Algorithms to Compute Appraisal Variables

Algorithm 1 (Relevance)

1: **function** IsEventRelevant(*Events* ε_t)
2: Initialize graph $\mathcal{G}_t$ with current mental state $\mathcal{S}_t$.
3: $\vec{g}_t \leftarrow$ extractGoal($\mathcal{G}_t$)
4: $\mathcal{P}_t \leftarrow$ extractPaths($\varepsilon_t, \vec{g}_t$)
5: **if** ($\mathcal{P}_t = \emptyset$) **then**
6: **return** 0
7: **else**
8: $\mathcal{U}_t \leftarrow$ getEventUtility($\varepsilon_t, \vec{g}_t$)
9: **if** ($\mathcal{U}_t \geq \tau_e$) **then**
10: **return** ($\mathcal{U}_t$)
11: **else**
12: **return** 0
13: **end function**

Algorithm 2 (Desirability)

function IsEventDesirable(*Events* ε_t)

    Initialize graph $\mathcal{G}_t$ with current mental state $\mathcal{S}_t$.

    $\vec{g}_t \leftarrow$ extractGoals($\mathcal{G}_t$)

    if ($topLevelTaskStatus()$ = ACHIEVED) **then**
        return 1.0
    else if ($topLevelTaskStatus()$ = BLOCKED) **then**
        return -1.0
    else if ($topLevelTaskStatus()$ = INPROGRESS) **then**
        if ($currentTaskStatus()$ = ACHIEVED) **then**
            return 0.75
        else if ($currentTaskStatus()$ = BLOCKED) **then**
            return -0.75
        else if ($currentTaskStatus()$ = INPROGRESS) **then**
            return 0.25
        else if ($currentTaskStatus()$ = UNKNOWN) **then**
            if ($taskPreconditionStatus()$ = SATISFIED) **then**
                return 0.5
            else if ($taskPreconditionStatus()$ = UNSATISFIED) **then**
                return -0.75
            else if ($taskPreconditionStatus()$ = UNKNOWN) **then**
                if ($doesContribute(\varepsilon_t, \vec{g}_t)$ = TRUE) **then**
                    return -0.5
                else if ($doesContribute(\varepsilon_t, \vec{g}_t)$ = FALSE) **then**
                    if ($recipeApplicability(\varepsilon_t, \vec{g}_t)$ = APPLICABLE) **then**
                        return -0.5
                    else if ($recipeApplicability(\varepsilon_t, \vec{g}_t)$ = INAPPLICABLE) **then**
                        return -0.75
                    else if ($recipeApplicability(\varepsilon_t, \vec{g}_t)$ = UNKNOWN) **then**
                        return -0.25
end function

Algorithm 3 (Get Utterance Utility)

function GETUTTERANCEUTILITY(*Paths* $\mathcal{P}_{\vec{g}_t}$, *Paths* $\mathcal{P}_{\vec{g}_{t-1}}$)

$\mathcal{U}_{\vec{g}_t} \leftarrow \sum_{\mathcal{P}^{U_i}_{\vec{g}_t} \in \mathcal{P}^{U}_{\vec{g}_t}}$ GETMENTALSTATEUTILITY($\mathcal{P}^{U_i}_{\vec{g}_t}$)

$\hat{\mathcal{U}}_{\vec{g}_t} \leftarrow \frac{\mathcal{U}_{\vec{g}_t}}{\left|\mathcal{P}^{U}_{\vec{g}_t}\right|}$

$\mathcal{U}_{\vec{g}_{t-1}} \leftarrow \sum_{\mathcal{P}^{U_i}_{\vec{g}_{t-1}} \in \mathcal{P}^{U}_{\vec{g}_{t-1}}}$ GETMENTALSTATEUTILITY($\mathcal{P}^{U_i}_{\vec{g}_{t-1}}$)

