



# Computational Theories of Collaboration

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PhD Comprehensive Exam
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#### **Collaboration Theories > Introduction**

**Collaboration** is a special type of coordinated activity in which the participants work jointly, together performing a task or carrying out the activities needed to satisfy a shared goal.

- Participants possess:
  - different beliefs and capabilities,
  - partial knowledge of the collaborative activities.
- Collaborators need to:
  - maintain mutual beliefs about their shared goal throughout the collaboration,
  - be able to communicate with others effectively,
  - commit to the group activities and to their role in it,
  - commit to the success of others,
  - reconcile between commitments to the existing collaboration and their other activities.
- Collaborative plans are more than the sum of individual plans.

#### **Collaboration Theories > SharedPlans Theory:** *Overview*

#### Shared Plans & Recipes:

- Shows how a group of agents can incrementally form and execute a shared plan,
- Allows the process of expanding partial plans into full plans,
- Describes how a shared plan coordinates agents' activities towards achieving a shared goal,
- Agents have a library of how to do their actions (recipes),

#### Beliefs & Intentions:

 Emphasizes that collaborative plans are an interleaving of mutual beliefs and intentions about the actions in the plan,

#### Communication:

- Agents communicate their beliefs and intentions about the actions they can contribute to the shared plan,
- Communication makes the agents mutually believe that:
  - there is an agent responsible to execute an action in the plan,
  - that agent has intention to do so,
  - the actions in the plan contribute to the goal.

## Collaboration Theories > SharedPlans Theory: Full & Partial Shared Plans

- Full Shared Plan (FSP): A complete plan in which agents have fully determined how to perform an action.
- The required conditions for FSP:
  - All collaborators mutually believe that they have intention to do an action.
  - All collaborators mutually believe that they have a recipe for that action.
  - For each individual action in the recipe:
    - A subgroup has an FSP for that step using the corresponding part of the recipe.
    - Other members of the group believe that there is a recipe for this particular step that the above subgroup can use and have an FSP for the corresponding set of actions.
    - Other members of the group have intention that the above subgroup can do the mentioned set of action using the associated recipe.
- Partial Shared Plan (PSP): used as a snapshot of the collaborators' mental states to modify and evolve the partial plan, which leads to communication and planning to fulfill the above (FSP's) conditions.

## **Collaboration Theories > Joint Intention Theory:** *Overview*

- Based on the idea of individual and joint intentions to act as a team member.
- Joint Intentions theory describes how a team of agents can jointly act together by sharing mental states about their actions while an intention is viewed as a commitment to perform an action.
- A joint intention is a shared commitment to perform an action while in a group mental state.
- Once an agent entered into a joint commitment with other agents, the agent should communicate its private beliefs with other team members.
- Team members are committed to inform other team members when they
  reach the conclusion that a goal is achievable, impossible, or irrelevant.

# **Collaboration Theories > Joint Intention Theory:** *Joint Commitment & Joint Intention*

- Weak Achievement Goal (WAG): shows the state of a team member nominally working on a goal. An agent has a WAG about p if either of the following conditions holds:
  - The agent does not yet believe that p is true and wants p to be true as a goal.
  - The agent believes that p is true, will never be true, or is irrelevant, but has as a goal that the status of p be mutually believed by all the team members.
- **Joint commitment** or Joint Persistent Goal (JPG) requires all team members to mutually believe that p is currently false and want p to eventually be true.
- A JPG guarantees that team members cannot decommit until p is mutually known to be achieved, unachievable or irrelevant.
- JPG requires team members to each hold  $\boldsymbol{p}$  as a WAG.
- A team of agents jointly intends to do an action if and only if the members have a JPG of them having the action completed, and having it completed knowingly.

#### **Collaboration Theories > STEAM – A Hybrid Approach**

- Uses joint intentions as the basic building block of teamwork (formalizes commitment):
  - Reasoning about coordination and communication in a team.
  - Guidance for monitoring and maintenance of a team activity.
  - Reasoning about team activity and member's contribution.
  - To reinforce the teamwork coherency to build team members' mental states.
- It is informed by key concepts from SharedPlans theory (formulates team's attitude):
  - Mutual belief in a shared recipe and shared plans (adds coherency within the teamwork).
  - The limited required information about recipe to perform an action (only tracking who is responsible).
  - Uses the concept of intention-that for communication.

