Demonstrations of Periodic Motions Kinesthetic Teaching for Brooming Task Biological Oracle Turtle Forward Swim.

Turtle Reverse Swim. Oracle

0.8

0.4

-0.8

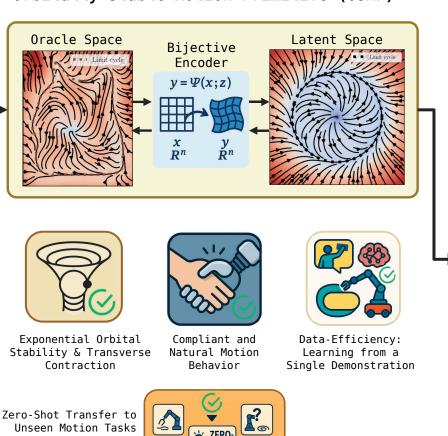
-1.2

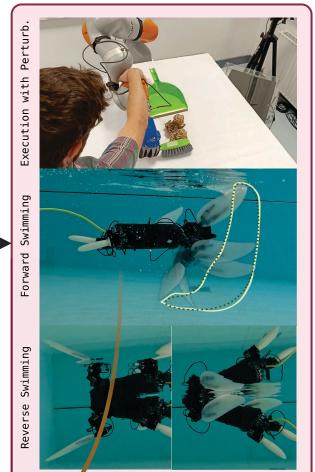
-0.8 -0.4 0.0

q1 [rad]

 q_3 [rad] -0.4

Orbitally Stable Motion Primitive (OSMP)





Stable, Compliant & Accurate

Execution of Motion Policy



- 4.0

- 3.5

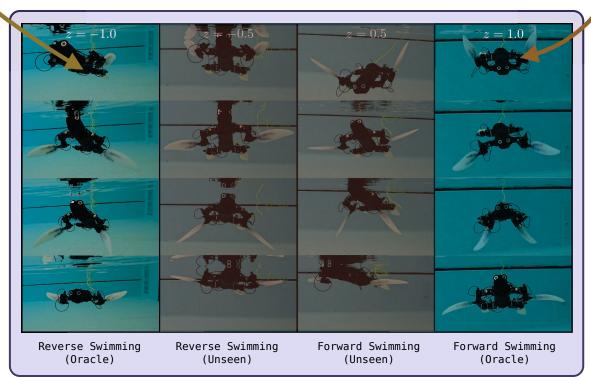
- 3.0 🕝

- 2.5 E

- 2.0 ·×

- 1.5

- 1.0



ZERO-SHOT

within Training Set

Distribution