## qLearn Week 3: Quantum Operations

Michael Silver, ECE 2T6
University of Toronto Quantum Computing Club

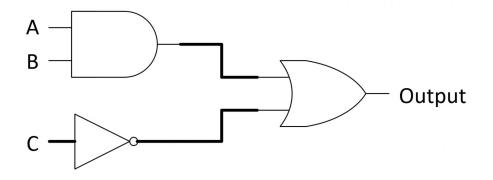


# Last Week Recap

# WHY LINEAR ALGEBRA?

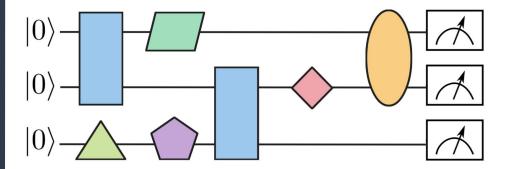
# Classical Circuits

- Boolean Logic

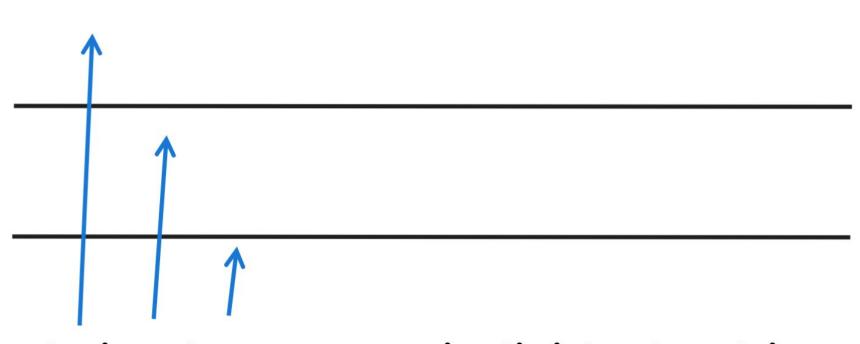


- Binary logic (0 and 1 inputs and outputs)
- **Physical** gates and wiring
- Different types of gates indicate different operations
- Every computer calculation and operation is a result of these circuits

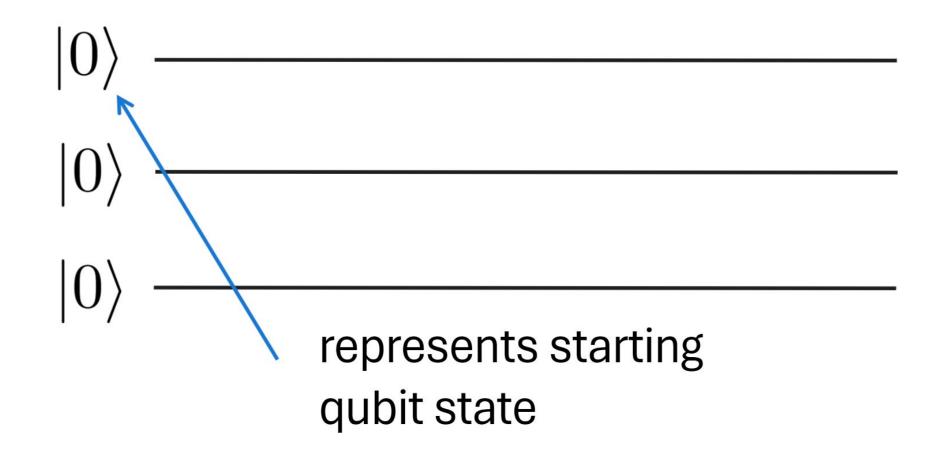
## Quantum Circuits

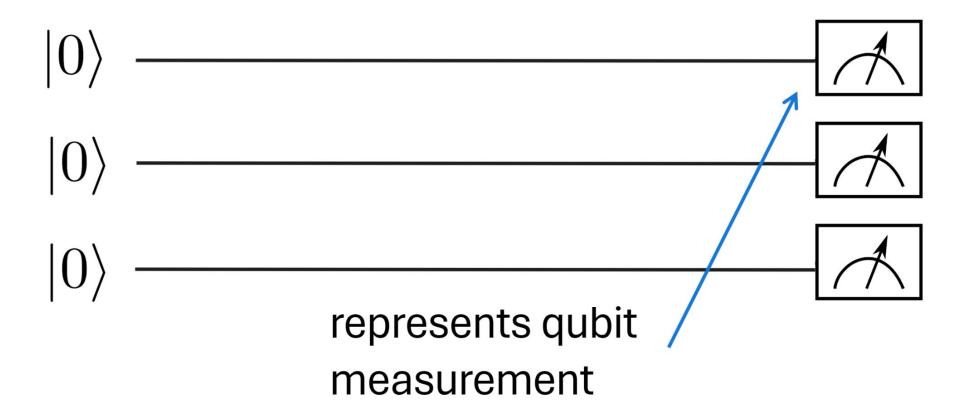


- <u>Visual</u> representation of operations being made on a qubit (very complicated physics, learn more in future hardware lectures)
- Represented by linear algebraic transformations mathematically
- Contains information about quantum algorithms, visual representation of them

