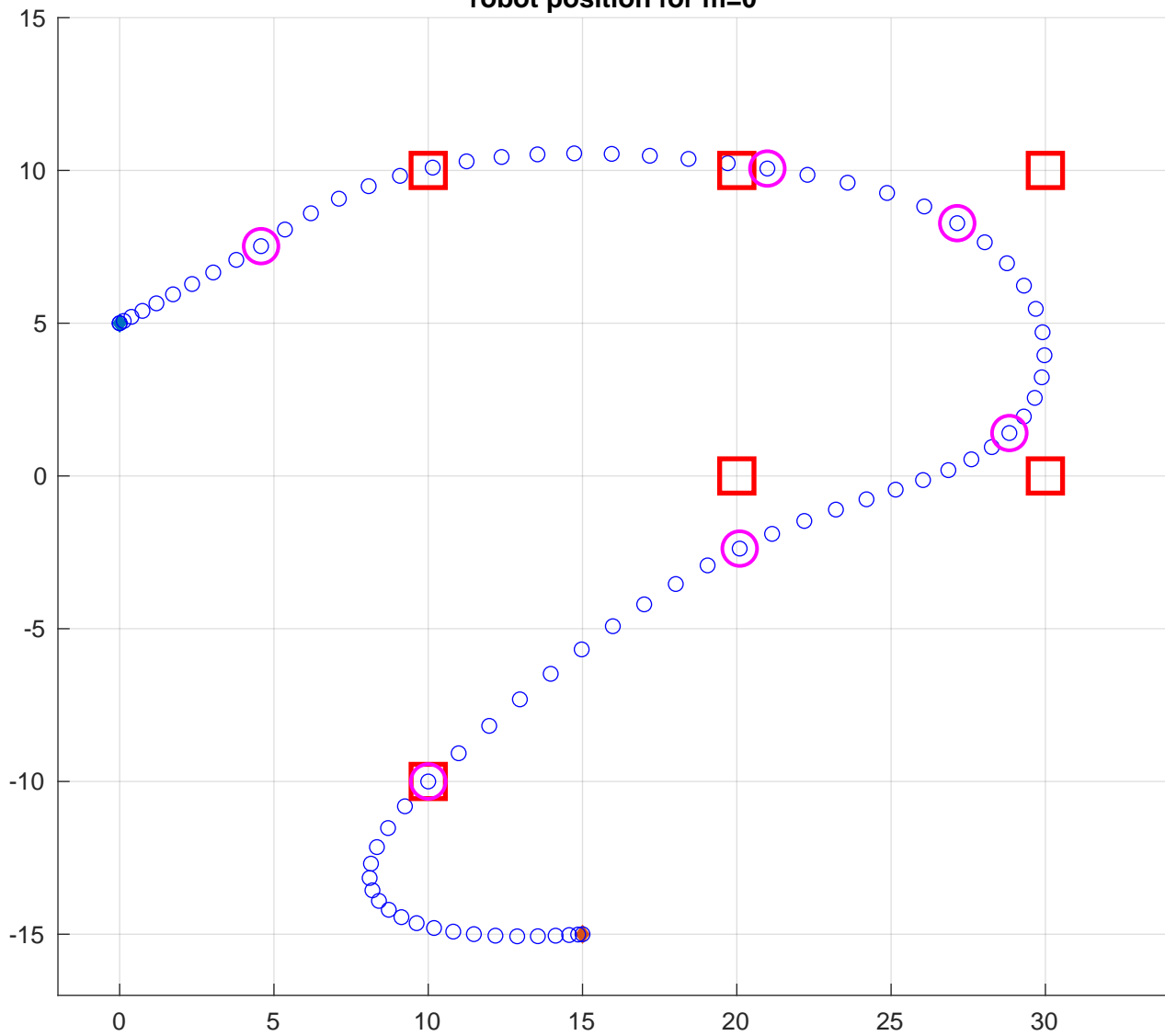


robot position for $m=0$ 

captured 1, dev 2.41569

