

Database RAVDESS

- The RAVDESS consists of total 1440 samples recorded from 24 professional actors (12 male and 12 female).
- It encompasses eight emotions: calm, surprise, neutral, happy, angry, sad, fearful, and disgust
- The sampling rate of original speech signals is 16000Hz.
- We have considered the 5 sec long speech samples to keep the uniformity in the Mel frequency log spectrogram.
- If the sample length is less than 5 sec then it is padded to 5 sec long. Otherwise the samples are cropped to 5 sec.

Sr. No.	Emotion	Number of Samples
1	Angry	192
2	Calm	192
3	Disgust	192
4	Fear	192
5	Happy	192
6	Neutral	96
7	Sad	192
8	Surprise	192

Data	Samples
Total samples	1440
Train (70%)	1005
Test (15 %)	218
Validation (15%)	217

Flow Diagram - MFLS+DCNN

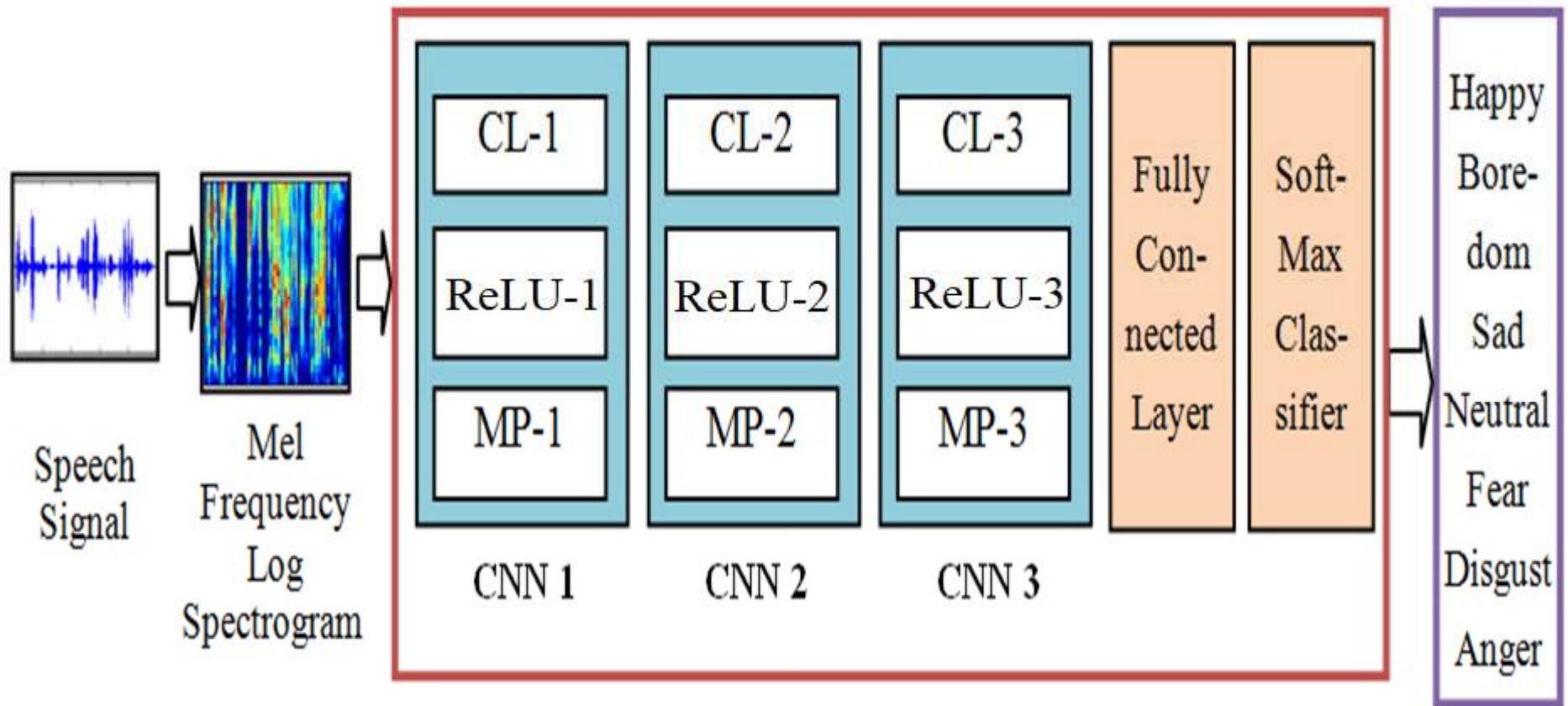


Fig. 2 Process flow of SER based on MFLS+DCNN

Mel Frequency Logarithmic Spectrum (MFLS)