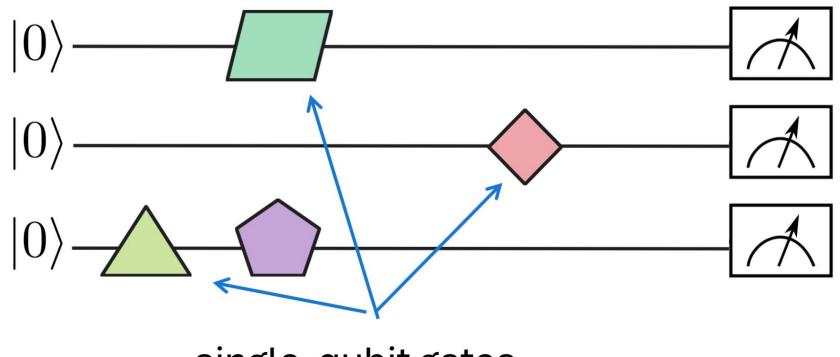


'wires' represent individual qubits

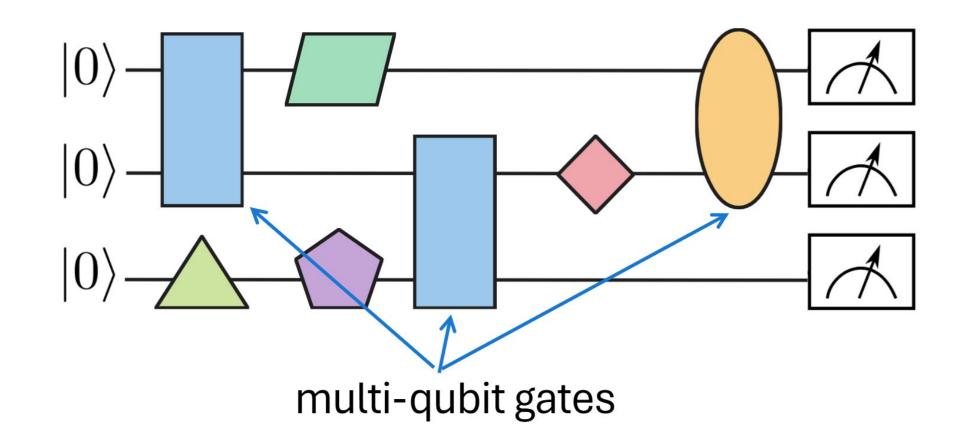




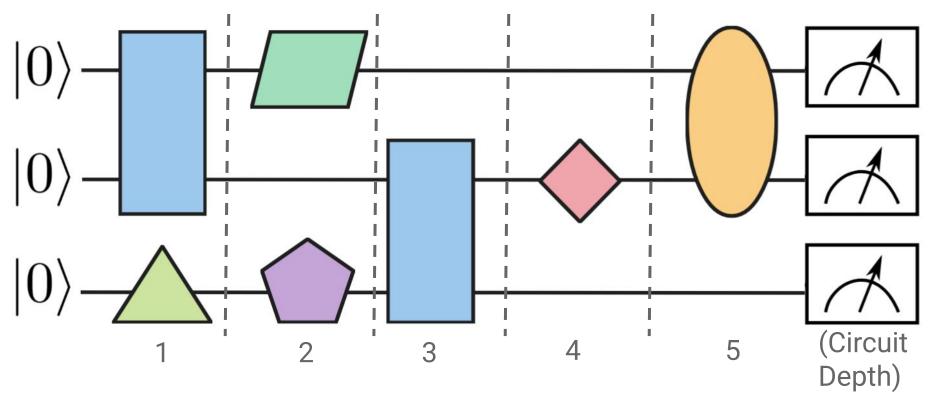
\*\*NOTE: Does not always have to go at end of circuit!!! We will see examples later



