

---

## Table of Contents

Description .....	1
General Variables .....	1
Input Variables .....	2
Generate Gaussian Input Beam .....	2
Target Image .....	2
Phase Initialization Step .....	3
Perform Gerchberg - Saxton (GS) Algorithm (check wikipedia for pseudo code) .....	5
Calibration Section by Dae Gwang .....	5
Figure of Calibrated CGH .....	6
Setting the position, magnification, etc. of the CGH .....	6
Show Result .....	7

## Description

```
%title: Hybrid Algorithm
%desc: an IFTA to determine phase distribution in CGH for beam shaping
%using amplitude freedom in certain region
%author: Muhammad Syahman Samhan
%email: mssamhan@students.itb.ac.id
%last update: November 21, 2019
%adapted from Gerchberg and Saxton (1971), Pasienski & DeMarco (2008),
%Gaunt A. L. & Hadzibabic Z. (2012), and Zhou W. (2018).
%inspired from
    %1. Musa Aydin (Sultan Mehmet Vakif University)
    %2. Dae Gwang Choi (KAIST, 2019)
    %3. Pasienski & DeMarco (2008)
```

## General Variables

```
clc
clear all
close all
pixelx = 1024;
pixely = 1024;
padx = 2*pixelx;
pady = 2*pixely;
sizex = 0.432;
sizey = 0.432;
mu = 0;
B_lin = 0;
x = linspace(-sizex, sizex, padx);
y = linspace(-sizey, sizey, pady);
[X,Y] = meshgrid(x,y); %meshgrid for Input Beam
slmaperture = (X > -sizex/2 & X < sizex/2 & Y > -sizey/2 & Y <
    sizey/2);
x0=0; y0=0; %center of CGH and Input Beam
tilt = 0; %only if needed later
```

---

```

i_num = 15;           %number of iteration of GS and of SOMRAF
error = [];           %error array is empty for first

```

## Input Variables

```

R = 200;
B_con = 0;
aspect_ratio = 1;
m = 0.98;
offset = 1;
kernel_waist = 100;
sigma = 0.74;         %beam waist in cm
    (need to be corrected)

```

## Generate Gaussian Input Beam

```

A = 1;                %input amplitude
theta = ((X-x0).^2 + (Y-y0).^2)./(2*sigma^2); %phase of Input beam
input = A*exp(-theta); %input amplitude for a
    given position

```

## Target Image

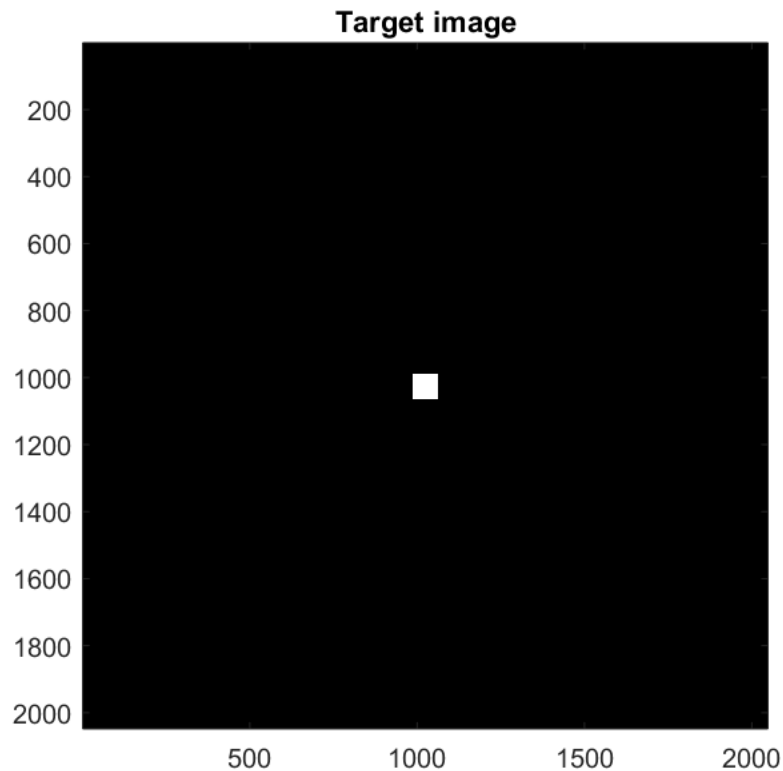
```

Target_Ori = rgb2gray(imread('square.bmp')); %target image input
Target = double(Target_Ori); %changing the target into
    matrix of doubles with precision

figure %Original Target Image
    imagesc(Target), axis image, colormap('gray');
    title('Target image')

SR_Ori = rgb2gray(imread('SR.bmp')); %signal region
    input
threshold = 0.5;
SR = (double(SR_Ori) >= threshold); %change signal
    region into matrix of 1 and 0
NR = 1-SR; %noise region =
    outside of signal region
MR = SR; %measure region to
    measure the RMS error
N_m = nnz(MR);
Target_m = MR.*Target;
Target = sqrt(Target.^2 + offset^2);

