Sample 4-4

線形シフト不変システム

循環シフト

画像処理特論

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動作確認: MATLAB R2023a

Linear shift-invariant systems

Circular shift

Advanced Topics in Image Processing

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Verified: MATLAB R2023a

準備

(Preparation)

close all

単変量循環シフト

(Univariate circular shift)

単変量の有限なサポート領域をもつ配列 $\{u[n] \in \mathbb{K}\}_{n \in \Omega_{\mathbf{u}} \subset \mathbb{Z}}$ の循環シフトは, (The circular shift of sequences with univariate finite support region can be represented as)

$$\{v[n]\}_n = T(\{u[n]\}_n) = \{u[((n-k))_Q]\}_n,$$

のように表現できる.ここで, $Q \in \mathbb{N}$ は周期, $\{v[n] \in \mathbb{K}\}_{n \in \Omega \subset \mathbb{Z}}$ は出力配列,(where $Q \in \mathbb{N}$ is the period, $\{v[n] \in \mathbb{K}\}_{n \in \Omega \subset \mathbb{Z}}$ is the destination sequence and)

$$((n))_Q = n - Q \lfloor Q^{-1} n \rfloor.$$

は、Qを法とする n の剰余である. (denotes the n modulo Q.)

【Example】(In case of) Q = 6, k = 1 の場合:

$$(v[0] \ v[1] \ v[2] \ v[3] \ v[4] \ v[5])$$

= $T(u[0] \ u[1] \ u[2] \ u[3] \ u[4] \ u[5]) = (u[5] \ u[0] \ u[1] \ u[2] \ u[3] \ u[4])$

信号の生成

(Signal generation)

```
% Generating an input sequence u[n] of finite support region
Q = 6;
ugen = "(0:Q-1)";
u = eval(ugen)
```

```
u = 1 \times 6
0 1 2 3 4 5
```

シフト量の設定

(Setting the shift amount)

```
% Setting the shift amount
k = 1;
```

写像の定義

(Definition of a map)

```
% Definition of map T as a circular shift
mapT = @(x) circshift(x,k);
```

写像

(Mapping)

```
% Mapping with the circular shift T(.)
v = mapT(u)
```

```
v = 1 \times 6
5 0 1 2 3 4
```

循環シフトの行列表現

(Matrix representation of the circular shift)

```
Q=6,\ k=1 の循環シフトは (The circular shift of Q=6,\ k=1 can be represented as a matrix as) {f v}={f T}{f u},
```

のように行列表現できる. ただし, (where)

$$\mathbf{v} = \text{vec}(\{v[n]\}_n) = \begin{pmatrix} v[0] \\ v[1] \\ v[2] \\ v[3] \\ v[4] \\ v[5] \end{pmatrix}, \mathbf{u} = \text{vec}(\{u[n]\}_n) = \begin{pmatrix} u[0] \\ u[1] \\ u[2] \\ u[3] \\ u[4] \\ u[5] \end{pmatrix}$$

$$\mathbf{T} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}.$$

循環シフトの行列生成

(Circular shift matrix generation)

行列演算による単変量循環シフト

(Univariate circular shift by matrix operation)

循環シフトは可換図に沿って (Circular shifts can be computed as)

$$\{v[n]\}_n = \operatorname{vec}_{\Omega_v}^{-1}(\mathbf{v}) = \operatorname{vec}_{\Omega_v}^{-1}(\mathbf{T}\mathbf{u}) = \operatorname{vec}_{\Omega_v}^{-1} \circ \mathbf{T} \operatorname{vec}_{\Omega_u}(\{u[n]\}_n)$$

のように行列演算が可能である. すなわち, (along the commutative diagram. That is, we have)

```
T = \operatorname{vec}_{\Omega_{\mathbf{v}}}^{-1} \circ \mathbf{T} \operatorname{vec}_{\Omega_{\mathbf{u}}}.
```

と表現できる.

```
% Column vectorization of sequence u[n]
vecu = u(:);

% Matrix operation
vecv = T*vecu;

% Reshaping the result into the original
recv = reshape(vecv,[1 Q])
recv = 1×6
```

行列演算による単変量循環シフトの評価

(Evaluation of univariate circular shift by matrix operation)

```
% Comparizon between mapping and matrix operation
mymse = @(x,y) mean((double(x)-double(y)).^2,'all');
mymse(v,recv)
```

ans = 0

2変量循環シフト

(Bivariate circular shift)

2 変量の有限なサポート領域をもつ配列 $\{u[\mathbf{n}] \in \mathbb{K}\}_{\mathbf{n} \in \Omega_\mathbf{u} \subset \mathbb{Z}^2}$ の循環シフトは, (The circular shift of arrays with bivariate finite support region can be represented as)

$$\{v[\mathbf{n}]\}_{\mathbf{n}} = T(\{u[\mathbf{n}]\}_{\mathbf{n}}) = \{u[((\mathbf{n} - \mathbf{k}))_{\mathbf{O}}]\}_{\mathbf{n}},$$

のように表現できる. ただし、 $\mathbf{Q} \in \mathbb{Z}^{2 \times 2}(\det \mathbf{Q} \neq 0)$ は周期行列、 $\{\nu[\mathbf{n}] \in \mathbb{K}\}_{\mathbf{n} \in \Omega \subset \mathbb{Z}^2}$ は出力配列、(where $\mathbf{Q} \in \mathbb{Z}^{2 \times 2}(\det \mathbf{Q} \neq 0)$ is the period matrix, $\{\nu[\mathbf{n}] \in \mathbb{K}\}_{\mathbf{n} \in \Omega \subset \mathbb{Z}^2}$ is the destination array and)

$$((\mathbf{n}))_{\mathbf{Q}} = \mathbf{n} - \mathbf{Q} |\mathbf{Q}^{-1}\mathbf{n}|$$

は、 Qを法とする n の剰余である. (denotes the n modulo Q.)

