/>	ID10	<input type="checkbox"/>	ID11	<input type="checkbox"/>
ID12	<input type="checkbox"/>	ID13	<input type="checkbox"/>	ID14	<input type="checkbox"/>	ID15	<input type="checkbox"/>				
Output Channel											
ID0	<input checked="" type="checkbox"/>	ID1	<input type="checkbox"/>	ID2	<input type="checkbox"/>	ID3	<input type="checkbox"/>	ID4	<input type="checkbox"/>	ID5	<input type="checkbox"/>
ID6	<input type="checkbox"/>	ID7	<input type="checkbox"/>	ID8	<input checked="" type="checkbox"/>	ID9	<input type="checkbox"/>	ID10	<input checked="" type="checkbox"/>	ID11	<input type="checkbox"/>
ID12	<input type="checkbox"/>	ID13	<input type="checkbox"/>	ID14	<input type="checkbox"/>	ID15	<input type="checkbox"/>				
Input Readings											
Click the switch to display value of ID0						Click the switch to display value of ID1					
Click the switch to display value of ID2						Click the switch to display value of ID3					
Click the switch to display value of ID4						Click the switch to display value of ID5					
Click the switch to display value of ID6						Click the switch to display value of ID7					
Click the switch to display value of ID8						Click the switch to display value of ID9					
Click the switch to display value of ID10						Click the switch to display value of ID11					
Click the switch to display value of ID12						Click the switch to display value of ID13					
Click the switch to display value of ID14						Click the switch to display value of ID15					

Advantech USB-4750 Hardware Manual Links

Startup Manual Link

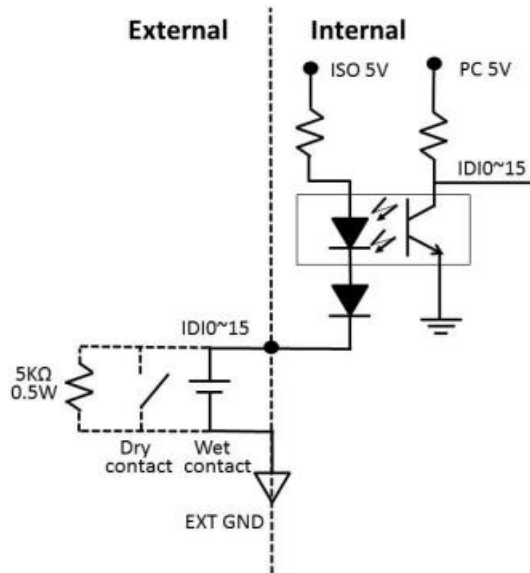
https://advdownload.advantech.com/productfile/Downloadfile2/1-14HO1G7/USB-4750_Startup%20Manual_Ed2-2.PDF

User Manual Link

https://advdownload.advantech.com/productfile/Downloadfile2/1-2A7WYPD/USB-4750_User_Manual_Ed.3_FINAL.pdf

Input Contacts

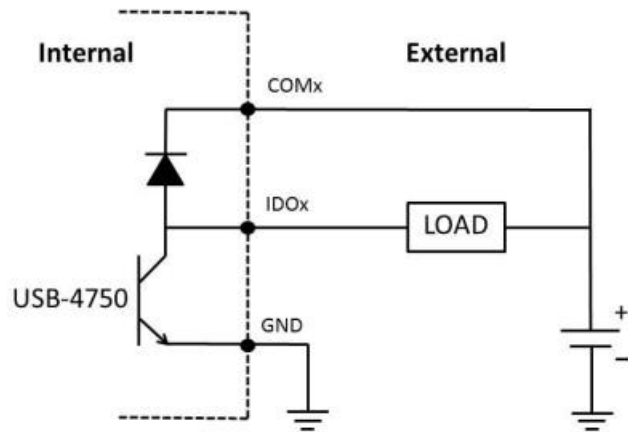
The circuits for the dry/wet contacts for the inputs is as follows:-



Each input can support up to 5-60V DC, the dry contact capability will allow the channel to respond to changes in external circuitry when no voltage is present in the external circuit

Output Contacts:

The circuitry contacts for the inputs is as follows:-



Appendix (Code)

