

1. (1)  $(Y_1, \dots, Y_k) \sim \text{Dir}(a_1, \dots, a_k)$ . Consider a partition  $I_1, \dots, I_M$  of  $\{1, \dots, k\}$ . Let  $U_j = \sum_{i \in I_j} Y_i$  for  $j = 1, \dots, M$ . Using the definition of the Dirichlet as independent gamma random variables,  $(Y_1, \dots, Y_k)$  can be constructed as  $(\frac{Z_1}{Z}, \dots, \frac{Z_k}{Z})$  where  $Z_i \stackrel{\text{ind}}{\sim} \Gamma(a_i, 1)$  and  $Z = \sum_{i=1}^k Z_i$ . Then

$$\begin{aligned} (U_1, \dots, U_M) &= \left( \sum_{i \in I_1} Y_i, \sum_{i \in I_2} Y_i, \dots, \sum_{i \in I_M} Y_i \right) \\ &= \frac{1}{\sum_{i=1}^k Z_i} \left( \sum_{i \in I_1} Z_i, \sum_{i \in I_2} Z_i, \dots, \sum_{i \in I_M} Z_i \right) \\ &\stackrel{d}{=} \frac{1}{\Gamma(\sum_{i=1}^k a_i, 1)} \left( \Gamma\left(\sum_{i \in I_1} a_i, 1\right), \Gamma\left(\sum_{i \in I_2} a_i, 1\right), \dots, \Gamma\left(\sum_{i \in I_M} a_i, 1\right) \right) \\ &\stackrel{d}{=} \text{Dir}\left(\sum_{i \in I_1} a_i, \sum_{i \in I_2} a_i, \dots, \sum_{i \in I_M} a_i\right) \\ &\stackrel{d}{=} \text{Dir}(b_1, \dots, b_M) \end{aligned}$$

Therefore,  $(U_1, \dots, U_M) \sim \text{Dir}(b_1, \dots, b_M)$  where  $b_j = \sum_{i \in I_j} a_i$ .

- (2) Since we just showed  $U_j \sim \text{Dir}(b_j, \dots, b_m)$ , then  $Y_i/U_j \stackrel{\text{ind}}{\sim} \text{Dir}(a_i, i \in I_j)$
- (3) I never got around to these.

2. Show that for any (measurable) disjoint subsets  $B_1$  and  $B_2$  of  $\mathcal{X}$ ,  $\text{Corr}(P(B_1), P(B_2))$  is negative. Is the negative correlation for random probabilities induced by the DP prior a restriction? Discuss.

**Solution:** Define  $B_1 \cup B_2 \cup B_3 = X$ , where  $B_3 = (B_1 \cup B_2)^c$ . Without loss of generality,  $B_1$  and  $B_2$  are any measurable subset of the sample space. In order to compute the correlation, it is sufficient to show that the covariance is negative because the variance is just a positive scalar factor.

Given that  $P$  is a Dirichlet process

$$P(B_1), P(B_2), P(B_3) \sim \text{Dir}(\alpha P_0(B_1), \alpha P_0(B_2), \alpha P_0(B_3))$$

where  $\alpha > 0$  and  $P_0(\cdot)$  is a probability measure.

The covariance is computed as

$$\text{Cov}(P(B_1), P(B_2)) = E[P(B_1)P(B_2)] - E[P(B_1)]E[P(B_2)]$$

Using the definition of the Dirichlet distribution in terms of independent gamma random variables,  $Z_i \sim \text{Gamma}(\alpha P_0(B_i), 1)$  and  $Z \sim \text{Gamma}(\sum_{i=1}^k \alpha P_0(B_i), 1)$ . Then the expected value is defined as

$$E[P(B_i)] = \frac{E(Z_i)}{E(Z)} = \frac{\alpha P_0(B_i)}{\alpha P_0(B_1) + \alpha P_0(B_2) + \alpha P_0(B_3)} = \frac{\alpha P_0(B_i)}{\alpha P_0(X)} = P_0(B_i)$$

