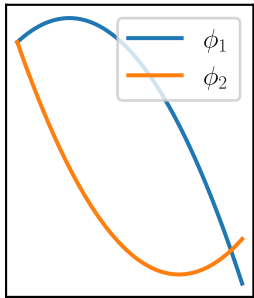
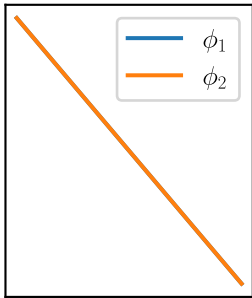


Torque on bend. strain: τ_{be}



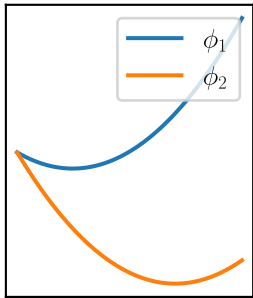
Control input ϕ

Torque on shear strain: τ_{sh}



Control input ϕ

Torque on axial strain: τ_{ax}



Control input ϕ