#### Novel aspects:

- Has team (expressing joint activities) vs. individual (individual's activities) operators.
- Team synchronization protocol.
- Constructs to monitoring team performance.
- Communication's (based on joint intention) overhead and risks.

#### **Collaboration Theories > Similarities:** *SharedPlans & Joint Intentions*

- Both specify executing actions as a team.
- 2. Both based on BDI model and Bratman's view of intention.
- 3. In both joint actions are not collection of individual actions (agents need to share beliefs).
- 4. Both emphasize on communication.
- 5. Both are concerned about commitment.

#### **Collaboration Theories > Differences:** *SharedPlans & Joint Intentions*

- SharedPlans theory is based on mutual beliefs and notion of intentionthat, while Joint Intentions theory is based on joint intentions.
- 2. In **SharedPlans** theory teammates agree on the shared plan, whereas in **Joint Intentions** theory teammates agree on intentions.
- 3. SharedPlans theory employs hierarchical structures over intentions (in contrast to Joint Intentions theory).
- 4. SharedPlans theory describe a way to achieve a shared goal whereas Joint Intentions theory only describes the shared goal.
- 5. Joint Intentions theory assumes knowledge about the teammates is always available (in contrast to partial plan in SharedPlans theory).
- 6. In **SharedPlans** theory communication requirements are derived from intention-that concept whereas it is "hard-wired" in **Joint Intentions** theory.

# **Collaboration Theories > Applications**

- Assistant robots
- Emotional awareness (COCHI)
- Communication
- Joint actions and commitments
- Task-based planning
- Discourse generation and interpretation (COLLAGEN)
- Conversational agents
- Network management
- Proactive behaviors and information exchange (CAST)
- Instructional systems
- Group decision support systems
- Authors' assistant
- Sociable robots
- Combat air missions
- Robot soccer
- Rescue responses

#### **Collaboration Theories > Conclusion**

- **SharedPlans** is more convincing than the others.
  - Inclusive explanation of collaboration structure.
  - Association to discourse structure (improve communicative aspects).
- Joint Intentions theory is clearly defined and fulfills most of the key collaboration requirements.
- Hybrid approaches are valuable and make the theories closer to applications.
- The lack of underlying domain-independent collaboration processes which can construct and evolve the collaboration structure.





# **Affective Computing**

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# **Affective Computing > Introduction**

- Four categories of computational emotion modeling:
  - Detecting and recognizing human emotions,
  - Interpreting and understanding human emotions,
  - Generating artificial emotions,
  - Expressing human-perceivable emotions.
- Major emotion theories:
  - Appraisal
  - Dimensional
  - Discrete (basic)
- We majorly focus on Appraisal and Dimensional theories.

#### **Affective Computing > Appraisal Theory:** *Overview*

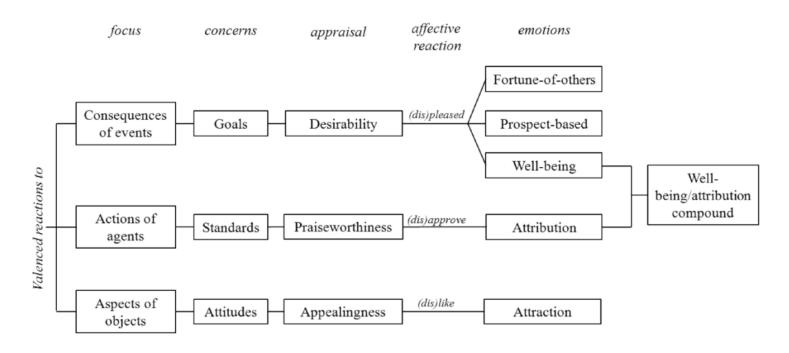
- Appraisal theory describes the cognitive process by which an individual evaluates
  the situation in the environment with respect to the individual's well-being and
  triggers emotions to control internal changes and external actions.
- Cognitive appraisal process:
  - Distinct components of emotions,
  - Components are called appraisal variables,
  - Agent Evaluates the stimuli with respect to their consequences;
    - According to Scherer's appraisal objectives (i.e., relevance, implication, coping, and normative significance),
    - Objectives include different appraisal variables,
  - Specific values will be assigned to appraisal variables,
  - Determined appraisal variables are mapped onto a particular emotion,
    - Appraisal variables are the semantic primitives for representing emotions.

