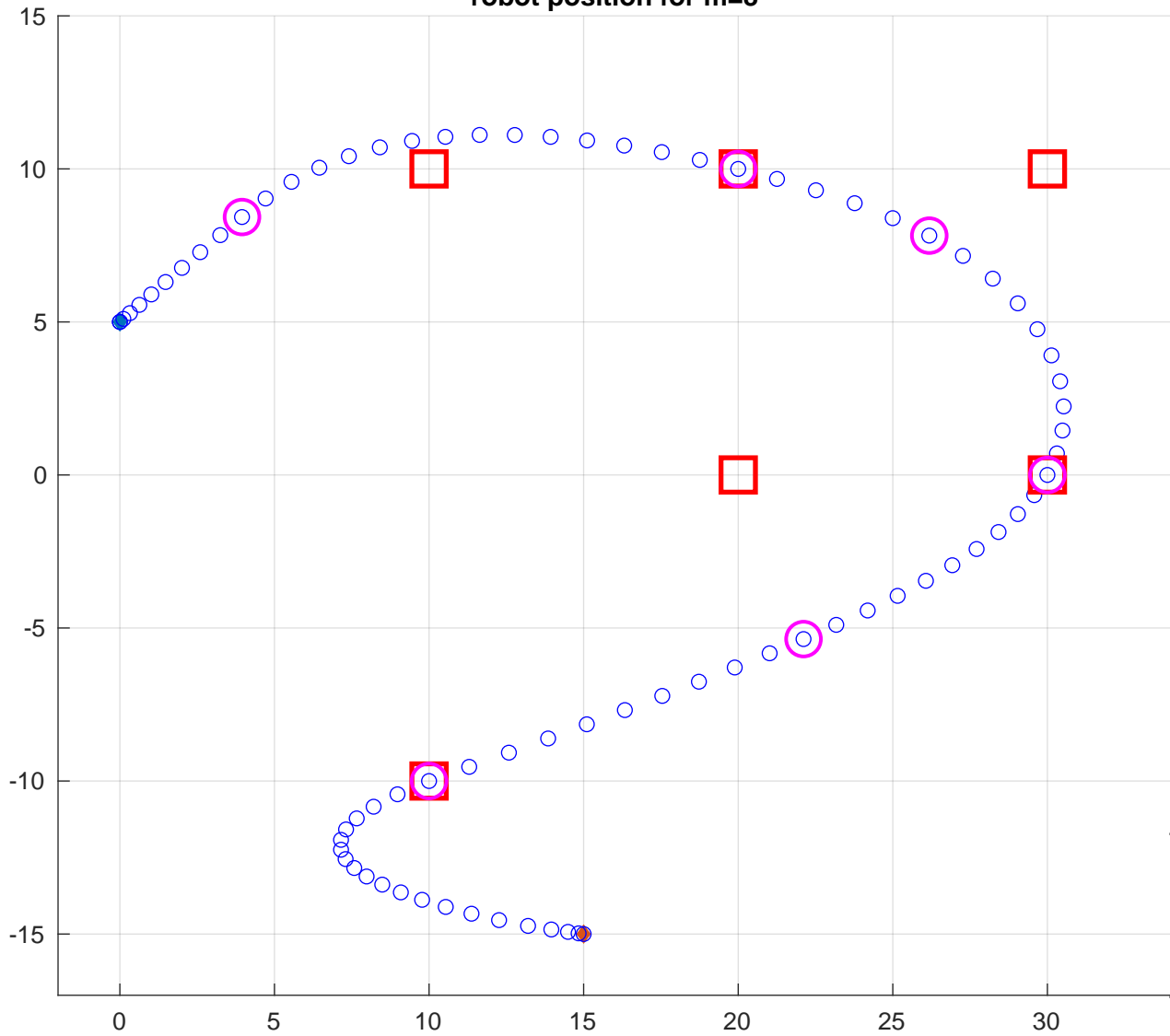


robot position for  $m=8$ 

captured 3, dev 2.73546

