BIL 717 Image Processing-Spring 2016 Final Project Analysis of Two Non-Uniform Motion Deblurring Studies

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Abstract

In this paper we evaluate two blind motion-deblurring methods in the recent literature using a non-traditional metric that was developed in order to create a more perceptionally sound deblurring comparison criteria. In general terms, the first method, which was developed by Sun et al. [6], uses a convolutional neural network (CNN) to learn non-uniform motion blur removal. The second method, which was developed by Whyte et al. [7], proposes a geometric model to define the blurring kernels. Both methods tackle with the same blind non-uniform motion blur removal problem. In the upcoming sections we first define the blind motion-deblurring problem, then we discuss the related work focusing mostly on the recent literature, next we describe the two methods along with the no-reference metric, subsequently we define the methodology and experimentation, and we finish with conclusion.

1. Introduction

Motion blur is caused by moving the camera or objects within view when the camera shutter is open. This harms sharpness and causes losing the edges and thus objects in the scene seem intermingled. If the entire scene was blurred in the same way, this type of blur is called uniform blur. Non-uniform blur arises when the blur does not show the same type or magnitude of intermingling throughout the scene. A typical example of non-uniform blur emerges when the camera is rotated when the camera shutter is open and the recording of the information of the outside world is under way. When this happens the scene gets blurred in a rotational pattern (different parts of the scene blurred depending on the distance to a certain rotational center) [EXAMPLE]. Another example would be moving the camera towards or away from the scene (transposition in the

depth axis). In this case the blurring pattern looks more like a tunnel effect; namely blurring happens less in magnitude around a certain center in the scene (like a target), and more and more towards the image boundaries [EXAM-PLE]. More complex movements such as a combination of transposition and rotation of the camera complicate the issue even further.

Uniform deblurring typically have been defined as a convolution of an image with a kernel and added noise. Therefore, the basic approach is to subtract the noise and deconvolve the image with the same kernel. The problem with this approach is that the kernel is generally unknown. When the blur kernel is unknown, the problem is called blind deblurring problem. Researchers have attacked this problem with a range of different approaches. Some of the approaches will be covered in the next section. In this paper we analyze two of the recent papers that tackle with blind motion-deblurring problem.

1.1. Sun et al. (2015)

In Sun *et al.* (2015), the authors attack the problem of removing non-uniform motion blur from a single image using deep learning. The method they use depends on predicting motion kernels at a patch level. In order to do this they formulate the non-uniform blur as a field throughout the image. To find this field they divide the image into overlapping 30×30 patches, estimate the kernels at this level and then smooth the field depending on a smoothness of motion assumption. CNN is used to learn deblurring at a patch level. The general view of the CNN is seen on (Figure) [6].

Before training, the authors generated motion blur kernels with varying sizes from 1 pixel to 25 pixels with interval of two, and orientations ranging from 0 degree to 150 degree with intervals of 30, totaling 73 kernels. These kernels can be seen in (figure). To train the CNN model, the authors used these 73 kernels to artificially generate 1.4 million blurred patch/kernel pairs using PASCAL VOC 2010

database. They then used these patches as the input to the CNN during the training phase [6].

As can be seen in (figure) the CNN finds a probability distribution at the softmax layer. The authors state that the kernel space, which consists of 73 kernels, is not dense enough to represent all types of motions. To overcome this problem, they extend the motion kernel set by rotating image patches in the range between 0 and 24 degrees and use the trained CNN on these patches. Note that at this point they do not retrain the CNN, but rather they use the trained CNN with rotated images. By doing this they overcome the trainability problem of a high number of motion kernels and get a good amount of motion orientation detail [6].

The next phase is using the Markov Random Field (MRF) to find a dense field of kernels on the image. The previous phases find a number of motion kernels at every patch location on the image. Here, the main assumption is that the camera moves in a smooth trajactory when the shutter is open and thus the change of kernels throughout the image must also be smooth. This implies that there mut not be sudden changes when moving from one patch to another. This is made possible by using an MRF model and optimizing it. This enforces closeness of nearby kernels [6].

1.2. Whyte et al. (2012)

In Whyte *et al.* (2012), the authors emphasize that during the exposure, the camera sees a sequence of interrelated views and integrate them to form the blurry image. If we take one sensor pixel in the camera into consideration, it is subjected to photons coming from different points in space when the camera moves. It is also possible that nearby pixels are seeing the same points with passing time and recording the light coming from the same points. Therefore, they make an observation that the views of the camera are all related and they state that this relation can be explained using geometry [7].

2. Related Work

3. Methodology

One of the reasons why we decided on to analyze these two studies was the availability of the codes and data related to the studies. We have got in contact with some other researchers about their papers and queried whether the codes and related material were available, but we have not been able to get the sufficient material to conduct the experiments.

Sun *et al.* (2015) code is available Dr. Sun's website ¹. Whyte *et al.* (2012) code is available at the study's website ².

In conducting the experiments, we used five blurry images that was provided with [7]. These blurry images are available on the study's website ³. These pictures pose very challanging deblurring problems. The movements show quite complex patterns throughout the images and the images amount of intermingling among nearby pixels is quite high.

In this study, we use Liu *et al.* (2013)'s no-reference metric to measure the success of the two deblurring methods. In the following section no-reference metric is explained.