【Example】(In case of)
$$\mathbf{Q} = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$$
, $\mathbf{k} = \begin{pmatrix} k_1 & k_2 \end{pmatrix}^T = \begin{pmatrix} 1 & 2 \end{pmatrix}^T$ の場合:

```
 \begin{pmatrix} v[0,0] & v[0,1] & v[0,2] \\ v[1,0] & v[1,1] & v[1,2] \end{pmatrix} 
 = T \begin{pmatrix} u[0,0] & u[0,1] & u[0,2] \\ u[1,0] & u[1,1] & u[1,2] \end{pmatrix} = \begin{pmatrix} u[1,1] & u[1,2] & u[1,0] \\ u[0,1] & u[0,2] & u[0,0] \end{pmatrix}
```

信号の生成

(Signal generation)

```
% Generating an input array u[n1,n2] of finite support region
N1 = 2; % # of rows
N2 = 3; % # of columns
ugen = "reshape((0:N1*N2-1),[N1 N2])";
u = eval(ugen)
```

```
u = 2 \times 3
0 2 4
1 3 5
```

シフト量の設定

(Setting the shift amount)

```
% Settings of the shift amount
k1 = 1; % # of shifts in the vertical direction
k2 = 2; % # of shifts in the horizontal direction
```

写像の定義

(Definition of a map)

```
% Definition of map T as a circular shift
mapT = @(x) circshift(x,[k1,k2]);
```

写像

(Mapping)

```
% Mapping with the circular shift T(.)
v = mapT(u)
```

```
v = 2 \times 3
3 	 5 	 1
2 	 4 	 0
```

循環シフトの行列表現

(Matrix representation of the circular shift)

 $\mathbf{Q} = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$, $\mathbf{k} = \begin{pmatrix} k_1 & k_2 \end{pmatrix}^T = \begin{pmatrix} 1 & 2 \end{pmatrix}^T$ の循環シフトは (The circular shift of $\mathbf{Q} = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$, $\mathbf{k} = \begin{pmatrix} k_1 & k_2 \end{pmatrix}^T = \begin{pmatrix} 1 & 2 \end{pmatrix}^T$ can be represented as a matrix as)

v = Tu,

のように行列表現できる. ただし, (where)

$$\mathbf{v} = \text{vec}(\{v[\mathbf{n}]\}_{\mathbf{n}}) = \begin{pmatrix} v[0,0] \\ v[1,0] \\ v[0,1] \\ v[1,1] \\ v[0,2] \\ v[1,2] \end{pmatrix}, \mathbf{u} = \text{vec}(\{u[\mathbf{n}]\}_{\mathbf{n}}) = \begin{pmatrix} u[0,0] \\ u[1,0] \\ u[0,1] \\ u[0,1] \\ u[1,1] \\ u[0,2] \\ u[1,2] \end{pmatrix},$$

$$\mathbf{T} = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

循環シフトの行列生成

(Circular shift matrix generation)

```
% Find the matrix representation of the circular shift
T = zeros(numel(u));
for idx = 1:numel(u)
    % Generating a standard basis vector
    e = zeros(size(u),'like',u);
    e(idx) = 1;
    % Response to the standard basis vector
    T(:,idx) = reshape(mapT(e),[size(T,1) 1]);
end
% Matrix representation of the circular shift
T
```

行列演算による2変量循環シフト

(Bivariate circular shift by matrix operation)

循環シフトは可換図に沿って (Circular shifts can be computed as)

$$\{\nu[\mathbf{n}]\}_{\mathbf{n}} = \mathrm{vec}_{\Omega_{\mathbf{v}}}^{-1}(\mathbf{v}) = \mathrm{vec}_{\Omega_{\mathbf{v}}}^{-1}(\mathbf{T}\mathbf{u}) = \mathrm{vec}_{\Omega_{\mathbf{v}}}^{-1} \circ \mathbf{T} \mathrm{vec}_{\Omega_{\mathbf{u}}}(\{u[\mathbf{n}]\}_n)$$

のように行列演算が可能である. すなわち, (along the commutative diagram. That is, we have)

$$T = \operatorname{vec}_{\Omega_{\mathbf{v}}}^{-1} \circ \operatorname{Tvec}_{\Omega_{\mathbf{u}}}.$$

と表現できる.

```
% Column vectorization of sequence u[n]
vecu = u(:);

% Matrix operation
vecv = T*vecu;

% Reshaping the result into the original
recv = reshape(vecv,[N1 N2])
```

```
recv = 2×3
3 5 1
2 4 6
```

行列演算による単変量循環シフトの評価

(Evaluation of univariate circular shift by matrix operation)

```
% Comparizon between mapping and matrix operation
mymse(v,recv)
```

ans = 0

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