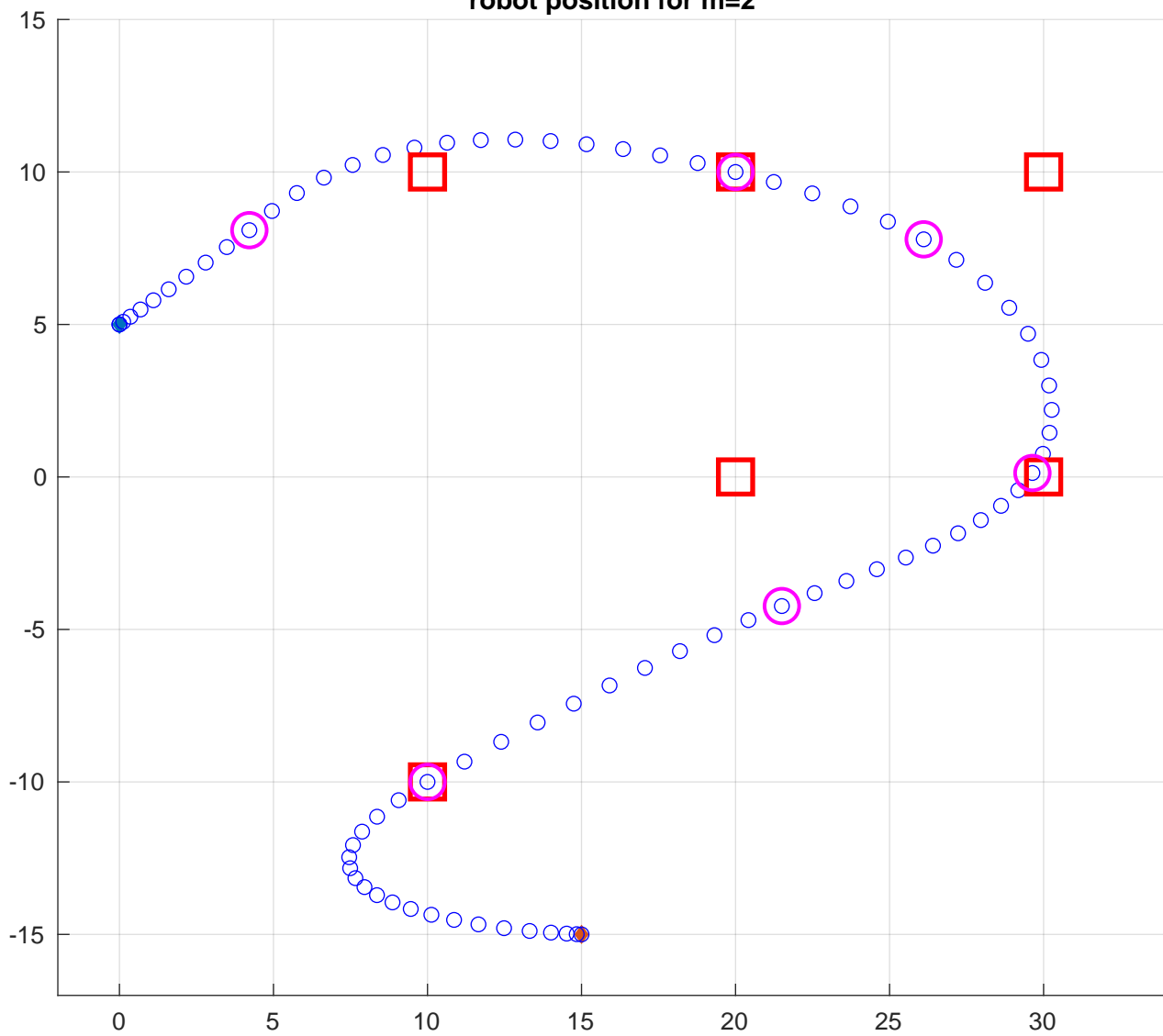


robot position for  $m=2$ 

captured 2, dev 2.57366