#### Affective Computing > Appraisal Theory: Appraisal & Coping processes

- Appraisals are separable antecedents of emotions.
- Overall process:
  - Evaluation of the environment according to the internalized goals,
    - Systematic assessment of several elements.
  - Outcome triggers emotions and coping strategies.
- Appraisal variables, e.g., relevance, desirability, expectedness, controllability.
- Coping process:
  - Determines whether and how agent should respond to an event.
  - Coping strategies control (enable or suppress) cognitive processes operate on causal interpretation of the appraisals.
- Coping strategies can be grouped into different categories:
  - Problem-focused (e.g., planning)
  - Emotion-focused (seeking social support for instrumental reasons)

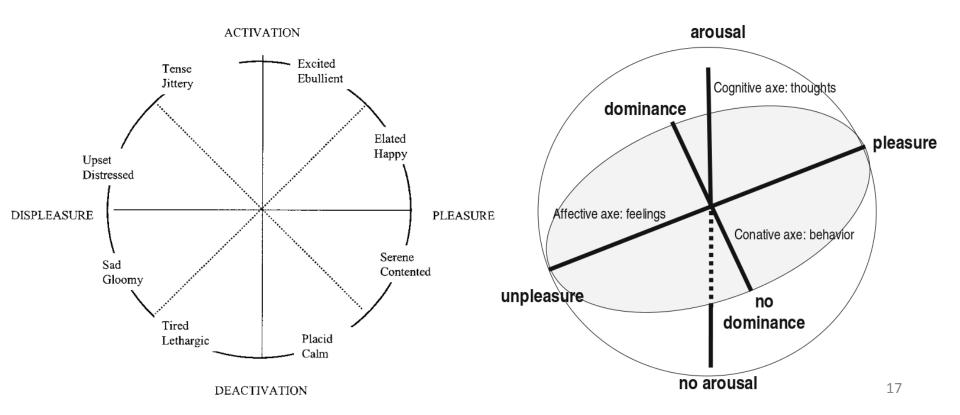
## Affective Computing > Appraisal Theory: OCC – A structural Appraisal Theory

- The model categorizes emotions based on their underlying appraisal patterns.
- Patterns are fundamental criteria and involve:
  - One's focus of attention,
  - One's concern,
  - One's appraisals.
- OCC model introduces some global variables of an emotion's intensity to distinguish all types of emotions (e.g., sense of reality, and arousal).



# **Affective Computing > Dimensional Emotion Theories**

- They conceptualize emotions by defining where they lie in two or three dimensions.
- Russell's Circumplex model (Valence and Arousal).
- Mehrabian and Russell's PAD model (Pleasure, Arousal, Dominance).



## **Affective Computing > Discrete Emotion Theories**

- These theories emphasize a small set of discrete and fundamental emotions.
- The underlying assumption is that these emotions are mediated by associated neural circuitry, with a hardwired component.
- Different emotions are characterized by stable patterns of triggers, behavioral expression, and associated distinct subjective experiences.
- The emotions are called basic emotions: happiness, sadness, fear, anger, surprise, and disgust.
- This universality has a production side and a recognition side.
- Computational models focus on low-level perceptual-motor tasks (fast and automatic vs. slower, reasoning-based).