InputDI

```
"""
import sys
sys.path.append('.')
from CommonUtils import kbhit
import time

from Automation.BDaq import *
from Automation.BDaq.InstantDiCtrl import InstantDiCtrl
from Automation.BDaq.BDaqApi import AdxEnumToString, BioFailed

import random

from paho.mqtt import client as mqtt_client

broker = 'localhost'
port = 1883
topic = "PORT1"
topic_1 = "PORT2"
reverse_invert = "INVERT1"
reverse_invert1 = "INVERT2"

deviceDescription = "USB-4750,BID#0"
profilePath = u"..\\..\\profile\\USB_4750.xml"
startPort = 0
portCount = 2

def AdvInstantDI():
    ret = ErrorCode.Success

    # Step 1: Create a 'InstantDiCtrl' for DI function.
    # Select a device by device number or device description and specify the access
mode.
    # In this example we use ModeWrite mode so that we can fully control the device,
    # including configuring, sampling, etc.
    instantDiCtrl = InstantDiCtrl(deviceDescription)

    for _ in range(1):
        instantDiCtrl.loadProfile = profilePath
```

```

# Step 2: Read DI ports' status and show.
print("Reading ports status is in progress, any key to quit!")

def connect_mqtt():
    def on_connect(client, userdata, flags, rc):
        if rc == 0:
            print("Connected to MQTT Broker!")
        else:
            print("Failed to connect, return code %d\n", rc)

    client = mqtt_client.Client()
    client.on_connect = on_connect
    client.connect(broker, port)
    return client

def reverse_binary_string(s):
    # Convert the string to a list of characters
    char_list = list(s)

    # Reverse the list
    char_list.reverse()

    # Join the list back into a string and return it
    return ''.join(char_list)

while not kbhit():
    def publish(client):
        msg_count = 0
        while True:
            time.sleep(1)
            ret, data = instantDiCtrl.readAny(startPort, portCount)
            if BioFailed(ret):
                break

            for i in range(startPort, startPort + portCount):
                print("DI port %d status is %#x" % (i, data[i-startPort]))

        msg_1 = data[startPort]
        msg_1 = '{0:08b}'.format(msg_1)
        msg = msg_1
        binary_string = msg
        reversed_string = reverse_binary_string(binary_string)
        invert_1 = reversed_string

```

```

msg_2 = data[i-startPort]
print(type([i-startPort]))
msg_2 = '{0:08b}'.format(msg_2)
binary_string_1 = msg_2
reversed_string_1 = reverse_binary_string(binary_string_1)
invert_2 = reversed_string_1

```

```

result = client.publish(topic, msg)
# result: [0, 1]
status = result[0]
if status == 0:
    print(f"Send `{msg}` to topic `{topic}`")
else:
    print(f"Failed to send message to topic {topic}")

```

```

result = client.publish(topic_1, msg_2)
# result: [0, 1]
status = result[0]
if status == 0:
    print(f"Send `{msg_2}` to topic `{topic_1}`")
else:
    print(f"Failed to send message to topic {topic_1}")

```

```

result = client.publish(reverse_invert, invert_1)
# result: [0, 1]
status = result[0]
if status == 0:
    print(f"Send `{invert_1}` to topic `{reverse_invert}`")
else:
    print(f"Failed to send message to topic {reverse_invert}")

```

```

result = client.publish(reverse_invert1, invert_2)
# result: [0, 1]
status = result[0]
if status == 0:
    print(f"Send `{invert_2}` to topic `{reverse_invert1}`")
else:

```

```

    print(f"Failed to send message to topic
{reverse_invert1}")

```

```

        msg_count += 1
        time.sleep(1)

def run():
    client = connect_mqtt()
    client.loop_start()
    publish(client)

if __name__ == '__main__':
    run()

# Step 3: Close device and release any allocated resource
instantDiCtrl.dispose()

# If something wrong in this execution, print the error code on screen for tracking.
if BioFailed(ret):
    enumStr = AdxEnumToString("ErrorCode", ret.value, 256)
    print("Some error occurred. And the last error code is %#x. [%s]" % (ret.value,
enumStr))

    return 0

if __name__ == '__main__':
    mainData = AdvInstantDI()