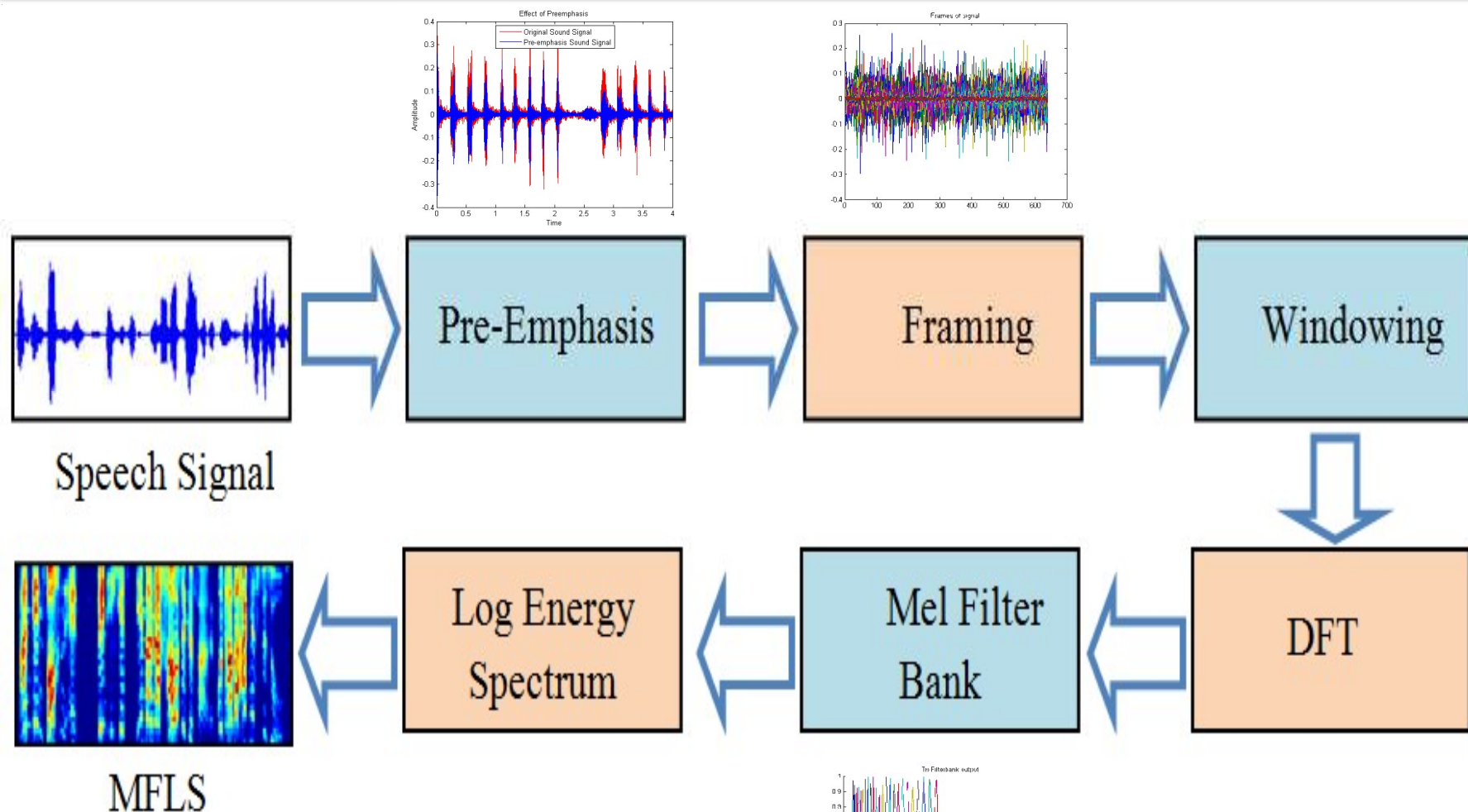


Fig. 3 MFLS process

Mel Frequency Logarithmic Spectrum (MFLS)