```

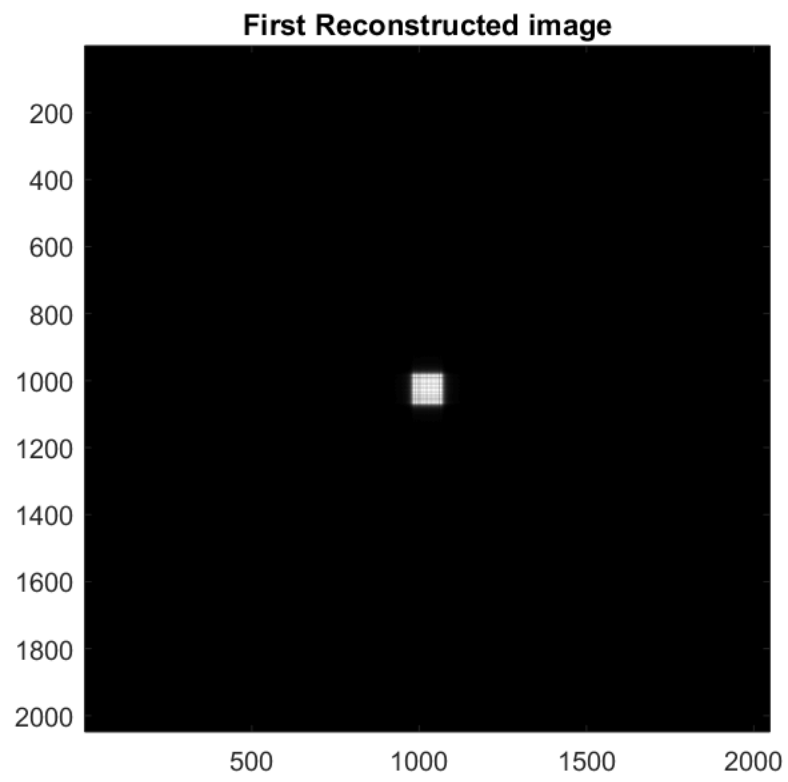
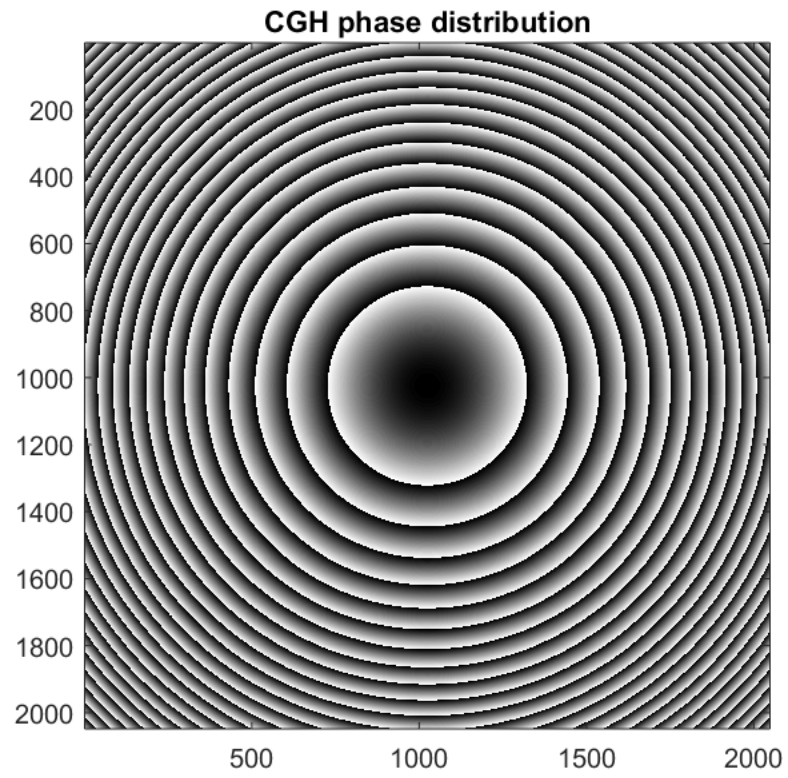


