

Sample 12-4

画像復元

高速繰り返し縮退閾値アルゴリズム (FISTA)

画像処理特論

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動作確認: MATLAB R2023a

Image restoration

Fast iterative shrinkage/thresholding algorithm (FISTA)

Advanced Topics in Image Processing

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Verified: MATLAB R2023a

準備

(Preparation)

```
clear
close all
import msip.download_img
msip.download_img
```

```
kodim01.png already exists in ./data/
kodim02.png already exists in ./data/
kodim03.png already exists in ./data/
kodim04.png already exists in ./data/
kodim05.png already exists in ./data/
kodim06.png already exists in ./data/
kodim07.png already exists in ./data/
kodim08.png already exists in ./data/
kodim09.png already exists in ./data/
kodim10.png already exists in ./data/
kodim11.png already exists in ./data/
kodim12.png already exists in ./data/
kodim13.png already exists in ./data/
kodim14.png already exists in ./data/
kodim15.png already exists in ./data/
kodim16.png already exists in ./data/
kodim17.png already exists in ./data/
kodim18.png already exists in ./data/
kodim19.png already exists in ./data/
kodim20.png already exists in ./data/
kodim21.png already exists in ./data/
kodim22.png already exists in ./data/
kodim23.png already exists in ./data/
kodim24.png already exists in ./data/
See Kodak Lossless True Color Image Suite
```

問題設定

(Problem settings)

$$\hat{\mathbf{s}} = \arg \min_{\mathbf{s}} \frac{1}{2} \|\mathbf{v} - \mathbf{D}\mathbf{s}\|_2^2 + \lambda \|\mathbf{s}\|_1$$

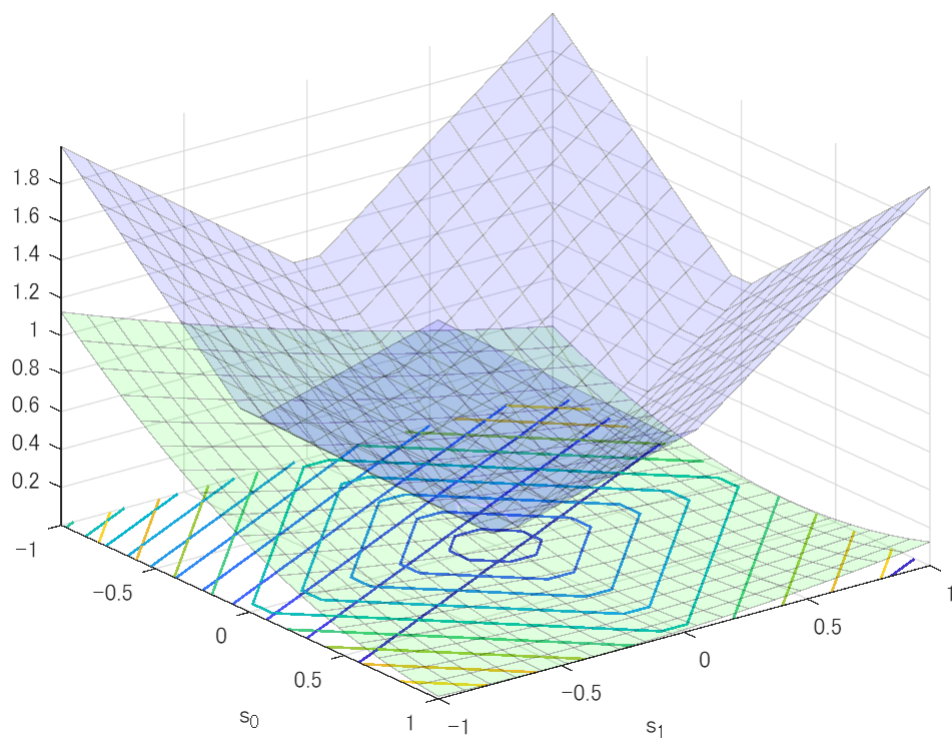
- $\mathbf{D} = \begin{pmatrix} 2 & 1 \\ 3 & 3 \end{pmatrix}: \mathbb{R}^2 \rightarrow \mathbb{R}^1$
- $\mathbf{v} = \frac{1}{2} \in \mathbb{R}^1$
- $\lambda \in [0, \infty)$
- $\mathbf{s} \in \mathbb{R}^2$

```
D = [2 1]/3;  
v = 0.5;
```