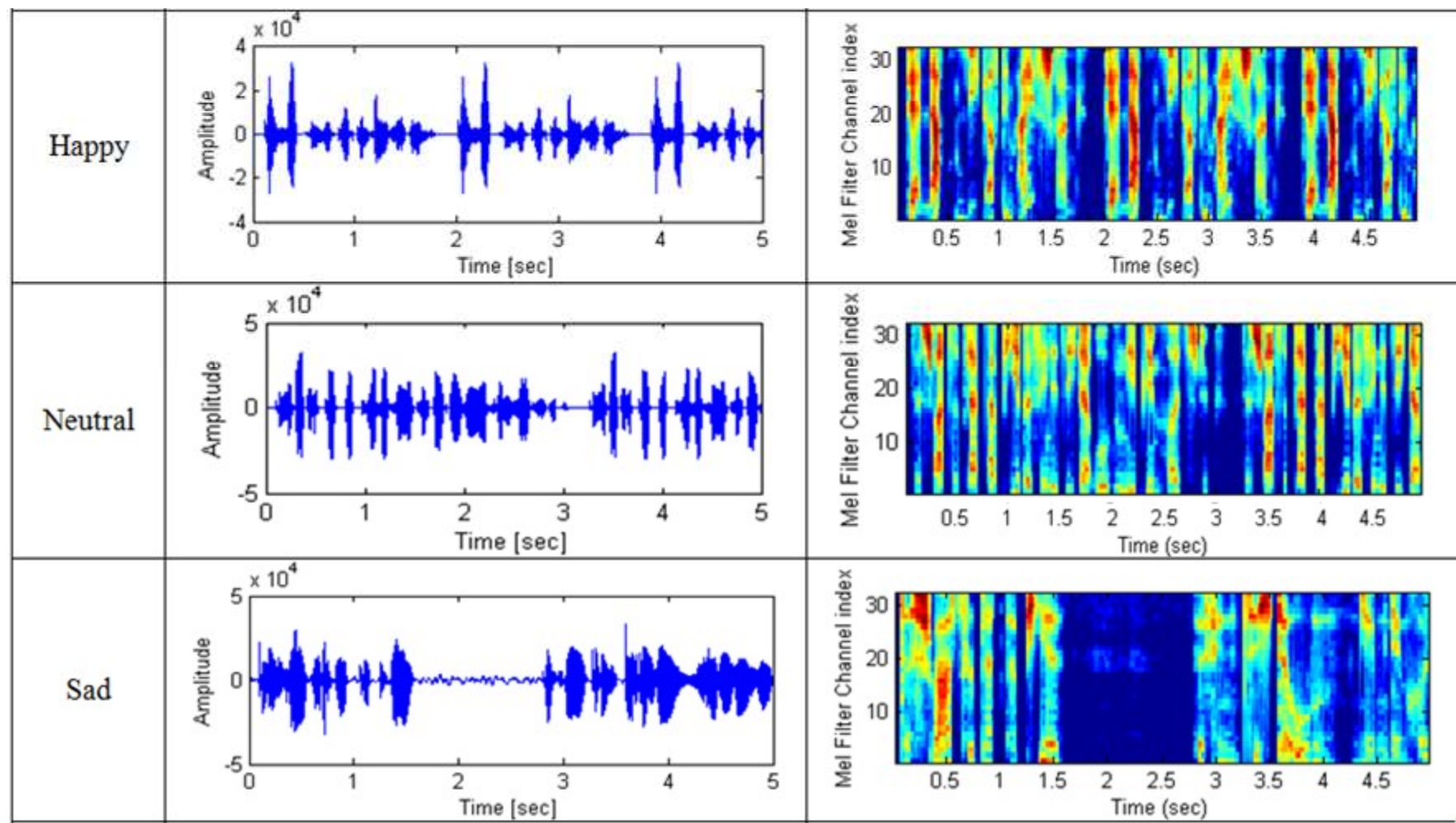


Fig. 4 MFLS representation

Convolution Neural Network Architecture

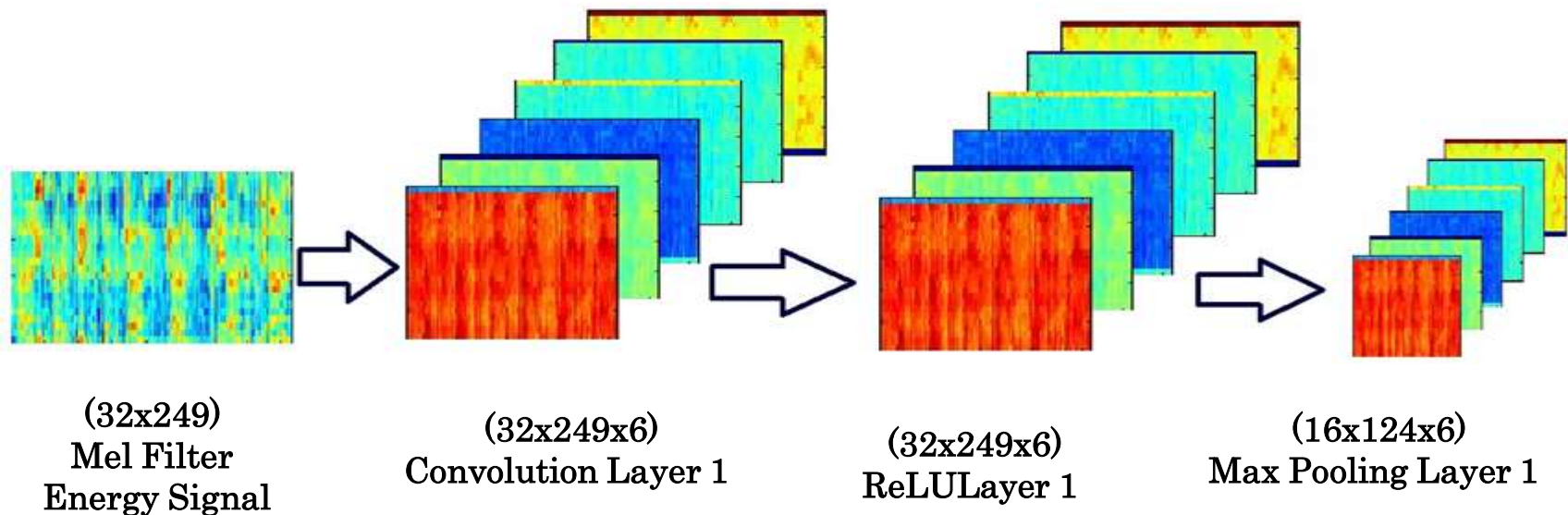


Fig. 5 CNN architecture

□ Training Method

Mini-Batch Gradient Descent Algorithm is used for training CNN.

In mini-batch gradient descent algorithm a complete dataset is divided into small batches b , then the model coefficients are updated using model error.

$$E_t[f(w)] = \frac{1}{b} \sum_{i=(t-1)b+1}^{tb} f(w, x_i) \quad (1)$$

The weights are updated using equation;

$$w^{t+1} = w^t - \mu \nabla_w E_t[f(w^t)] \quad (2)$$

Where,

E_t = model error , X_i = training samples

