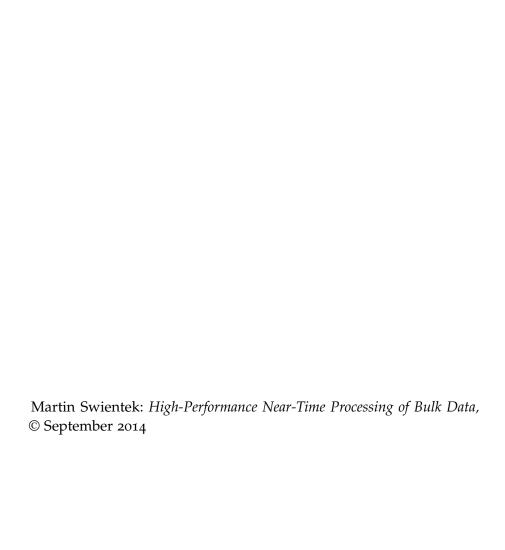
# HIGH-PERFORMANCE NEAR-TIME PROCESSING OF BULK DATA

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# RESEARCH WITH PLYMOUTH UNIVERSITY

A thesis submitted the Plymouth University in partial fulfilment for the degree of DOCTOR OF PHILOSOPHY

September 2014 – version 0.1



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### ACRONYMS

| API  | Application Programming Interface |
|------|-----------------------------------|
| CDR  | Call Detail Records               |
| ETL  | Extract, Transform, Load          |
| ESB  | Enterprise Service Busx           |
| NCDR | Normalized Call Detail Records    |
| FIFO | First In, First Out               |
| FTP  | File Transfer Protocol            |
| JAXB | Java Architecture for XML Binding |
| JMS  | Java Messaging Service            |
| JPA  | Java Persistence API              |
| NTP  | Network Time Protocol             |
| PTP  | Precision Time Protocol           |
| SLA  | Service Level Agreements          |

Service Oriented Architecture

SOA

# Part I FIELD OF RESEARCH

INTRODUCTION

Enterprise Systems like customer-billing systems or financial transaction systems are required to process large volumes of data in a fixed period of time. For example, a billing system for a large telecommunication provider has to process more than 1 million bills per day. Those systems are increasingly required to also provide near-time processing of data to support new service offerings.

Traditionally, enterprise systems for bulk data processing are implemented as batch processing systems (Fleck, 1999). Batch processing delivers high throughput but cannot provide near-time processing of data, that is the end-to-end latency of such a system is high. End-to-end latency refers to the period of time that it takes for a business process, implemented by multiple subsystems, to process a single business event. For example, consider the following billing system of telecommunications provider:

- Customers are billed once per month
- Customers are partitioned in 30 billing groups
- The billing system processes 1 billing group per day, running 24h under full load.

In this case, the mean time for a call event to be billed by the billing system is 1/2 month. That is, the mean end-to-end latency of this system is 1/2 month.

A lower end-to-end latency can be achieved by using single-event processing, for example by utilizing a message-oriented middleware for the integration of the services that form the enterprise system. While this approach is able to deliver near-time processing, it is hardly capable for bulk data processing due to the additional communication overhead for each processed message. Therefore, message-based processing is usually not considered for building a system for bulk data processing requiring high throughput.

The processing type is usually a fixed property of an enterprise system that is decided when the architecture of the system is designed, prior to implementing the system. This choice depends on the non-functional requirements of the system. These requirements are not fixed and can change during the lifespan of a system, either anticipated or not anticipated.

Additionally, enterprise systems often need to handle load peaks that occur infrequently. For example, think of a billing system with moderate load over most of the time, but there are certain events

#### 4 INTRODUCTION

with very high load such as New Year's Eve. Most of the time, a low end-to-end latency of the system is preferable when the system faces moderate load. During the peak load, it is more important that the system can handle the load at all. A low end-to-end latency is not as important as an optimized maximum throughput in this situation.

#### 1.1 AIMS AND OBJECTIVES OF THE RESEARCH

This research project aims to find a solution for the following problem:

### How to achieve high-performance near-time processing of bulk data?

To approach this problems, the research project has the following key objectives:

- A. Performance evaluation of batch and messaging systems regarding throughput and latency.
- B. Development of a concept for an adaptive middleware that delivers low latency while providing high throughput.
- C. Implementation of a research prototype used for demonstrating the practicability of the concept.
- D. Specification and conduction of appropriate performance tests to evaluate the developed approach.
- E. Development of a conceptional framework containing guidelines and rules for the practitioner how to implement an enterprise system based on the adaptive middleware for near-time processing of bulk data.

#### 1.2 CONTRIBUTIONS

- Performance evaluation of batch and messaging systems regarding throughput and latency
- Concept and prototype implementation of an adaptive middleware
- Conceptional Framework

#### 1.3 OUTLINE OF THE THESIS

We consider a distributed system for bulk data processing consisting of several subsystems running on different nodes that together form a processing chain, that is, the output of subsystem S1 is the input of the next subsystem S2 and so on (see Figure 1a).

Add reference to Pipes and Filters architectural style (EIP)



(b) Parallel processing lines

Figure 1: A system consisting of several subsystems forming a processing chain

To facilitate parallel processing, the system can consist of several lines of subsystems with data beeing distributed among each line. For simplification, we consider a system with a single processing line in the remainder of this paper.

We discuss two processing types for this kind of system, batch processing and message-based processing.

#### 2.1 BATCH PROCESSING

The traditional operation paradigm of a system for bulk data processing is batch processing (see Figure 2). A batch processing system is an application that processes bulk data without user interaction. Input and output data is usually organised in records using a file- or database-based interface. In the case of a file-based interface, the application reads a record from the input file, processes it and writes the record to the output file.

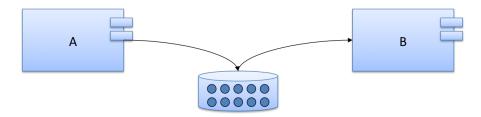


Figure 2: Batch processing

A batch processing system exhibits the following key characteristics:

#### • Bulk processing of data

A Batch processing system processes several gigabytes of data in a single run thus providing a high throughput. Multiple systems are running in parallel controlled by a job scheduler to speed up processing. The data is usually partitioned and sorted by certain criteria for optimized processing. For example, if a batch only contains data for a specific product, the system can pre-load all necessary reference data from the database to speed up the processing.

#### • No user interaction

There is no user interaction needed for the processing of data. It is impossible due to the amount of data being processed.

#### • File- or database-based interfaces

Input data is read from the file system or a database. Output data is also written to files on the file system or a database. Files are transferred to the consuming systems through FTP by specific jobs.

#### • Operation within a limited timeframe

A batch processing system often has to deliver its results in a limited timeframe due to Service Level Agreements (SLA) with consuming systems.

#### • Offline handling of errors

Erroneous records are stored to a specific persistent memory (file or database) during operation and are processed afterwards.

Applications that are usually implemented as batch processing systems are billing systems for telecommunication companies used for mediating, rating and billing of call events.

