# Algorithms to Compute Appraisal Variables

# Algorithm 1 (Relevance)

```
1: function ISEVENTRELEVANT(Events \varepsilon_t)
           Initialize graph \mathcal{G}_t with current mental state \mathcal{S}_t.
 2:
           \vec{g} \leftarrow \text{EXTRACTGOAL}(\mathcal{G}_t)
 3:
           \mathcal{P}_t \leftarrow \text{EXTRACTPATHS}(\varepsilon_t, \vec{g})
 4:
           if (\mathcal{P}_t = \emptyset) then
 5:
                 \mathbf{return}\ 0
 6:
 7:
                 \mathcal{U}_t \leftarrow \text{getEventUtility}(\varepsilon_t, \vec{g})
                 if (\mathcal{U}_t \geq \tau_e) then
 9:
                       \mathbf{return}(\mathcal{U}_t)
10:
                 else
11:
                       return 0
13: end function
```

```
Algorithm 2 (Desirability)
```

```
1: function IsEventDesirable(MentalState S_t, Event \varepsilon_t)
              Initialize graph \mathcal{G}_{t-1} with previous mental state \mathcal{S}_{t-1}.
 2:
              Initialize graph \mathcal{G}_t with current mental state \mathcal{S}_t.
 3:
              \vec{g}_{t-1} \leftarrow \text{EXTRACTGOALS}(\mathcal{G}_{t-1})
 4:
              \mathcal{P}_{\vec{g}_{t-1}} \leftarrow \text{EXTRACTPATHS}(\mathcal{G}_{t-1}, \vec{g}_{t-1})
 5:
              \vec{g}_t \leftarrow \text{EXTRACTGOALS}(\mathcal{G}_t)
 6:
              \mathcal{P}_{\vec{g}_t} \leftarrow \text{EXTRACTPATHS}(\mathcal{G}_t, \vec{g}_t)
 7:
 8:
              if (\varepsilon_t.type = \text{EXTERNAL}) then
                     \chi \leftarrow \text{GetUtteranceUtility}(\mathcal{P}_{\vec{g}_t}, \mathcal{P}_{\vec{g}_{t-1}})
 9:
                     \begin{array}{l} \boldsymbol{\Lambda} \leftarrow \operatorname{GETACTIONUTILITY}(\mathcal{P}_{\vec{g}_t}, \mathcal{P}_{\vec{g}_{t-1}}) \\ \boldsymbol{\mathcal{E}} \leftarrow \operatorname{GETEMOTIONUTILITY}(\mathcal{P}_{\vec{g}_t}, \mathcal{P}_{\vec{g}_{t-1}}) \end{array}
10:
11:
                     \vec{\omega} \leftarrow \text{GetUtilityWeights}()
12:
                     \Delta U \leftarrow \frac{\omega_0 \cdot \chi + \omega_1 \cdot \Lambda + \omega_2 \cdot \mathcal{E}}{(\omega_0 + \omega_1 + \omega_2)}
13:
              else if (\varepsilon_t.type = INTERNAL) then
14:
                     \Delta U \leftarrow \text{GetMentalStateUtility}(\mathcal{P}_{\vec{g}_t})
15:
16:
              if (\Delta U \ge \tau) then
                     return TRUE
17:
              else
18:
                     return FALSE
19:
20: end function
```

# Algorithm 3 (Get Utterance Utility)

- 1: function GetUtteranceUtility( $Paths \ \mathcal{P}_{\vec{g}_t}, \ Paths \ \mathcal{P}_{\vec{g}_{t-1}}$ )

