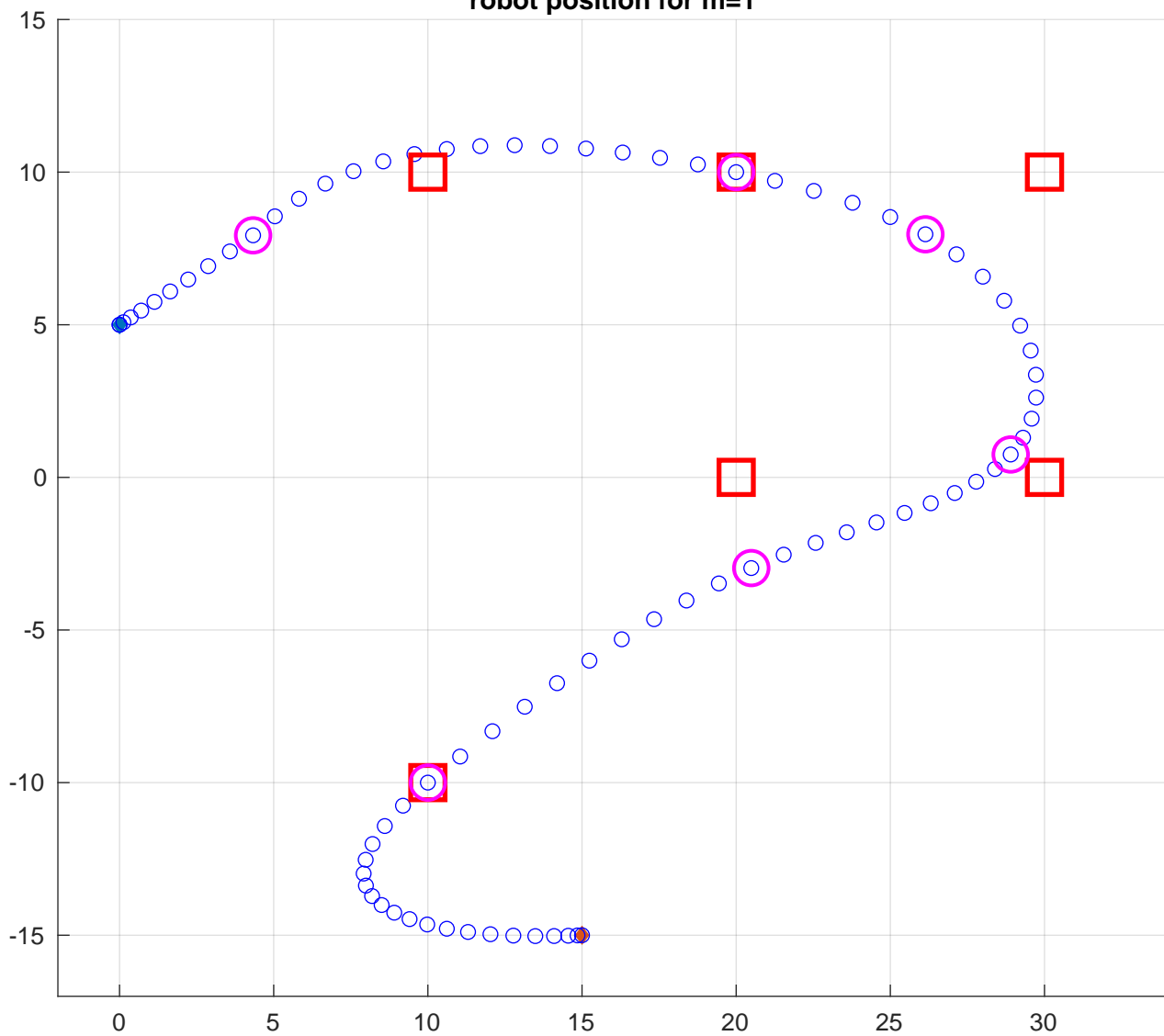


robot position for  $m=1$ 

captured 2, dev 2.45674

