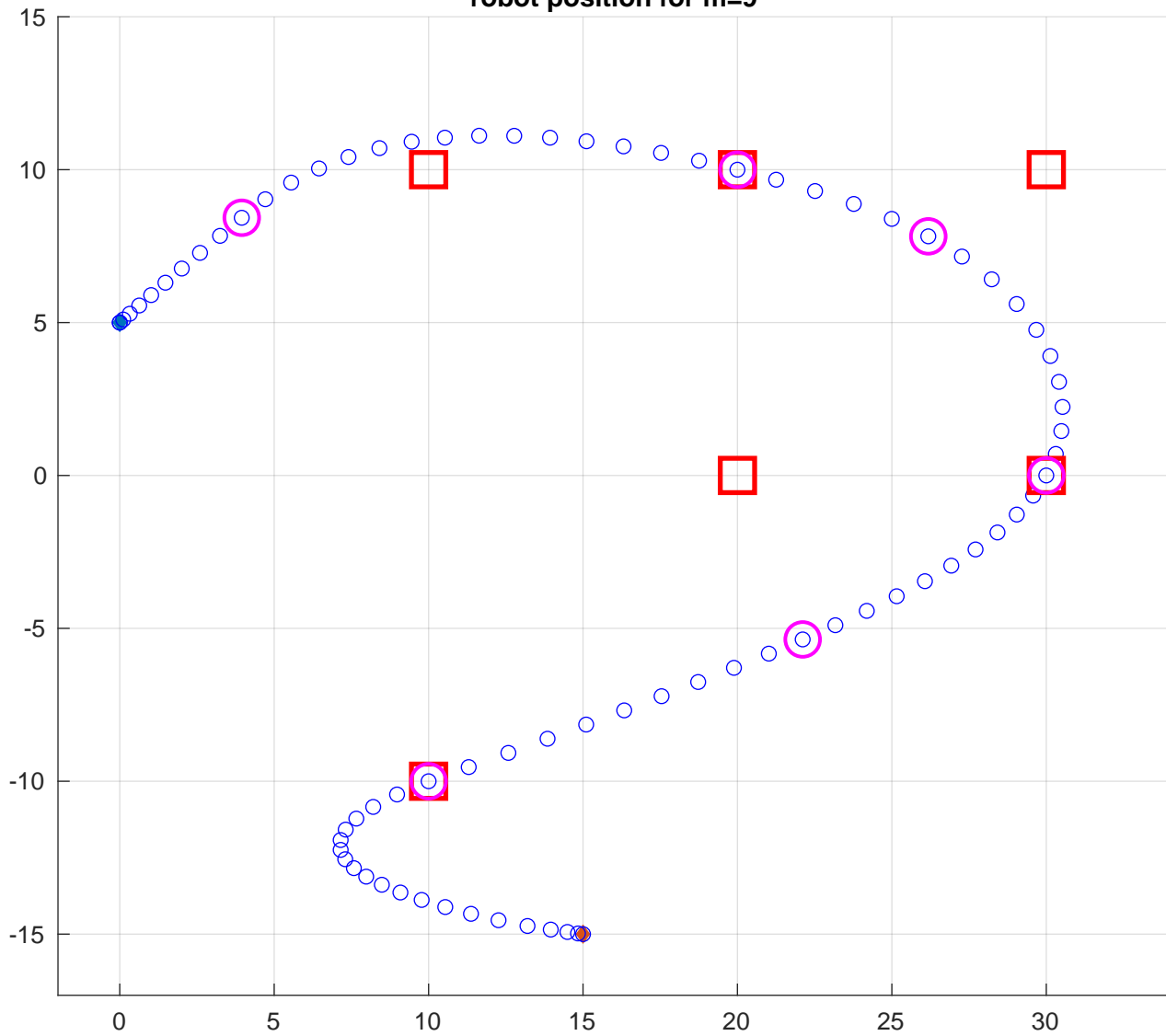


robot position for  $m=9$ 

captured 3, dev 2.73546