- $\mathcal{U}_{\vec{g}_{t}} \leftarrow \sum_{\mathcal{P}_{\vec{g}_{t}}^{U_{i}} \in \mathcal{P}_{\vec{g}_{t}}^{U}} \text{GETMENTALSTATEUTILITY}(\mathcal{P}_{\vec{g}_{t}}^{U_{i}})$   $\hat{\mathcal{U}}_{\vec{g}_{t}} \leftarrow \frac{\mathcal{U}_{\vec{g}_{t}}}{\left|\mathcal{P}_{\vec{g}_{t}}^{U}\right|}$   $\mathcal{U}_{\vec{g}_{t-1}} \leftarrow \sum_{\mathcal{P}_{\vec{g}_{t-1}}^{U_{i}} \in \mathcal{P}_{\vec{g}_{t-1}}^{U}} \text{GETMENTALSTATEUTILITY}(\mathcal{P}_{\vec{g}_{t-1}}^{U_{i}})$   $\hat{\mathcal{U}}_{\vec{g}_{t-1}} \leftarrow \frac{\mathcal{U}_{\vec{g}_{t-1}}}{\left|\mathcal{P}_{\vec{g}_{t-1}}^{U}\right|}$
- return  $(\hat{\mathcal{U}}_{\vec{q}_t}$   $\hat{\mathcal{U}}_{\vec{q}_{t-1}})$
- 7: end function

# Algorithm 4 (Get Action Utility)

- 1: function GetActionUtility( $Paths \ \mathcal{P}_{\vec{g}_t}, \ Paths \ \mathcal{P}_{\vec{g}_{t-1}}$ )
- $\theta \leftarrow \text{GetPreconditionUtility}(\mathcal{P}_{\vec{g}_t}, \mathcal{P}_{\vec{g}_{t-1}})$
- $\psi \leftarrow \text{GetPostConditionUtility}(\mathcal{P}_{\vec{g}_t}, \mathcal{P}_{\vec{g}_{t-1}})$ 3:
- $\vec{\omega} \leftarrow \text{GetUtilityWeights}()$ 4:
- $\Delta U \leftarrow \frac{\omega_0 \cdot \theta + \omega_1 \cdot \psi}{\omega_0 + \omega_1}$ 5:
- return  $\Delta U$
- 7: end function

# Algorithm 5 (Get Emotion Utility)

- 1: function GetemotionUtility( $Paths \ \mathcal{P}_{\vec{g}_t}, \ Paths \ \mathcal{P}_{\vec{g}_{t-1}}$ )
- $\begin{aligned} & \mathcal{P}^{\mathcal{E}}_{\vec{g}_{t-1}} \leftarrow \text{ExtractEmotionPaths}(\mathcal{P}_{\vec{g}_{t-1}}) \\ & \mathcal{P}^{\mathcal{E}}_{\vec{g}_t} \leftarrow \text{ExtractEmotionPaths}(\mathcal{P}_{\vec{g}_t}) \end{aligned}$
- 3:
- 4:
- $\begin{array}{l} \mathcal{E}_{t-1}^{other} \leftarrow \text{ExtractOthersEmotion}(\mathcal{P}_{\overline{g}_{t-1}}^{\mathcal{E}}) \\ \mathcal{E}_{t}^{other} \leftarrow \text{ExtractOthersEmotion}(\mathcal{P}_{\overline{g}_{t}}^{\mathcal{E}}) \end{array}$
- $$\begin{split} & \Upsilon_{t-1} \leftarrow \text{GetSomaticMarkers}(\mathcal{E}_{t-1}^{other}) \\ & \Upsilon_t \leftarrow \text{GetSomaticMarkers}(\mathcal{E}_t^{other}) \end{split}$$
  6:
- 7:

$$8: \qquad \Delta U \leftarrow \frac{\left(\left(\left(\left((\Upsilon_t^A - \Upsilon_{t-1}^A) \times 15\right) + (\Upsilon_t^V - \Upsilon_{t-1}^V)\right) \times 15\right) + (\Upsilon_t^S - \Upsilon_{t-1}^S)\right) \times 15 + (\Upsilon_t^I - \Upsilon_{t-1}^I)}{15^4}$$

