Sample 9-3

離散ウェーブレット変換

重複変換のフィルタバンク実装

画像処理特論

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動作確認: MATLAB R2023a

Discrete wavelet transform

Filter bank implementation of lapped transforms

Advanced Topics in Image Processing

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Verified: MATLAB R2023a

準備

(Preparation)

```
close all
```

入力信号の生成

(Generation of input)

```
% Input signal
u = [ 0 3 1 3 1 5 3 0 ]; % Set to even length
```

並列フィルタバンク実装

(Parallel filter bank implementation)

分析フィルタバンクをデシメータで、合成フィルタバンクをインタポレータで実装 (Analysis filter banks are implemented with decimetors and synthesis filter banks are implemented with interpolators.)

```
% # of channels
nChs = 2;

% Analysis filters (Daubiches 2 wavelet filter)
h0 = [ (1-sqrt(3)) (3-sqrt(3)) (3+sqrt(3)) (1+sqrt(3)) ]/(4*sqrt(2));
h1 = [ -(1+sqrt(3)) (3+sqrt(3)) -(3-sqrt(3)) (1-sqrt(3)) ]/(4*sqrt(2));

% Synthesis filters (Daubiches 2 wavelet filter)
f0 = fliplr(h0);
f1 = fliplr(h1);
```

```
% Or the function WFILTERS from Wavelet Toolbox as
% [h0,h1,f0,f1] = wfilters('db2');

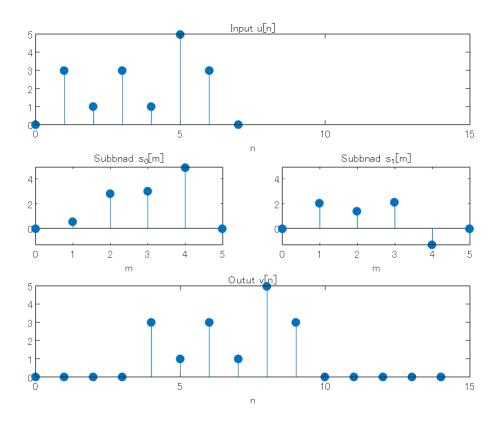
% Analysis process
s0 = downsample(conv(h0,u),nChs);
s1 = downsample(conv(h1,u),nChs);

% Synthesis process
v0 = conv(f0,upsample(s0,nChs));
v1 = conv(f1,upsample(s1,nChs));
v = v0 + v1;
```

信号表示

(Signal display)

```
figure(1)
% Input
subplot(3,2,[1,2])
stem(0:length(u)-1,u,'filled')
title('Input u[n]')
xlabel('n')
ax = gca;
ax.XLim =[ 0 length(v)];
% Subband 0
subplot(3,2,3)
stem(0:length(s0)-1,s0,'filled')
title('Subbnad s_0[m]')
xlabel('m')
ax = gca;
ax.YLim = [min([s0(:);s1(:)]) max([s0(:);s1(:)])];
% Subband 1
subplot(3,2,4)
stem(0:length(s1)-1,s1,'filled')
title('Subbnad s_1[m]')
xlabel('m')
ax = gca;
ax.YLim = [min([s0(:);s1(:)]) max([s0(:);s1(:)])];
% Output
subplot(3,2,[5,6])
stem(0:length(v)-1,v,'filled')
title('Outut v[n]')
xlabel('n')
ax = gca;
ax.XLim =[ 0 length(v)];
```

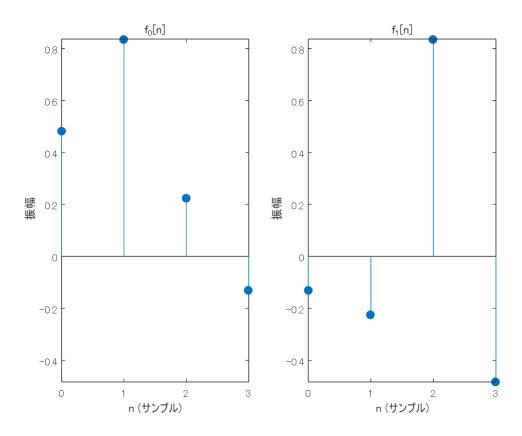


インパルス応答(局所基底ベクトル)

(Impluse responses of synthesis filters; local basis vectors)

```
figure(2)
% Low-pass filter
subplot(1,2,1)
impz(f0)
title('f_0[n]')
ax = gca;
ax.YLim =[ min([f0(:);f1(:)]) max([f0(:);f1(:)]) ];

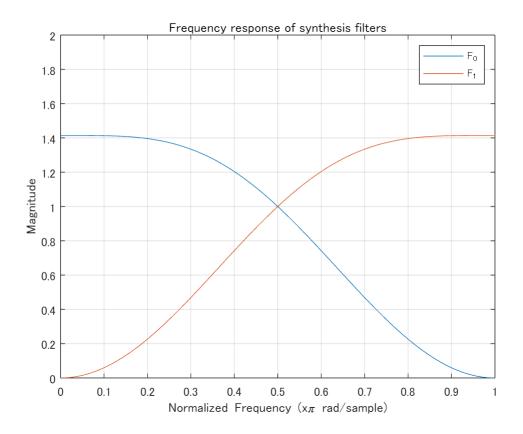
% High-pass filter
subplot(1,2,2)
impz(f1)
title('f_1[n]')
ax = gca;
ax.YLim =[ min([f0(:);f1(:)]) max([f0(:);f1(:)]) ];
```