$\hat{\mathcal{U}}_{\vec{g}_{t-1}} \leftarrow \frac{\mathcal{U}_{\vec{g}_{t-1}}}{\left|\mathcal{P}^{U}_{\vec{g}_{t-1}}\right|}$

return ($\hat{\mathcal{U}}_{\vec{g}_t}$ - $\hat{\mathcal{U}}_{\vec{g}_{t-1}}$)

end function

Algorithm 4 (Get Action Utility)

function GETACTIONUTILITY(*Paths* $\mathcal{P}_{\vec{g}_t}$, *Paths* $\mathcal{P}_{\vec{g}_{t-1}}$)

$\theta \leftarrow$ GETPRECONDITIONUTILITY($\mathcal{P}_{\vec{g}_t}, \mathcal{P}_{\vec{g}_{t-1}}$)

$\psi \leftarrow$ GETPOSTCONDITIONUTILITY($\mathcal{P}_{\vec{g}_t}, \mathcal{P}_{\vec{g}_{t-1}}$)

$\vec{\omega} \leftarrow$ GETUTILITYWEIGHTS()

$\Delta U \leftarrow \frac{\omega_0 \cdot \theta + \omega_1 \cdot \psi}{\omega_0 + \omega_1}$

return ΔU

end function

Algorithm 5 (Get Emotion Utility)

function GetEmotionUtility(*Paths* $\mathcal{P}_{\vec{g}_t}$, *Paths* $\mathcal{P}_{\vec{g}_{t-1}}$)

$\mathcal{P}^{\mathcal{E}}_{\vec{g}_{t-1}} \leftarrow$ ExtractEmotionPaths($\mathcal{P}_{\vec{g}_{t-1}}$)

$\mathcal{P}^{\mathcal{E}}_{\vec{g}_t} \leftarrow$ ExtractEmotionPaths($\mathcal{P}_{\vec{g}_t}$)

$\mathcal{E}^{other}_{t-1} \leftarrow$ ExtractOthersEmotion($\mathcal{P}^{\mathcal{E}}_{\vec{g}_{t-1}}$)

$\mathcal{E}^{other}_{t} \leftarrow$ ExtractOthersEmotion($\mathcal{P}^{\mathcal{E}}_{\vec{g}_t}$)

$\Upsilon_{t-1} \leftarrow$ GetSomaticMarkers($\mathcal{E}^{other}_{t-1}$)

$\Upsilon_{t} \leftarrow$ GetSomaticMarkers($\mathcal{E}^{other}_{t}$)

$$\Delta U \leftarrow \frac{\left(\left(\left(\left((\Upsilon^A_t - \Upsilon^A_{t-1})\times 15\right) + (\Upsilon^V_t - \Upsilon^V_{t-1})\right)\times 15\right) + (\Upsilon^S_t - \Upsilon^S_{t-1})\right)\times 15 + (\Upsilon^I_t - \Upsilon^I_{t-1})}{15^4}$$

return ΔU

end function

Algorithm 6 (Get Precondition Utility)

function GETPRECONDITIONUTILITY(*Paths* $\mathcal{P}_{\vec{g}_t}$, *Paths* $\mathcal{P}_{\vec{g}_{t-1}}$)

  $ratio^{sat}_{\vec{g}_t/\vec{g}_{t-1}} \leftarrow ratio^{sat/total}_{\vec{g}_t} \leftarrow 0$

  $\mathcal{P}^A_{\vec{g}_t} \leftarrow$ EXTRACTACTIONPATHS($\mathcal{P}_{\vec{g}_t}$)

  if $(\vec{g}_t = \vec{g}_{t-1})$ **then**
    if $(\mathcal{P}^A_{t-1} \neq \emptyset)$ ***OR*** $(\mathcal{P}^A_t \neq \emptyset)$ **then**

      $\mathcal{P}^A_{\vec{g}_{t-1}} \leftarrow$ EXTRACTACTIONPATHS($\mathcal{P}_{\vec{g}_{t-1}}$)

