Affective Motivational Collaboration Theory

by

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ABSTRACT

Abstract Here!

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CHAPTER 1

INTRODUCTION

1.1 Motivation

1.2 Thesis Statement and Scope

1.3 Contributions

Throughout this work we aim to show how a robot can leverage emotion-driven processes using appraisal algorithms to improve collaboration with humans. As such, in this thesis work, we introduce a novel framework, called Affective Motivational Collaboration (AMC) framework, which allows a robotic agent to collaborate with humans incooperating the underlying emotion-driven processes and the expressed emotion of human collaborator. Such a framework is built based on computational models of collaboration and appraisal allowing for task-driven interaction with robots or other agents. The theoretical foundation, computational models and algorithms as well as the overall framework, and the end-to-end evaluation of the framework make the following contributions:

1. Introducing Affective Motivational Collaboration Theory:

(Chapter 3) As mentioned earlier, since the theoretical foundation of AMC framework is built on the combination of Shared-Plans theory of collaboration [cite] and cognitive appraisal theory of emotions [cite], one of the contributions

of our work is to introduce theoretical concepts incorporating key notions of both theories in a dyadic collaboration context. Applying cognitive appraisal theory in the collaboration context is novel. Other models of the appraisal theory have not paid attention to the dynamics of the collaboration.

2. Developing new computational models and algorithms for Affective Motivational Collaboration Framework:

(Chapter 4) Another contributions of our work is to create computational models and algorithms to compute the value of appraisal variables in a dyadic collaboration. We have also developed a new algorithm for the emotion-driven goal management in the context of collaboration. Goal management is one of the important functions of emotions during collaboration. Existing models and implementations of emotions focus only on how emotions regulate and control internal processes and sometimes behaviors. This part of our work shows how appraisal components of the self and the human collaborator contributes to the goal management as an emotion function.

3. Developing a computational framework based on Affective Motivational Collaboration Theory:

(Chapter 5) In order to evaluate our computational models and algorithms within an interaction with human collaborators, we have developed a computational framework based on our theoretical foundations in Affective Motivational Collaboration Theory. Our computational framework implements the key concepts related to Affective Motivational Collaboration Theory as well as minimal implementation of other processes which are required for validation of the model but are not part of this thesis contributions. The emphasis of the model is on underlying cognitive processes embracing collaboration and appraisal concepts, rather than the Perception and the Action mechanisms.

4. Validating Affective Motivational Collaboration Theory:

(Chapters 4 and 6) We have conducted two user studies a) to validate our appraisal algorithms before further development of our framework, and b) to investigate the overall functionality of our framework within an end-to-end system evaluation with human subjects and a robot. The second user study was also conducted to evaluate the benefit of using our computational framework in human-robot collaboration. In the first user study, we crowd sourced our questionnaires to test our hypothesis that humans and our algorithms will provide similar answers to questions related to different factors within our appraisal algorithms. In the second user study, we investigated the importance of emotional awareness in human-robot collaboration, and the overall functionality of the AMC framework with the participants in our study environment.

CHAPTER 2

BACKGROUND AND RELATED WORK

	2.1	Computational	Collaboration	Theorie
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- 2.1.1 Shared-Plans Theory
- 2.1.2 Joint-Intentions Theory
- 2.1.3 Hybird Theories
- 2.1.4 Similarities and Differences
- 2.1.5 Applications of Collaboration Theories

2.2 Affective Computing

- 2.2.1 Affect and Emotions
- 2.2.2 Functions of Emotions
- 2.2.3 Motivation and Theory of Mind

2.3 Computational Models of Emotions

- 2.3.1 Appraisal Theory
- 2.3.2 Other Computational Models
- 2.3.3 Similarities and Differences
- 2.3.4 Applications in Autonomous Agents and Robots

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- 3.1.1 Scenario
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- 3.2 Design and Architecture
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- 3.2.2 Functions of Emotions
- 3.2.3 Mental States
- 3.2.4 Attributes of Mental States

CHAPTER 4 APPRAISAL PROCESSES IN COLLABORATION CONTEXT

- 4.1 Introduction
- 4.2 Appraisal and Collaboration
- 4.3 Appraisal Algorithms
- 4.3.1 Relevance
- 4.3.2 Desirability
- 4.3.3 Expectedness
- 4.3.4 Controllability
- 4.4 Methodology [This chapter will contain the crowdsourding study.]
- 4.5 Results and Evaluation

${\bf CHAPTER~5}$ ${\bf COMPUTATIONAL~FRAMEWORK}$

- 5.1 System Overview
- 5.2 Components of the Architecture
- 5.2.1 Mental States
- 5.2.2 Collaboration
- 5.2.3 Appraisal
- **5.2.4** Coping
- 5.2.5 Motivation
- 5.2.6 Theory of Mind
- 5.2.7 Perception
- **5.2.8** Action

CHAPTER 6

IMPROVING HUMAN-ROBOT

COLLABORATION LATEX ERROR: THERE'S

NO LINE HERE TO ENDSEE THE LATEX

MANUAL OR LATEX COMPANION FOR

EXPLANATION.YOUR COMMAND WAS

IGNORED.TYPE I ¡COMMAND¿ ¡RETURN¿

TO REPLACE IT WITH ANOTHER

COMMAND,OR ¡RETURN¿ TO CONTINUE

WITHOUT IT.

- 6.1 Introduction
- 6.2 Collaborative Behaviors and Emotional-Awareness
- 6.2.1 Goal Postponement
- 6.2.2 Goal Management
- 6.2.3 Task Delegation
- 6.3 Methodology
- 6.4 Results and Evaluation

CHAPTER 7 CONCLUSION

- 7.1 Discussion
- 7.2 Future Work

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