W = weights of filter kernel

F = cost function

μ = Learning rate

∇ = Gradient of cost function

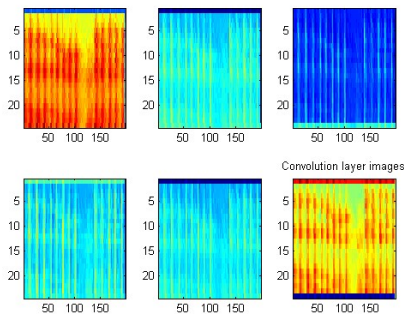
tb = number of batches

CNN Architecture Layer

□ Convolution layer

$$I_{CNN} = \text{Im} \otimes W_{N \times N} \quad (3)$$

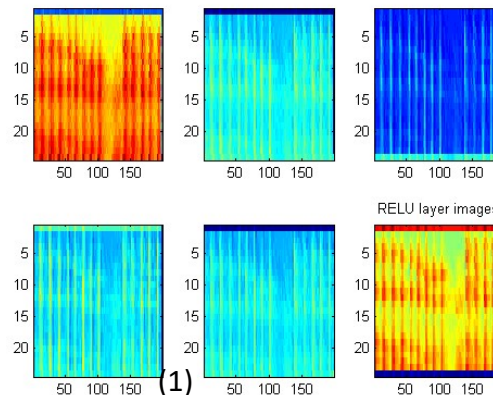
Convolution layer gives local connectivity of image local region and discriminancy weights of image region.



□ ReLU Layer

$$I_{ReLU} = \begin{cases} 0 & \text{if}(I_{CNN(i,j)} < 0) \\ I_{CNN(i,j)} & \text{Otherwise} \end{cases} \quad (4)$$

Rectified linear Unit removes the linearity by replacing negative weights by zero.