      $Precond^{sat}_{\mathcal{P}^A_{\vec{g}_t}} \leftarrow$ CHECKPRECONDITIONS($\mathcal{P}^A_{\vec{g}_t}$)
      $Precond^{sat}_{\mathcal{P}^A_{\vec{g}_{t-1}}} \leftarrow$ CHECKPRECONDITIONS($\mathcal{P}^A_{\vec{g}_{t-1}}$)

      $ratio^{sat}_{\vec{g}_t/\vec{g}_{t-1}} \leftarrow \omega_0 \cdot \frac{Precond^{sat}_{\mathcal{P}^A_{\vec{g}_t}}}{Precond^{sat}_{\mathcal{P}^A_{\vec{g}_{t-1}}}|_{\neq 0}} + \omega_1 \cdot \frac{Precond^{sat}_{\mathcal{P}^A_{\vec{g}_t}}}{Precond^{total}_{\mathcal{P}^A_{\vec{g}_t}}|_{\neq 0}}$

      return $ratio^{sat}_{\vec{g}_t/\vec{g}_{t-1}}$
    else
      return 0
  else
    if $(\mathcal{P}^A_t \neq \emptyset)$ **then**
      $Precond_{\mathcal{P}^A_{\vec{g}_t}} \leftarrow$ CHECKPRECONDITIONS($\mathcal{P}^A_{\vec{g}_t}$)

      $ratio^{sat/total}_{\vec{g}_t} \leftarrow \frac{Precond^{sat}_{\mathcal{P}^A_{\vec{g}_t}}}{Precond^{total}_{\mathcal{P}^A_{\vec{g}_t}}|_{\neq 0}}$

      return $ratio^{sat/total}_{\vec{g}_t}$
    else
      return 0
end function

Algorithm 7 (Check Preconditions)

function CHECKPRECONDITIONS(*Paths* $\mathcal{P}^A_{\vec{g}}$)
  $count^{sat}_{precond} \leftarrow count^{total}_{precond} \leftarrow 0$
  $\Theta_{\vec{g}} \leftarrow$ EXTRACTPRECONDITIONS($\mathcal{P}^A_{\vec{g}}$)
  for each $\theta^i_{\vec{g}} \in \Theta_{\vec{g}}$ **do**
    if (ISSATISFIED($\theta^i_{\vec{g}}$)) **then**
      $count^{sat}_{precond} \leftarrow count^{sat}_{precond} + 1$
    $count^{total}_{precond} \leftarrow count^{total}_{precond} + 1$
  return $\langle count^{sat}_{precond}, count^{total}_{precond} \rangle$
end function

Algorithm 8 (Get Postcondition Utility)

function GETPOSTCONDITIONUTILITY(*Paths* $\mathcal{P}_{\vec{g}_t}$, *Paths* $\mathcal{P}_{\vec{g}_{t-1}}$)
  $\mathcal{P}^A_{\vec{g}_t} \leftarrow$ EXTRACTACTIONPATHS($\mathcal{P}_{\vec{g}_t}$)
  if ($\vec{g}_t = \vec{g}_{t-1}$) **then**
    if ($\mathcal{P}^A_{t-1} \neq \emptyset$) ***OR*** ($\mathcal{P}^A_t \neq \emptyset$) **then**
      $\mathcal{P}^A_{\vec{g}_{t-1}} \leftarrow$ EXTRACTACTIONPATHS($\mathcal{P}_{\vec{g}_{t-1}}$)
      $\Psi_{\vec{g}_t} \leftarrow$ EXTRACTPOSTCONDITIONS($\mathcal{P}^A_{\vec{g}_t}$)
      $\Psi_{\vec{g}_{t-1}} \leftarrow$ EXTRACTPOSTCONDITIONS($\mathcal{P}^A_{\vec{g}_{t-1}}$)
      if (ISSATISFIED($\Psi_{\vec{g}_t}$)) **then**
        if (ISSATISFIED($\Psi_{\vec{g}_{t-1}}$)) **then**
          return γ^t ▷ Discount rate: $0 \leq \gamma \leq 1$
        else
          return 1
      else
        if ISSATISFIED($\Psi_{\vec{g}_{t-1}}$)) **then**
          return -1
        else
          return 0
end function

Algorithm 9 (Expectedness)

function IsEventExpected(*MentalStates* $\mathcal{S}_t$, *Event* ε_t)

  Initialize graph $\mathcal{G}_{t-1}$ with previous mental state $\mathcal{S}_{t-1}$.
  Initialize graph $\mathcal{G}_t$ with current mental state $\mathcal{S}_t$.

