

Derivatives in Entanglement-Driven Gravity

1 Introduction

In approaches where spacetime geometry is tied to quantum entanglement (for example, Jacobson’s entanglement equilibrium or Verlinde’s entropic gravity), various derivatives of entanglement entropy and of the stress-energy tensor appear in the field equations. We focus here on interpreting each derivative term: e.g. gradients like $\nabla S_{\text{ent}}/V$ or $\partial_i S_{\text{ent}}$, and covariant derivatives like $\nabla^\mu T_{\mu\nu}$. Throughout, S_{ent} denotes an entanglement entropy (or entropy density) of some region, and $T_{\mu\nu}$ the usual energy-momentum tensor. We ensure each derivative is defined mathematically, explained physically, and derived step by step.

2 Spatial Gradient of Entanglement Entropy Density $\nabla(S_{\text{ent}}/V)$

In many emergent gravity ideas, one considers an *entanglement entropy density* $\rho_S = S_{\text{ent}}/V$ (for some volume V). Its spatial gradient $\nabla(\rho_S)$ measures how entanglement per unit volume varies in space. The *original equation* where this appears is often an entropic-force relation analogous to Newton’s law. For example, Verlinde proposed that a particle near a holographic screen experiences a force

$$F_i = T \partial_i S_{\text{ent}},$$

i.e. proportional to the gradient of entropy:contentReference[oaicite:0]index=0. If V is taken constant, $\nabla(S_{\text{ent}}/V) = (1/V)\nabla S_{\text{ent}}$. More generally, one may absorb V into redefinitions, so we focus on ∇S_{ent} .

Mathematical meaning: For a scalar function $S_{\text{ent}}(x)$ on a spatial manifold, the gradient ∇S_{ent} is the vector field whose components are the partial derivatives $\partial_i S_{\text{ent}}$. Formally,

$$(\nabla S_{\text{ent}})_i = \partial_i S_{\text{ent}} = \lim_{\delta x^i \rightarrow 0} \frac{S_{\text{ent}}(x^i + \delta x^i) - S_{\text{ent}}(x^i)}{\delta x^i}.$$

It points in the direction of steepest increase of S_{ent} . Dividing by a volume V (assumed constant here) makes it an *entropy density gradient*.

Physical interpretation: A nonzero ∇S_{ent} means entanglement is inhomogeneous. In thermodynamic terms, systems tend to evolve towards higher entropy, so a gradient in entropy can drive an “entropic force” in the direction of increasing S_{ent} . Verlinde’s picture is that matter creates an information gradient, and particles move so as to increase S_{ent} :contentReference[oaicite:1]index=1. Geometrically, one can think of ∇S_{ent} as defining equipotential surfaces of entanglement; matter feels a force normal to these surfaces. In quantum-information terms, ∇S_{ent} quantifies how quickly quantum correlations vary across space. For example, Jacobson notes that vacuum entanglement scales with area (an area law) rather than volume:contentReference[oaicite:2]index=2. Thus spatial changes in entanglement are linked to the shape of regions (their boundary curvature, etc.). Conversely, assuming a volume-law entropy ($S_{\text{ent}} \propto V$) leads to uniform density and no gradient, which is inconsistent with a dynamical geometry:contentReference[oaicite:3]index=3:contentReference[oaicite:4]index=4.

Step-by-step derivation: Starting from the assumption that $S_{\text{ent}}(x)$ is a smooth scalar field, one can write down the difference quotient above to define $\partial_i S_{\text{ent}}$. No special assumptions beyond differentiability are needed. Verlinde further assumes a *temperature* T associated with the entangling screen (e.g. via the Unruh effect) and invokes the first law of thermodynamics $dE = T dS$. He shows that the work done by an effective force F moving a test mass by dx is $F dx = T dS$:contentReference[oaicite:5]index=5. Solving for F gives $F = T \nabla S_{\text{ent}}$. This derivation assumes (1) the existence of a local temperature field $T(x)$, (2) that S_{ent} changes

linearly with displacement (as in Verlinde's postulate $dS \propto m dx$:contentReference[oaicite:6]index=6), and (3) equipartition of energy on the holographic screen.

Multi-perspective discussion:

- *Geometric perspective:* In a Riemannian manifold, ∇S_{ent} is a covector field. Its norm $|\nabla S_{\text{ent}}|$ measures how fast entanglement changes per unit distance. Curvature could be introduced by assuming S_{ent} depends on the geometry (e.g. on area or curvature tensors), so that ∇S_{ent} implicitly carries geometric information.
- *Thermodynamic viewpoint:* The entropic force picture sees $\partial_i S_{\text{ent}}$ as the thermodynamic driving term. Analogous to a pressure gradient causing fluid flow, ∇S_{ent} drives matter motion. Because $F = T\nabla S$, a higher entropy region pulls matter toward it, reproducing gravitational attraction. This is akin to osmotic pressure in statistical physics, where $-\nabla S$ is proportional to an effective force:contentReference[oaicite:7]index=7.
- *Quantum-informational viewpoint:* Entanglement entropy quantifies quantum correlations across a boundary. The spatial derivative $\partial_i S_{\text{ent}}$ then measures how correlations differ between neighboring regions. A gradient implies an information imbalance. One can interpret a nonzero ∇S_{ent} as a signal that the vacuum state is not uniform, potentially curving spacetime. In holographic theories, varying entanglement on boundary regions corresponds to changing bulk geometry (as in Ryu–Takayanagi or tensor-network models).