□ Max Pooling layer

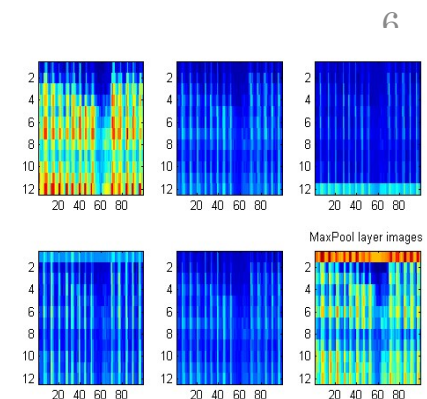
140	26	36	56
100	187	45	9
120	125	204	20
146	68	25	65

→

187	56
146	204

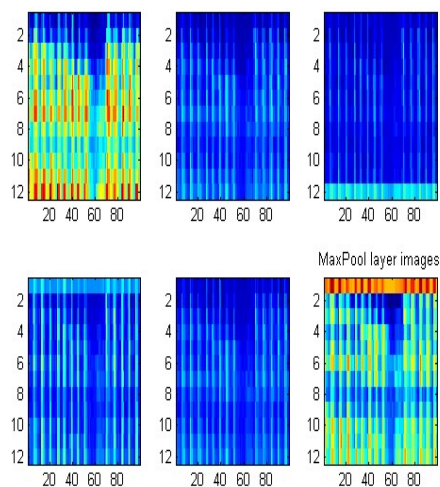
(5)

Max Pooling layer down sample the image to reduce feature map.

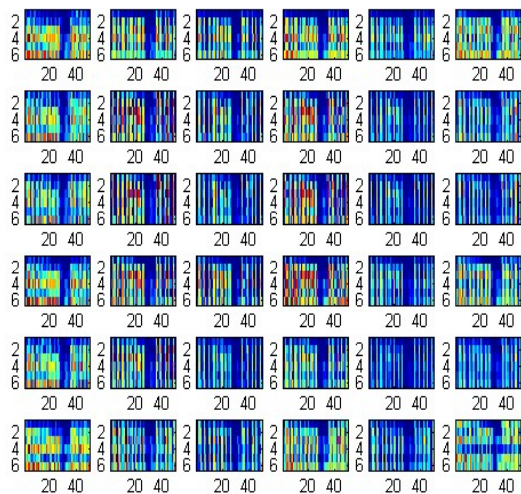


CNN layer Feature Visualization (2-D Color)

CNN Layer - 1



CNN Layer - 2



CNN Layer - 3



Fig. 6 Visualization of various DCNN maps

Experimental Results

Table 3 : Feature maps for various CNN layers

Layer	Sub-Layer	Kernel Size	Stride	Feature map
Input Layer	Mel Frequency Log Spectrogram	-	-	32×249
CNN layer 1	Convolution Layer 1	$3 \times 3 \times 6$	1	$29 \times 247 \times 6$
	ReLU Layer 1	-	-	$29 \times 247 \times 6$
	Max Pooling Layer 1	2×2	2	$14 \times 123 \times 6$
CNN layer 2	Convolution Layer 2	$3 \times 3 \times 36$	1	$12 \times 121 \times 36$
	ReLU Layer 2	-	-	$12 \times 121 \times 36$
	Max Pooling Layer 2	2×2	2	$6 \times 60 \times 36$
CNN layer 3	Convolution Layer 3	$3 \times 3 \times 216$	1	$4 \times 58 \times 216$
	ReLU Layer 3	-	-	$4 \times 58 \times 216$
	Max Pooling Layer 3	2×2	2	$2 \times 29 \times 216$
FC Layer	-	-	-	12528×1