関数プロット

(Function plot)

```
% Function settings  
f = @(s0,s1) 0.5*(v-(D(1)*s0+D(2)*s1)).^2;  
g = @(s0,s1) (abs(s0)+abs(s1));  
% Variable settins  
s0 = linspace(-1,1,20);  
s1 = linspace(-1,1,20);  
[S0,S1] = ndgrid(s0,s1);  
F = f(S0,S1);  
G = g(S0,S1);  
% Surfc plot of the fidelity  
figure(1)  
hf = surf(s0,s1,F);  
hf(1).FaceAlpha = 0.125;  
hf(1).FaceColor = 'green';  
hf(1).EdgeAlpha = 0.25;  
hf(2).LineWidth = 1;  
set(gca, 'YDir', 'reverse');  
hold on  
% Surfc plot of the regularizer  
hg = surf(s0,s1,G);  
hg(1).FaceAlpha = 0.125;  
hg(1).FaceColor = 'blue';  
hg(1).EdgeAlpha = 0.25;  
hg(2).LineWidth = 1;  
xlabel('s_1')  
ylabel('s_0')  
hold off
```



パラメータ設定

(Parameter settings)

```
lambda = 0.2;
gamma = 0.4;
nitters = 20;
```

ℓ_1 -ノルム正則化最小自乗法による近似

(ℓ_1 -norm-regularized least square method)

$$\hat{\mathbf{s}} = \arg \min_{\mathbf{s}} \frac{1}{2} \|\mathbf{v} - \mathbf{D}\mathbf{s}\|_2^2 + \lambda \|\mathbf{s}\|_1$$

近接勾配法に帰着させる. (Reduced to a proximal gradient method)

$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x} \in V} f(\mathbf{x}) + g(\mathbf{x})$$

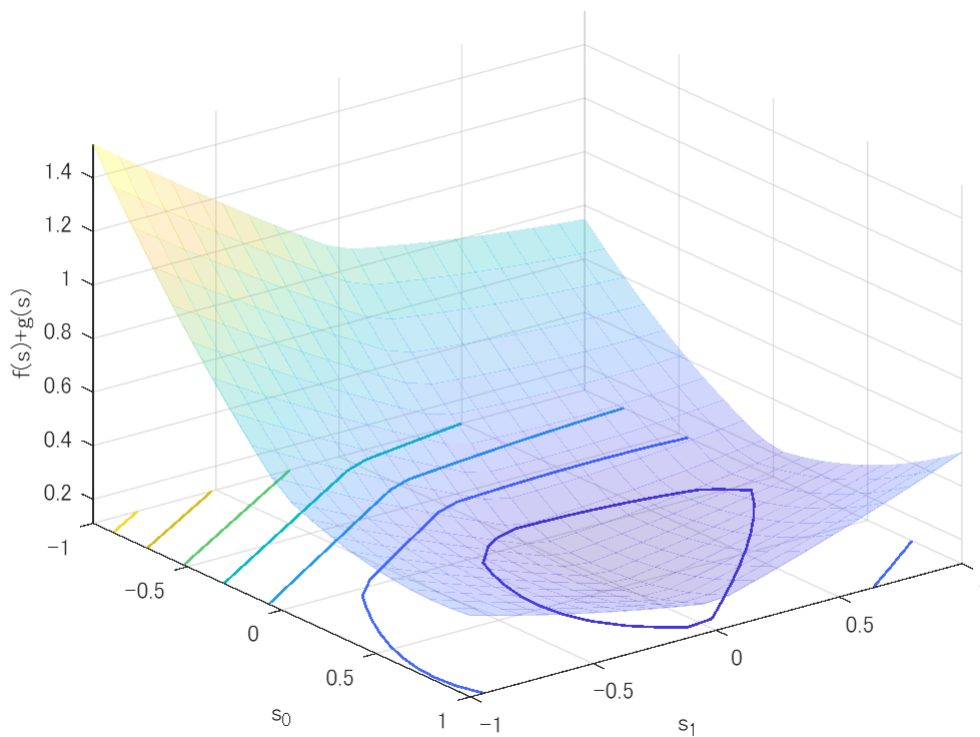
- $f(\cdot), g(\cdot) \in \Gamma_0(\mathbb{R}^L)$: Convex functions
- $f(\cdot)$ is differentiable (β -Lipschitz continuous)
- $\Gamma_0(\mathbb{R}^L)$: Set of proper semi-lower-continuous convex functions