## Phase Initialization Step

```
%A = fftshift(iff2(fftshift(Target))); %performing GS initialization
step, IFFT
% Notes: 2 times fftshift is used to shift the matrix (q1<->q3, q2<-
>q4)

alpha = aspect_ratio/(1+aspect_ratio);
A_quad = 4*R*(alpha*X.^2 + (1-alpha)*Y.^2);
A_lin = B_lin*(X*cos(mu) + Y*sin(mu));
A_con = B_con*sqrt(X.^2+Y.^2);
A = mod(A_quad + A_con + A_lin ,2*pi);
B = abs(input).*exp(1i*A);
C = fftshift(fft2(fftshift(B)));
figure %CGH Phase Distribution Result
    imagesc(abs(A)), axis image, colormap('gray');
    title('CGH phase distribution');

%
figure %First Reconstructed Image
    imagesc(abs(C)), axis image, colormap('gray');
    title('First Reconstructed image')
```



---

## Perform Gerchberg - Saxton (GS) Algorithm (check wikipedia for pseudo code)

```
for i=1:i_num
    D = abs(Target).*exp(1i*angle(C));
    A = fftshift(ifft2(fftshift(D)));
    B = abs(input).*exp(1i*angle(A));
    C = fftshift(fft2(fftshift(B)));
    %Error Calculation: Root Mean Square Error of Measure Region
    C_m = MR.*C;
    error_cur = sqrt((1/N_m)*sum(sum(((abs(C_m)./
max(max(abs(C_m)))) - abs(Target_m)./max(max(abs(Target_m))))).^2 ) ));
    error = [error; error_cur];
end

for i=i_num+1 : 2*i_num
    D = (m*abs(Target).*SR + (1-m)*abs(C).*NR).*exp(1i*angle(C)); %the
    main line of MRAF algorithm
    A = fftshift(ifft2(fftshift(D)));
    B = abs(input).*exp(1i*angle(A));
    C = fftshift(fft2(fftshift(B)));
    %Error Calculation: Root Mean Square Error of Measure Region
    C_m = MR.*C;
    error_cur = sqrt((1/N_m)*sum(sum(((abs(C_m)./
max(max(abs(C_m)))) - abs(Target_m)./max(max(abs(Target_m))))).^2 ) ));
    error = [error; error_cur];
end
```

## Calibration Section by Dae Gwang

```
Crop=angle(A)+pi; % change range, from -pi to pi into 0 to 2pi
aaaa=136; % maximum gray level for 2pi phase shift (depends
on SLM)
Crop=floor(aaaa.*Crop./(2.0*pi)); % converting the phase shift into
gray level

% This line changes the black into the white
for j=1:pady
    for k=1:padx
        if Crop(j,k) == 0;
            Crop(j,k)=aaaa;
        end
    end
end

% This line is the main calibration section, which we got after
experiment
for qi=1:pady
    for qj=1:padx
        k= Crop(qi,qj);
```

---

```

Crop(qi,qj)=round(0.863*k-0.00596*(k)^2+0.00008035*k^3-0.000000238*k^4+0.00000000
end
end

