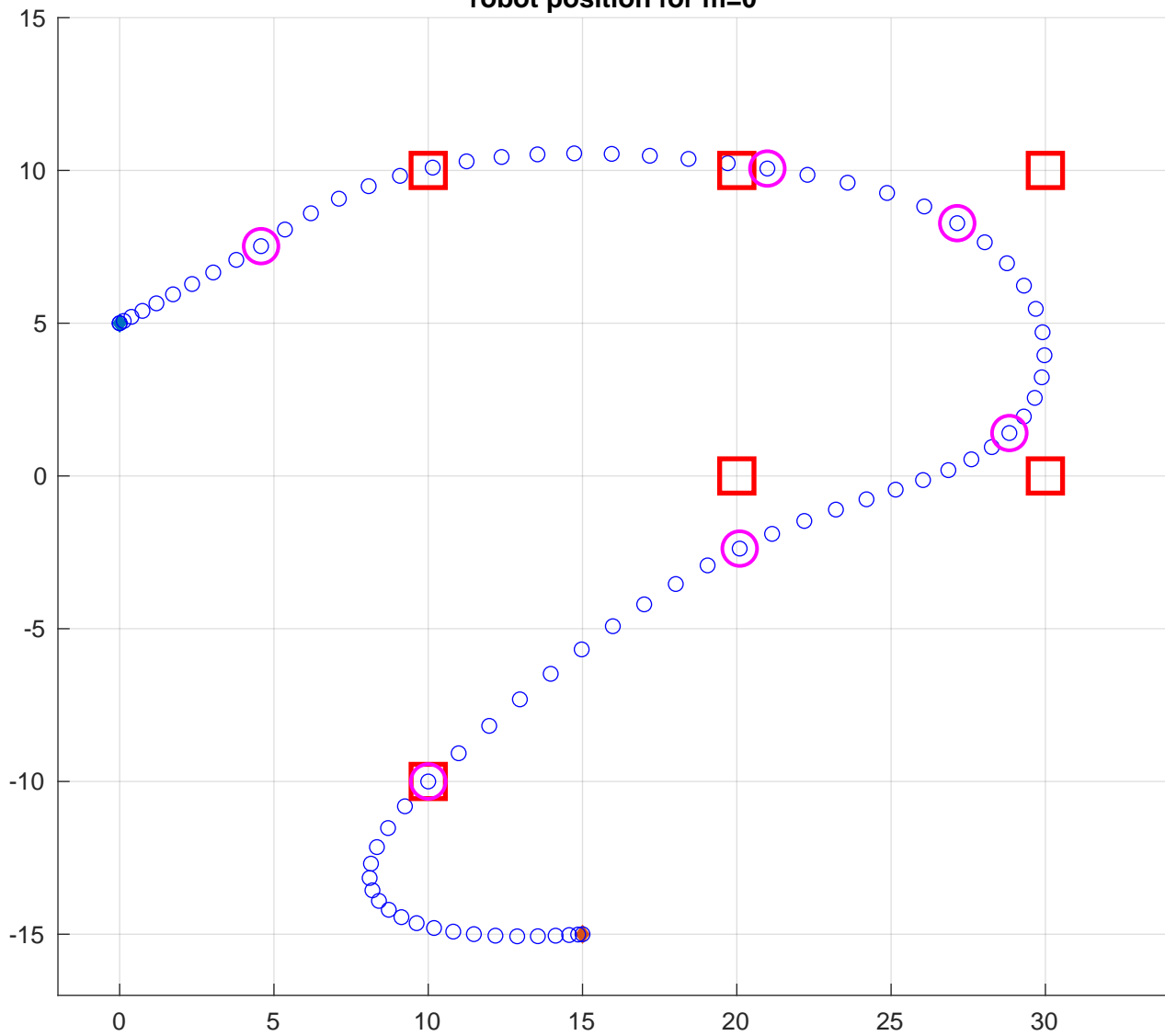


robot position for m=0



captured 1, dev 2.41569