- 9: return  $\Delta U$
- 10: end function

# Algorithm 6 (Get Precondition Utility)

```
1: function GetPreconditionUtility(Paths \ \mathcal{P}_{\vec{g}_t}, \ Paths \ \mathcal{P}_{\vec{g}_{t-1}})
                                                      ratio_{\vec{g}_t/\vec{g}_{t-1}}^{sat} \leftarrow ratio_{\vec{g}_t}^{sat/total} \leftarrow 0
         2:
                                                     \mathcal{P}_{\vec{g}_t}^A \leftarrow \text{ExtractActionPaths}(\mathcal{P}_{\vec{g}_t})
                                                      \begin{array}{l} \textbf{if} \ (\vec{g}_t = \vec{g}_{t-1}) \ \textbf{then} \\ \textbf{if} \ (\mathcal{P}_{t-1}^A \neq \emptyset) \ \textit{OR} \ (\mathcal{P}_t^A \neq \emptyset) \ \textbf{then} \end{array}
                                                                                                             \mathcal{P}^{A}_{\vec{g}_{t-1}} \leftarrow \text{ExtractActionPaths}(\mathcal{P}_{\vec{g}_{t-1}})
        6:
                                                                                                         \begin{split} & Precond_{\mathcal{P}_{\vec{J}_{t}}^{A}}^{sat} \leftarrow \text{CheckPreconditions}(\mathcal{P}_{\vec{g}_{t}}^{A}) \\ & Precond_{\mathcal{P}_{\vec{J}_{t-1}}^{A}}^{sat} \leftarrow \text{CheckPreconditions}(\mathcal{P}_{\vec{g}_{t-1}}^{A}) \\ & ratio_{\vec{g}_{t}/\vec{g}_{t-1}}^{sat} \leftarrow \omega_{0} \cdot \frac{Precond_{\mathcal{P}_{\vec{J}_{t-1}}^{A}}^{sat}}{Precond_{\mathcal{P}_{\vec{J}_{t-1}}^{A}}^{sat}} + \omega_{1} \cdot \frac{Precond_{\mathcal{P}_{\vec{J}_{t}}^{A}}^{sat}}{Precond_{\mathcal{P}_{\vec{J}_{t-1}}^{A}}^{total}} + \omega_{1} \cdot \frac{Precond_{\mathcal{P}_{\vec{J}_{t}}^{A}}^{sat}}{Precond_{\mathcal{P}_{\vec{J}_{t}}^{A}}^{total}} + \omega_{1} \cdot \frac{Precond_{\mathcal{P}_{t}}^{sat}}{Precond_{\mathcal{P}_{\vec{J}_{t}}^{A}}^{total}} + \omega_{1} \cdot \frac{Precond_{\mathcal{P}_{\vec{J}_{t}}^{A}}^{sat}}{Precond_{\mathcal{P}_{\vec{J}_{t}}^{A}}^{sat}} + \omega_{1} \cdot
        7:
        9:
                                                                                                             return ratio_{\vec{q}_t/\vec{q}_{t-1}}^{sat}
 10:
                                                                                   else
11:
                                                                                                                return 0
 12:
                                                         else
 13:
                                                                                   if (\mathcal{P}_t^A \neq \emptyset) then
 14:
                                                                                                                Precond_{\mathcal{P}_{\vec{q}_t}^A} \leftarrow \text{CHECKPRECONDITIONS}(\mathcal{P}_{\vec{q}_t}^A)
 15:
                                                                                                            ratio_{ec{g}_{t}}^{sat/total} \leftarrow rac{Precond_{ec{\mathcal{P}}_{A}}^{sat}}{Precond_{ec{\mathcal{P}}_{A}}^{total}}_{ec{\mathcal{P}}_{A}}^{total}
 16:
                                                                                                            return ratio_{\vec{g}_t}^{sat/total}
 17:
 18:
                                                                                                                return 0
 19:
 20: end function
```