```

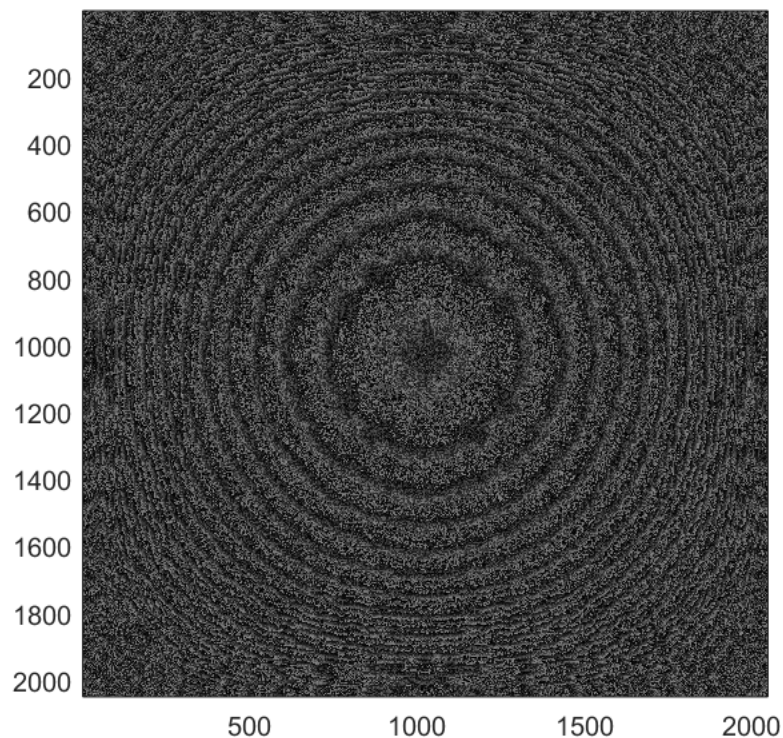
## Figure of Calibrated CGH

```

Crop=Crop';

figure
imagesc(Crop), axis image ,colormap('gray'), caxis([0,255]);

```



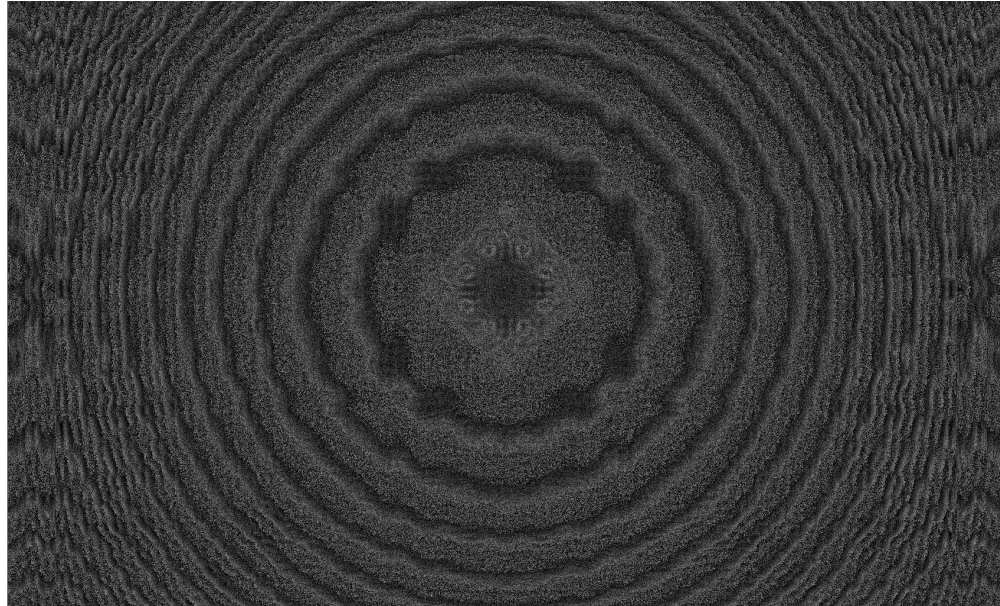
## Setting the position, magnification, etc. of the CGH

```

magni=1.65;

set(gcf, 'Units', 'Normalized', 'OuterPosition', [1 0.00 1 1]);
set(gca, 'Units', 'normalized', 'Position', [0. -0.3 1 magni]);
set(gcf, 'Toolbar', 'none', 'Menu', 'none', 'menubar', 'none', 'NumberTitle', 'off');
set(gca, 'Yticklabel', [], 'Xticklabel', [], 'ytick', [], 'xtick', [])