- 2.1.1 *Integration Styles*
- 2.1.1.1 File Transfer
- 2.1.1.2 Shared Database
- 2.1.2 Batch Architectures

#### 2.2 MESSAGE-BASE PROCESSING

Messaging facilitates the integration of heterogeneous applications using asynchronous communication. Applications are communicating with each other by sending messages (see Figure 3). A messaging server or message-oriented middleware handles the asynchronous exchange of messages including an appropriate transaction control Conrad et al. (2006).

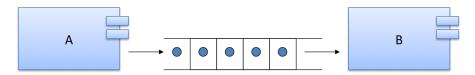


Figure 3: Message-based processing

Hohpe et al. Hohpe and Woolf (2003) describe the following basic messaging concepts:

#### • Channels

Messages are transmitted through a channel. A channel connects a message sender to a message receiver.

#### Messages

A message is packet of data that is transmitted through a channel. The message sender breaks the data into messages and sends them on a channel. The message receiver in turn reads the messages from the channel and extracts the data from them.

#### Pipes and Filters

A message may pass through several processing steps before it reaches its final destination. Multiple processing steps are chained together using a pipes and filters architecture.

#### Routing

A message may have to go through multiple channels before it reaches its destination. A message router acts as a filter and is capable of routing a message to the next channel or to another message router.

#### • Transformation

A message can be transformed by a message translator if the

message sender and receiver do not agree on the format for the same conceptual data.

#### • Endpoints

A message endpoint is a software layer that connects arbitrary applications to the messaging system.

#### 2.2.1 Integration Styles

#### 2.2.1.1 Point To Point

#### 2.2.1.2 Publish/Subscribe

Message-based systems are able to provide near-time processing of data due to their lower latency compared with batch processing systems. The advantage of a lower latency comes with a performance cost in regard to a lower throughput because of the additional overhead for each processed message. Every message needs amongst others to be serialised and deserialised, mapped between different protocols and routed to the appropriate receiving system.

#### 2.3 LATENCY VS. THROUGHPUT

Throughput and latency are performance metrics of a system. The following definitions of throughput and latency are used in this paper:

#### Maximum Throughput

The number of events the system is able to process in a fixed timeframe.

#### Ent-to-end Latency

The period of time between the occurrence of an event and its processing. End-to-end latency refers to the total latency of a complete business process implemented by multiple subsystems. The remainder of this paper focusses on end-to-end latency using the general term latency as an abbreviation.

#### 2.3.1 Batch processing

A business process, such as billing, implemented by a system using batch processing exhibits a high end-to-end latency. For example, consider the following billing system:

- Customers are billed once per month
- Customers are partitioned in 30 billing groups
- The billing system processes 1 billing group per day, running 24h under full load.

In this case, the mean time for a call event to be billed by the billing system is 1/2 month. That is, the mean end-to-end latency of this system is 1/2 month.

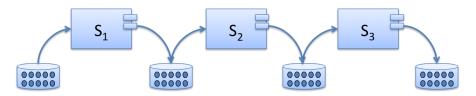


Figure 4: Batch processing system comprised of three subsystems

Assuming the system  $S_{Batch}$  which is comprised of N subsystems  $S_1, S_2, ..., S_N$  (see Figure 4 for an example with N = 3):

$$S_{Batch} = \{S_1, S_2, ..., S_N\}$$

The subsystem  $S_i$  reads its input data from the database  $DB_i$  in one chunk, processes it and writes the output to the database  $DB_{i+1}$ . When  $S_i$  has finished the processing, the next subsystem  $S_{i+1}$  reads the input data from  $DB_{i+1}$ , processes it and writes the output to  $DB_{i+2}$ , which in turn is read and processed from subsystem  $S_{i+3}$  and so on.

The latency  $L_{E_{S_{\mathrm{Batch}}}}$  of a single event processed by the system  $S_{\mathrm{Batch}}$  is determined by the total processing time  $PT_{S_{\mathrm{Batch}}}$ , which is the sum of the processing time  $PT_i$  of each subsystem  $S_i$ :

$$L_{E_{S_{Batch}}} = PT_{S_{Batch}} = \sum_{i=1}^{N} PT_{i}$$

where N is the number of subsystems.

The processing time  $PT_i$  of the subsystem  $S_i$  is the sum of the processing time of each event  $PT_{E_j}$  and the additional processing overhead  $OH_i$ , which includes the time spent for reading and writing the data, opening and closing transactions, etc:

$$PT_{i} = \left(\sum_{j=1}^{M} PT_{E_{j}}\right) + OH_{i}$$

where M is the number of events.

To allow for near-time processing, it is necessary to decrease the latency  $L_{E_S}$  of a single event. This is can be achieved by using message-based processing instead of batch processing.

#### 2.3.2 Message-based processing

The subsystem  $S_i$  of a message-based system  $S_{Message}$  reads a single event from its input message queue  $MQ_i$ , processes it and writes it to

the output message queue  $MQ_{i+1}$ . As soon as the event is written to the message queue  $MQ_{i+1}$ , it is read by the subsystem  $S_{i+1}$ , which processes the event and writes to the message queue MQi + 2 and so on (see Figure 5).

The latency  $L_{E_{S_{Message}}}$  of a single event processed by the system  $S_{Message}$  is determined by the total processing time  $PT_{E_{S_{Message}}}$  of this event, which is the sum of the processing time  $PT_{E_i}$  and the processing overhead  $OH_{E_i}$  for the event of each subsystem:

$$L_{E_{S_{Message}}} = PT_{E_{S_{Message}}} = \sum_{i+1}^{N} (PT_{E_i} + OH_{E_i})$$

where N is the number of subsystems. Please note that the wait time of the event is assumed to be o for simplification.

The processing overhead  $OH_{E_{i}}$  includes amongst others the time spent for unmarshalling and marshalling, protocol mapping and opening and closing transactions, which is done for every processed event.

Figure 5: Message-based system comprised of three subsystems

Since the processing time  $PT_{E_{S_{Message}}}$  of a single event is much shorter than the total processing time  $PT_{S_{Batch}}$  of all events, the latency  $L_{E_{S_{Message}}}$  of a single event using a message-based system is much smaller than the latency  $L_{E_{S_{Batch}}}$  of a single event processed by a batch-processing system.

$$PT_{E_{S_{Message}}} < PT_{S_{Batch}} \Rightarrow L_{E_{S_{Message}}} < L_{E_{S_{Batch}}}$$

Message-based processing adds an overhead to each processed event in contrast to batch processing, which adds a single overhead to each processing cycle. Hence, the accumulated total processing overhead  $OH_{S_{Message}}$  of a message-based system  $S_{Message}$  for processing m events is larger than the total processing overhead of a batch processing system:

$$OH_{S_{Message}} = \sum_{i=1}^{n} OH_{E_i} * m > OH_{S_{Batch}} = \sum_{i=1}^{n} OH_i$$

A message-based system, while having a lower end-to-end latency, is not able to process the same amount of events in the same time as a batch processing system and therefore cannot provide the same maximum throughput.

