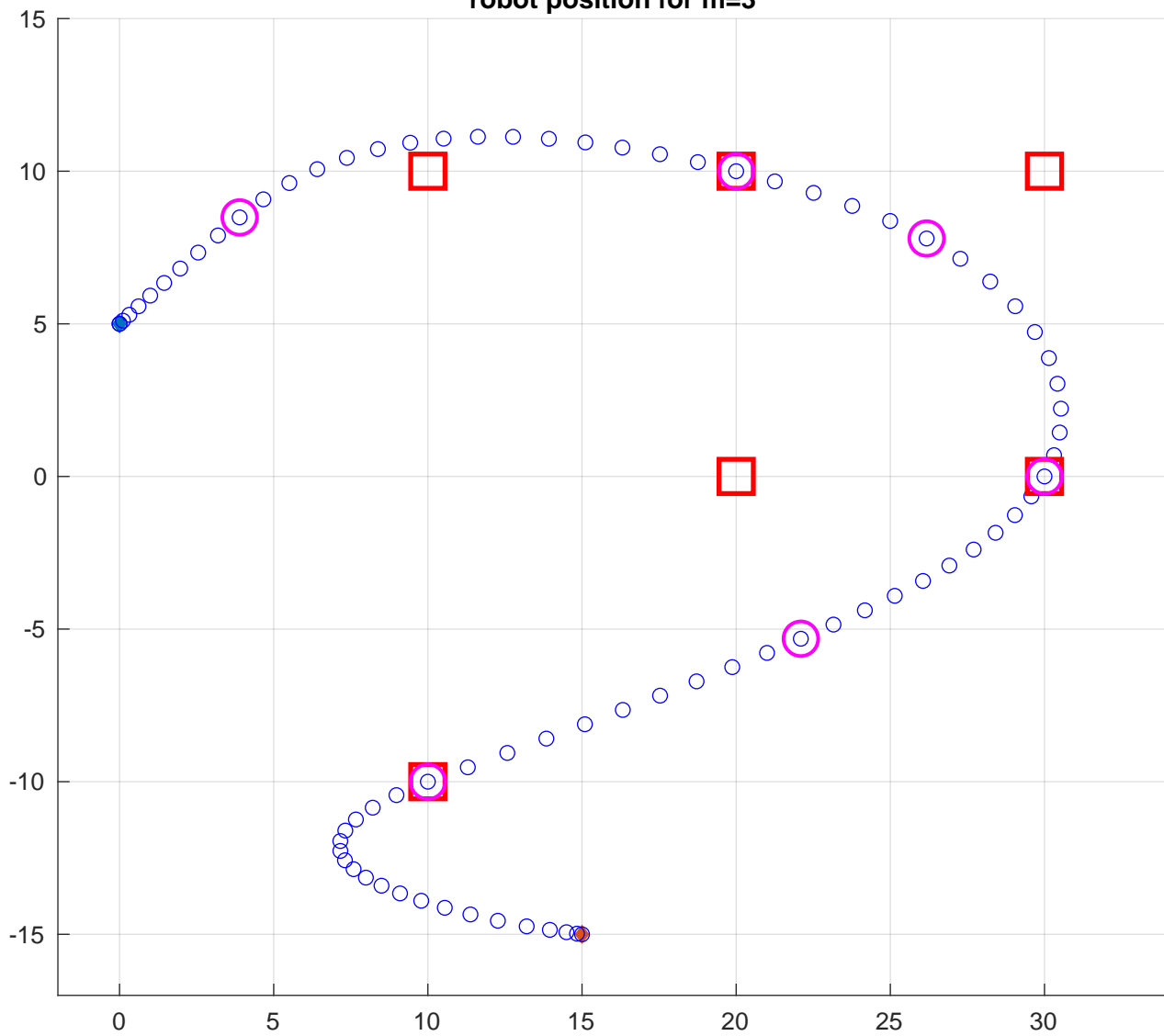


robot position for $m=3$ 

captured 3, dev 2.73622