```



## Show Result

```
figure %Input Beam Distribution
imagesc(input), axis image;
title('Gaussian Input Beam Amplitude Distribution')
xlabel('x')
ylabel('y')

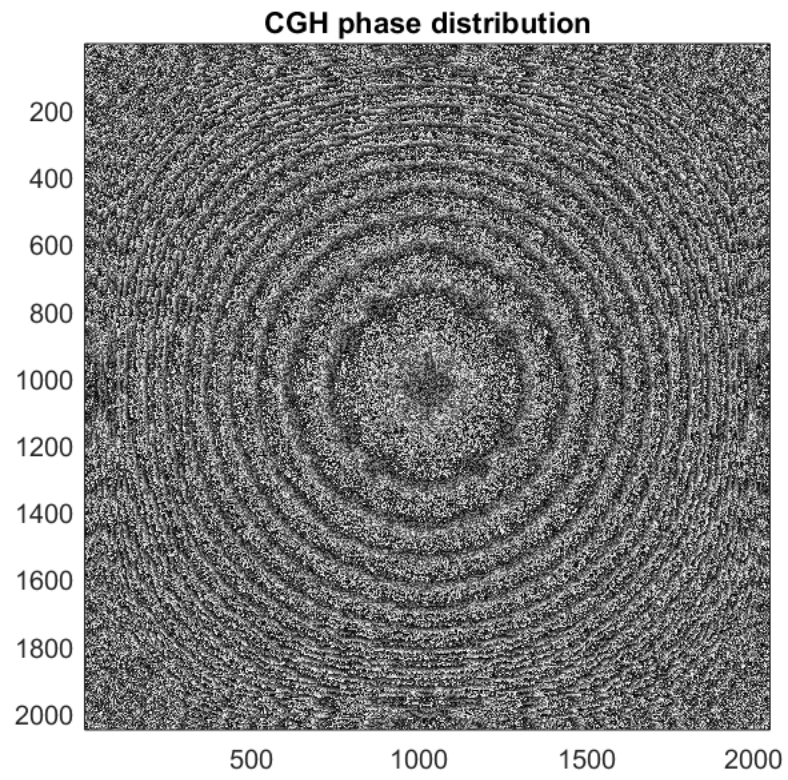
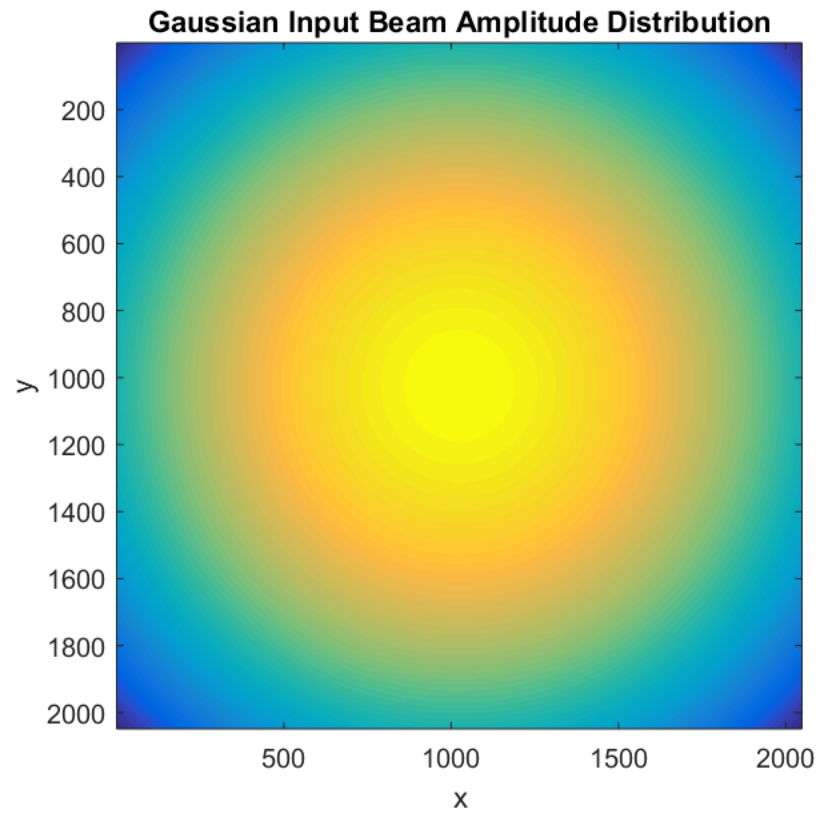
figure %CGH Phase Distribution Result
imagesc(Crop), axis image, colormap('gray');
title('CGH phase distribution');

figure %Original Target Image