From this follows that latency and throughput are opposed to each other (see Figure 6). High throughput, as provided by batch processing, leads to high latency, which impedes near-time processing. On

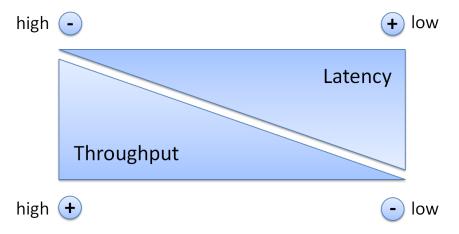


Figure 6: Latency and throughput are opposed to each other

the other hand, low latency, as provided by a message-based system, cannot provide the throughput needed for bulk data processing because of the additional overhead for each processed event.

#### 2.4 SERVICE-ORIENTED ARCHITECTURE

Service Oriented Architecture (SOA) is an architectural pattern to build application landscapes from single business components. These business components are loosely coupled by providing their functionality in form of services. A service represents an abstract business view of the functionality and hides all implementation details of the component providing the service. The definition of a service acts as a contract between the service provider and the service consumer. Services are called using a unified mechanism, which provides a plattform independent connection of the business components while hiding all the technical details of the communication. The calling mechanism also includes the discovery of the appropriate service (Richter et al., 2005).

By separating the technical from the business aspects, SOA aims for a higher level of flexibility of enterprise applications.

#### 2.5 ENTERPRISE SERVICE BUS

An Enterprise Service Busx (ESB) is an integration platform that combines messaging, web services, data transformation and intelligent routing (Schulte, 2002). Table 1 shows the main characteristics of an ESB (Chappell, 2004). All application components and integration services that are connected to the ESB are viewed as abstract service endpoints. Abstract endpoints are logical abstractions of services that are plugged into the ESB and are all equal participants (Chappell, 2004). An abstract endpoint can represent a whole application package such

| Pervasiveness  | An ESB supports multiple protocols and client technologies. It can span an entire organisation including its business partners.       |  |  |
|--|---|--|--|
| Highly distributed                                     | An ESB integrates loosely coupled application components that form a highly distributed network.                                      |  |  |
| Selective deploy-<br>ment of integration<br>components | The services of an ESB are independent of each other and can be separately deployed.  |  |  |
| Security and reliability                               | An ESB provides reliable messaging, transactional integrity and secure authentication.  |  |  |
| Orchestration and process flow                         | An ESB supports the orchestration of application components controlled by message metadata or an orchestration language like WS-BPEL. |  |  |
| Autonomous yet federated managed environment           | Different departments can still separately manage an ESB that spans the whole organisation.   |  |  |
| Incremental adoption                                   | The adoption of an ESB can be incremental one project after another.  |  |  |
| XML support  | XML is the native data format of an ESB.  |  |  |
| Real-time insight                                      | An ESB provides real-time throughput of data by the use of its underlying message-oriented middleware and thus decreases latency.     |  |  |

Table 1: Main characteristics of an ESB (Chappell, 2004)

as a CRM or ERP system, a small web service or an integration service of the ESB such as a monitoring, logging or transformation service. As integration platform the ESB supports various types of connections for the service endpoints. These can be SOAP, HTTP, FTP, JMS or other programming APIs for C, C++, C#, etc. It is often stated that "if you can't bring the application to the bus, bring the bus to the application" (Chappell, 2004).

The backbone of the ESB is a message-oriented middleware (MOM), which provides an asynchronous, reliable and efficient transport of data between the service endpoints. The concrete protocol of the MOM, such as JMS, WS-Rel\* or a proprietary protocol is thereby abstracted by the service endpoint. The ESB is thus a logical layer over the messaging middleware. The utilised protocol can also be varied by the ESB depending on the Quality of Service (QoS) requirements or deployment situations. Service endpoints can be orchestrated to process flows, which are mapped to concrete service invocations by the ESB.

The physical representation of a service endpoint is the service container. The service container is a remote process, which hosts the business or technical components that are connected through the bus. The set of all service containers therefore constitute the logical ESB.

A service container provides the following interfaces (Chappell, 2004):

#### • Service interface

The service interface provides an entry endpoint and exit endpoint to dispatch messages to and from the service.

#### Management interface

The management interface provides an entry endpoint for retrieving configuration data and an exit endpoint for sending logging, event tracking and performance data.

#### 2.6 PERFORMANCE ISSUES

This section describes the performance issues of an SOA middleware that inhibit their appropriateness for systems with high performance requirements.

#### 2.6.1 Distributed Architecture

A system implemented according to the principles of SOA is a distributed system. Services are hosted on different locations belonging to different departments and even organizations. Hence, the performance drawbacks of a distributed system generally also apply to SOA. This includes the marshalling of the data that needs to be sent

to the service provider by the service consumer, sending the data over the network and the unmarshalling of data by the service provider.

#### 2.6.2 Integration of Heterogeneous Technologies

A main goal of introducing an SOA is to integrate applications implemented with heterogeneous technologies. This is achieved by using specific middleware and intermediate protocols for the communication. These protocols are typically based on XML, like SOAP (SOAP Specification, 2007). XML, as a very verbose language, adds a lot of meta-data to the actual payload of a message. The resulting request is about 10 to 20 times larger than the equivalent binary representation (O'Brien et al., 2007), which leads to a significant higher transmission time of the message. Processing these messages is also time-consuming, as they need to get parsed by a XML parser before the actual processing can occur.

The usage of a middleware like an Enterprise Service Bus (ESB) adds further performance costs. An ESB usually processes the messages during transferring. Among other things, this includes the mapping between different protocols used by service providers and service consumers, checking the correctness of the request format, adding message-level security and routing the request to the appropriate service provider (See, for example, Josuttis (2007) or Krafzig et al. (2005)).

#### 2.6.3 Loose Coupling

Another aspect of SOA that has an impact on performance is the utilisation of loose coupling. The aim of loose coupling is to increase the flexibility and maintainability of the application landscape by reducing the dependency of its components on each other. This denotes that service consumers shouldn't make any assumptions about the implementation of the services they use and vice versa. Services become interchangeable as long they implement the interface the client expects.

Engels et al. (2008) consider two components A and B loosely coupled when the following constraints are satisfied:

#### Knowlegde

Component A knows only as much as it is needed to use the operations offered by component B in a proper way. This includes the syntax and semantic of the interfaces and the structure of the transferred data.

#### Dependence on availability

Component A provides the implemented service even when component B is not available or the connection to component B is not available.

#### • Trust

Component B does not rely on component A to comply with pre-conditions. Component A does not rely on component B to comply with post-conditions.

The gains in flexibility and maintainability of loose coupling are amongst others opposed by performance costs.

Service consumers and service provider are not bound to each other statically. Thus, the service consumer needs to determine the correct end point of the service provider during runtime. This can be done by looking up the correct service provider in a service repository either by the service consumer itself before making the call or by routing the message inside the ESB.

Apart from very few basic data types, Service consumers and service providers do not share the same data model. It is therefore necessary to map data between the data model used by the service consumer and the data model used by the service provider.