We can derive the multivariate moment of the Dirichlet random variables. For simplicity of notation, let  $U_i = P(B_i)$  and  $v_i = P_0(B_i)$ . Then we have

$$\begin{aligned} E[P(B_1)P(B_2)] &= E(U_1 U_2) \\ &= \int u_1 u_2 \frac{\Gamma(\alpha v_1 + \alpha v_2 + \alpha v_3)}{\Gamma(\alpha v_1)\Gamma(\alpha v_2)\Gamma(\alpha v_3)} u_1^{\alpha v_1 - 1} u_2^{\alpha v_2 - 1} u_3^{\alpha v_3 - 1} d\mathbf{u} \\ &= \frac{\Gamma(\alpha v_1 + 1)\Gamma(\alpha v_2 + 1)}{\Gamma(\alpha v_1 + \alpha v_2 + \alpha v_3 + 2)} \frac{\Gamma(\alpha v_1 + \alpha v_2 + \alpha v_3)}{\Gamma(\alpha v_1)\Gamma(\alpha v_2)} \times \\ &\times \int \frac{\Gamma(\alpha v_1 + \alpha v_2 + \alpha v_3 + 2)}{\Gamma(\alpha v_1 + 1)\Gamma(\alpha v_2 + 1)\Gamma(\alpha v_3)} u_1^{(\alpha v_1 + 1) - 1} u_2^{(\alpha v_2 + 1) - 1} u_3^{\alpha v_3 - 1} d\mathbf{u} \\ &= \frac{\Gamma(\alpha v_1 + 1)\Gamma(\alpha v_2 + 1)}{\Gamma(\alpha v_1 + \alpha v_2 + \alpha v_3 + 2)} \frac{\Gamma(\alpha v_1 + \alpha v_2 + \alpha v_3)}{\Gamma(\alpha v_1)\Gamma(\alpha v_2)} \\ &= \frac{\Gamma(\alpha)}{\Gamma(\alpha + 2)} \frac{\alpha v_1 \Gamma(\alpha v_1) \cdot \alpha v_2 \Gamma(\alpha v_2)}{\Gamma(\alpha v_1)\Gamma(\alpha v_2)} \\ &= \frac{\alpha v_1 v_2}{(\alpha + 1)} \\ &= \frac{\alpha P_0(B_1)P_0(B_2)}{(\alpha + 1)} \end{aligned}$$

Then

$$\begin{aligned} \text{Cov}(P(B_1), P(B_2)) &= \frac{\alpha}{\alpha + 1} P_0(B_1)P_0(B_2) - \alpha P_0(B_1)\alpha P_0(B_2) \\ &= \left( \frac{\alpha}{\alpha + 1} - 1 \right) P_0(B_1)P_0(B_2) < 0 \end{aligned}$$

Since  $\frac{\alpha}{\alpha + 1} < 1$  given that  $\alpha > 0$  and  $P_0(\cdot)$  is a probability measure.

4. **Simulation of Dirichlet process prior realizations** Consider a  $DP(\alpha, G_0)$  prior over the space of distributions (equivalently c.d.f.'s)  $G$  on  $\mathbb{R}$ , with  $G_0 = N(0, 1)$ .

- (a) Use both Ferguson's original definition and Sethuraman's constructive definition to generate (multiple) prior c.d.f. realizations from the  $DP(\alpha, N(0, 1))$ , for different values of  $\alpha$  ranging from small to large.

I choose  $\alpha$  to be 0.1, 1, 10 and 100. DP's are drawn from Ferguson's definition as well

as from the constructive definition (both are comparable). Changing  $\alpha$  changes the shapes of each realization of the prior distributions. As  $\alpha$  increase, we see less discreteness and the distributions are more concentrated around the theoretical  $N(0,1)$  – which represented by the black line. This is due to the fact that  $\alpha$  represents how confident we are that the prior distribution is true. For each simulation using the DP I am generating 10 CDF, each represented with a different color.

