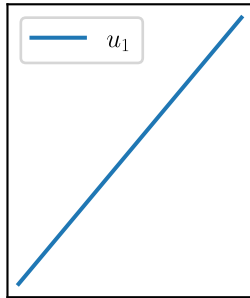
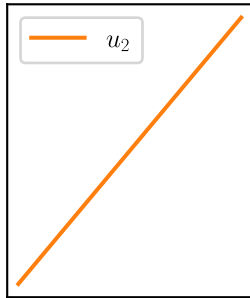


Torque on 1st act. coord.: τ_{φ_1}



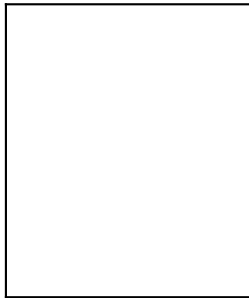
Control input u

Torque on 2nd act. coord.: τ_{φ_2}



Control input u

Torque on unact. coord.: τ_{φ_3}



Control input u