# 2.7 CURRENT APPROACHES FOR IMPROVING THE PERFORMANCE OF AN SOA MIDDLEWARE

This section describes current approaches to the performance issues introduced in the previous section.

#### 2.7.1 Hardware

The obvious solution to improve the processing time of a service is the utilization of faster hardware and more bandwidth. SOA performance issues are often neglected by suggesting that faster hardware or more bandwidth will solve this problem. However, it is often not feasible to add faster or more hardware due to high cost pressure.

#### 2.7.2 Compression

The usage of XML as an intermediate protocol for service calls has a negative impact on their transmission times over the network. The transmission time of service calls and responses can be decreased by compression. Simply compressing service calls and responses with gzip can do this. The World Wide Web Consortium (W<sub>3</sub>C) proposes a binary presentation of XML documents called binary XML (*EXI Working Group*, 2007) to achieve a more efficient transportation of XML over networks.

It must be pointed out that the utilisation of compression adds the additional costs of compressing and decompressing to the overall processing time of the service call.

#### 2.7.3 Service Granularity

To reduce the communication overhead or the processing time of a service, the service granularity should be reconsidered.

Coarse-grained services reduce the communication overhead by achieving more with a single service call and should be the favoured service design principle (Hess et al., 2006). However, the processing time of a coarse grained service can pose a problem to a service consumer that only needs a fracture of the data provided by the service. To reduce the processing time it could be considered in this case to add a finer grained service that provides only the needed data (Josuttis, 2007).

It should be noted that merging multiple services to form a more coarse grained service or splitting a coarse grained service into multiple services to solve performance problems specific to a single service consumer reduces the reusability of the services for other service consumers (Josuttis, 2007).

#### 2.7.4 Degree of Loose Coupling

The improvements in flexibility and maintainability gained by loose coupling are opposed by drawbacks on performance. Thus, it is crucial to find the appropriate degree of loose coupling.

Hess et al. (2006) introduce the concept of distance to determine an appropriate degree of coupling between components. The distance of components is comprised of the functional and technical distance. Components are functional distant if they share few functional similarities. Components are technical distant if they are of a different category. Categories classify different types of components like inventory components, process components, function components and interaction components.

Distant components trust each other in regard to the compliance of services levels to a lesser extent than near components do. The same applies to their common knowledge. Distant components share a lesser extent of knowledge of each other. Therefore, Hess et al. (2006) argue that distant components should be coupled more loosely than close components.

The degree of loose coupling between components that have been identified to be performance bottlenecks should be reconsidered to find the appropriate trade-off between flexibility and performance. It can be acceptable in that case to decrease the flexibility in favour of a better performance.

#### 2.8 SUMMARY

Message-oriented middleware facilitates the integration of applications using asynchronous messages. An Enterprise Service Bus is such a middleware combining messaging, web services, data transformation and intelligent routing. Message-based systems are able to provide near-time processing of data due to their lower latency compared with batch processing systems. The advantage of a lower latency comes with a performance cost in regard to a lower throughput because of the additional overhead for each processed message. Every message needs amongst others to be serialised and deserialised, mapped between different protocols and routed to the appropriate receiving system.

Current approaches to improve the throughput performance of message-based systems try to reduce the transmission time by compressing messages. Another approach is to adjust the service granularity to form more coarse-grained services or to adjust the degree of loose coupling to reduce the communication overhead.

While these approaches generally improve the performance of message-based systems, they are still not able provide the same throughput as that can be achieved with a batch processing system. Additionally, the current approaches are static and thus need to be considered at the design-time of the system. The next chapter presents an SOA middle-ware for high performance near-time processing of bulk data which is a novel approach to dynamically reduce the latency of a system while still providing high throughput.

#### RELATED WORK

This chapter gives an overview of work related to this PhD project (see figure 7). It starts with work that addresses the performance of Service-Oriented systems in general. Further work in the area of SOA performance can be classified into the categories performance modeling, performance measuring and performance optimisation.

The proposed middleware for high-performance near-time processing of bulk data adjusts the data granularity itself at runtime. Work on middleware discusses different approaches for self-adjustment and self-awareness of middleware, which can be classified as adaptive or reflective middleware, discussed in the next section.

In order to dynamically adjust the data granularity at runtime, the proposed middleware needs to constantly measure the throughput and latency of the system. Work on SLA-monitoring proposes different approaches to monitor the compliance of business processes to Service Level Agreements.

Finally, the chapter concludes with a summary which relates the discussed approaches to the approach proposed in this PhD project.



Figure 7: Related Work

#### 3.1 PERFORMANCE OF SERVICE-ORIENTED SYSTEMS

O'Brien et al. (2007) argue that the introduction of an SOA generally has a negative impact on the performance of the system. They identify the following key aspects responsible for the performance degradation:

#### • Network communication

Service provider and service consumer need to communicate over a network, which usually does not offer a deterministic latency.

#### • Lookup of services in a directory

The lookup of a service provider in a directory increases the total transaction time of a service request.

# Interoperability of services on different platforms The interoperability of services on different platforms is real-

ized by a middleware which handles the whole communication. The needed marshalling and unmarshalling of data adds a performance overhead to the communication.

#### • Usage of standard messaging formats

The usage of a standard message format, like XML, increases the processing time of a service due to parsing, validation and transformation of messages. An XML message can be 10 to 20 times larger than the binary representation which increases the the transport time of the message over the network.

In another paper, O'Brien et al. (2008) state that the performance issues of an SOA are caused by:

- Overhead of XML
- Implementation of composite services
- Service orchestration
- Service invocation
- Resources, e.g. threads, CPUs
- Resource models, e.g. virtualization

The authors suggest that it is vital to consider performance aspects early in the development lifecycle, which can be supported by using an SOA performance model.

Woodall et al. (2007) describe in their paper the challenges they encountered when analysing a performance problem of a concrete Service-Oriented System:

- Physical distribution of services
- Continual use of services by local users or developers during the performance investigation
- Heterogeneity of the underlying service software plattform

#### 3.2 PERFORMANCE MODELING

Performance modeling allows to predict the performance of a system in an early stage of development. It facilitates for example capacity and resource planning before the system is already available or helps to evaluate design alternatives in regard of their performance impact.

Brebner (2008) developed a tool for performance modeling of Service-Oriented Architectures. It is comprised of SOA models, a simulation engine and a graphical user interface. The SOA models are generated from architectural artifacts such as UML sequence or deployment diagrams and automatically transformed into runtime models for execution.

An approach to predict the performance of J2EE applications using messaging services using queueing network models has been presented by Liu et al. (2007). As opposed to prior approaches, their solution models the underlying component infrastructure that implements the messaging service which allows an accurate prediction with an error within 15% when compared to the real performance of the implemented system.