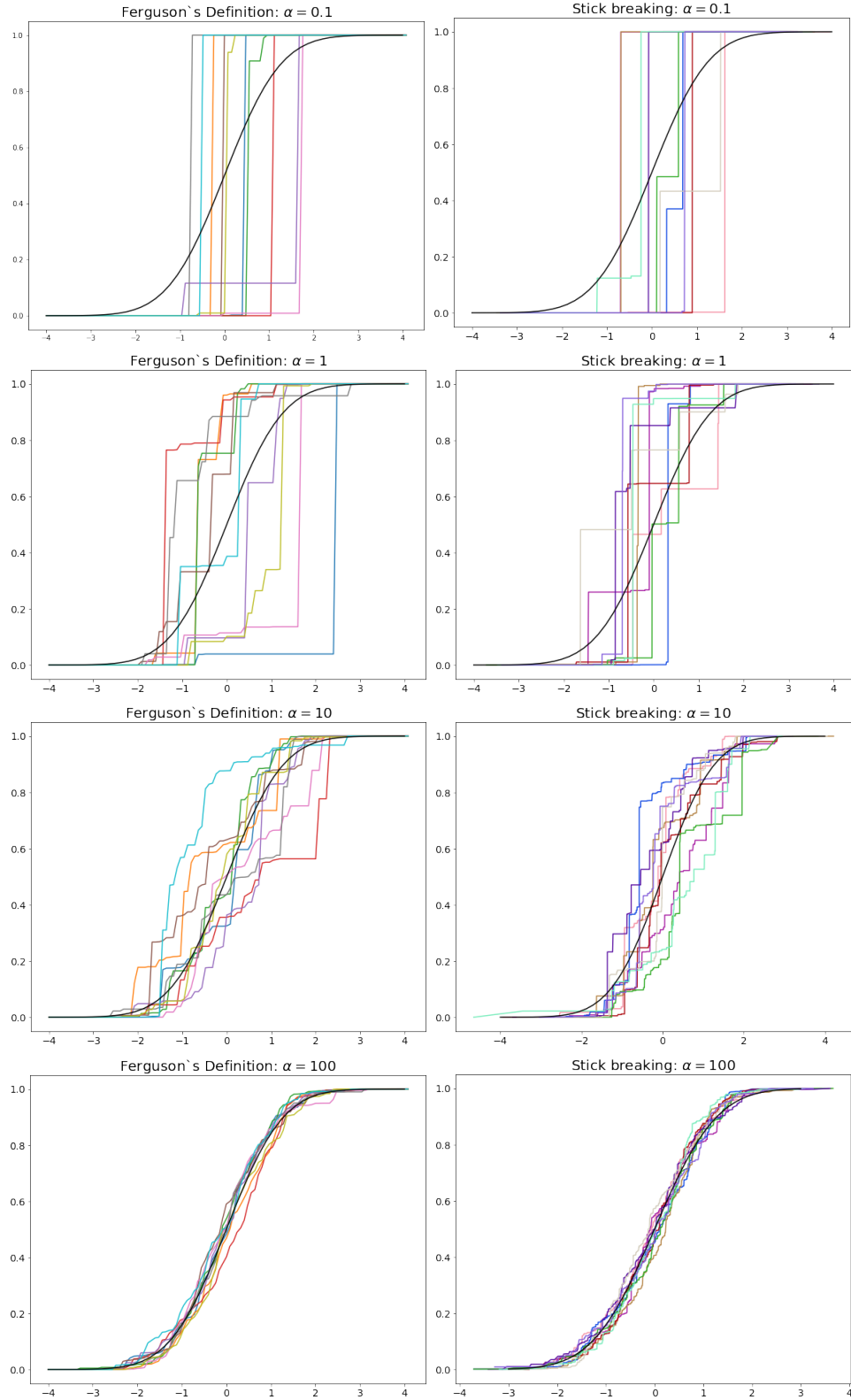


Figure 1: The left plots use Ferguson's original definition and the right plots use Sethuraman's constructive definition with various  $\alpha$ . For reproducible code, see [https://github.com/msilva00/BNP\\_Homework/blob/master/HW1/HW1\\_Prob4.ipynb](https://github.com/msilva00/BNP_Homework/blob/master/HW1/HW1_Prob4.ipynb)

- (b) In addition to prior c.d.f. realizations, obtain, for each value of  $\alpha$ , the corresponding prior distribution for the mean functional

