

- Part I - Physics-Based Models
- Part II - Learned Models
- Part III - Conclusion & Outlook
- Part IV - Appendices

Appendix B
Towards Holistic
Co-Design

Appendix C
Software Libraries
& Lab Infrastructure

Chapter 3
A Safety Metric
for Soft Robots

Chapter 7
Guiding with
Motor Imagery

Human Robot Interaction

Chapter 12
Learning Stable
Periodic Motions

Motion Generation

Chapter 8
Backstepping
Control

Chapter 5 & 6
Modeling & Control
of HSA Robots

Chapter 10
Control w/ Learned
Strain Models

Chapter 11
Control w/ Learned
Oscillator Models

Control

Chapter 4
Shape Sensing
with vSLAM

Chapter 9
Proprioception w/
Magnetic Sensors

Shape Sensing