In another work, Liu et al. (2007) developed a performance model of an service-oriented application based on an Enterprise Service Bus using a queuing network. Their modeling approach includes the following steps:

- Mapping of application components of the design level to analytical model elements
- Characterisation of workload patterns for the application components used as input for performance model
- Calibrating the performance model
- Validating the performance model

D'Ambrogio and Bocciarelli (2007) describe "a model-driven approach for integrating performance prediction into service composition processes carried out by use of BPEL (Business Process Execution Language for Web Services)." Using their approach, a BPEL process is described using an UML model. The model is automatically annotated with performance data and transformed into a Layered Queueing Network which is used to predict the performance of the BPEL process. For the automatic annotation of the model, a performance-oriented extension to WSDL is utilised called P-WSDL (D'Ambrogio, 2005).

#### 3.3 PERFORMANCE MEASURING

Performance measuring is applied to evaluate if an implemented system meets its performance requirements and to spot possible performance problems.

Her et al. (2007) propose the following set of metrics for measuring the performance of a service-oriented system:

#### • Service response time

Elapsed time between the end of request to service and the beginning of the response of the service. This metric is further split in 20 sub-metrics such as message processing time, service composition time and service discovery time.

#### • Think time

Elapsed time between the end of a response generated by a service and the beginning of a response of an end user.

#### • Service tournaround time

Time needed to get the result from a group of related activities within a transaction.

#### • Throughput

Number of requests served at a given period of time. The authors distinguish between the throughput of a service and the throughput of a business process.

In their work, Henjes et al. investigated the throughput performance of the JMS server FioranaMQ, SunMQ and WebsphereMQ. The authors came to the following conclusion (Henjes et al. (2006) and Menth et al. (2006a)):

- Message persistence reduces the throughput significantly.
- Message replication increases the overall throughput of the server.
- Throughput is limited either by the processing logic for small messages or by the transmission capacity for large messages.
- Filtering reduces the throughput significantly.

Chen and Greenfield (2004) propose that the following performance metrics should be used to evaluate a JMS server:

- Maximum sustainable throughput
- Latency
- Elapsed time taken to send batches messages
- Persistent message loss after recovery

The authors state that "although messaging latency is easy to understand, it is difficult to measure precisely in a distributed environment without synchronised high- precision clocks." They discovered that latencies increase with increasing message sizes.

SPECjms2007 is a standard benchmark for the evaluation of Message-Oriented Middleware platforms using JMS (Sachs et al., 2009). It provides a flexible performance analysis framework for tailoring the workload to specific user requirements. According to Sachs et al. (2007), the workload of the SPECjms2007 benchmark has to meet the following requirements:

#### Representativeness

The workload should reflect how the messaging platform is used in typical user scenarios.

#### Comprehensiveness

The workload should incorporate all platform features typically used in JMS application including publish/subscript and point-to-point messaging.

#### Focus

The workload should focus on measuring the performance of the messaging middleware and should minimize the impact of other components and services.

#### Configurability

It should be possible to configure the workload to meet the requirements of the user.

#### Scalability

It should be possible to scale the workload by the number of destinations with a fixed traffic per destination or by increasing the traffic with a fixed set of destinations.

#### 3.4 PERFORMANCE OPTIMISATION

Most of the work that aims to optimise the performance of serviceoriented systems is done in the area of Web Services since it is a common technology to implement a SOA.

In particular, various approaches have been proposed to optimise the performance of SOAP, the standard protocol for Web Service communication. This includes approaches for optimising the processing of SOAP messages (see for example Abu-Ghazaleh and Lewis (2005), Suzumura et al. (2005) and Ng (2006)), compression of SOAP messages (see for example Estrella et al. (2008) and Ng et al. (2005)) and caching (see for example Andresen et al. (2004) and Devaram and Andresen (2003)).

Wichaiwong and Jaruskulchai (2007) propose an approach to transfer bulk data between web services per FTP. The SOAP messages transferred between the web services would only contain the necessary details how to download the corresponding data from an FTP server since this protocol is optimized for transferring huge files. This approach solves the technical aspect of efficiently transferring the input and output data but does not pose any solutions how to implement loose coupling and how to integrate heterogeneous technologies, the fundamental means of an SOA to improve the flexibility of an application landscape.

Data-Grey-Box Web Services are an approach to transfer bulk data between Web Services (Habich, Richly and Grasselt, 2007). Instead of transferring the data wrapped in SOAP messages, it is transferred using an external data layer. For example when using database systems as data layer, this facilitates the use of special data transfer methods such ETL (Extract, Transform, Load) to transport the data between the database of the service requestor and the database of the Web service. The data transfer is transparent for both service participants in this case. The approach includes an extension of the Web service interface with properties describing the data aspects. Compared to

the SOAP approach, the authors measured a speedup of up to 16 using their proposed approach. To allow the composition and execution of Data-Grey-Box Web services, Habich, Richly, Preissler, Grasselt, Lehner and Maier (2007) developed BPEL data transitions to explicitly specify data flows in BPEL processes.

#### 3.5 SELF-ADAPTIVE MIDDLEWARE

Self-Adaptive Software is a "a closed-loop system with a feedback loop aiming to adjust itself to changes during its operation" (Salehie and Tahvildari, 2009). These changes can originate from internal causes of the system (the system's self) or from the context of the system.

Laddaga and Robertson (2008) provides a definition for self-adaptive software: "Self-adaptive software evaluates its own behavior and changes behavior when the evaluation indicates that it is not accomplishing what the software is intended to do, or when better functionality or performance is possible."

Another definition is given by Oreizy et al. (1999): "Self-adaptive software modifies its own behavior in response to changes in its operating environment. By operating environment, we mean anything observable by the software system, such as end-user input, external hardware devices and sensors, or program instrumentation."

Salehie and Tahvildari (2009) describe the following properties (also called self-\* properties) of a self-adaptive system:

#### Self-configuring

The system is able to reconfigure itself in response to changes.

#### Self-healing

The system is able to discover, diagnose and react on failures.

#### Self-optimizing

The system is able to manage performance and resource allocation to meet different performance requirements.

#### Self-protecting

The system is able to detect security breaches and to recover from them.

More general self-\* properties are described as:

#### • Self-Awareness

The system is aware of its self states and behaviours.

#### • Context-Awareness

The system is aware of its context.

Duran-Limon et al. (2004) argue that "the moste adequate level and natural locus for applying adaption is at the middleware level".

Adaption at the operating system level is platform-dependent and changes at this level affect every application running on the same node. On the other hand, adaption at application level assigns the responsibility to the developer and is also not reusable.

Lee et al. (2009) propose an adaptive, general-purpose runtime infrastructure for effective resource management of the infrastructure. Their approach is comprised of three components:

- 1. dynamic performance prediction
- 2. adaptive intra-site performance management
- 3. adaptive inter-site resource management

The runtime infrastructure is able to choose from a set of performance predictions for a given service and to dynamically choose the most appropriate prediction over time by using the prediction history of the service.

AutoGlobe (Gmach et al., 2008) provides a platform for adaptive resource management comprised of

- 1. Static resource management
- 2. Dynamic resource management
- 3. Adaptive control of Service Level Agreements (SLA)

Static resource management optimises the allocation of services to computing resources and is based on on automatically detected service utilisation patterns. Dynamic resource management uses a fuzzy controller to handle exceptional situations at runtime. The Adaptive control of Service Level Agreements schedules service requests depending on their SLA agreement.

