Sample 10-2

冗長変換

分析問題

画像処理特論

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動作確認: MATLAB R2020a

Redundant transforms

Analysis problem

Advanced Topics in Image Processing

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Verified: MATLAB R2020a

準備

(Preparation)

```
close all
```

フィルタ係数設定と入力信号の生成

(Setting of filter Coefs. and generation of input)

```
% Coefficients of analysis filters
gamma = 0.5;
delta = 1 - gamma;

% Input signal
u = [ 0 3 1 3 1 5 3 0 ]; % Set to even length
```

並列フィルタバンク実装

(Parallel filter bank implementation)

分析フィルタバンクをデシメータで、合成フィルタバンクをインタポレータで実装

```
% # of channels
nChs = 2;

% Analysis filters
h0 = [ gamma delta ];
h1 = [ gamma -delta ];

% Synthesis filters
f0 = [ 1 1 ]/2;
```

```
f1 = [ -1 1 ]/2;

% Analysis process
s0 = conv(h0,u);
s1 = conv(h1,u);

% Synthesis process
v0 = conv(f0,s0);
v1 = conv(f1,s1);
v = v0 + v1;

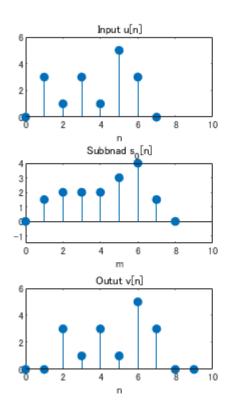
% Energy of subband Coefs.
disp(['||s||_2^2 = ' num2str(norm([s0(:);s1(:)],2)^2)])
```

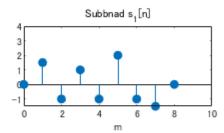
 $||s||_2^2 = 54$

信号表示

(Signal display)

```
figure(1)
% Input
subplot(3,2,1)
stem(0:length(u)-1,u,'filled')
title('Input u[n]')
xlabel('n')
ax = gca;
ax.XLim =[ 0 length(v)];
% Subband 0
subplot(3,2,3)
stem(0:length(s0)-1,s0,'filled')
title('Subbnad s_0[n]')
xlabel('m')
ax = gca;
ax.XLim =[ 0 length(v)];
ax.YLim = [\min([s0(:);s1(:)])\max([s0(:);s1(:)])];
% Subband 1
subplot(3,2,4)
stem(0:length(s1)-1,s1,'filled')
title('Subbnad s_1[n]')
xlabel('m')
ax = gca;
ax.XLim =[ 0 length(v)];
ax.YLim = [min([s0(:);s1(:)]) max([s0(:);s1(:)])];
% Output
subplot(3,2,5)
stem(0:length(v)-1,v,'filled')
title('Outut v[n]')
xlabel('n')
ax = gca;
ax.XLim =[ 0 length(v)];
```





```
% MSE 評価
mymse = @(x,y) mean((x(:)-y(:)).^2);
disp(['MSE = ', num2str(mymse(u, v(2:end-1)))]);
```

MSE = 0

インパルス応答

(Impluse responses of synthesis filters)

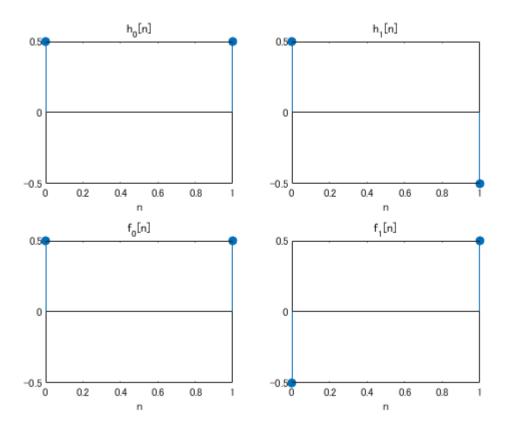
```
figure(2)

% Low-pass analysis filter
subplot(2,2,1)
stem(0:length(h0)-1,h0,'filled')
title('h_0[n]')
xlabel('n')
ax = gca;
ax.YLim =[ min([h0(:);h1(:)]) max([h0(:);h1(:)]) ];

% High-pass analysis filter
subplot(2,2,2)
stem(0:length(h1)-1,h1,'filled')
title('h_1[n]')
xlabel('n')
ax = gca;
ax.YLim =[ min([h0(:);h1(:)]) max([h0(:);h1(:)]) ];
```

```
% Low-pass synthesis filter
subplot(2,2,3)
stem(0:length(f0)-1,f0,'filled')
title('f_0[n]')
xlabel('n')
ax = gca;
ax.YLim =[ min([f0(:);f1(:)]) max([f0(:);f1(:)]) ];

% High-pass synthesis filter
subplot(2,2,4)
stem(0:length(f1)-1,f1,'filled')
title('f_1[n]')
xlabel('n')
ax = gca;
ax.YLim =[ min([f0(:);f1(:)]) max([f0(:);f1(:)]) ];
```



