Practical Dependent Types: Type-Safe Neural Networks

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Lambdaconf 2017, May 27, 2017

Preface

Slide available at https://mstksg.github.io/talks/lambdaconf-2017/dependent-types/dependent-types.html.

Exercises we will be doing available at https://github.com/mstksg/talks/tree/master/lambdaconf-2017/dependent-types.

Libraries required: (available on Hackage)

- hmatrix
- singletons
- MonadRandom

GHC 8.x assumed.

The Big Question

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Dependent types are simply the extension of this question, pushing the power of types further.

Artificial Neural Networks

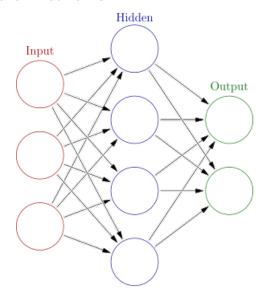


Figure 1: Feed-forward ANN architecture

Parameterized functions

Each layer receives an input vector, $\mathbf{x} : \mathbb{R}^n$, and produces an output $\mathbf{y} : \mathbb{R}^m$.

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They are parameterized by a weight matrix $W: \mathbb{R}^{m \times n}$ (an $m \times n$ matrix) and a bias vector $\mathbf{b}: \mathbb{R}^m$, and the result is:

$$\mathbf{y} = f(W\mathbf{x} + \mathbf{b})$$

Where f is some (differentiable) activation function. A neural network would take a vector through many layers.

Networks in Haskell

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```
data Weights = W { wBiases :: !(Vector Double) --n , wNodes :: !(Matrix Double) --n x m }
```

A network with one input layer, two hidden layers, and one output layer would be:

```
h1 :~ h2 :~ 0 o
```

Running them

Generating them

randomNet i (h:hs) o = (:~) <\$> randomWeights i h <*> random

randomNet i [] o = 0 <\$> randomWeights i o

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- What if layers in the network are incompatible?
- How does the user know what size vector a network expects?
- Is our runLayer and runNet implementation correct?

```
train :: Double -- ^ learning rate
-> Vector Double -- ^ input vector
-> Vector Double -- ^ target vector
-> Network -- ^ network to train
-> Network
train rate x0 target = fst . go x0
where
```

Backprop (Outer layer)

```
go :: Vector Double -- ^ input vector
   -> Network -- ^ network to train
   -> (Network, Vector Double)
-- handle the output layer
go !x (0 w@(W wB wN))
   = let y = runLayer w x
         o = logistic y
          -- the gradient (how much y affects the error
          -- (logistic' is the derivative of logistic
         dEdy = logistic' y * (o - target)
          -- new bias weights and node weights
         wB' = wB - scale rate dEdy
         wN' = wN - scale rate (dEdy `outer` x)
         w' = W wB' wN'
          -- bundle of derivatives for next step
         dWs = tr wN \# > dEdy
      in (O w', dWs)
```

Backprop (Inner layer)

```
-- handle the inner layers
go !x (w@(W WB WN) :~ n)
   = let y = runLayer w x
         o = logistic y
         -- get dWs', bundle of derivatives from rest
         (n', dWs') = go o n
         -- the gradient (how much y affects the error
         dEdy = logistic' y * dWs'
         -- new bias weights and node weights
         wB' = wB - scale rate dEdy
         wN' = wN - scale rate (dEdy `outer` x)
         w' = W wB' wN'
         -- bundle of derivatives for next step
         dWs = tr wN \# > dEdy
     in (w' :~ n', dWs)
```

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► Haskell is all about the compiler helping guide you write your code. But how much did the compiler help there?

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- ▶ How can the "shape" of the matrices guide our programming?

Haskell Red Flags

► How many ways can we write the function and have it still typecheck?

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- ► How many ways can we write the function and have it still typecheck?
- How many of our functions are partial?

```
data Weights i o = W { wBiases :: !(R o)
      , wNodes :: !(L o i)
}
```

An o x i layer

From HMatrix:

```
R :: Nat -> Type
```

 $L :: Nat \rightarrow Nat \rightarrow Type$

An R 3 is a 3-vector, an L 4 3 is a 4×3 matrix.

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```
R :: Nat -> Type
L :: Nat -> Nat -> Type
```

An R 3 is a 3-vector, an L 4 3 is a 4×3 matrix.