The coBRA framework proposed by Irmert et al. (2008) is an approach to replace service implementations at runtime as a foundation for self-adaptive applications. The framework facilitates the replacement of software components to switch the implementation of a service with the interface of the service staying the same.

DREAM (Dynamic Reflective Asynchronous Middleware) (Leclercq et al., 2004) is a component-based framework for the construction of reflective Message-Oriented Middleware. Reflective middleware "refers to the use of a causally connected self-presentation to support the inspection and adaption of the middleware system" (Kon et al., 2002). DREAM is based on FRACTAL, a generic component framework and supports various asynchronous communication paradigms such as message passing, event-reaction and publish/subscribe. DREAM facilitates the construction and configuration of Message-Oriented Middleware from a library of components such as message queues, filters, routers and aggregators, which can be assembled either at deploy-time or runtime.

#### 3.6 SLA-MONITORING OF BUSINESS PROCESSES

The SECMOL framework (Service Centric Monitoring Language), developed by Guinea et al. (2009), allows to monitor the quality of service constraints of BPEL processes. It is comprised of three components. Data Collectors for capturing data, Data Analyzers for analysing the captured data and the Monitoring Manager for coordinating the monitoring process. SECMOL also defines a XML-based monitoring specification, which consists of monitoring policies that specify how the monitoring should be done and monitoring rules that express the quality of service properties the system needs to satisfy.

Duc et al. (2009) argue that a monitoring middleware component should fulfill the following requirements:

#### • Coherency of data

All data used in one decision must reflect the same state of the system.

#### • Flexibility in data access

Every monitored service provider should be able to respond using its own measurement units. This should be transparent for the client using the monitoring data.

#### • Performance in data access

The monitoring should have the slightest possible impact on the performance of the business process.

#### • Network usage optimisation

The transmission of monitoring data should have the slightest possible impact on the network performance.

The authors propose M4ABP (Monitoring for Adaptive Business Process), a distributed monitoring and data delivery middleware subsystem, which implements these requirements.

SALMon (Ameller and Franch, 2008) is a system for monitoring the services of an SOA for Service Level Agreement violations. It is itself implemented as an service-oriented system and consists of the following services:

#### • Monitor

The Monitor service collects the monitoring data from components called Measure Instruments that are instantiated in each monitored service.

#### Analyzer

The Analyzer service manages the Monitor service and checks for Service Level Agreement violations of the monitored services.

#### Decision Maker

The Decision Maker service is able to select an action to solve the SLA violation. The appropriate action for a specific SLA violation is stored in a repository.

The attributes measured by SALMon are taken from an ISO/IEC 9126-1-based quality model.

Textor et al. (2009) propose an approach to map implementation level monitoring data to business level activities. Non-functional constraints are specified on a workflow model in the modelling phase. Additionally, an instrumentation model is used to specify the instrumentation points of the application. At runtime, the monitoring data of the system is mapped to the workflow model. The monitoring data is received by a component called ConstraintMonitor, which evaluates and validates the constraints specified in the workflow model.

Wetzstein et al. (2009) present a framework to monitor and analyse the factors that influence the performance of WS-BPEL processes. The authors distinguish between PPM (Process Performance Metrics) and QoS (Quality of Service) metrics, which influence the Key Performance Indicators (KPI) of business processes. PPMs are based on process runtime events, that are published by the WS-BPEL runtime engine, for example the "number of orders which can be served as inhouse stock". QoS metrics are technical parameters of the underlying services that implement the business process, for example the response time and availability of a service. KPIs are based on business goals, for example "order fulfillment lead time < 3". The proposed framework monitors KPIs, PPMs and QoS metrics at runtime, which are modeled in a Process Metrics Definition Model (PMDM). These collected metrics can then be used to perform a dependency analysis of the influential factors of a KPI using machine learning techniques to construct dependency trees.

iBOM (Castellanos et al., 2005) is a platform to analyse, manage and optimise business operations based on business goals. Optimisations are performed by using simulation techniques. iBom simulates different configurations of a business process to identify the configuration that best meets the business goals. First, the user needs to define the optimisation metric and constraints on this metric and on the resources. The configuration candidates are then either computed by iBOM using different resource allocations of the given configuration within the defined constraints or are provided by the user in the form of a process model.

#### 3.7 SUMMARY

Most of the work done in the field of performance of service-oriented systems involves performance aspects of Web Services including the SOAP standard. This includes performance modeling, performance measuring and performance optimisation.

Approaches to optimise the transfer of bulk data of Web services, as proposed by Wichaiwong and Jaruskulchai (2007) and Habich, Richly and Grasselt (2007) deliver an overall better performance than using SOAP. However, like a traditional batch-processing system using file-or database-based integration, they are not able to reduce the latency and thus cannot deliver near-time processing of bulk data.

Current self-adapting middleware platforms, like the AutoGlobe platform (Gmach et al., 2008), are focused on adaptive resource management to dynamically allocate services to computing nodes or to replace service implementations at runtime, as proposed by the co-BRA framework (Irmert et al., 2008).

Work on SLA-monitoring of business processes proposes different approaches to monitor the compliance of a business process to Service Level Agreements, which include the end-to-end latency and throughput of the business process. However, they do not propose any solutions for improving the end-to-end latency in order to provide near-time processing of bulk data.

The research project presented in this report proposes an adaptive middleware to reduce the latency of a system for bulk data processing by dynamically adjusting the data granularity at runtime based on the current throughput and the minimum acceptable throughput of the system. To the best of our knowledge, this is a novel approach which has not yet been discussed in current literature.

# Part II CONTRIBUTIONS

# PERFORMANCE EVALUATION OF BATCH AND MESSAGE-BASED SYSTEMS

#### 4.1 INTRODUCTION

Traditionally, business information systems for bulk data processing are implemented as batch processing systems. Batch processing delivers high throughput but cannot provide near-time processing of data, that is the end-to-end latency of such a system is high.

A lower end-to-end latency can be achieved by using message-based processing, for example by utilising a message-oriented middleware for the integration of the services that form the business information system. While this approach is able to deliver near-time processing, it is hardly capable for bulk data processing due to the additional communication over- head for each processed message. Therefore, message-based processing is ususally not considered for building a system for bulk data processing requiring high throughput.

This chapter compares the performance of a batch and messagebased system. The main objectives of this comparison are:

- What is the impact of different processing styles, that is batch and message-based processing, on throughput and latency?
- What is the impact of data granularity on latency and throughput when using a message-based processing style?

To find solutions for these questions, the following approach has been taken:

- Two prototypes of a billing system for each processing type (see Section 4.2) have been built.
- A performance evaluation has been conducted to compare the prototypes with each other with the focus on throughput and latency (see Section 4.3).
- To evaluate the impact of different aggregatation sizes on throughput and latency, the messaging prototype has been extended with an aggregator. A performance test has been conducted with different static aggregation sizes (see Section 4.4).