imagesc(Target./max(max(Target))),axis image, colormap('gray');
title('Target image')

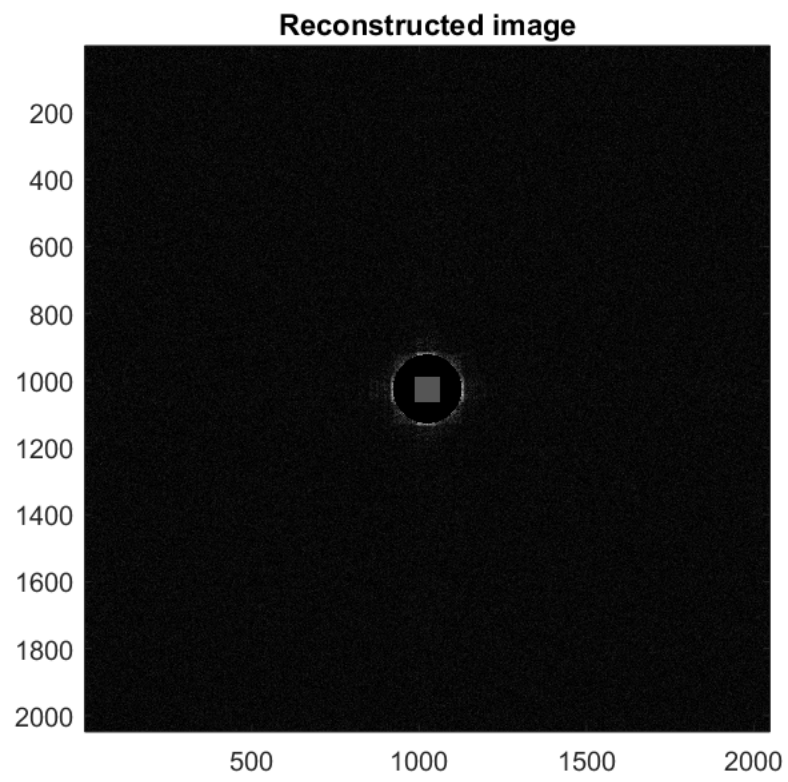
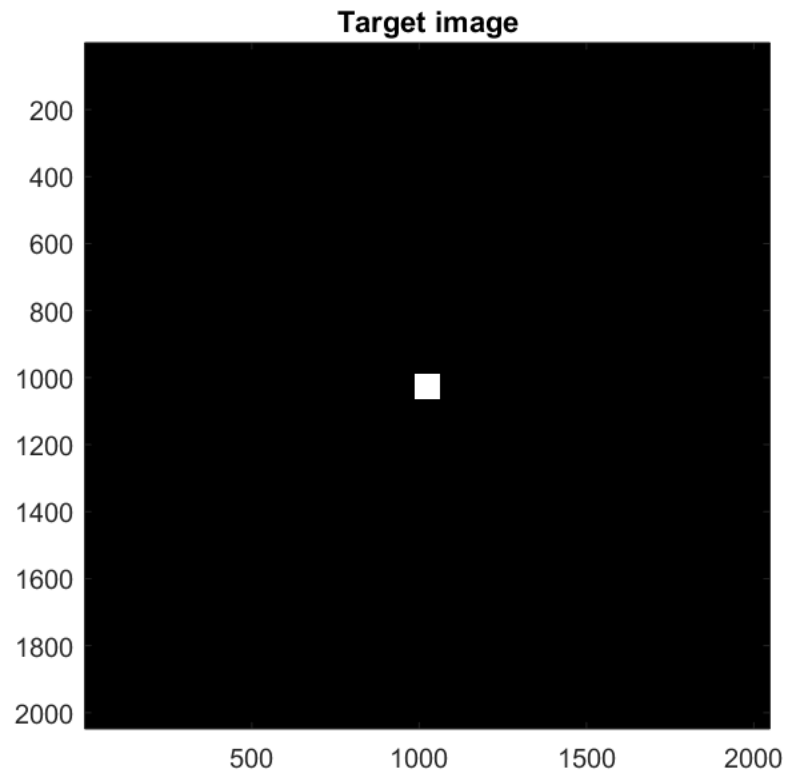
figure %Reconstructed Image
imagesc(abs(C)./max(max(abs(C)))), axis image, colormap('gray');
title('Reconstructed image');

figure %Error vs iteration
i = 1:1:i;
plot(i,(error'));
ylim([0 300])
title('Error vs Iteration');
```











*Published with MATLAB® R2016b*