Operations are typed:

(KnownNat n lets hmatrix use the n in the type)

Typed holes can guide our development, too!

Data Kinds

With -XDataKinds, all values and types are lifted to types and kinds.

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In addition to the values True, False, and the type Bool, we also have the **type** 'True, 'False, and the **kind** Bool.

In addition to : and [] and the list type, we have ': and '[] and the list kind.

Data Kinds

```
ghci> :t True
Bool
ghci> :k 'True
Bool
ghci> :t [True, False]
[Bool]
ghci> :k '[ 'True, 'False ]
[Bool]
```

```
data Network :: Nat -> [Nat] -> Nat -> Type where
     :: !(Weights i o)
          -> Network i ' [] o
    (:~) :: KnownNat h
         => !(Weights i h)
         -> !(Network h hs o)
         -> Network i (h ': hs) o
infixr 5 :~
h1 :: W 10 8
h2:: W 8 5
o :: W 5 2
h1 :~ h2 :~ o :: Network 10 '[8, 5] 2
h2 :~ h1 :~ o -- type error
```

Running

```
runLayer :: (KnownNat i, KnownNat o)
         => Weights i o
         -> R i
         −> R o
runLayer (W wB wN) v = wB + wN #> v
runNet :: (KnownNat i, KnownNat o)
      => Network i hs o
      -> R. i
      ->R
runNet (0 w) !v = logistic (runLayer w v)
runNet (w :~ n') !v = let v' = logistic (runLayer w v)
                      in runNet n' v'
```

Exactly the same! No loss in expressivity!

Running			

Much better! Matrices and vector lengths are guaranteed to line up!

Generating

No need for explicit arguments! User can demand i and o. No reliance on documentation and parameter orders.

Generating

But, for generating nets, we have a problem:

Pattern matching on types

The solution for pattern matching on types: singletons.

```
-- (not the actual impelentation)
data Sing :: Bool -> Type where
   SFalse :: Sing 'False
   STrue :: Sing 'True
data Sing :: [k] -> Type where
   SNil :: Sing '[]
   SCons :: Sing x -> Sing xs -> Sing (x ': xs)
data Sing :: Nat -> Type where
   SNat :: KnownNat n => Sing n
```

Pattern matching on types

```
ghci> :t SFalse
Sing 'False
ghci> :t STrue `SCons` (SFalse `SCons` SNil)
Sing '[True, False]
ghci> :t SNat @1 `SCons` (SNat @2 `SCons` SNil)
Sing '[1, 2]
```

Random networks

Implicit passing

```
go :: forall j js. KnownNat j
   => R j
                  -- ^ input vector
   -> Network j js o -- ^ network to train
   -> (Network j js o, R j)
-- handle the output layer
go !x (0 w@(W wB wN))
   = let y = runLayer w x
         o = logistic y
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         dEdy = logistic' y * (o - target)
          -- new bias weights and node weights
         wB' = wB - konst rate * dEdy
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         w' = W wB' wN'
          -- bundle of derivatives for next step
         dWs = tr wN #> dEdy
         (0 w', dWs)
```

```
-- handle the inner layers
go !x (w@(W WB WN) :~ n)
   = let y = runLayer w x
         o = logistic y
         -- get dWs', bundle of derivatives from rest
         (n', dWs') = go o n
         -- the gradient (how much y affects the error
         dEdy
                   = logistic' y * dWs'
         -- new bias weights and node weights
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         wN' = wN - konst rate * (dEdy `outer` x)
         w' = W wB' wN'
         -- bundle of derivatives for next step
         dWs = tr wN \# > dEdy
     in (w' :~ n', dWs)
```

Surprise! It's actually identical! No loss in expressivity. Typed holes can write our code for us in many cases. And shapes are all verified.

Type-Driven Development

We wrote an untyped implementation, then realized what was wrong. Then we added types, and everything is great!

Further reading

Blog series: https://blog.jle.im/entries/series/ +practical-dependent-types-in-haskell.html