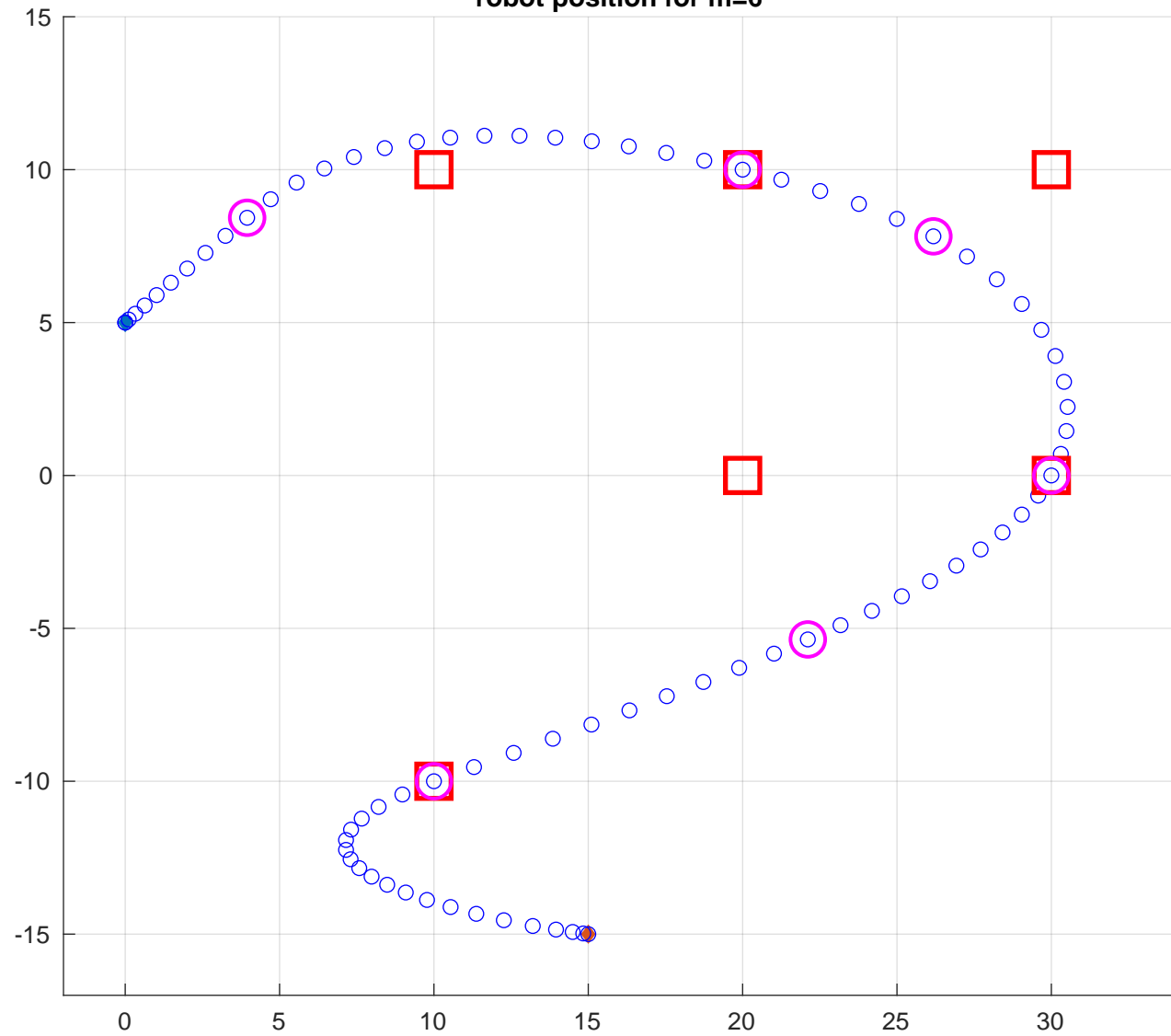


robot position for $m=6$ 

captured 3, dev 2.73546