  $\vec{g}_{t-1} \leftarrow$ extractGoals($\mathcal{G}_{t-1}$)
  $\vec{g}_t \leftarrow$ extractGoals($\mathcal{G}_t$)

  $\mathcal{P}_{t-1} \leftarrow$ extractPaths($\mathcal{G}_{t-1}, \vec{g}_{t-1}$)
  $\mathcal{P}_t \leftarrow$ extractPaths($\mathcal{G}_t, \vec{g}_t$)

  if ($\vec{g}_t \neq \vec{g}_{t-1}$) **then**
    if (IsAchieved(g^{c}_{t-1})) **then**
      if ($\neg$IsAchieved(g^{p}_{t-1})) **then**
        $\mathcal{P}'_{t-1} \leftarrow$ extractPaths($\mathcal{G}_{t-1}, \vec{g}_t$)
        if ($\mathcal{P}'_{t-1} = \emptyset$) **then**
          return FALSE
        else
          $\mathcal{U}'_{t-1} \leftarrow$ getUtilities($\mathcal{G}_{t-1}, \vec{g}_t$)
          $\mathcal{U}_{t-1} \leftarrow$ getUtilities($\mathcal{G}_{t-1}, \vec{g}_{t-1}$)
          if ($\mathcal{U}'_{t-1} - \mathcal{U}_{t-1}) \geq \tau_e$ **then**
            return TRUE
          else
            return FALSE
      else ▷ Collaborative and personal goals have achieved.
        return TRUE
    else ▷ Collaborative goal has not achieved.
      return FALSE
  else ▷ Goals have not changed.
    return TRUE
end function

Algorithm 10 (Likelihood)

1: **function** GETEVENTSLIKELIHOOD(*MentalStates* $\mathcal{S}_t$, *Event* ε_t)

2: $\mathcal{G}_t \leftarrow$ UPDATEGRAPH$(\mathcal{S}_t, \varepsilon_t)$
3: $\vec{g}_t \leftarrow$ EXTRACTGOALS$(\mathcal{G}_t)$
4: $\mathcal{P}_t \leftarrow$ EXTRACTPATHS$(\mathcal{G}_t, \vec{g}_t)$

5: **if** $(\mathcal{P}_t = \emptyset)$ **then**
6: **return** 0
7: **else**
8: **for each** $\mathcal{P}_t^i \in \mathcal{P}_t$ **do**
9: **for each** $\varepsilon_{t+1}^j \in \varepsilon_{t+1}$ **do**
10: $\vec{P}\left(\varepsilon_{t+1}^j \middle| \mathcal{F}(\mathcal{P}_t^i)\right) = \frac{\vec{P}\left(\mathcal{F}(\mathcal{P}_t^i)\middle|\varepsilon_{t+1}^j\right)\vec{P}(\varepsilon_{t+1}^j)}{\sum_{e_{t+1}^k \in \varepsilon_{t+1}^j} \vec{P}\left(\mathcal{F}(\mathcal{P}_t^i)\middle|e_{t+1}^k\right)}$
11:
return $\vec{P}\left(\varepsilon_{t+1}\middle|\mathcal{F}(\mathcal{P}_t^i)\right)$
12: **end function**

Algorithm 11 (Controllability)

function IsEventControllable(*MentalStates* $\mathcal{S}_t$, *Event* ε_t)

$\alpha^{agency}_{self/other} \leftarrow \beta^{autonomy}_{self/other} \leftarrow 0$

$\kappa^{preconditions}_{satisfied/total} \leftarrow \lambda^{predecessors}_{succeeded/failed} \leftarrow \mu^{inputs}_{available/required} \leftarrow 0$

Initialize graph $\mathcal{G}_t$ with current mental state $\mathcal{S}_t$.