$$\mu(G) = \int t dG(t)$$

and for the variance functional

$$\sigma^2(G) = \int t^2 dG(t) - \left\{ \int t dG(t) \right\}^2$$

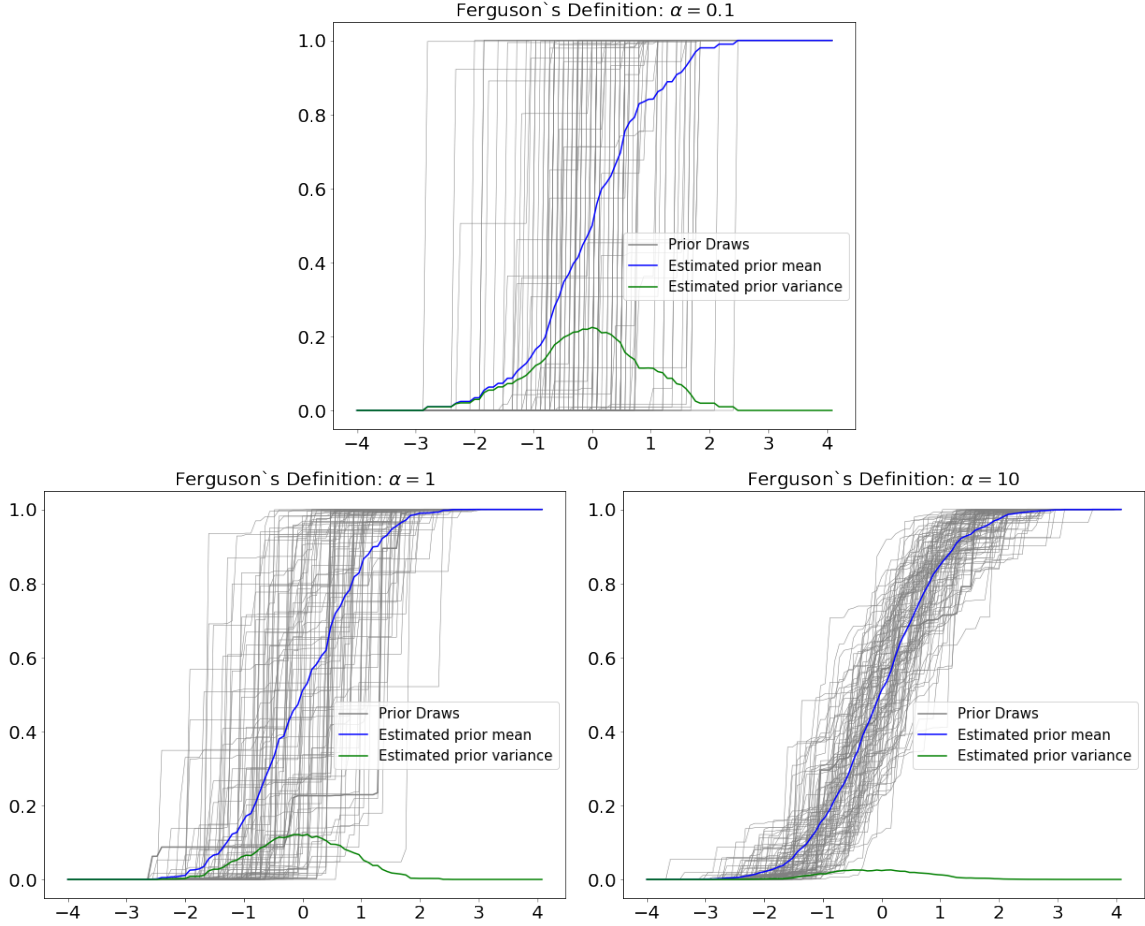


Figure 2: Using Ferguson's definition of the DP, I can compute the functional mean and the functional variance for each simulation, fixing the value of  $\alpha$ . For reproducible code, see [https://github.com/msilva00/BNP\\_Homework/blob/master/HW1/HW1\\_Prob4.ipynb](https://github.com/msilva00/BNP_Homework/blob/master/HW1/HW1_Prob4.ipynb)

- (c) Consider also a simulation under a mixture of DPs (MDP) prior, which extends the DP above by adding a prior for  $\alpha$ . Therefore, the MDP prior for  $G$  is defined such that,  $G|\alpha \sim DP(\alpha, N(0,1))$ , with a prior assigned to the precision parameter  $\alpha$  from its prior. You can work with a gamma prior for  $\alpha$  and 2-3 different choices for the gamma prior parameters.

Next, we extend the Dirichlet process by adding a gamma prior for  $\alpha$ .