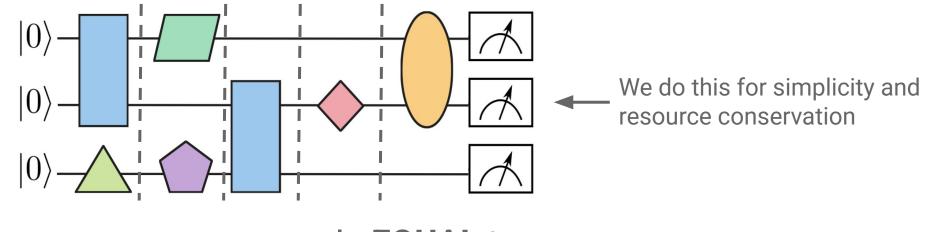
single-qubit gates



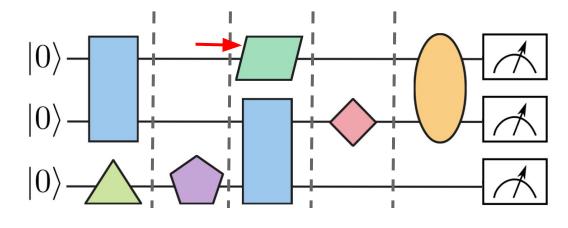




Gates acting on seperate qubits act in parallel



### Is **EQUAL** to



## Recal: Unitary Matrices

#### Key Vocab:

- Identity: Square matrix with 1s on diagonal and 0s elsewhere
- 2) Transpose<sup>T</sup>: flipped matrix values over its diagonal
- 3) Conjugate\* (for this lecture's sake): sign of imaginary part of a complex number is flipped

As previously mentioned, qubit operations are represented **mathematically** as **unitary matrices** 

What is a unitary matrix and why do we use them?

- Qubit state vectors are normalized, as in they always have length 1
- Unitary matrices have special properties that, when applied to qubit state vectors, preserve their length

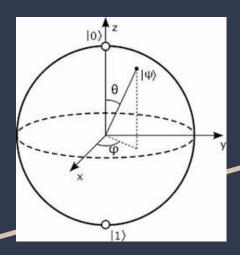
A  $n \cdot n$  matrix U is unitary if

$$UU^{\dagger} = U^{\dagger}U = I_n$$

Where  $I_n$  represents the n-dimensional identity, and  $U^\dagger$  is the notation for the conjugate transpose of U

# How do these represent qubit transformations???

bloch.kherb.io



Parameterization of a unitary matrix!!

Proof: Representing a Unitary in Polar Form

For unitary with complex elements

$$U = egin{bmatrix} a & b \ c & d \end{bmatrix}$$

Write each element in their polar forms

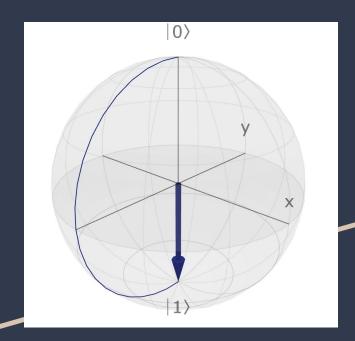
$$\begin{split} a &= e^{i\alpha}\cos(\theta/2), b = -e^{i(\beta-\gamma)}\sin(\theta/2) \\ c &= e^{i\gamma}\sin(\theta/2), d = e^{i(\beta-\alpha)}\cos(\theta/2) \\ U &= \begin{pmatrix} e^{i\alpha}\cos(\theta/2) & -e^{i(\beta-\gamma)}\sin(\theta/2) \\ e^{i\gamma}\sin(\theta/2) & e^{i(\beta-\alpha)}\cos(\theta/2) \end{pmatrix} \end{split}$$

Using substitutions:  $\phi=\beta-\alpha-\gamma, \omega=\gamma-\alpha$  (and phases) We obtain:

$$U(\phi, \theta, \omega) = \begin{pmatrix} e^{-i(\phi+\omega)/2} \cos(\theta/2) & -e^{i(\phi-\omega)/2} \sin(\theta/2) \\ e^{-i(\phi-\omega)/2} \sin(\theta/2) & e^{i(\phi+\omega)/2} \cos(\theta/2) \end{pmatrix}$$

## Single-Qubit Quantum Gates

#### Pauli X Gate

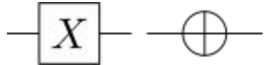


\*\* Reversible (Hermitian, ask me what that means if you're reading this!)