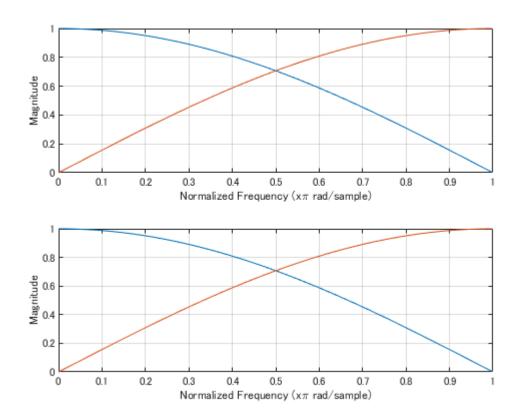
周波数応答

(Frequency responses)

```
figure(3)
fftPoints = 512;

% Analysis filters
subplot(2,1,1)
H = zeros(fftPoints,nChs);
% Low-pass filter
```

```
[H(:,1),W] = freqz(h0,1,fftPoints);
% High-pass filter
H(:,2)
          = freqz(h1,1,fftPoints);
plot(W/pi,abs(H)) %20*log10(abs(F)))
%axis([0 1 0 1]) %-70 10])
xlabel('Normalized Frequency (x\pi rad/sample)')
ylabel('Magnitude') % (dB)')
grid on
% Synthesis filters
subplot(2,1,2)
F = zeros(fftPoints,nChs);
% Low-pass filter
[F(:,1),W] = freqz(f0,1,fftPoints);
% High-pass filter
F(:,2)
           = freqz(f1,1,fftPoints);
plot(W/pi,abs(F)) %20*log10(abs(F)))
axis([0 1 0 1]) %-70 10])
xlabel('Normalized Frequency (x\pi rad/sample)')
ylabel('Magnitude') % (dB)')
grid on
```



ポリフェーズ行列実装 (PPMATRIXオブジェクト利用)

(Polyphase matrix implemenation with PPMATRIX object)

フィルタバンクをポリフェーズフィルタに分解して、ポリフェーズ行列として実装 (Decompose the filter bank into polyphase filters and implement them in a polyphase matrix.)

```
\mathbf{E}(z) = \binom{h_0[0]}{h_1[0]} + \binom{h_0[1]}{h_1[1]} z^{-1} = \binom{h_0[0] + h_0[1]z^{-1}}{h_1[0] + h_1[1]z^{-1}}
```

```
\mathbf{R}(z) = (f_0[0] \ f_1[0]) + (f_0[1] \ f_1[1])z^{-1} = (f_0[0] + f_0[1]z^{-1} \ f_1[0] + f_1[1]z^{-1})
```

```
% Type-I polyphase filters of analyzer
e00 = h0(1:end);
e10 = h1(1:end);
% Type-II polyphase filters of synthesizer
r00 = f0(1:end);
r01 = f1(1:end);
```

ポリフェーズ行列演算が簡便となるよう以下のクラスを定義した。インスタンス化の際、3番目の添え字が遅延 を示す3次元配列を渡す。(In order to make polyphase matrix operations easier, the following classe is defined. At instantiation, plase pass a three-dimensional array where the third subscript indicates a delay.)

 PPMATRIX: Polyphase Matrix Class (originally from saivdr.dictionary.utility.PolyPhaseMatrix1D in SaivDr package)

分析合成処理 (Analysis and synthesis process)

z^(-1)

```
import msip.ppmatrix
  % Polyphase matrix of analysis bank
  e00 = reshape(e00,1,1,length(e00));
  e10 = reshape(e10,1,1,length(e10));
  E = ppmatrix(cat(1,e00,e10))
  E =
  0.5 + 0.5*z^{(-1)};
   0.5 - 0.5*z^{(-1)}
  % Polyphase matrix of synthesis bank
  r00 = reshape(r00,1,1,length(r00));
  r01 = reshape(r01,1,1,length(r01));
  R = ppmatrix(cat(2,r00,r01))
  R =
   0.5 + 0.5*z^{(-1)}, -0.5 + 0.5*z^{(-1)}
完全再構成条件の確認 (Confirmation of perfect reconstruction)
\mathbf{R}(z)\mathbf{E}(z) = (\mathbf{R}_0 + \mathbf{R}_1 z^{-1})(\mathbf{E}_0 + \mathbf{E}_1 z^{-1}) = \mathbf{R}_0 \mathbf{E}_0 + (\mathbf{R}_1 \mathbf{E}_0 + \mathbf{R}_0 \mathbf{E}_1)z^{-1} + \mathbf{R}_1 \mathbf{E}_1 z^{-2} = z^{-1} \mathbf{I}
  disp(R*E)
```

```
% Define delaychain
clear delaychain
delaychain(1,1,1) = 1;
delaychain = ppmatrix(delaychain)
delaychain =
[
1
]
% Z-transform of input
u = ppmatrix(reshape(u,1,1,length(u)));
disp(u)
[
3*z^{(-1)} + z^{(-2)} + 3*z^{(-3)} + z^{(-4)} + 5*z^{(-5)} + 3*z^{(-6)}
% Polyphase decomposition of input
x = delaychain*u;
disp(x)
3*z^{(-1)} + z^{(-2)} + 3*z^{(-3)} + z^{(-4)} + 5*z^{(-5)} + 3*z^{(-6)}
% Analysis process w/ the polyphase matrix
s = E*x;
disp(s)
1.5*z^{(-1)} + 2*z^{(-2)} + 2*z^{(-3)} + 2*z^{(-4)} + 3*z^{(-5)} + 4*z^{(-6)} + 1.5*z^{(-7)};
1.5*z^{(-1)} - z^{(-2)} + z^{(-3)} - z^{(-4)} + 2*z^{(-5)} - z^{(-6)} - 1.5*z^{(-7)}
]
% Synthesis process w/ the polyphase matrix
y = R*s;
disp(y)
3*z^{(-2)} + z^{(-3)} + 3*z^{(-4)} + z^{(-5)} + 5*z^{(-6)} + 3*z^{(-7)}
% Parallel/Serial conversion
v = delaychain.'*y;
disp(v)
3*z^{(-2)} + z^{(-3)} + 3*z^{(-4)} + z^{(-5)} + 5*z^{(-6)} + 3*z^{(-7)}
disp(squeeze(double(v)).')
```

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3

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0

3

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