```

InputDO

```
#!/usr/bin/python
# -*- coding:utf-8 -*-

from paho.mqtt import client as mqtt_client
broker = 'localhost'
port = 1883
topic = "DAQ/DO"
MSG = ""

"""
/*****
Copyright (c) 1983-2021 Advantech Co., Ltd.
*****/

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WHICH IS THE PROPERTY OF ADVANTECH CORP., ANY DISCLOSURE, USE, OR REPRODUCTION,
WITHOUT WRITTEN AUTHORIZATION FROM ADVANTECH CORP., IS STRICTLY PROHIBITED.

=====
REVISION HISTORY
-----
$Log:  $

-----
$NoKeywords:  $
*/

/*****
*
* Windows Example:
*   StaticDO.py
*
* Example Category:
*   DIO
*
* Description:
*   This example demonstrates how to use Static DO function.
*
* Instructions for Running:
*   1. Set the 'deviceDescription' for opening the device.
*   2. Set the 'profilePath' to save the profile path of being initialized
device.
*   3. Set the 'startPort' as the first port for Do .
*   4. Set the 'portCount' to decide how many sequential ports to operate Do.
```

```

*
* I/O Connections Overview:
*   Please refer to your hardware reference manual.
*
*****/
"""

import sys
sys.path.append('..')

from Automation.BDaq import *
from Automation.BDaq.InstantDoCtrl import InstantDoCtrl
from Automation.BDaq.BDaqApi import AdxEnumToString, BioFailed

deviceDescription = "USB-4750,BID#0"
profilePath = u"..\\..\\profile\\DemoDevice.xml"
startPort = 0
portCount = 1

def connect_mqtt() -> mqtt_client:
    def on_connect(client, userdata, flags, rc):
        if rc == 0:
            print("Connected to MQTT Broker!")
        else:
            print("Failed to connect, return code %d\n", rc)

    client = mqtt_client.Client('')
    client.on_connect = on_connect
    client.connect(broker, port)
    return client

def subscribe(client: mqtt_client, deviceDescription):
    def on_message(client, userdata, msg):
        print(f"Received `{msg.payload.decode()}` from `{msg.topic}` topic")
        temp(deviceDescription, msg.payload)

    client.subscribe(topic)
    client.on_message = on_message

def run(instantDoCtrl):
    client = connect_mqtt()
    subscribe(client, instantDoCtrl)
    client.loop_forever()

```



```

def AdvInstantDO(deviceDescription):

    ret = ErrorCode.Success

    # Step 1: Create a instantDoCtrl for DO function.
    # Select a device by device number or device description and specify the
    access mode.
    # In this example we use ModeWrite mode so that we can fully control the
    device,
    # including configuring, sampling, etc.

    run(deviceDescription)

def temp(deviceDescription,msg):
    instantDoCtrl = InstantDoCtrl(deviceDescription)

    for _ in range(1):
        instantDoCtrl.loadProfile = profilePath
        print(msg)

        # Step 2: Write DO ports
        dataBuffer = [0] * portCount
        for i in range(startPort, portCount + startPort):
            # inputVal = input("Input a 16 hex number for DO port %d to
            output(for example, 0x00): " % i)
            inputVal = msg
            if not isinstance(inputVal, int):
                inputVal = int(inputVal, 16)

            dataBuffer[i-startPort] = inputVal

        ret = instantDoCtrl.writeAny(startPort, portCount, dataBuffer)
        if BioFailed(ret):
            break
        print("DO output completed!")

    # Step 3: Close device and release any allocated resource.

```

```
instantDoCtrl.dispose()

# If something wrong in this execution, print the error code on screen
for tracking.
    if BioFailed(ret):
        enumStr = AdxEnumToString("ErrorCode", ret.value, 256)
        print("Some error occurred. And the last error code is %#x. [%s]" %
            (ret.value, enumStr))

    return 0

if __name__ == "__main__":
    AdvInstantDO(deviceDescription)
```

In the input section:

The function:-

`connect_mqtt()` – Set ups the connection between node-red and the python file using MQTT

`AdvantisDI()` – Processes the data, converts it from hexa-decimal to binary to make it easier for node-red to read the data and process it

In the output section:-

`connect_mqtt()` – Set ups the connection between node-red and the python file using MQTT

`AdvantisDO()` – Receives the push signal from node-red using MQTT and lights up the intended port in the device