-> Similar to a classical NOT Gate

$$egin{aligned} X\ket{0} &= \ket{1} \;\; ext{For} \ket{\psi} = lpha \ket{0} + eta \ket{1} \ X\ket{1} &= \ket{0} \;\; X\ket{\psi} = lpha X\ket{0} + eta X\ket{1} \ &= lpha \ket{1} + eta \ket{0} \end{aligned}$$

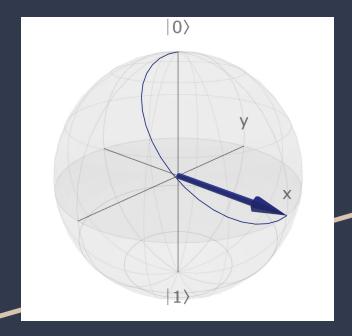
- -> Geometrically, 180° rotation around x-axis in Bloch sphere
- ->Gate representation



-> Matrix representation

$$X = egin{bmatrix} 0 & 1 \ 1 & 0 \end{bmatrix}$$

## H (Hadamard) Gate



-> Creates a uniform superposition of states

$$H|0
angle=rac{1}{\sqrt{2}}(|0
angle+|1
angle)=|+
angle$$

$$H|1
angle=rac{1}{\sqrt{2}}(|0
angle-|1
angle)=|-
angle$$

-> Geometrically, reflection over the diagonal of the XZ plane in Bloch sphere

H

-> Matrix representation

$$H=rac{1}{\sqrt{2}}egin{bmatrix}1&1\1&-1\end{bmatrix}$$

## Code Break!

#### Reminder:

$$H|0
angle=rac{1}{\sqrt{2}}(|0
angle+|1
angle)=|+
angle$$

$$H|1
angle=rac{1}{\sqrt{2}}(|0
angle-|1
angle)=|-
angle$$



#### A Note on Phases

$$egin{aligned} |\psi
angle &= lpha |0
angle + eta |1
angle \ &lpha = ae^{i heta}, eta = be^{iarphi} \ |\psi
angle &= ae^{i heta} |0
angle + be^{iarphi} |1
angle \ &= e^{i heta} (a|0
angle + be^{i(arphi - heta)} |1
angle) \ &= a|0
angle + be^{i(arphi - heta)} |1
angle \end{aligned}$$

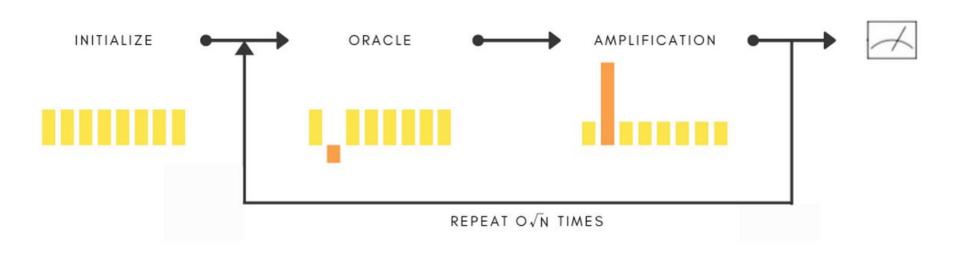
#### Global Phase:

- Transformation that multiplies the <u>entire</u> state by a complex number of unit magnitude
- Note: No observable impact on measurement probabilities
- ullet EX.  $Y=egin{bmatrix} 0 & -i \ i & 0 \end{bmatrix}, YY=-I, YY|\psi
  angle =-|\psi
  angle$

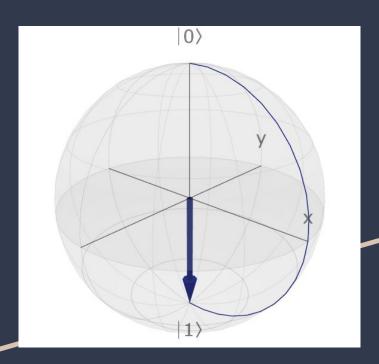
#### **Relative Phase:**

- Changes the phase relationship between the components of a superposition state
- Non-uniform impact on probabilities, thus affects measurement outcomes
- $\bullet$  EX.  $H|1
  angle=rac{1}{\sqrt{2}}(|0
  angle-|1
  angle)=|angle$

## Example of Relative Phase Use in Algorithm



### Pauli Y Gate



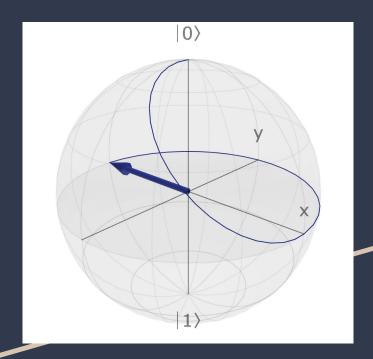
-> X, but adds **phase factors** +- i

$$egin{aligned} Y|0
angle &=i|1
angle & ext{For } |\psi
angle &=lpha|0
angle +eta|1
angle \ Y|\psi
angle &=lpha Y|0
angle +eta Y|1
angle &=lpha Y|0
angle +eta Y|1
angle \ &=lpha (i|1
angle) +eta (-i|0
angle) \end{aligned}$$