#### Affective Computing > Similarities & Differences: Dimensional Vs. Discrete

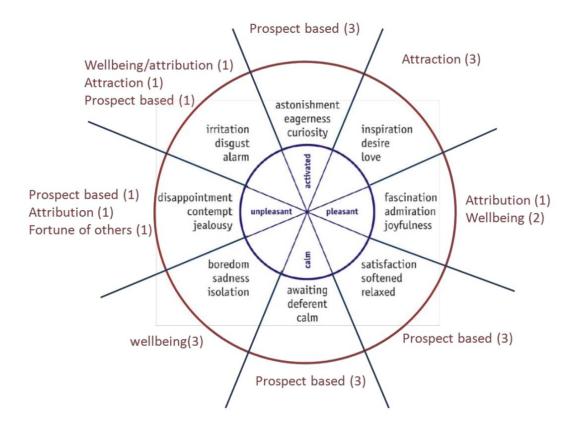
- In contrast to basic emotions, dimensional theory is compatible with the differences in the behavioral responses to the stimuli.
- **Dimensional** theories can represent instances of **basic** emotions.
- In contrast to basic emotions, dimensional theory argues that emotion may not necessarily be aimed at a particular object.
- **Dimensional** models of emotion are capable of accounting for a wider range of affective phenomena.
- In contrast to **dimensional** theory, **basic** emotion theory's categorization of emotions captures elicitation of a **facial expression** of the emotion.

## Affective Computing > Similarities & Differences: Appraisal & Dimensional

- Dimensional theories might struggle to adequately distinguish emotions because
  of the existence of limited dimensions.
- Pleasure dimension roughly maps onto appraisal dimensions that characterize the valence of an appraisal-eliciting event (e.g., desirability).
- Dominance roughly maps onto the appraisal dimension of coping potential.
- Arousal can be considered as a measure of intensity.
- Appraisals are relational constructs (between an event and one's mental states),
  whereas emotions in dimensional are non-relational and just a unique overall
  state of individual.
- **Dimensional** emotion theory does not address affects' antecedents like appraisal and they question the causal linkage between appraisal and emotion.

#### Affective Computing > Similarities & Differences: OCC & Dimensional

- Both consider emotions to descend from valenced reactions to the stimuli.
- Both acknowledge the role of arousal in determining emotional reactions (as intensity in OCC model – as coping potential by Scherer).
- Dimensional theories and OCC model can relate to each other in terms of categorization of emotions.



# **Affective Computing > Applications**

- Companion robots
- Expressive robots
- Robots with affective behaviors
- Robots with affect recognition capability
- Robots with adaptive behaviors
- Interactive robots
- Learning in robots
- Service robots
- Decision-making in robots
- Human-computer interaction

## **Affective Computing > Conclusion**

- It is good to follow well-established computational models with theoretical foundations.
- They can explain more details of the structure or the processes involved in affective situations.
- It is not necessary to exactly follow only one theory and its descriptions.
- We believe the interpersonal functions of emotions should be our first concern.
- We can see the importance of interpretive, communicative and regulatory aspects of emotion functions in our proposed work.





# Uncertainty in Modeling and Reasoning about Beliefs

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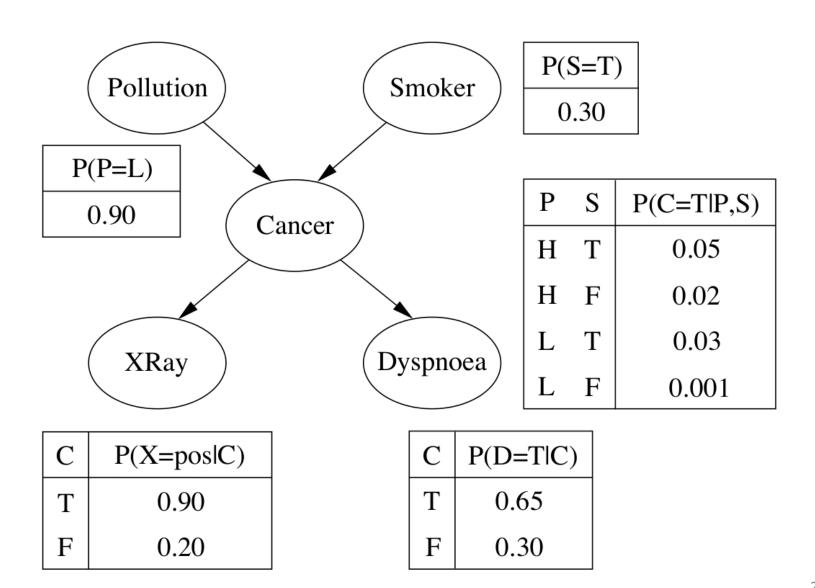
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# **Uncertainty in AI > Introduction**