This chapter is organised as follows. Section 4.2 introduces the batch and message-based prototype systems that have been implemented. To compare the performance characterics of the two process-

ing types, batch processing and message-based processing, a performance evaluation has been conducted, which is presented in Section 4.3. Section 4.4 shows the impact of data granularity on throughput and latency of the messaging prototype. Section 4.5 gives an overview of other work related to the contents of this chapter. Finally, this chapter concludes with a summary in Section 4.6

#### 4.2 A REAL WORLD EXAMPLE APPLICATION

This section introduces the two prototypes of a billing system that have been built to evaluate the performance of batch and messagebased processing.

A billing system is a distributed system consisting of several sub components that process the different billing sub processes like mediation, rating, billing and presentment (see Figure 8).



Figure 8: Billing process

The mediation components receive usage events from delivery systems, like switches and transform them into a format the billing system is able to process. For example, transforming the event records to the internal record format of the rating and billing engine or adding internal keys that are later needed in the process. The rating engine assigns the events to the specific customer account, called guiding, and determines the price of the event, depending on the applicable tariff. It also splits events if more than one tariff is applicable or the customer qualifies for a discount. The billing engine calculates the total amount of the bill by adding the rated events, recurring and one-time charges and discounts. The output is processed by the presentment components, which format the bill, print it, or present it to the customer in self-service systems, for example on a website.

In order to compare batch and message-based types of processing, two different prototypes of a billing application have been developed. Each prototype implements the mediation and rating steps of the billing process. Figure 9 shows the components of the billing prototype:

#### Event Generator

The *Event Generator* generates the calling events, i.e. the Call Detail Records (CDR) that are processed by the billing application.

# • Mediation

The *Mediation* component checks wether the calltime of the calldetail record exceeds the minimal billable length or if it belongs to

a flatrate account and sets the corresponding flags of the record. The output of the *Mediation* component are Normalized Call Detail Records (NCDR) that are further processed by the *Rating* component.

# Rating

The *Rating* component processes the output from the *Mediation* component. It assigns the calldetail record to a customer account and determines the price of the call event by looking up the correspondant product and tariff in the *Master Data DB*. The output of the *Rating* component (costed events) is afterwards written to the *Costed Events DB*.

#### • Master Data DB

The *Master Data DB* contains products, tariffs and accounts used by the *Event Generator* and the *Rating* component.

# • Costed Events DB

The *Costed Events DB* contains the result of the *Rating* component, i.e. the costed events.

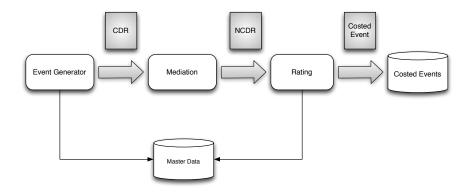


Figure 9: Components of the billing application prototype

The prototypes are implemented with Java 1.6 using Java Persistence API (JPA) for the data-access layer and a MySQL database. To ensure comparability, the prototypes share the same business components, database and data-access layer, varying only in different integration layers (see Figure 10).

# 4.2.1 *Batch prototype*

The batch prototype implements the billing application utilizing the batch processing type. It uses the Spring Batch framework (*Spring Batch*, 2013), a Java framework that facilitates the implementation of batch applications by providing basic building blocks for reading, writing and processing data.

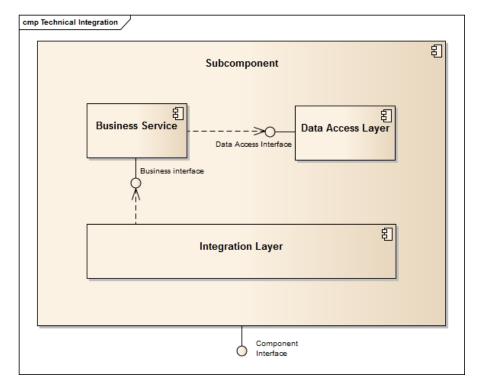


Figure 10: The prototypes share the same business components, database and data-access layer.

Figure 11 shows the architecture of the batch prototype. It consists of two nodes, mediation batch and rating batch, each implemented as a separate spring batch application. The nodes are integrated using Apache Camel (*Apache Camel*, 2014), an Java integration framework based on enterprise integration patterns, as described by Hohpe and Woolf (2003). Apache Camel is responsible for listening on the file system, calling the Spring batch application when a file arrives and transferring the output from the mediation batch node to the rating batch node using File Transfer Protocol (FTP).

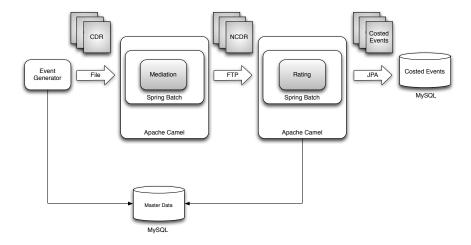


Figure 11: Batch prototype

The batch prototype performs the following steps:

- 1. The *Event generator* generates call detail records and writes them to a single file.
- 2. The *Mediation component* opens the file, processes it and writes the output to a single output file. The output file is getting transfered using FTP to the *Rating component*.
- 3. The *Rating component* opens the file, processes it and writes the costed events to the costed event database.

# 4.2.1.1 Implementation details

The main entities in Spring Batch are Jobs and Steps. A Job defines the processing flow of the batch application and consists of one or more steps. A basic step is comprised of an item reader, item processor and item writer (see Figure 12).

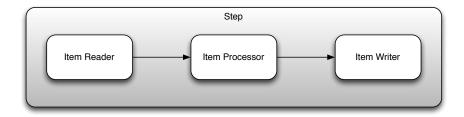


Figure 12: A Step consists of an item reader, item processor and item writer

The item reader reads records of data in chunks, for example from a file, and converts them to objects. These objects are then processed by the item processor, which contains the business logic of the batch application. Finally, the processed objects are getting written to the output destination, for example a database, by the item writer.

Listing 1: Mediation batch job definition

```
<batch:job id="mediationMultiThreadedJob" incrementer="</pre>
      jobRunIdIncrementer">
    <batch:step id="mediationMultiThreadedStep" next="</pre>
2
         renameFileMultiThreadedStep">
      <batch:tasklet transaction-manager="batchTransactionManager"</pre>
3
         start-limit="100"
4
         task-executor="taskExecutor" throttle-limit="${batch.step.
5
             throttle-limit}">
         <batch:chunk reader="rawUsageMultiThreadedEventReader"</pre>
6
             processor="rawUsageEventProcessor" writer="
             loggingSimpleCdrWriter" commit-interval="1000" />
      </batch:tasklet>
8
    </batch:step>
    <batch:step id="renameFileMultiThreadedStep">
```

```
description
```

Listing 1 shows the definition of the mediation batch job mediation-MultiThreadedJob. It consists of two steps, the mediationMultiThreaded-Step (line 2) and the renameFileMultiThreadedStep (line 10). The step mediationMultiThreadedStep is multithreaded and uses 10 threads for processing. It consists of a rawUsageMultiThreadedEventReader (line 6), a thread safe reader implementation that reads call detail records from the input file and converts them to objects, a rawUsageEventProcessor, that processes the call detail objects by calling the mediation business logic and a loggingSimpleCdrWriter (line 7), which writes the processed call detail objects to the output file. The step uses an commit interval of 1000, meaning that the input data is processed in chunks of 1000 records. After the input file has been processed by the mediationMultiThreadedStep it is getting renamed to its final name by the renameFileMultiThreadedStep (line 10).