- -> Geometrically, 180° rotation around Y-axis
- ->Gate representation
- -> Matrix representation

$$Z = egin{bmatrix} 1 & 0 \ 0 & -1 \end{bmatrix}$$

#### Pauli Z Gate



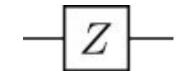
-> 'Flips' the phase of the state

$$egin{aligned} Z|0
angle 
ightarrow |0
angle \ Z|1
angle 
ightarrow -|1
angle \end{aligned}$$

$$Z|+
angle = rac{1}{\sqrt{2}}(|0
angle - |1
angle) = |-
angle$$

$$|Z|-
angle=rac{1}{\sqrt{2}}(|0
angle+|1
angle)=|+
angle$$

-> Geometrically, 180° rotation around Z-axis



-> Matrix representation

$$Z = egin{bmatrix} 1 & 0 \ 0 & -1 \end{bmatrix}$$

#### **Rotational Gates**

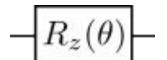
$$RX( heta) = egin{bmatrix} \cos(rac{ heta}{2}) & -i\sin(rac{ heta}{2}) \ -i\sin(rac{ heta}{2}) & \cos(rac{ heta}{2}) \end{bmatrix}$$

$$RY( heta) = egin{bmatrix} \cos(rac{ heta}{2}) & -\sin(rac{ heta}{2}) \ \sin(rac{ heta}{2}) & \cos(rac{ heta}{2}) \end{bmatrix}$$

$$RZ(\omega) = egin{bmatrix} e^{-irac{\omega}{2}} & 0 \ 0 & e^{irac{\omega}{2}} \end{bmatrix}$$

- -> 'Rotates' the state around chosen axis
- ->Gate representation

-> Pauli Z:  $RZ(\pi)$ 

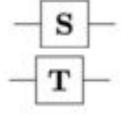


- -> Pauli Y: RY( $\pi$ )
- -> Pauli X:  $RX(\pi)$

#### **Special Cases**

-> S is  $RZ(\pi/2)$ 

-> T is RZ( $\pi$ /4)



(Notice anything interesting? If we can rotate around all our axes, what does that mean)

$$H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

# Code Break!

$$RX( heta) = egin{bmatrix} \cos(rac{ heta}{2}) & -i\sin(rac{ heta}{2}) \ -i\sin(rac{ heta}{2}) & \cos(rac{ heta}{2}) \end{bmatrix}$$

$$RY( heta) = egin{bmatrix} \cos(rac{ heta}{2}) & -\sin(rac{ heta}{2}) \ \sin(rac{ heta}{2}) & \cos(rac{ heta}{2}) \end{bmatrix}$$
  $RZ(\omega) = egin{bmatrix} e^{-irac{\omega}{2}} & 0 \ 0 & e^{irac{\omega}{2}} \end{bmatrix}$ 

## Equivalent Gate Identities

$$U(\phi, \theta, \omega) = \begin{pmatrix} e^{-i(\phi+\omega)/2} \cos(\theta/2) & -e^{i(\phi-\omega)/2} \sin(\theta/2) \\ e^{-i(\phi-\omega)/2} \sin(\theta/2) & e^{i(\phi+\omega)/2} \cos(\theta/2) \end{pmatrix}$$

1) 
$$H = Ry(\frac{\pi}{2})Rx(\pi)$$

2) 
$$Ry(\theta) = Rz(-\frac{\pi}{2})Rx(\theta)Rz(\frac{\pi}{2})$$

3) 
$$Rx(\theta) = Rz(\frac{\pi}{2})Ry(\theta)Rz(-\frac{\pi}{2})$$

4) 
$$Rz(\theta) = Ry(\frac{\pi}{2})Rx(\theta)Ry(-\frac{\pi}{2})$$

5) 
$$U(\phi, \theta, \omega) = Rz(\omega)Ry(\theta)Rz(\phi)$$

#### **Universal Gates**

A set of gates is **universal** if any quantum computation can be approximated to arbitrary accuracy using **just gates from that set** 

$$U(\phi, \theta, \omega) = Rz(\omega)Ry(\theta)Rz(\phi)$$

- -> Example universal single-qubit gates:
  - Hadamard (H) + T gate (pi/8 RZ gate)
  - RX, RY, RZ
- -> This has huge applications in hardware and error correction; we don't need a large breadth of instructions

## Quantum Gates Cheat Sheet



# See you next week!

- -Multi-Qubit Operations
- -Introduction to Quantum Utility