Practical Dependent Types: Type-Safe Neural Networks

Justin Le https://blog.jle.im (justin@jle.im)

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Preface

Slide available at https://mstksg.github.io/talks/kievfprog/dependent-types.html.

All code available at https://github.com/mstksg/talks/tree/master/kievfprog.

Libraries required: (available on Hackage) *hmatrix*, *singletons*, *MonadRandom*. GHC 8.x assumed.

The Big Question

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Dependent types are simply the extension of this question, pushing the power of types further.

Artificial Neural Networks

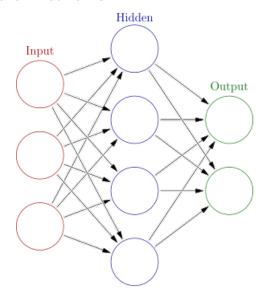


Figure 1: Feed-forward ANN architecture

Parameterized functions

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They are parameterized by a weight matrix $W: \mathbb{R}^{m \times n}$ (an $m \times n$ matrix) and a bias vector $\mathbf{b}: \mathbb{R}^m$, and the result is: (for some activation function \mathbf{f})

$$\mathbf{y} = f(W\mathbf{x} + \mathbf{b})$$

A neural network would take a vector through many layers.

Networks in Haskell

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```
data Weights = W { wBiases :: !(Vector Double) --n , wNodes :: !(Matrix Double) --n x m }
```

A network with one input layer, two hidden layers, and one output layer would be:

```
h1 :~ h2 :~ 0 o
```

Running them

Generating them

randomNet i (h:hs) o = (:~) <\$> randomWeights i h <*> random

randomNet i [] o = 0 <\$> randomWeights i o

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- ▶ What if the *user* mixed up the dimensions for randomWeights?
- What if layers in the network are incompatible?
- How does the user know what size vector a network expects?
- Is our runLayer and runNet implementation correct?

Backprop

```
train :: Double -- ^ learning rate
-> Vector Double -- ^ input vector
-> Vector Double -- ^ target vector
-> Network -- ^ network to train
-> Network
train rate x0 target = fst . go x0
where
```

Backprop (Outer layer)

```
go :: Vector Double -- ^ input vector
   -> Network -- ^ network to train
   -> (Network, Vector Double)
-- handle the output layer
go !x (0 w@(W wB wN))
   = let y = runLayer w x
         o = logistic y
          -- the gradient (how much y affects the error
          -- (logistic' is the derivative of logistic
         dEdy = logistic' y * (o - target)
          -- new bias weights and node weights
         wB' = wB - scale rate dEdy
         wN' = wN - scale rate (dEdy `outer` x)
         w' = W wB' wN'
          -- bundle of derivatives for next step
         dWs = tr wN \# > dEdy
      in (O w', dWs)
```

Backprop (Inner layer)

```
-- handle the inner layers
go !x (w@(W WB WN) :~ n)
   = let y = runLayer w x
         o = logistic y
         -- get dWs', bundle of derivatives from rest
         (n', dWs') = go o n
         -- the gradient (how much y affects the error
         dEdy = logistic' y * dWs'
         -- new bias weights and node weights
         wB' = wB - scale rate dEdy
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         w' = W wB' wN'
         -- bundle of derivatives for next step
         dWs = tr wN \# > dEdy
     in (w' :~ n', dWs)
```

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- ► Haskell is all about the compiler helping guide you write your code. But how much did the compiler help there?
- ▶ How can the "shape" of the matrices guide our programming?
- We basically rely on naming conventions to make sure we write our code correctly.

Haskell Red Flags

► How many ways can we write the function and have it still typecheck?

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- How many of our functions are partial?

An o x i layer

From HMatrix:

```
R :: Nat -> Type
```

L :: Nat -> Nat -> Type

An R 3 is a 3-vector, an L 4 3 is a 4×3 matrix.

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Operations are typed:

```
(+) :: KnownNat n => R n -> R n -> R n -> R n \\ (<\#) :: (KnownNat m, KnownNat n) => L m n -> R n -> R m
```

KnownNat n lets hmatrix use the n in the type. Typed holes can guide our development, too!

Data Kinds

With -XDataKinds, all values and types are lifted to types and kinds.

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In addition to the values True, False, and the type Bool, we also have the **type** 'True, 'False, and the **kind** Bool.

In addition to : and [] and the list type, we have ': and '[] and the list kind.

Data Kinds