# Algorithm 7 (Check Preconditions)

```
1: function CHECKPRECONDITIONS(Paths \ \mathcal{P}_{\overline{g}}^{A})
2: count_{precond}^{sat} \leftarrow count_{precond}^{total} \leftarrow 0
3: \Theta_{\overline{g}} \leftarrow \text{EXTRACTPRECONDITIONS}(\mathcal{P}_{\overline{g}}^{A})
4: for each \theta_{\overline{g}}^{i} \in \Theta_{\overline{g}} do
5: if (IsSatisfied(\theta_{\overline{g}}^{i})) then
6: count_{precond}^{sat} \leftarrow count_{precond}^{sat} + 1
7: count_{precond}^{total} \leftarrow count_{precond}^{total} + 1
8: return \langle count_{precond}^{sat}, count_{precond}^{total} \rangle
9: end function
```

# Algorithm 8 (Get Postcondition Utility)

```
1: function GetPostconditionUtility(Paths \mathcal{P}_{\vec{q}_t}, Paths \mathcal{P}_{\vec{q}_{t-1}})
             \mathcal{P}_{\vec{g}_t}^A \leftarrow \text{ExtractActionPaths}(\mathcal{P}_{\vec{g}_t})
 2:
             \begin{array}{l} \textbf{if} \ (\vec{g}_t = \vec{g}_{t-1}) \ \textbf{then} \\ \textbf{if} \ (\mathcal{P}_{t-1}^A \neq \emptyset) \ \textit{OR} \ (\mathcal{P}_t^A \neq \emptyset) \ \textbf{then} \end{array}
 3:
  4:
                          \mathcal{P}_{\vec{q}_{t-1}}^A \leftarrow \text{ExtractActionPaths}(\mathcal{P}_{\vec{q}_{t-1}})
 5:
                           \Psi_{\vec{g}_t} \leftarrow \text{ExtractPostconditions}(\mathcal{P}_{\vec{q}_t}^A)
 6:
                           \Psi_{\vec{g}_{t-1}} \leftarrow \text{ExtractPostConditions}(\mathcal{P}_{\vec{g}_{t-1}}^{A})
 7:
                           if (IsSatisfied(\Psi_{\vec{g}_t})) then
 8:
                                 if (IsSatisfied(\Psi_{\vec{g}_{t-1}})) then
 9:
                                        return \gamma^t
                                                                                                     \triangleright Discount rate: 0 \le \gamma \le 1
10:
                                 else
11:
12:
                                        return 1
13:
                          else
                                 if IsSatisfied(\Psi_{\vec{g}_{t-1}})) then
                                        return -1
15:
                                 else
16:
                                        return 0
17:
18: end function
```