Accuracy for RAVDESS dataset

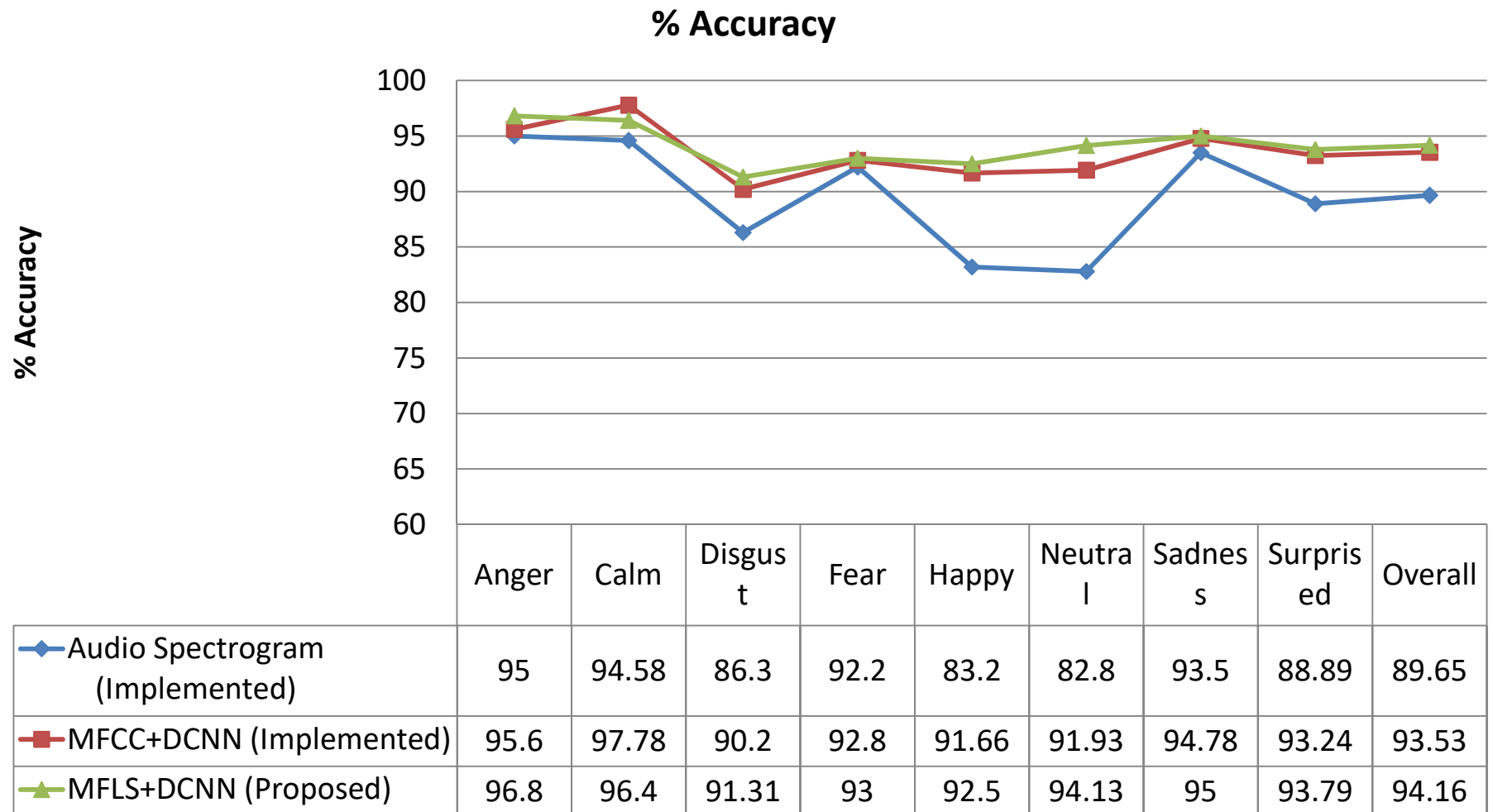


Fig. 9 % Accuracy for MFLS+MFCC database

Recall, Precision and F1-score for RAVDESS dataset