周波数応答

(Frequency responses)

```
figure(3)
fftPoints = 512;
F = zeros(fftPoints,nChs);
% Low-pass filter
[F(:,1),W] = freqz(f0,1,fftPoints);
% High-pass filter
F(:,2) = freqz(f1,1,fftPoints);
plot(W/pi, abs(F)) %20*log10(abs(F)))
axis([0 1 0 ceil(sqrt(nChs))]) %-70 10])
xlabel('Normalized Frequency (x\pi rad/sample)')
ylabel('Magnitude') % (dB)')
title('Frequency response of synthesis filters')
legend({ 'F_0', 'F_1'})
grid on
```



ポリフェーズ行列実装

(Polyphase matrix implemenation)

フィルタバンクをポリフェーズフィルタに分解して、ポリフェーズ行列として実装 (Decompose the filter bank into polyphase filters and implement them in a polyphase matrix.)

$$\mathbf{E}(z) = \begin{pmatrix} h_0[0] & h_0[1] \\ h_1[0] & h_1[1] \end{pmatrix} + \begin{pmatrix} h_0[2] & h_0[3] \\ h_1[2] & h_1[3] \end{pmatrix} z^{-1} = \begin{pmatrix} h_0[0] + h_0[2]z^{-1} & h_0[1] + h_0[3]z^{-1} \\ h_1[0] + h_1[2]z^{-1} & h_1[1] + h_1[3]z^{-1} \end{pmatrix}$$

$$\mathbf{R}(z) = \begin{pmatrix} f_0[1] & f_1[1] \\ f_0[0] & f_1[0] \end{pmatrix} + \begin{pmatrix} f_0[3] & f_1[3] \\ f_0[2] & f_1[2] \end{pmatrix} z^{-1} = \begin{pmatrix} f_0[1] + f_0[3]z^{-1} & f_1[1] + f_1[3]z^{-1} \\ f_0[0] + f_0[2]z^{-1} & f_1[0] + f_1[2]z^{-1} \end{pmatrix}$$

```
% Type-I polyphase filters of analyzer
e00 = h0(1:nChs:end);
e01 = h0(2:nChs:end);
e10 = h1(1:nChs:end);
e11 = h1(2:nChs:end);

% Type-II polyphase filters of synthesizer
r00 = f0(2:nChs:end);
r10 = f0(1:nChs:end);
r01 = f1(2:nChs:end);
r11 = f1(1:nChs:end);
```

```
% Input Signal
 uadj = [zeros(1,nChs-1) u 0]; % Adjust delay for downsampling
 disp(uadj)
      0
            0
                 3
                                  1
                                        5
                                              3
                                                   0
                                                         0
 % Serial/Pallalel conversion
 phase = 0;
 u0 = downsample(uadj,nChs,mod(nChs-1-phase,nChs));
 phase = 1;
 u1 = downsample(uadj,nChs,mod(nChs-1-phase,nChs));
 x = [u0;
        u1 ];
 disp(x)
            3
                 3
 (補足) z-変換の定義 (Definition of z-transform)
X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n}
畳み込みとの関係 (Relation to convolution)
y[n] = h[n] * x[n] \leftrightarrow Y(z) = H(z)X(z)
 % Analysis process w/ the polyphase matrix
 % s = E*x
 s0 = conv(e00,u0) + conv(e01,u1);
 s1 = conv(e10,u0) + conv(e11,u1);
 disp([s0;s1])
          0
               0.5430
                        2.8284
                                 3.0179
                                           4.9244
                        1.4142
               2.0266
                                 2.1213
                                          -1.3195
 % Synthesis process w/ the polyphase matrix
 % v = R*s
 v0 = conv(r00, s0) + conv(r01, s1);
 v1 = conv(r10,s0) + conv(r11,s1);
 disp([v0;v1])
          0
                                                                  0
               0.0000
                        1.0000
                                 1.0000
                                           3.0000
                                                    0.0000
          0
               0.0000
                        3.0000
                                 3.0000
                                           5.0000
                                                    0.0000
 % Parallel/Serial conversion
 v = upsample(v0,nChs,1) + upsample(v1,nChs,0);
 disp(v)
          0
                        0.0000
                                 0.0000
                                           3.0000
                                                    1.0000
                                                              3.0000
                                                                       1.0000
                                                                                5.0000
                                                                                          3.0000
                                                                                                   0.0000
```

ポリフェーズ行列実装(PPMATRIX オブジェクト利用)

(Polyphase matrix implemenation with PPMATRIX object)

ポリフェーズ行列演算が簡便となるよう以下のクラスを定義した。インスタンス化の際、3 番目の添え字が遅延を示す 3 次元配列を渡す。(In order to make polyphase matrix operations easier, the following classe is defined. At instantiation, plase pass a three-dimensional array where the third subscript indicates a delay.)