#### Algorithm 9 (Expectedness)

```
1: function ISEVENTEXPECTED(MentalStates S_t, Event \varepsilon_t)
          Initialize graph \mathcal{G}_{t-1} with previous mental state \mathcal{S}_{t-1}.
 2:
 3:
           Initialize graph \mathcal{G}_t with current mental state \mathcal{S}_t.
           \vec{g}_{t-1} \leftarrow \text{EXTRACTGOALS}(\mathcal{G}_{t-1})
 4:
           \vec{g}_t \leftarrow \text{EXTRACTGOALS}(\mathcal{G}_t)
 5:
 6:
           \mathcal{P}_{t-1} \leftarrow \text{EXTRACTPATHS}(\mathcal{G}_{t-1}, \vec{g}_{t-1})
          \mathcal{P}_t \leftarrow \text{extractPaths}(\mathcal{G}_t, \vec{g}_t)
 7:
          if (\vec{g}_t \neq \vec{g}_{t-1}) then
 8:
               if (IsAchieved(g_{t-1}^c)) then
 9:
                     if (\neg \text{IsAchieved}(g_{t-1}^p)) then
10:
                          \mathcal{P'}_{t-1} \leftarrow \text{EXTRACTPATHS}(\mathcal{G}_{t-1}, \vec{g}_t)
11:
                          if (\mathcal{P'}_{t-1} = \emptyset) then
12:
                               return FALSE
13:
14:
                               \mathcal{U'}_{t-1} \leftarrow \text{GETUTILITIES}(\mathcal{G}_{t-1}, \vec{g}_t)
15:
                               \mathcal{U}_{t-1} \leftarrow \text{GETUTILITIES}(\mathcal{G}_{t-1}, \vec{g}_{t-1})
16:
                               if (\mathcal{U'}_{t-1} - \mathcal{U}_{t-1}) \ge \tau_e then
17:
                                     return TRUE
18:
19:
                               else
                                     return FALSE
20:
                     else
                                            ▷ Collaborative and personal goals have achieved.
21:
22:
                          return TRUE
                                                             ▷ Collaborative goal has not achieved.
23:
                else
                     return FALSE
24:
           else
25:
                                                                                ▷ Goals have not changed.
               return TRUE
26:
27: end function
```

```
{\bf Algorithm} \ {\bf 10} \ ({\rm Likelihood})
```

```
1: function GetEventsLikelihood(MentalStates S_t, Event \varepsilon_t)
                          \begin{aligned} &\mathcal{G}_t \leftarrow \text{UPDATEGRAPH}(\mathcal{S}_t, \varepsilon_t) \\ &\vec{g}_t \leftarrow \text{EXTRACTGOALS}(\mathcal{G}_t) \\ &\mathcal{P}_t \leftarrow \text{EXTRACTPATHS}(\mathcal{G}_t, \vec{g}_t) \end{aligned}
   2:
   3:
   4:
                          if (\mathcal{P}_t = \emptyset) then
   5:
                                        return 0
   6:
                          else
   7:
                                       \begin{split} \text{for each } \mathcal{P}_t^i &\in \mathcal{P}_t \text{ do} \\ \text{for each } \varepsilon_{t+1}^j &\in \varepsilon_{t+1} \text{ do} \\ \vec{P}\left(\varepsilon_{t+1}^j \middle| \mathcal{F}(\mathcal{P}_t^i) \right) &= \frac{\vec{P}\left(\mathcal{F}(\mathcal{P}_t^i) \middle| \varepsilon_{t+1}^j \right) \vec{P}(\varepsilon_{t+1}^j)}{\sum_{e_{t+1}^k \in \varepsilon_{t+1}^j} \vec{P}\left(\mathcal{F}(\mathcal{P}_t^i) \middle| e_{t+1}^k \right)} \end{split} 
   8:
   9:
10:
11:
                                       return \vec{P}\left(\varepsilon_{t+1}\middle|\mathcal{F}(\mathcal{P}_t^i)\right)
12: end function
```