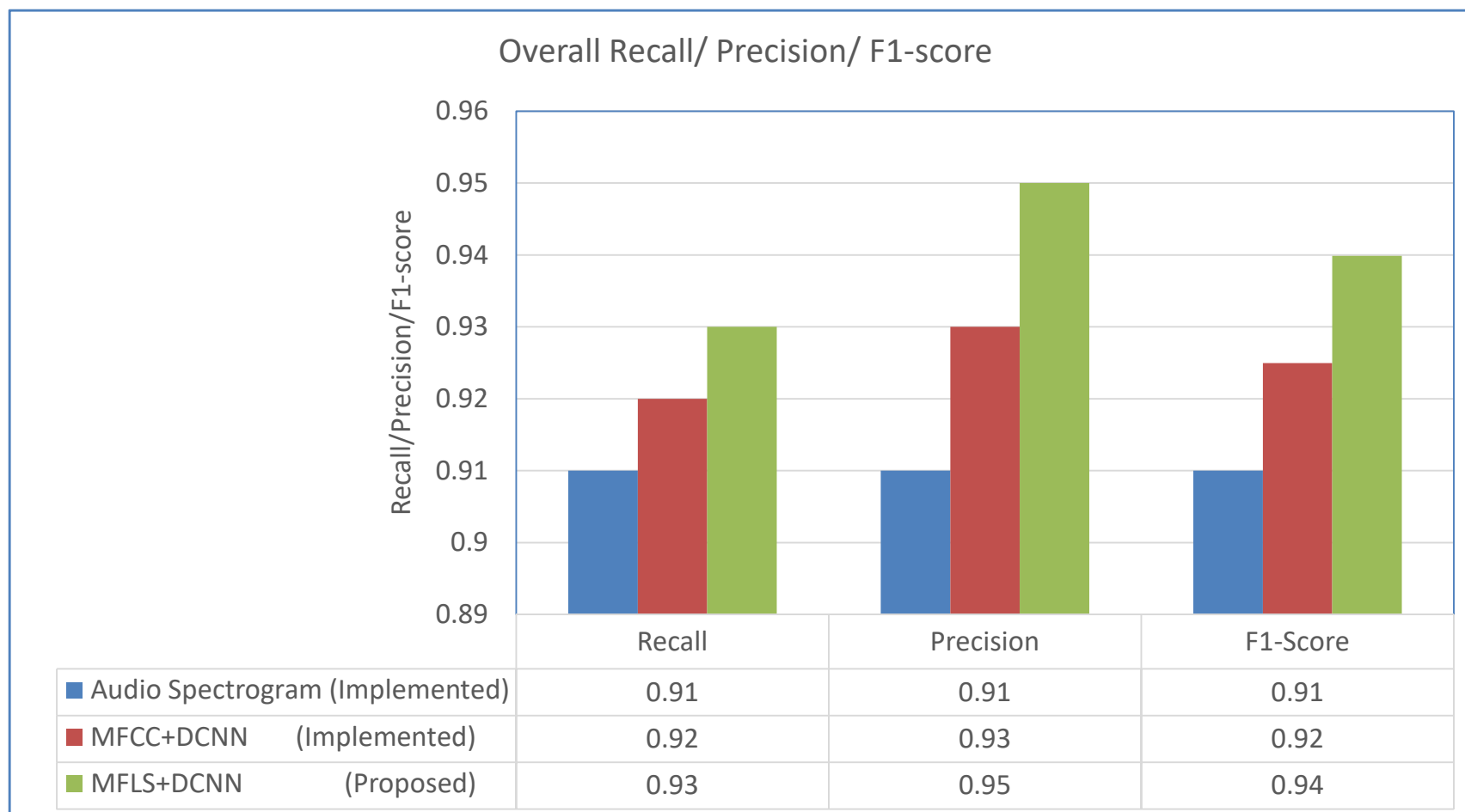


Fig 10. Recall/ Precision/F1-score for MFLS+DCNN for RAVDESS database

Performance for Various Parameters of DCNN

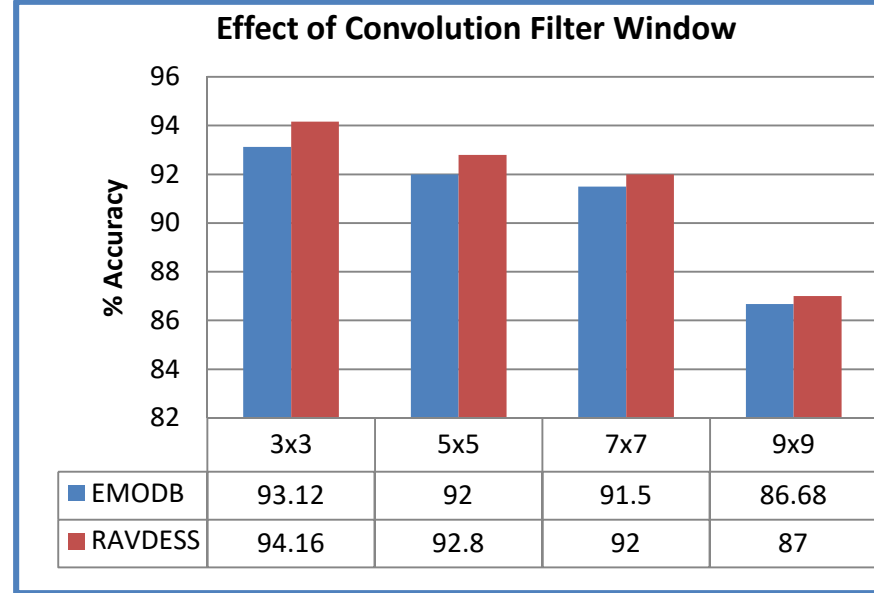