$\vec{g}_t \leftarrow$ extractGoals($\mathcal{G}_t$)
$\mathcal{P}_{\vec{g}_t} \leftarrow$ extractPaths($\mathcal{G}_t, \vec{g}_t$)

$\mathcal{P}^A_{\vec{g}_t} \leftarrow$ ExtractActionPaths($\mathcal{P}_{\vec{g}_t}$)
$\varphi^A_{\vec{g}_t} \leftarrow$ GetRecipeApplicability($\mathcal{P}^A_{\vec{g}_t}$)

$\mathcal{P}^{\mathcal{E}}_{\vec{g}_t} \leftarrow$ ExtractEmotionPaths($\mathcal{P}_{\vec{g}_t}$)

$\mathcal{E}^{other}_t \leftarrow$ ExtractOthersEmotion($\mathcal{P}^{\mathcal{E}}_{\vec{g}_t}$)

$\mathcal{I}^{emotion}_{other} \leftarrow$ GetEmotionIntensity($\mathcal{E}^{other}_t$)

$\Upsilon_t \leftarrow$ GetSomaticMarkers($\mathcal{E}^{other}_t$)
$\mathcal{V}^{\mathcal{E}}_t \leftarrow$ GetEmotionValue($\Upsilon_t, \varepsilon_t$)

$Agency_{\vec{g}_t} \leftarrow$ GetAgencyValue($\mathcal{P}_{g_t}$)
$\alpha^{agency}_{self/other} \leftarrow {}^{Agency^{self}_{\vec{g}_t}}/_{Agency^{other}_{\vec{g}_t}}$

$\beta^{autonomy}_{self/other} \leftarrow {}^{\text{GetAutonomyValue}(\mathcal{P}_{g^{self}_t})}/_{\text{GetAutonomyValue}(\mathcal{P}_{g^{other}_t})}$

$Precond_{\mathcal{P}^A_{\vec{g}_t}} \leftarrow$ CheckPreconditions($\mathcal{P}^A_{\vec{g}_t}$)

$\kappa^{preconditions}_{satisfied/total} \leftarrow {}^{Precond^{satisfied}_{\mathcal{P}^A_{\vec{g}_t}}}/_{Precond^{total}_{\mathcal{P}^A_{\vec{g}_t}}}$

$Predecessors_{\mathcal{P}^A_{\vec{g}_t}} \leftarrow$ CheckPredecessors($\mathcal{P}^A_{\vec{g}_t}$)

$\lambda^{predecessors}_{succeeded/total} \leftarrow {}^{Predecessors^{succeeded}_{\mathcal{P}^A_{\vec{g}_t}}}/_{Predecessors^{total}_{\mathcal{P}^A_{\vec{g}_t}}}$

$Inputs_{\mathcal{P}^A_{\vec{g}_t}} \leftarrow$ CheckInputs($\mathcal{P}^A_{\vec{g}_t}$)

$\mu^{inputs}_{available/required} \leftarrow {}^{Inputs^{available}_{\mathcal{P}^A_{\vec{g}_t}}}/_{Inputs^{required}_{\mathcal{P}^A_{\vec{g}_t}}}$

$\mathcal{U}_t \leftarrow \frac{\omega_0 \cdot \alpha^{agency}_{self/other} + \omega_1 \cdot \beta^{autonomy}_{self/other}}{\omega_0 \cdot + \omega_1 \cdot}$

$+ \frac{\omega_2 \cdot \kappa^{preconditions}_{satisfied/total} + \omega_3 \cdot \lambda^{predecessors}_{succeeded/total} + \omega_4 \cdot \mu^{inputs}_{available/required}}{\omega_2 + \omega_3 + \omega_4}$