【Example】

- $f(s) = \frac{1}{2} \|v - Ds\|_2^2$
- $g(s) = \lambda \|s\|_1$

関数プロット (Function plot)

```
% Function setting
fg = @(s0,s1) 0.5*(v-(D(1)*s0+D(2)*s1)).^2 + lambda*(abs(s0)+abs(s1));
% Surfc plot of cost function f+g
figure(2)
J = fg(S0,S1);
hf = surfc(s0,s1,J);
hf(1).FaceAlpha = 0.25;
hf(1).EdgeAlpha = 0.25;
hf(1).EdgeColor = 'interp';
hf(2).LineWidth = 1;
set(gca, 'YDir', 'reverse')
ylabel('s_0')
xlabel('s_1')
zlabel('f(s)+g(s)')
hold on
```



ネステロフの加速法

(Nesterov's acceleration)

1. Initialization: $\mathbf{y}^{(1)} = \mathbf{x}^{(0)}, a^{(1)} = 1, t \leftarrow 0$
2. Proximal gradient descent: $\mathbf{x}^{(t+1)} \leftarrow \text{prox}_{\gamma g}(\mathbf{y}^{(t)} - \gamma \nabla_{\mathbf{x}} f(\mathbf{y}^{(t)}))$
3. $a^{(t+1)} \leftarrow \frac{1 + \sqrt{1 + (a^{(t)})^2}}{2}$
4. $\mathbf{y}^{(t)} \leftarrow \mathbf{x}^{(t)} + \frac{a^{(t)} - 1}{a^{(t+1)}}(\mathbf{x}^{(t)} - \mathbf{x}^{(t-1)})$
5. If a stopping criteria is satisfied then finish, otherwise $t \rightarrow t + 1$ and go to Step 2.

【Example】

- $\nabla_{\mathbf{s}} f(\mathbf{s}) = \mathbf{D}^T(\mathbf{D}\mathbf{s} - \mathbf{v})$
- $\text{prox}_{\gamma \lambda \|\cdot\|_1}(\mathbf{s}) = \mathcal{T}_{\gamma \lambda}(\mathbf{s}) = \text{sign}(\mathbf{s}) \odot \max(\text{abs}(\mathbf{s}) - \gamma \lambda \mathbf{1}, \mathbf{0})$

ソフト閾値処理 (Soft-thresholding)

```
softthresh = @(x,t) sign(x).*max(abs(x)-t,0);
```