$$\alpha \sim \text{Gamma}(3, 3)$$

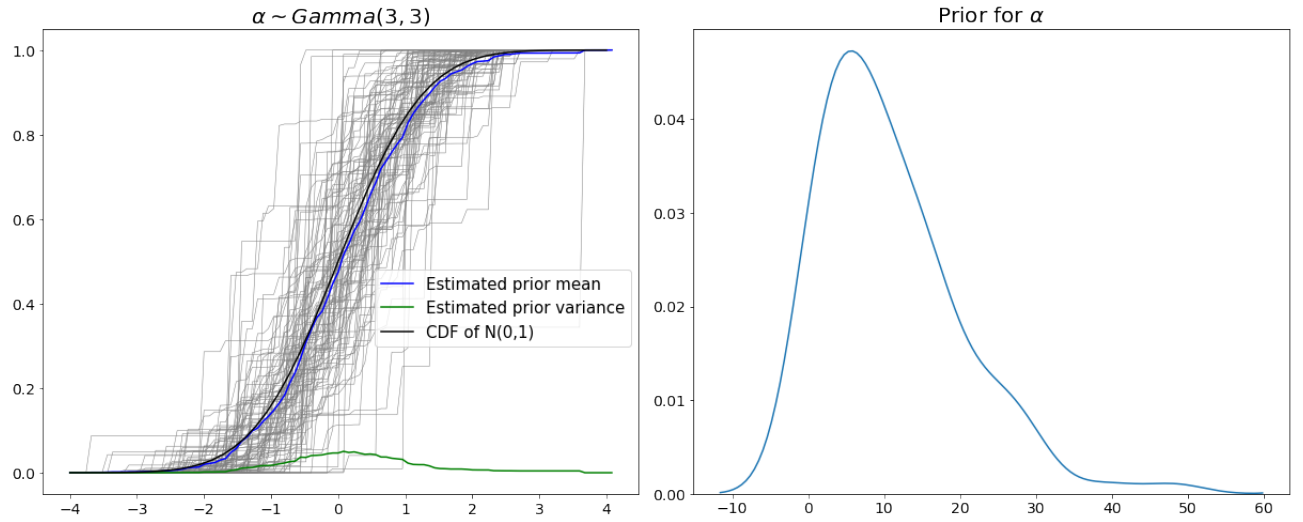


Figure 3: Here I simulate from the MDP using Ferguson's original definition given draws for  $\alpha$  from a Gamma prior. The result considering  $\alpha \sim \text{Gamma}(3,3)$  is similar to the result in part a, when  $\alpha = 1$  because the mean of the  $\alpha$  prior distribution is close to 1.

Last, consider the following Gamma prior

$$\alpha \sim \text{Gamma}(1,10)$$

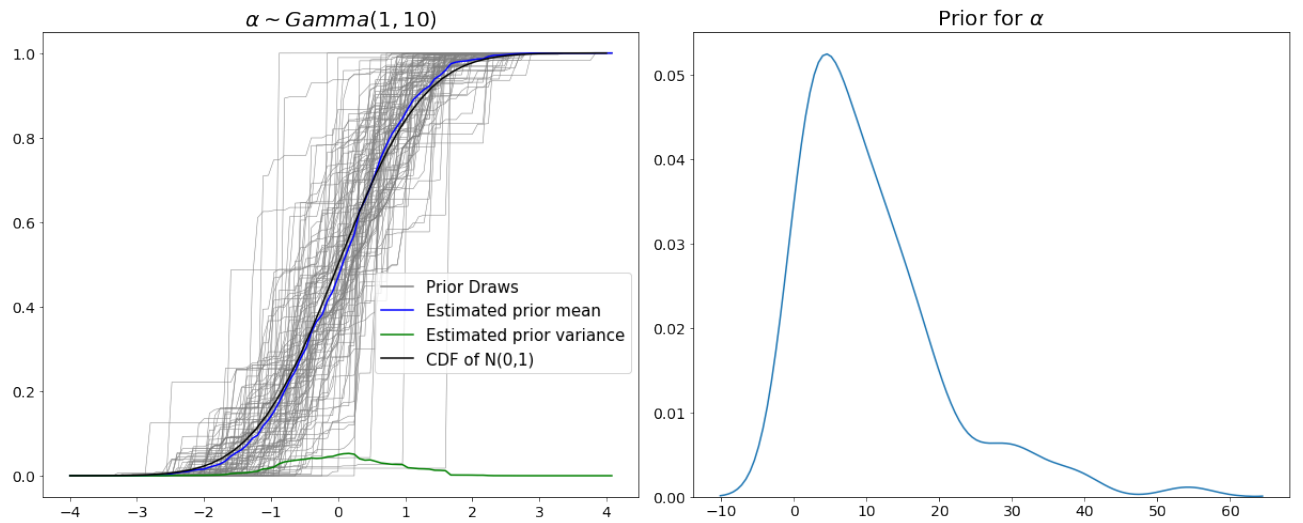


Figure 4: Here I simulate from the MDP using Ferguson's original definition given draws for  $\alpha$  from a Gamma prior. The result considering  $\alpha \sim \text{Gamma}(1,10)$  has low variance and also small mean, putting heavy emphasis on highly discrete DP draws.