#### Algorithm 11 (Controllability)

```
1: function IsEventControllable(MentalStates S_t, Event \varepsilon_t)
                     \alpha_{self/other}^{^{agency}} \leftarrow \beta_{self/other}^{^{autonomy}} \leftarrow 0
   2:
                     \kappa_{satisfied/total}^{\textit{preconditions}} \leftarrow \lambda_{succeeded/failed}^{\textit{predecessors}} \leftarrow \mu_{available/required}^{\textit{inputs}} \leftarrow 0
   3:
                     Initialize graph \mathcal{G}_t with current mental state \mathcal{S}_t.
   4:
                      \vec{g}_t \leftarrow \text{EXTRACTGOALS}(\mathcal{G}_t)
   5:
                     \mathcal{P}_{\vec{g}_t} \leftarrow \text{EXTRACTPATHS}(\mathcal{G}_t, \vec{g}_t)
                     \mathcal{P}^{A}_{\vec{g}_t} \leftarrow \text{ExtractActionPaths}(\mathcal{P}_{\vec{g}_t}) 
 \varphi^{A}_{\vec{g}_t} \leftarrow \text{GetRecipeApplicability}(\mathcal{P}^{A}_{\vec{g}_t}) 
   7:
   8:
                    \mathcal{P}_{\vec{q}_t}^{\mathcal{E}} \leftarrow \text{ExtractEmotionPaths}(\mathcal{P}_{\vec{q}_t})
   9:
                    \mathcal{E}_t^{other} \leftarrow \text{ExtractOthersEmotion}(\mathcal{P}_{\vec{q}_t}^{\mathcal{E}})
10:
                     \mathcal{I}_{other}^{^{emotion}} \leftarrow \text{GetEmotionIntensity}(\mathcal{E}_{t}^{other})
11:
                      \begin{split} & \Upsilon_t \leftarrow \text{GetSomaticMarkers}(\mathcal{E}_t^{other}) \\ & \mathcal{V}_t^{\mathcal{E}} \leftarrow \text{GetEmotionValue}(\Upsilon_t, \varepsilon_t) \end{split} 
12:
13:
                     \begin{aligned} & Agency_{\vec{g}_t} \leftarrow \text{GetAgencyValue}(\mathcal{P}_{g_t}) \\ & \alpha_{self/other}^{agency} \leftarrow \frac{Agency_{\vec{g}_t}^{self}}{Agency_{\vec{g}_t}^{other}} \middle/_{Agency_{\vec{g}_t}^{other}} \end{aligned}
14:
15:
                     \beta_{self/other}^{autonomy} \leftarrow \frac{\text{GetAutonomyValue}(\mathcal{P}_{g_t^{self}})}{\text{GetAutonomyValue}(\mathcal{P}_{g_t^{other}})}
16:
                     Precond_{\mathcal{P}_{\vec{q}_t}^A} \leftarrow \text{CHECKPRECONDITIONS}(\mathcal{P}_{\vec{q}_t}^A)
17:
                     \kappa_{satisfied/total}^{preconditions} \leftarrow \frac{Precond_{\mathcal{P}_{\overline{g}_{t}}^{A}}^{satisfied}}{P_{\overline{g}_{t}}^{A}} / Precond_{\mathcal{P}_{A}^{A}}^{total}
18:
                     \begin{aligned} & Predecessors_{\mathcal{P}_{\vec{g}_t}^A} \leftarrow \text{CheckPredecessors}(\mathcal{P}_{\vec{g}_t}^A) \\ & \lambda_{succeeded/total}^{predecessors} \leftarrow & \frac{Predecessors_{\mathcal{P}_A^A}^{succeeded}}{|\vec{g}_t|} /_{Predecessors_{\mathcal{P}_{\vec{q}_t}^A}^{A}} \end{aligned}
19:
20:
                     \begin{split} &Inputs_{\mathcal{P}^{A}_{\vec{g}t}} \leftarrow \text{CHECKINPUTS}(\mathcal{P}^{A}_{\vec{g}_{t}}) \\ &\mu_{available/required}^{inputs} \leftarrow \frac{Inputs_{\mathcal{P}^{A}_{\vec{g}_{t}}}^{available}}{/Inputs_{\mathcal{P}^{A}_{\vec{g}_{t}}}^{required}} \end{split}
21:
22:
```

```
\mathcal{U}_t \leftarrow \frac{\omega_0 \cdot \alpha_{self/other}^{agency} + \omega_1 \cdot \beta_{self/other}^{autonomy}}{\alpha_{self/other}}
23:
                                                                     \overline{\omega_0 \cdot + \omega_1 \cdot}
                                     +\frac{\omega_2 \cdot \kappa_{satisfied/total}^{predecessors} + \omega_3 \cdot \lambda_{succeeded/total}^{predecessors} + \omega_4 \cdot \mu_{available/required}}{\omega_2 + \omega_3 + \omega_4}
24:
                                    + \frac{\omega_{5} \cdot \mathcal{I}_{other}^{emotion} + \omega_{6} \cdot \varphi_{\vec{g}_{t}}^{A} + \omega_{7} \cdot \mathcal{V}_{t}^{\mathcal{E}}}{2}
25:
                      if (\mathcal{U}_t \geq \tau_e) then
26:
                                 \mathbf{return}\ \mathrm{TRUE}
27:
28:
                                 return FALSE
29:
30: end function
```