$+ \frac{\omega_5 \cdot \mathcal{I}^{emotion}_{other} + \omega_6 \cdot \varphi^{A}_{\vec{g}_t} + \omega_7 \cdot \mathcal{V}^{\mathcal{E}}_t}{\omega_5 + \omega_6 + \omega_7}$

if $(\mathcal{U}_t \geq \tau_e)$ **then**
  return TRUE
else
  return FALSE
end function

Algorithm 12 (Check Predecessors)

function CHECKPREDECESSORS(*Paths* $\mathcal{P}^A_{\vec{g}}$)

$count^{succeeded}_{predecessor} \leftarrow count^{total}_{predecessor} \leftarrow 0$

$\Phi_{\vec{g}} \leftarrow$ EXTRACTPREDECESSORS$(\mathcal{P}^A_{\vec{g}})$

for each $\phi^i_{\vec{g}} \in \Phi_{\vec{g}}$ **do**
  if (ISSUCCEEDED$(\phi^i_{\vec{g}})$) **then**
    $count^{succeeded}_{predecessor} \leftarrow count^{succeeded}_{predecessor} + 1$
  $count^{total}_{predecessor} \leftarrow count^{total}_{predecessor} + 1$

return $\langle count^{succeeded}_{predecessor}, count^{total}_{predecessor} \rangle$
end function

Algorithm 13 (Check Inputs)

function CHECKINPUTS(*Paths* $\mathcal{P}^A_{\vec{g}}$)

$count^{available}_{input} \leftarrow count^{required}_{input} \leftarrow 0$

$\mathcal{X}_{\vec{g}} \leftarrow$ EXTRACTINPUTS$(\mathcal{P}^A_{\vec{g}})$

for each $\chi^i_{\vec{g}} \in \mathcal{X}_{\vec{g}}$ **do**
  if (ISSUCCEEDED$(\chi^i_{\vec{g}})$) **then**
    $count^{available}_{input} \leftarrow count^{available}_{input} + 1$
  $count^{required}_{input} \leftarrow count^{required}_{input} + 1$

return $\langle count^{available}_{input}, count^{required}_{input} \rangle$
end function

Algorithm 14 (Get Agency Value)

function GETAGENCYVALUE(*Paths* $\mathcal{P}^A_{\vec{g}}$)

  $count^{self}_{responsibility} \leftarrow count^{other}_{responsibility} \leftarrow 0$

  $\Theta_{\vec{g}} \leftarrow$ EXTRACTPRECONDITIONS($\mathcal{P}^A_{\vec{g}}$)

  for each $\theta^i_{\vec{g}} \in \Theta_{\vec{g}}$ **do**
    if (GETRESPONSIBLE($\theta^i_{\vec{g}}$) = SELF) **then**
      $count^{self}_{responsibility} \leftarrow count^{self}_{responsibility} + 1$
    else
      $count^{other}_{responsibility} \leftarrow count^{other}_{responsibility} + 1$

  return $\langle count^{self}_{responsibility}, count^{other}_{responsibility} \rangle$

end function

Algorithm 15 (Get Autonomy Value)

function GETAUTONOMYVALUE(*Paths* $\mathcal{P}^A_{\vec{g}}$)

  $\mathcal{A} \leftarrow$ EXTRACTACTION($\mathcal{P}^A_{\vec{g}}$)
  $\mathcal{R}_{\mathcal{A}} \leftarrow$ GETRESPONSIBLE($\mathcal{A}$)
  $\mathcal{M}_{\mathcal{R}_{\mathcal{A}}} \leftarrow$ GETMOTIVE($\mathcal{R}_{\mathcal{A}}$)

  if ($\mathcal{M}_{\mathcal{R}_{\mathcal{A}}} \neq \emptyset$) **then**
    return MAX
  else
    return MIN

end function