初期化 (Initialization)

```
sp0 = 2*rand(2,1)-1; % in [-1,1]^2
```

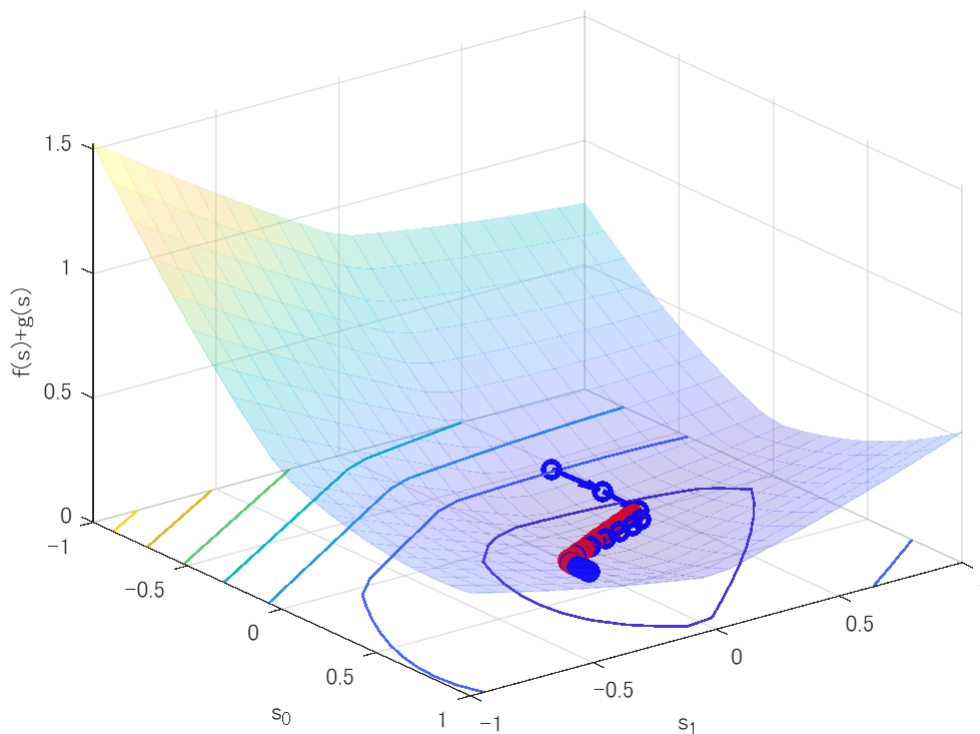
近接勾配降下 (Proximal gradient descent)

```
beta = D*D';
assert(gamma < 2/beta, 'Step size condition is violated.')
for isaxel = [ false, true ]
    ac = 1;
    sp = sp0;
    z = sp0;
    for idx=1:niters
        % Preious state
        s(1,1) = sp(1); % s0
        s(2,1) = sp(2); % s1
        % Proximal gradient descent
        sc = softthresh(z-gamma*D'*(D*z-v), gamma*lambda);
        %
        if isaxel
            an = (1+sqrt(1+4*ac^2))/2;
        else
            an = 1;
        end
        %
        z = sc + (ac-1)/an*(sc-sp);
        % Current state
        s(1,2) = sc(1); % s0
```

```

s(2,2) = sc(2); % s1
% Quiver plot
xp = s(2,1);
yp = s(1,1);
xn = s(2,2);
yn = s(1,2);
hp = quiver(xp,yp,xn-xp,yn-yp);
hp.Marker = 'o';
hp.ShowArrowHead = 'on';
hp.MaxHeadSize = 120;
hp.MarkerSize = 6;
if isaxel
    hp.MarkerEdgeColor = 'b';
    hp.Color = 'b';
else
    hp.MarkerEdgeColor = 'r';
    hp.Color = 'r';
end
hp.LineWidth = 2;
% Update
sp = sc;
ac = an;
end
end
hold off

```



パラメータ設定

(Parameter settings)

- sgm: ノイズ標準偏差 σ_w (Standard deviation of noise)
- nlevels: ウェーブレット段数 (Wavelet levels)

```
% Parameter settings
isaprxleft = true;
lambda = 10^-1% -0.1
```

```
lambda = 0.1000
```

```
gamma = 10^0.1% -0.8
```

```
gamma = 1.2589
```

```
sgmuint8 = 10;
sgm = sgmuint8/255;
nlevels = 3;
niters = 40;
```

画像の読込

(Read image)

```
u = rgb2gray(im2double(imread('./data/kodim23.png')));
```

観測画像

(Observation image)

- $\mathbf{v} = \mathbf{P}\mathbf{u} + \mathbf{w}$
- $\mathbf{u} = \mathbf{D}\mathbf{s}$
- $\mathbf{w} \sim \text{Norm}(\mathbf{w} | \boldsymbol{\mu}_w = \mathbf{0}, \sigma_w^2 \mathbf{I})$

```
% Definition of measurment process
psf = fspecial('motion',21,11);
measureproc = @(x) imfilter(x,psf,'conv','circular');
% Adjoint process of the measurment process
measureadjp = @(x) imfilter(x,psf,'corr','circular');
% Simulation of AWGN
v = imnoise(measureproc(u),'gaussian',0,sgm^2);
```

非間引きハール DWT

(Undecimated Haar DWT)

```
import msip.udhaarwtdec2
import msip.udhaarwtrec2
```

完全再構成の確認 (Check the perfect reconstruction)