- Bayesian Belief Networks (probabilistic reasoning)
- Dempster-Shafer theory (evidential reasoning)
- Fuzzy logic (reasoning under ambiguity)

# **Uncertainty in AI > Bayesian Belief Networks:** *Overview*

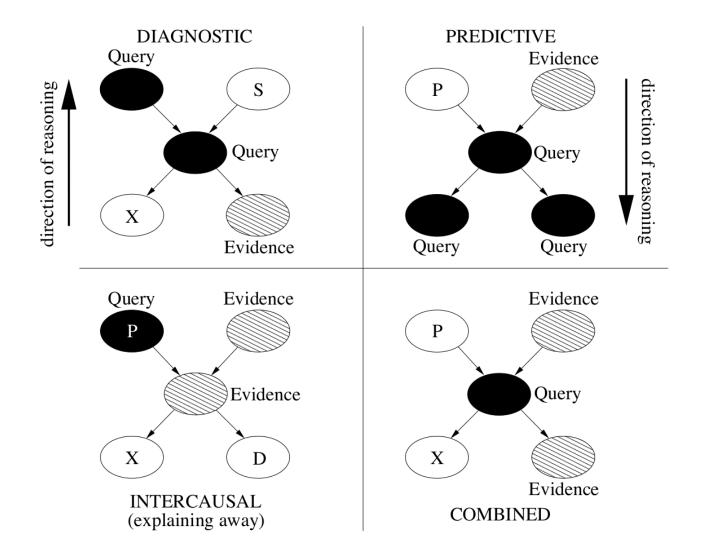


#### **Uncertainty in AI > Bayesian Belief Networks:** *Joint Probability Distribution*

Given Markov property, the product of only the appropriate elements (parent nodes) of the CPTs in the network represents the value of each individual entry in the joint probability distribution.

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | parents(X_i))$$

# **Uncertainty in AI > Bayesian Belief Networks:** *Reasoning in BBNs*



## **Uncertainty in AI > Dempster-Shafer Theory:** *Overview*

- Dempster-Shafer theory is designed to deal with the distinction between uncertainty and ignorance.
- Rather than computing the probability of a proposition, it computes the probability that the evidence supports the proposition.
- The set of hypotheses (frame of discernment) represent all of the possible states of the system considered.
- The relation between a piece of evidence and a hypothesis corresponds to a cause-effect chain.
- There are three basic functions required for modeling purposes: mass function, belief function, and plausibility function.

# **Uncertainty in AI > Dempster-Shafer Theory:** *important functions*

• Mass Function: A Basic Probability Assignment (BPA) or mass function is a function  $2^{\Theta} \rightarrow [0,1]$  such that:

$$m(\emptyset) = 0$$
, and  $\sum_{x \in 2^{\Theta}} m(x) = 1$ 

• **Belief Function:** It is the measure of total belief committed to  $A \subseteq \Theta$  that can be obtained by simply adding up the mass of all the subsets of A, denoted by Belief(A). It is a function  $Belief: 2^{\Theta} \to [0,1]$ :

$$Belief(A) = \sum_{B \subseteq A} m(B)$$
 for all  $A \subseteq \Theta$ 

• Plausibility Function: It represents the maximum possibility that a set A is true given all the evidences. It is a function  $Plausible: 2^{\Theta} \rightarrow [0,1]$ :

$$Plausible(A) = \sum_{B \cap A \neq \emptyset} m(B)$$
 for all  $A \subseteq \Theta$ 