3.1. Liu et al. (2013)

The main goal this study tries to achieve is finding a good metric to measure specifically quality of deblurring. The authors argue that a metric specific to this problem will yield better results than more general metrics that measure the quality of the solutions to other types of image processing problems such as denoising etc. To this end, they measure the principal artifacts related to deblurring in general, i.e. ringing artifacts, noise, and residual blur and use these as features to learn a metric for blind deblurring.

This metric used crowdsourcing to perceptually assign deblurring quality to image patches. The users were shown image pairs and they decided which has a better deblurring quality. The researchers used this quality information to rank different images that were deblurred using different algorithms and parameters. They decided on which artifacts are most important in the process of deciding on the quality of deblurring and which features are more important to use when giving a score to a deblurring result.

4. Experimental Results

5. Conclusions

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¹http://gr.xjtu.edu.cn/
2http://www.di.ens.fr/willow/research/
deblurring/

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Saying "this builds on the work of Lucy Smith [1]" does not say that you are Lucy Smith; it says that you are building on her work. If you are Smith and Jones, do not say "as we show in [7]", say "as Smith and Jones show in [7]" and at the end of the paper, include reference 7 as you would any other cited work.

An example of a bad paper just asking to be rejected:

An analysis of the frobnicatable foo filter.

In this paper we present a performance analysis of our previous paper [1], and show it to be inferior to all previously known methods. Why the previous paper was accepted without this analysis is beyond me.

[1] Removed for blind review

An example of an acceptable paper:

An analysis of the frobnicatable foo filter.

In this paper we present a performance analysis of the paper of Smith *et al*. [1], and show it to be inferior to all previously known methods. Why the previous paper was accepted without this analysis is beyond me.

[1] Smith, L and Jones, C. "The frobnicatable foo filter, a fundamental contribution to human knowledge". Nature 381(12), 1-213.

If you are making a submission to another conference at the same time, which covers similar or overlapping material, you may need to refer to that submission in order to explain the differences, just as you would if you had previously published related work. In such cases, include the anonymized parallel submission [4] as additional material and cite it as

[1] Authors. "The frobnicatable foo filter", F&G 2014 Submission ID 324, Supplied as additional material fg324.pdf.

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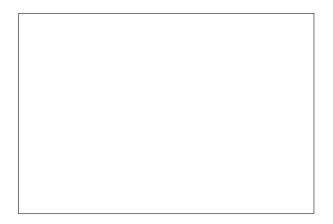


Figure 1. Example of caption. It is set in Roman so that mathematics (always set in Roman: $B \sin A = A \sin B$) may be included without an ugly clash.

lander source code makes us a wow at parties", by Zeus et al.

You can handle this paper like any other. Don't write "We show how to improve our previous work [Anonymous, 1968]. This time we tested the algorithm on a lunar lander [name of lander removed for blind review]". That would be silly, and would immediately identify the authors. Instead write the following:

We describe a system for zero-g frobnication. This system is new because it handles the following cases: A, B. Previous systems [Zeus et al. 1968] didn't handle case B properly. Ours handles it by including a foo term in the bar integral.

The proposed system was integrated with the Apollo lunar lander, and went all the way to the moon, don't you know. It displayed the following behaviours which show how well we solved cases A and B: ...

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5.7. Miscellaneous

Compare the following:

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 \begin{array}{ll} & \text{conf}_a \$ & conf_a \\ \$ \text{mathit} \{ \text{conf} \} \_a \$ & conf_a \\ \text{See The TpXbook, p165.} \end{array}
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The space after e.g., meaning "for example", should not be a sentence-ending space. So e.g. is correct, e.g. is not. The provided \eq macro takes care of this.

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This is incorrect: "... subsequently developed by Alpher *et al.* [2] ..." because reference [2] has just two authors. If you use the \etal macro provided, then you need not worry about double periods when used at the end of a sentence as in Alpher *et al.*

For this citation style, keep multiple citations in numerical (not chronological) order, so prefer [2, 1, 4] to [1, 2, 4].

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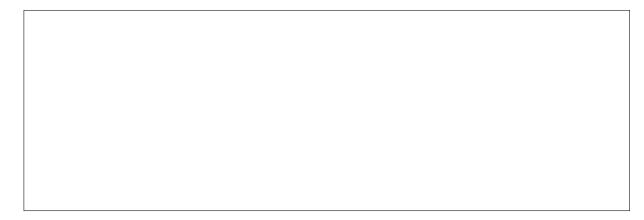


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FIRST-ORDER HEADINGS. (For example, **1. Introduction**) should be Times 12-point boldface, initially capitalized, flush left, with one blank line before, and one blank line after.

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Method	Frobnability
Theirs	Frumpy
Yours	Frobbly
Ours	Makes one's heart Frob

Table 1. Results. Ours is better.

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Please use footnotes⁴ sparingly. Indeed, try to avoid footnotes altogether and include necessary peripheral observations in the text (within parentheses, if you prefer, as in this sentence). If you wish to use a footnote, place it at the bottom of the column on the page on which it is referenced. Use Times 8-point type, single-spaced.

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 $^{^4\}mathrm{This}$ is what a footnote looks like. It often distracts the reader from the main flow of the argument.

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References

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