# Algorithm 12 (Check Predecessors)

```
1: function CHECKPREDECESSORS(Paths \mathcal{P}_{\vec{a}}^A)
```

2: 
$$count_{predecessor}^{succeeded} \leftarrow count_{predecessor}^{total} \leftarrow 0$$

3: 
$$\Phi_{\vec{g}} \leftarrow \text{EXTRACTPREDECESSORS}(\mathcal{P}_{\vec{g}}^A)$$

4: for each 
$$\phi^i_{\vec{q}} \in \Phi_{\vec{q}}$$
 do

5: **if** (IsSucceeded(
$$\phi_{\vec{q}}^i$$
)) **then**

5: **if** 
$$(ISSUCCEEDED(\phi_{\vec{q}}^{i}))$$
 **then**
6:  $count_{predecessor}^{succeeded} \leftarrow count_{predecessor}^{succeeded} + 1$ 
7:  $count_{predecessor}^{total} \leftarrow count_{predecessor}^{total} + 1$ 

7: 
$$count_{predecessor}^{total} \leftarrow count_{predecessor}^{total} + 1$$

8: 
$$\mathbf{return} \ \langle count_{predecessor}^{succeeded}, count_{predecessor}^{total} \rangle$$

## 9: end function

# Algorithm 13 (Check Inputs)

```
1: function CHECKINPUTS(Paths \mathcal{P}_{\vec{q}}^A)
```

$$2: \qquad count_{input}^{available} \leftarrow count_{input}^{required} \leftarrow 0$$

3: 
$$\mathcal{X}_{\vec{g}} \leftarrow \text{EXTRACTINPUTS}(\mathcal{P}_{\vec{g}}^A)$$

4: for each 
$$\chi^i_{\vec{q}} \in \mathcal{X}_{\vec{q}}$$
 do

5: **if** 
$$(IsSucceeded(\chi^i_{\vec{g}}))$$
 **then**

6: 
$$count_{input}^{available} \leftarrow count_{input}^{available} + 1$$
7: 
$$count_{input}^{required} \leftarrow count_{input}^{required} + 1$$

7: 
$$count_{input}^{required} \leftarrow count_{input}^{required} + 1$$

8: **return** 
$$\langle count_{input}^{available}, count_{input}^{required} \rangle$$

#### 9: end function

# Algorithm 14 (Get Agency Value)

```
1: function GetAgencyValue(Paths \ \mathcal{P}_{\vec{q}}^A)
            count_{responsibility}^{{}_{self}} \leftarrow count_{responsibility}^{{}_{other}} \leftarrow 0
 2:
            \Theta_{\vec{g}} \leftarrow \text{ExtractPreconditions}(\mathcal{P}_{\vec{g}}^A)
 3:
            for each \theta^i_{\vec{q}} \in \Theta_{\vec{q}} do
 4:
                  if (GetResponsible(\theta^i_{\vec{q}}) = SELF) then
 5:
                        count_{responsibility}^{self} \leftarrow count_{responsibility}^{self} + 1
 6:
                  \mathbf{else}
 7:
                        e \\ count_{responsibility}^{^{other}} \leftarrow count_{responsibility}^{^{other}} + 1
 8:
            \textbf{return} \ \langle count_{responsibility}^{self}, count_{responsibility}^{other} \rangle
10: end function
```

# Algorithm 15 (Get Autonomy Value)

```
1: function GETAUTONOMYVALUE(Paths \ \mathcal{P}_{\vec{g}}^{A})

2: \mathcal{A} \leftarrow \text{EXTRACTACTION}(\mathcal{P}_{\vec{g}}^{A})

3: \mathcal{R}_{\mathcal{A}} \leftarrow \text{GETRESPONSIBLE}(\mathcal{A})

4: \mathcal{M}_{\mathcal{R}_{\mathcal{A}}} \leftarrow \text{GETMOTIVE}(\mathcal{R}_{\mathcal{A}})

5: if (\mathcal{M}_{\mathcal{R}_{\mathcal{A}}} \neq \emptyset) then

6: return MAX

7: else

8: return MIN

9: end function
```