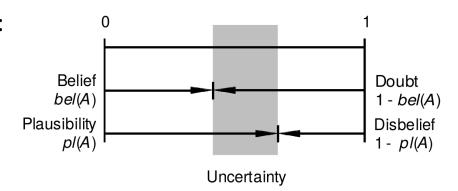
# **Uncertainty in AI > Dempster-Shafer Theory**

The plausibility and belief functions have the following relationship:

$$Belief(A) = 1 - Plausible(\neg A)$$
 and  $Plausible(A) = 1 - Belief(\neg A)$ ,

Uncertainty measure (belief interval):

Where:  $Belief(A) \leq Plausible(A)$ 



- Dempster's Rule of Combination:
  - A method to combine the measures of evidence from different sources.

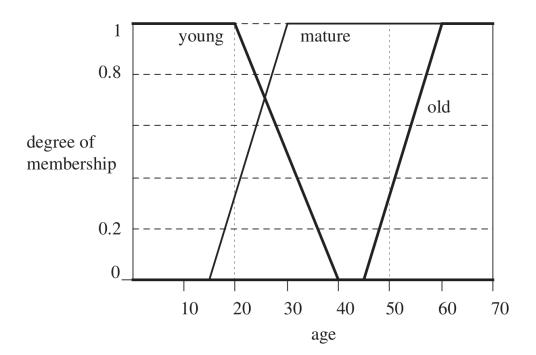
$$[m_1 \oplus m_2](y) = \begin{cases} 0, & y = \emptyset \\ \sum_{A \cap B = y} m_1(A)m_2(B) \\ 1 - \sum_{A \cap B \neq \emptyset} m_1(A)m_2(B) \end{cases}, \quad y \neq \emptyset$$

## **Uncertainty in AI > Fuzzy Logic Theory:** *Overview*

- Fuzzy Logic's ultimate goal is to provide foundations for approximate reasoning using imprecise propositions based on fuzzy set theory.
- In order to deal with such imprecise inference, Fuzzy Logic allows the imprecise linguistic terms such as:
  - fuzzy predicates (e.g., old, expensive),
  - fuzzy quantifiers (e.g., many, little),
  - and fuzzy truth values (e.g., unlikely false or unlikely true).
- Fuzzy Sets: A fuzzy set is a class of objects with a continuum of degrees of membership.
- A fuzzy set  $\bf A$  is defined by a membership function  $\mu_A$  from the universe of discourse  $\bf X$  to the closed unit interval [0,1]. We interpret  $\mu_A(x)$  as the degree of membership of  $\bf x$  in  $\bf A$ .

## **Uncertainty in AI > Fuzzy Logic Theory:** *Membership Functions*

- Membership functions are mathematical tools for indicating flexible membership to a set, modeling, and quantifying the meaning of symbols.
- Membership functions are used in the fuzzification and defuzzification steps of a Fuzzy Logic system.
- A membership function is used to quantify a linguistic term.



#### **Uncertainty in AI > Fuzzy Logic Theory:** *Algorithm*

- 1. Define the linguistic variables and terms (initialization)
- 2. Construct the membership functions (initialization)
- 3. Construct the rule base (initialization)
- 4. Convert crisp input data to fuzzy values using the membership functions (fuzzification)
- 5. Evaluate the rules in the rule base (inference)
- 6. Combine the results of each rule (inference)
- 7. Convert the output data to non-fuzzy values (defuzzification)

#### **Linguistic Variables:**

• Linguistic variables are the input or output variables of the system whose values (linguistic terms) are words or sentences from a natural language.

#### **Fuzzy Rules:**

A rule-base is constructed to determine and control the output variable.

IF (a statement of conditions is satisfied)

**THEN** (a set of consequences can be inferred)

#### **Uncertainty in AI > Fuzzy Logic Theory:** *Algorithm*

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- **Fuzzification:** The process of obtaining one fuzzy value for each crisp input.
- Reasoning: The process of combining the results of the rules to obtain a final result.
- **Defuzzification:** The process of obtaining a crisp value by defuzzifying the final fuzzy result using the membership function of the output variable.