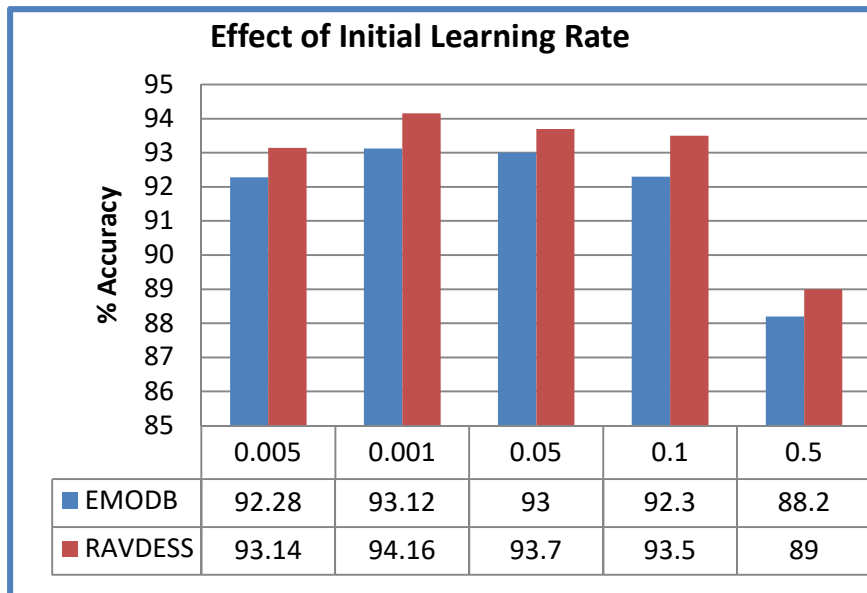
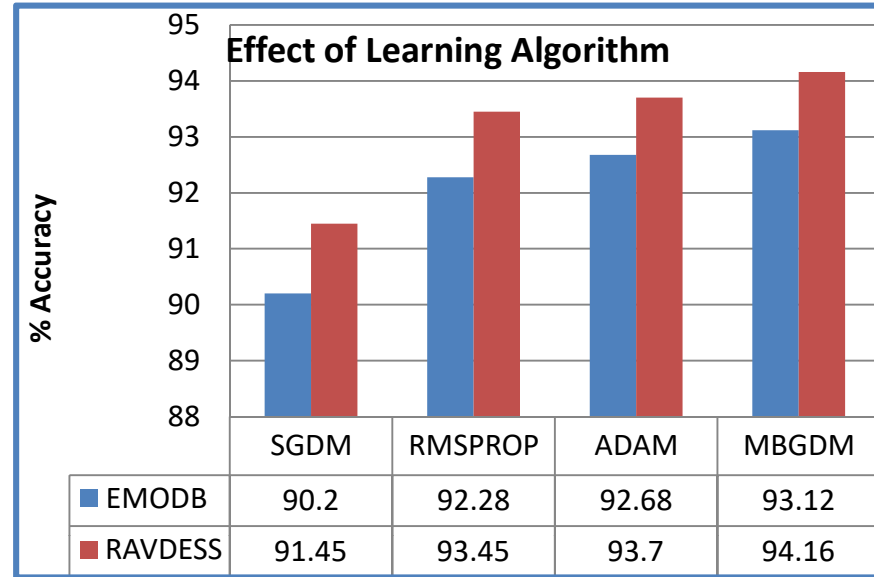
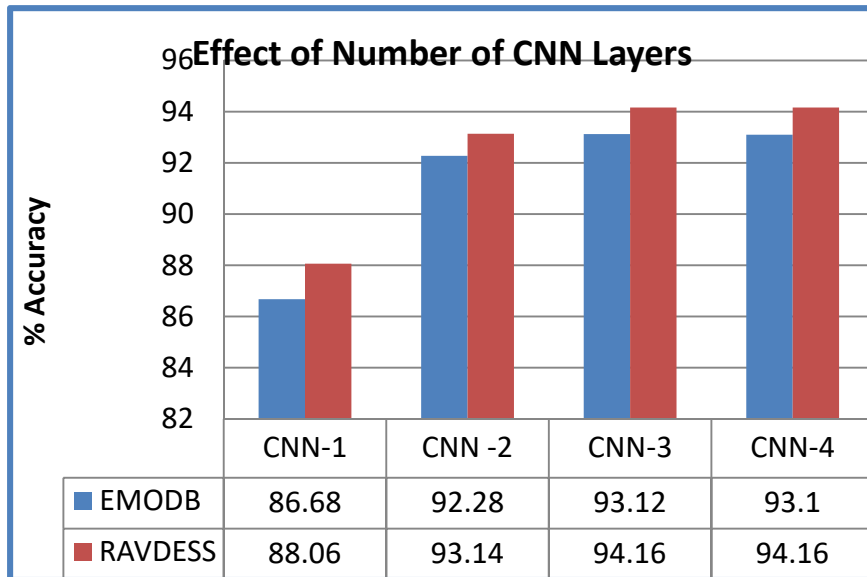


Fig. 11 % Accuracy for various DCNN parameters