非間引きハール DWT はパーセバルタイト性 (The undecimated DWT satisfies the Parseval tight property,)

$$\mathbf{D}\mathbf{D}^T = \mathbf{I}$$

を満たすため、 \mathbf{D} の転置システムは完全再構成分析システムとなり得る。 (and thus its transposition system can be a PR analysis system.)

```
[coefs,scales] = udhaarwtdec2(v,nlevels);  
r = udhaarwtrec2(coefs,scales);  
assert(norm(v-r,"fro")^2/numel(v)<1e-18,'Perfect reconstruction is violated.')
```

合成辞書と転置辞書の定義 (Definition of synthesis dictionary and its adjoint)

```
% Definon of dictionay and its adjoint  
adjdic = @(x) udhaarwtdec2(x,nlevels); % D  
syndic = @(x) udhaarwtrec2(x,scales); % D.'
```

高速 ISTA

(Fast ISTA)

問題設定 (Problem setting)

$$\hat{\mathbf{s}} = \arg \min_{\mathbf{s}} \frac{1}{2} \|\mathbf{v} - \mathbf{PD}\mathbf{s}\|_2^2 + \lambda \|\mathbf{s}\|_1$$

アルゴリズム (Algorithm)

1. Initialization: $\mathbf{y}^{(1)} = \mathbf{s}^{(0)}$, $a^{(1)} = 1$, $t \leftarrow 0$
2. $\mathbf{s}^{(t+1)} \leftarrow \text{prox}_{\gamma g}(\mathbf{y}^{(t)} - \gamma \nabla_{\mathbf{s}} f(\mathbf{y}^{(t)}))$
3. $a^{(t+1)} \leftarrow \frac{1 + \sqrt{1 + 4(a^{(t)})^2}}{2}$
4. $\mathbf{y}^{(t)} \leftarrow \mathbf{s}^{(t)} + \frac{a^{(t)} - 1}{a^{(t+1)}}(\mathbf{s}^{(t)} - \mathbf{s}^{(t-1)})$
5. If a stopping criteria is satisfied then finish, otherwise $t \rightarrow t + 1$ and go to Step 2.

ただし, (where)

- $\nabla_{\mathbf{s}} f(\mathbf{s}) = \mathbf{D}^T \mathbf{P}^T (\mathbf{PD}\mathbf{s} - \mathbf{v})$
- $\text{prox}_{\gamma \lambda \|\cdot\|_1}(\mathbf{s}) = \mathcal{T}_{\gamma \lambda}(\mathbf{s}) = \text{sign}(\mathbf{s}) \odot \max(\text{abs}(\mathbf{s}) - \gamma \lambda \mathbf{1}, \mathbf{0})$

ソフト閾値処理 (Soft-thresholding)

```
softthresh = @(x,t) sign(x).*max(abs(x)-t,0);
```

初期化 (Initialization)


```
[coefs,scales] = udhaarwtdec2(v,nlevels);
sp = coefs;
```

近接勾配降下 (Proximal gradient descent)

- $\gamma < 2/\beta$: Step size
- β : Lipschitz constant of ∇f , where $\beta = (\sigma_{\max}(\mathbf{PD}))^2$

```
beta = max(abs(fftn(psf,2.^nextpow2(size(v)))),[],'all');
assert(gamma < 2/beta,'Step size condition is violated.')
if isaprxleft
    mask = ones(size(coefs));
    mask(1:prod(scales(1,:))) = 0;
    lambda = lambda * mask;
end
yc = sp;
ac = 1;
for idx=1:niters
    % Proximal gradient descent
    sg = adjdic(measureadjp(measureproc(syndic(yc))-v));
    sc = softthresh(yc-gamma*sg,gamma*lambda);
    an = (1+sqrt(1+4*ac^2))/2;
    yc = sc + ((ac-1)/an)*(sc-sp);
    % Update
    sp = sc;
    ac = an;
end
```

復元画像

(Restored image)

```
r = syndic(sc);
```

画像表示

(Image show)

```
figure(1)
imshow(u);
title('Original image u')
```

Original image u



```
figure(2)
imshow(v)
title(sprintf('Blurred image v : PSNR = %5.2f [dB]',psnr(u,v)))
```

Blurred image v: PSNR = 23.70 [dB]



```
figure(3)
imshow(r)
title(sprintf('Restored image r w/ FISTA : PSNR = %5.2f [dB]',psnr(u,r)))
```

Restored image r w/ FISTA: PSNR = 26.15 [dB]



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