3 Partial Derivative $\partial_i S_{\text{ent}}$

The partial derivative $\partial_i S_{\text{ent}}$ is simply the i -th component of the gradient above. It appears, for example, when writing force components or stress. In index notation one often writes $F_i = T \partial_i S_{\text{ent}}$.

Mathematical explanation: This is the coordinate derivative along the i -th direction. In Cartesian coordinates, $\partial_i S = \frac{\partial S}{\partial x^i}$. More generally, one can choose local coordinates at each point. Under a change of coordinates, partial derivatives combine into covariant derivatives via Christoffel symbols if we want a tensor; but for a scalar S_{ent} , covariant and partial derivatives coincide (since $\Gamma_{ij}^k \partial_k S$ vanishes when acting on scalars). Thus $\partial_i S$ is a well-defined geometric object (a one-form) even in curved space.

Physical interpretation: $\partial_i S_{\text{ent}}$ indicates how entanglement entropy changes per unit distance in the x^i direction. If a system tries to maximize S_{ent} , then $\partial_i S_{\text{ent}}$ tells us which way S_{ent} increases. In entropic gravity, one posits that matter experiences a force F_i in the direction of increasing S_{ent} ; thus $\partial_i S_{\text{ent}}$ directly sources acceleration.

For example, if one assumes a static gravitational potential $\Phi(x)$ is related to entropy by $\Phi \propto -S_{\text{ent}}$, then $-\partial_i S_{\text{ent}}$ acts like $\partial_i \Phi$, the usual gravitational field. Indeed, Verlinde's derivation (section 3.1 of [?]) shows that identifying $dS \sim m dx$ and using Unruh temperature $T \sim a$ leads to $ma = -T \partial_i S_{\text{ent}}$, or $a_i = -\partial_i \Phi$ with $\Phi = -S_{\text{ent}}/(2\pi)$ in appropriate units:contentReference[oaicite:8]index=8:contentReference[oaicite:9]index=9.

Step-by-step origin: No special assumption beyond smoothness: from $S_{\text{ent}}(x)$ define $\partial_i S = \lim_{\Delta x \rightarrow 0} [S(x + \Delta x_i) - S(x)]/\Delta x$. In thermodynamic derivations, one additionally assumes a relation between S_{ent} and the position of a test particle. Verlinde's key postulate was

$$\Delta S_{\text{ent}} = 2\pi \frac{m}{\hbar} \Delta x_i$$

for a mass m approaching a screen:contentReference[oaicite:10]index=10. Plugging this into $F_i = T \partial_i S$ with $T = \hbar a/2\pi$ (Unruh temperature) yields $F_i = ma_i$. Crucially, this uses (i) S_{ent} changes linearly with displacement, (ii) equipartition to set a uniform temperature on the screen, and (iii) $T \sim a$.

Multiple perspectives:

- *Geometric:* Viewing $\Phi(x)$ as a potential, one can equivalently treat $\partial_i S_{\text{ent}}$ as $-\partial_i \Phi$ times a constant. Spatial derivatives of scalar fields generate force vectors. If S_{ent} is a harmonic function of x , $\partial_i S = 0$ means equilibrium (flat potential).

- *Thermodynamic:* In nonequilibrium thermodynamics, entropy gradients drive fluxes. Here, a positive $\partial_i S_{\text{ent}}$ in direction i would tend to draw matter along that direction (to increase total entropy). The assumption of a steady “heat bath” at temperature T on the screen implies the force is $F_i = T\partial_i S_{\text{ent}}$:contentReference[oaicite:11]index=11. Note this is analogous to osmotic or polymer entropic forces, where $\partial_i S$ enters as the force per temperature:contentReference[oaicite:12]index=12.
- *Quantum information:* $\partial_i S_{\text{ent}}$ can be seen as a finite-difference of entanglement entropy between neighboring regions. In holographic CFT contexts, linearized Einstein equations have been related to first-law variations of entanglement: $\delta S = \delta\langle K \rangle$ (modular Hamiltonian):contentReference[oaicite:13]index=13. There, a variation $\partial_i S$ (thinking of many small ball-shaped regions shifted in space) would backreact on geometry. Thus $\partial_i S_{\text{ent}}$ encodes how local perturbations in quantum correlations source gravitational effects.