• PPMATRIX : Polyphase Matrix Class (originally from saivdr.dictionary.utility.PolyPhaseMatrix1D in SaivDr package)

分析合成処理 (Analysis and synthesis process)

clear delaychain

delaychain(1,1,1) = 1;delaychain(2,1,2) = 1;

```
import msip.ppmatrix
  % Polyphase matrix of analysis bank
  e00 = reshape(e00,1,1,length(e00));
  e01 = reshape(e01,1,1,length(e01));
  e10 = reshape(e10,1,1,length(e10));
  e11 = reshape(e11,1,1,length(e11));
  E = ppmatrix(cat(1, cat(2, e00, e01), cat(2, e10, e11)))
  E =
  0.22414 + 0.48296*z^{(-1)};
      -0.12941 + 0.83652*z^{(-1)}
      -0.48296 - 0.22414*z^{(-1)}
                                      0.83652 - 0.12941*z^{(-1)}
  1
  % Polyphase matrix of synthesis bank
  r00 = reshape(r00,1,1,length(r00));
  r10 = reshape(r10,1,1,length(r10));
  r01 = reshape(r01,1,1,length(r01));
  r11 = reshape(r11,1,1,length(r11));
  R = ppmatrix(cat(1, cat(2, r00, r01), cat(2, r10, r11)))
  R =
  [
      0.83652 - 0.12941*z^{(-1)}
                                     -0.22414 - 0.48296*z^{(-1)};
      0.48296 + 0.22414*z^{(-1)}
                                     -0.12941 + 0.83652*z^{(-1)}
完全再構成条件の確認 (Confirmation of perfect reconstruction)
\mathbf{R}(z)\mathbf{E}(z) = (\mathbf{R}_0 + \mathbf{R}_1 z^{-1})(\mathbf{E}_0 + \mathbf{E}_1 z^{-1}) = \mathbf{R}_0 \mathbf{E}_0 + (\mathbf{R}_1 \mathbf{E}_0 + \mathbf{R}_0 \mathbf{E}_1)z^{-1} + \mathbf{R}_1 \mathbf{E}_1 z^{-2} = z^{-1} \mathbf{I}
  disp(R*E)
  5.5511e-17 + 1*z^{-1} + 5.5511e-17*z^{-2}
            5.5511e-17 + 1*z^{-1} + 5.5511e-17*z^{-2}
  1
  % Define delaychain
```

```
delaychain = ppmatrix(delaychain)
delaychain =
[
    1;
    z^(-1)
1
% Z-transform of input
u = ppmatrix(reshape(u,1,1,length(u)));
disp(u)
3*z^{(-1)} + z^{(-2)} + 3*z^{(-3)} + z^{(-4)} + 5*z^{(-5)} + 3*z^{(-6)}
]
% Polyphase decomposition of input
x = downsample(delaychain*u,nChs);
disp(x)
z^{(-1)} + z^{(-2)} + 3*z^{(-3)};
    3*z^{(-1)} + 3*z^{(-2)} + 5*z^{(-3)}
1
% Analysis process w/ the polyphase matrix
s = E*x;
disp(s)
0.54302*z^{(-1)} + 2.8284*z^{(-2)} + 3.0179*z^{(-3)} + 4.9244*z^{(-4)};
    2.0266*z^{(-1)} + 1.4142*z^{(-2)} + 2.1213*z^{(-3)} - 1.3195*z^{(-4)}
]
% Synthesis process w/ the polyphase matrix
y = R*s;
disp(y)
[
    1.6653e-16*z^{(-1)} + z^{(-2)} + z^{(-3)} + 3*z^{(-4)} + 2.2204e-16*z^{(-5)};
    2.2204e-16*z^{-1} + 3*z^{-2} + 3*z^{-3} + 5*z^{-4} + 2.2204e-16*z^{-5}
]
% Parallel/Serial conversion
v = delaychain.'*upsample(y,nChs);
disp(v)
[
    2.2204e-16*z^{-2} + 1.6653e-16*z^{-3} + 3*z^{-4} + z^{-5} + 3*z^{-6} + z^{-7} + 5*z^{-8} + 3*z^{-9} + 2.2204e-16
1
disp(squeeze(double(v)).')
                       0.0000
                                 0.0000
                                           3.0000
        0
                                                     1.0000
                                                               3.0000
                                                                         1.0000
                                                                                   5.0000
                                                                                             3.0000
                                                                                                      0.0000
                                                                                                                0
```

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