```
ghci> :t True
Bool
ghci> :k 'True
Bool
ghci> :t [True, False]
[Bool]
ghci> :k '[ 'True, 'False ]
[Bool]
```

```
data Network :: Nat -> [Nat] -> Nat -> Type where
     :: !(Weights i o)
         -> Network i '[] o
    (:~) :: KnownNat h
         => !(Weights i h)
         -> !(Network h hs o)
        -> Network i (h ': hs) o
infixr 5 :~
h1 :: Weight 10 8
h2 :: Weight 8 5
o :: Weight 5 2
           0 o :: Network 5 '[] 2
     h2 :~ 0 o :: Network 8 '[5] 2
h1 :~ h2 :~ 0 o :: Network 10 '[8, 5] 2
h2 :~ h1 :~ O o -- type error
```

Running

```
runLayer :: (KnownNat i, KnownNat o)
         => Weights i o
         -> R i
        -> R o
runLayer (W wB wN) v = wB + wN #> v
runNet :: (KnownNat i, KnownNat o)
      => Network i hs o
      -> R. i
      ->R
runNet (0 w) !v = logistic (runLayer w v)
runNet (w :~ n') !v = let v' = logistic (runLayer w v)
                      in runNet n' v'
```

Exactly the same! No loss in expressivity!

Running

Much better! Matrices and vector lengths are guaranteed to line up!

Also, note that the interface for runNet is better stated in its type. No need to reply on documentation.

runNet

```
:: (KnownNat i, KnownNat o)
=> Network i hs o -> R i -> R o
```

The user knows that they have to pass in an ${\tt R}\,$ i, and knows to expect an ${\tt R}\,$ o.

Generating

No need for explicit arguments! User can demand i and o. No reliance on documentation and parameter orders.

Generating

But, for generating nets, we have a problem:

Pattern matching on types

The solution for pattern matching on types: singletons.

```
-- (not the actual impelentation)
data Sing :: Bool -> Type where
   SFalse :: Sing 'False
   STrue :: Sing 'True
data Sing :: [k] -> Type where
   SNil :: Sing '[]
   SCons :: Sing x -> Sing xs -> Sing (x ': xs)
data Sing :: Nat -> Type where
   SNat :: KnownNat n => Sing n
```

Pattern matching on types

```
ghci> :t SFalse
Sing 'False
ghci> :t STrue `SCons` (SFalse `SCons` SNil)
Sing '[True, False]
ghci> :t SNat @1 `SCons` (SNat @2 `SCons` SNil)
Sing '[1, 2]
```

Random networks

Explicitly passing singletons can be ugly.

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```
class SingI x where
    sing :: Sing x
```

We can now recover the expressivity of the original function, and gain demand-driven shapes.

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We can also demand them explicitly:

```
randomNet @1 @'[8,5] @2
```

Ready for this?

```
go :: forall j js. KnownNat j
   => R j
                  -- ^ input vector
   -> Network j js o -- ^ network to train
   -> (Network j js o, R j)
-- handle the output layer
go !x (0 w@(W wB wN))
   = let y = runLayer w x
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          -- new bias weights and node weights
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         wN' = wN - konst rate * (dEdy `outer` x)
         w' = W wB' wN'
          -- bundle of derivatives for next step
         dWs = tr wN #> dEdy
         (0 w', dWs)
```

```
-- handle the inner layers
go !x (w@(W WB WN) :~ n)
   = let y = runLayer w x
                   = logistic y
         -- get dWs', bundle of derivatives from rest
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      in (w' :~ n', dWs)
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Surprise! It's actually identical! No loss in expressivity.

Also, typed holes can help you write your code in a lot of places.

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Type-Driven Development

The overall guiding principle is:

- 1. Write an untyped implementation.
- 2. Realize where things can go wrong:
 - Partial functions?
 - Many, many ways to implement a function incorrectly with the current types?
 - Unclear or documentation-reliant API?
- 3. Gradually add types in selective places to handle these.

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I recommend not going the other way (use perfect type safety before figuring out where you actually really need them). We call that "hasochism".

Further reading

- Blog series: https://blog.jle.im/entries/series/
 +practical-dependent-types-in-haskell.html
- Extra resources:
- https://www.youtube.com/watch?v=rhWMhTjQzsU
- http://www.well-typed.com/blog/2015/11/ implementing-a-minimal-version-of-haskell-servant/
- https://www.schoolofhaskell.com/user/konn/ prove-your-haskell-for-great-safety
- http://jozefg.bitbucket.org/posts/ 2014-08-25-dep-types-part-1.html