4 Covariant Derivative and Conservation: $\nabla^\mu T_{\mu\nu}$

A key derivative in gravitational theory is the covariant divergence $\nabla^\mu T_{\mu\nu}$. In General Relativity, the Einstein equation

$$G_{\mu\nu} + \Lambda g_{\mu\nu} = 8\pi G T_{\mu\nu}$$

satisfies $\nabla^\mu G_{\mu\nu} = 0$ by the Bianchi identity. Hence consistency requires

$$\nabla^\mu T_{\mu\nu} = 0,$$

i.e. local energy–momentum conservation:contentReference[oaicite:14]index=14.

Mathematical explanation: The covariant derivative ∇_μ reduces to the usual partial derivative for scalars but includes Christoffel terms for tensors. Explicitly,

$$\nabla_\mu T^\mu{}_\nu = \partial_\mu T^\mu{}_\nu + \Gamma^\mu_{\mu\lambda} T^\lambda{}_\nu - \Gamma^\lambda_{\mu\nu} T^\mu{}_\lambda.$$

The condition $\nabla^\mu T_{\mu\nu} = 0$ is a set of four differential equations (one for each ν), ensuring conservation of energy and momentum. In local inertial frames (where $\Gamma = 0$ at a point), it reduces to $\partial_\mu T^\mu{}_\nu = 0$, the usual divergence-free condition of flat space.

Physical interpretation: $\nabla^\mu T_{\mu\nu} = 0$ is interpreted as conservation of energy–momentum in curved spacetime. For $\nu = 0$, it is energy conservation; for $\nu = i$, it is momentum conservation. Equivalently, it encodes geodesic motion of matter and local energy balance. In emergent gravity models, any additional source of gravity (like entanglement) must respect this conservation. For instance, if one tries to introduce a spacetime-dependent term $\Lambda(x) \propto S_{\text{ent}}(x)$ in Einstein’s equation (so that $G_{\mu\nu} = 8\pi G T_{\mu\nu} + \Lambda(x)g_{\mu\nu}$), then $\nabla^\mu T_{\mu\nu} = 0$ and $\nabla^\mu G_{\mu\nu} = 0$ together imply $\partial_\nu \Lambda(x) = 0$. In other words, S_{ent} must be constant (or else extra dynamics must be introduced):contentReference[oaicite:15]index=15.

Step-by-step derivation: (i) The *contracted Bianchi identity* $\nabla^\mu G_{\mu\nu} = 0$ is a geometric identity following from the Riemann curvature tensor’s symmetries:contentReference[oaicite:16]index=16. (ii) Einstein’s equation $G_{\mu\nu} = 8\pi G T_{\mu\nu}$ then implies $\nabla^\mu T_{\mu\nu} = 0$ automatically. (iii) This is equivalent to $\nabla^\mu T_{\mu\nu} = 0$ as a statement that matter is covariantly conserved. No further assumptions (like a specific equation of state) are needed beyond diffeomorphism invariance of the action.

Multiple perspectives:

- *Geometric:* Covariant divergence vanishing is a consequence of general covariance. It means $T_{\mu\nu}$ is a conserved current in the curved spacetime. Geometrically, it ensures compatibility between geometry ($G_{\mu\nu}$) and matter ($T_{\mu\nu}$):contentReference[oaicite:17]index=17. If we introduce any new field (e.g. an entropic scalar) to the RHS of Einstein’s equation, its stress tensor must also be divergence-free or be supplemented by extra fields.
- *Thermodynamic:* Energy conservation is the first law of thermodynamics. In extended frameworks like Jacobson’s, one often interprets $\nabla^\mu T_{\mu\nu} = 0$ as a statement that the total *generalized entropy* (horizon area plus matter entropy) is extremized at equilibrium. A violation $\nabla^\mu T_{\mu\nu} \neq 0$ would imply an entropy production or violation of conservation.

- *Quantum information:* From a quantum perspective, $\nabla^\mu T_{\mu\nu} = 0$ means no net flow of energy-momentum out of any small region. If entanglement entropy gradients are supposed to generate gravity, one must embed them into the conservation law. In holographic setups, this often appears as a balance between bulk and boundary degrees of freedom ensuring a constant total entropy.

5 Summary

We have examined the key derivatives in entanglement-based gravity proposals. The spatial derivatives ∇S_{ent} or $\partial_i S_{\text{ent}}$ represent entropy gradients that can drive forces via thermodynamic arguments:contentReference[oaicite:18]index=18. Mathematically they are simply gradients of a scalar field, pointing in the direction of steepest entanglement change. The covariant divergence $\nabla^\mu T_{\mu\nu}$ encodes the conservation law that any gravity source (including entanglement) must satisfy:contentReference[oaicite:19]index=19. In modified gravity equations these derivatives must be handled carefully: for example, inserting a variable $\Lambda \propto S_{\text{ent}}$ naively would require $\partial_\nu S_{\text{ent}} = 0$ unless additional fields are introduced. Each derivative has a clear geometric definition (as a gradient or divergence in curved space) and a clear interpretation (thermodynamic force or energy conservation). These ensure the emergent gravitational dynamics remain self-consistent and physically grounded.