#### **Uncertainty in AI > Advantages & Disadvantages:** *Bayesian Networks*

#### **Advantages:**

- Transparent representation of causal relationships between variables.
- Relatively easy recognition of dependencies and independencies between various nodes.
- The ability to handle situations where the data set is incomplete since the model accounts for dependencies between all variables.
- Capable of being readily updated when a new evidence becomes available.
- Both predictive/deductive and diagnostic/abductive reasonings are possible.
- Computational tractability exists for most practical applications.

#### **Uncertainty in AI > Advantages & Disadvantages:** *Bayesian Networks*

#### **Disadvantages:**

- A high level of effort is required to build network models where a significant amount of probability data is required due to an increasing number of nodes and links in the structure (possible large CPT sizes).
- Computationally intensive if the conditional independencies are not properly considered among the variables.
- Challenging to obtain experts' knowledge in the form of probability to build the network.
- No feedback loops in the Bayesian network's structure, which has an acyclic nature. This structure prevents typical feedback loops in design of Bayesian network models.

#### **Uncertainty in AI > Advantages & Disadvantages:** *Dempster-Shafer Theory*

#### **Advantages:**

- Addressing the concept of possibility.
- The ability to represent the concept of ignorance to allow one to specify a degree of ignorance in a situation, instead of being forced to supply prior probabilities.
- Consistent with classical probability theory.
- Distinguishing randomness from missing information.
- No required a priori knowledge.
- Including an evidence combination rule which provides an operator to integrate multiple pieces of information from different sources.

## **Uncertainty in AI > Advantages & Disadvantages:** *Dempster-Shafer Theory*

#### **Disadvantages:**

- Computational complexity grows exponentially with the number of hypotheses (in original formulation).
- Small modifications in the evidence assignments may lead to a completely different conclusion, which can lead to misleading and counter-intuitive results.

## **Uncertainty in AI > Advantages & Disadvantages:** Fuzzy Logic Theory

#### **Advantages:**

- Describing algorithms in terms of a combination of numerics and linguistics.
- Capturing the concept of the ambiguity of information.
- Flexible and intuitive knowledge-base design.
- Easy computation.
- Relatively robust algorithms.

#### **Uncertainty in AI > Advantages & Disadvantages:** Fuzzy Logic Theory

#### **Disadvantages:**

- Determining the exact fuzzy rules and membership functions is a hard task.
- Requires manual tuning to obtain a better result.
- Requires tuning in many options in design of a system.
- The order of inference steps matters.
- After reasoning, it can be difficult to exactly interpret the membership value.
- Validation of a fuzzy knowledge-base is typically expensive.

# **Uncertainty in AI > Applications**

- Robot's motion control
- Sensory data fusion in robots
- Modeling domain knowledge
- Modeling human-robot interaction
- Modeling emotional state of the robot
- Modeling forward model of robot's actions
- Modeling object affordances
- Robot's navigation
- Learning robot's decision function
- Learning imitative body motions of humans
- Intention recognition
- Mobile-robot localization
- Modeling cooperative agents
- Agent's argumentation and decision making framework
- Modeling theory of mind

## **Uncertainty in AI > Conclusion**

- Uncertainty is involved in collaboration, Different theories are concerned about teamwork and the involvement of others:
  - to form an intention,
  - to generate or evolve the shared plan,
  - or even to establish a single mutual belief.
- There is a certain amount of uncertainty, ambiguity and lack of evidence in perceiving others' behaviors.
- Processes involved in collaboration need to be designed to address the existence of uncertainty.
- Beliefs include certain amount of uncertainty independent of their source:
  - the lack of evidence about a counterpart's belief about an event,
  - the lack of evidence about the feeling of a counterpart for a collaborative action.
- Consequences can be mitigated by having a mechanism to deal with uncertainty in some level.
- It is for us to choose where to apply the appropriate mechanism to make more stable collaborative behaviors.

# **Thank You!**