The mediation batch job is integrated using Apache Camel. Listing 2 shows the definition of the mediation batch route.

Listing 2: Mediation batch route definition

It consists of two routes, the first route listens on the file system for incoming files (line 2) and calls the mediation batch job, when a file arrives (line 3). The second route transfers the output file of the mediation batch job to the rating batch node using FTP (line 5-6).

Listing 3 shows the definition of the rating batch job *ratingMulti-ThreadedJob*. It consists of a single step *ratingMultiThreadedStep* (line 2), which is comprised of a *simpleCdrMultiThreadedItemReader*, which reads the normalized call detail records written by the mediation batch node, a *simpleCdrProcessor*, that processes the normalized call detail records by calling the rating business logic and a *costedEven-tWriter*, which writes the processed costed events to the Costed Events database (line 4).

Listing 3: Rating batch job definition

# 4.2.2 Messaging prototype

The messaging prototype implements the billing prototype utilizing the message-oriented processing type. It uses Apache Camel (*Apache Camel*, 2014) as the messaging middleware.

Figure 13 shows the architecture of the messaging prototype. It consists of three nodes, the billing route, mediation service and rating service. The billing route implements the main flow of the application. It is responsible for reading messages from the billing queue, extracting the payload, calling the mediation and rating service and writing the processed messages to the database. The mediation service is a webservice representing the mediation component. It is a SOAP service implemented using Apache CXF and runs inside an Apache Tomcat container. The same applies to the rating service, representing the rating component.

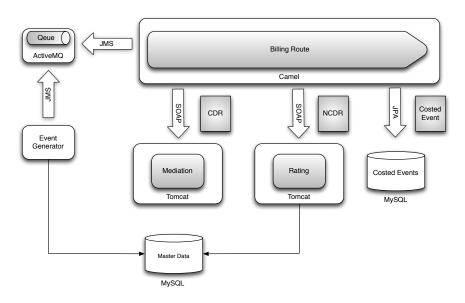


Figure 13: Message-based prototype

Listing 4 shows the definition of the billing route using the Apache Camel fluent Application Programming Interface (API). The billing route performs the following steps:

- 1. The message is read from the billing queue using Java Messaging Service (JMS) (line 5). The queue ist hosted by an Apache ActiveMQ instance.
- 2. The message is unmarshalled using Java Architecture for XML Binding (JAXB) (line 6).
- 3. The *Mediation service* is called by the CXF Endpoint of the billing route (line 7)
- 4. The response of the *Mediation webservice*, the normalized call detail record, is unmarshalled (line 8).
- 5. The *Rating service* is called by the CXF Endpoint of the billing route (line 9).
- 6. The response of the *Rating webservice*, that is the costed event, is unmarshalled (line 10).
- 7. The costed event is written to the *Costed Events DB* (line 11).

If an error occurs during the processing of an event, it is written to an error JMS queue (line 3).

Listing 4: Billing route definition

```
public void configure() {
2
     errorHandler(deadLetterChannel("activemq:queue:BILLING.ERRORS")
3
4
     from("activemq:queue:BILLING.USAGE_EVENTS")
5
       .unmarshal("jaxbContext")
6
       .to("cxf:bean:mediationEndpoint?dataFormat=P0J0&
7
           defaultOperationName=processEvent")
       .process(new ProcessEventPostProcessor())
8
       .to("cxf:bean:ratingEndpoint?dataFormat=P0J0&
9
           defaultOperationName=processCallDetail")
       .process(new ProcessCallDetailPostProcessor())
10
       .process(costedEventProcessor);
11
12 | }
```

# 4.3 PERFORMANCE EVALUATION

To compare the performance characterics of the two processing types, batch processing and message-based processing, a performance evaluation has been conducted with the main focus on latency and throughput.

This section describes the approach and the results of the performance evaluation.

# 4.3.1 Measuring points

A number of measuring points have been defined for each prototype by breaking down the processing in single steps and assigning a measuring point to each step. Figure 14 and 15 show the measuring points of the batch prototype and the messaging prototype.

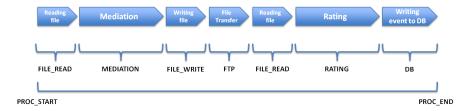


Figure 14: Measuring points of the batch prototye

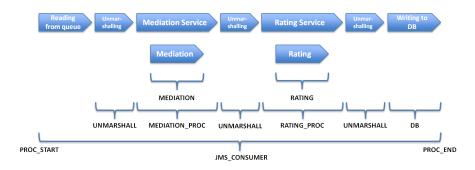


Figure 15: Measuring points of the messaging prototype

A detailed description of each point is shown in Table 2 and 3.

#### 4.3.2 *Instrumentation*

A logging statement for each measuring point has been added at the appropriate code location of the prototypes using different techniques.

# 1. Directly in the code

Whenever possible, the logging statements have been inserted directly in the code. This has been the case, when the code that should be measured, has been written exclusively for the protoype, for example the mediation and rating components.

#### 2. Delegation

When the code to instrument has been part of a framework that is configurable using Spring, an instrumented delegate has been used.

# 3. **AOP**

Finally, when the code that should get instrumented was part

| Measuring point | Description   |  |
|-----------------|---|--|
| PROC_START      | Timestamp denoting the start of processing an event |  |
| PROC_END        | Timestamp denoting the end of processing an event   |  |
| FILE_READ       | Elapsed time for reading events from file           |  |
| MEDIATION       | Elapsed time used by the mediation component        |  |
| FILE_WRITE      | Elapsed time for writing events to file             |  |
| FTP             | Elapsed time for file transfer using FTP            |  |
| RATING          | Elapsed time used by the rating component           |  |
| DB              | Elapsed time for writing event to the database      |  |

Table 2: Measuring points of the batch prototype

of a framework that was not configurable using Spring, the logging statements have been added using aspects, which are woven into the resulting class files using AspectJ.

# 4.3.3 Test environment

The two prototypes have been deployed to an Amazon EC2 environment to conduct the performance evaluation, with the characterics described in Table 4.

# 4.3.3.1 *Batch prototype*

The batch prototype comprises two EC2 nodes, the *Mediation Node* and the *Rating Node*, containing the *Mediation Batch* and the *Rating Batch*, respectively. The *Costed Event Database* is hosted on the *Rating Node* as well. Figure 16 shows the deployment diagramm of the Batch prototype.

# 4.3.3.2 *Messaging Prototype*

The messaging prototype consists of three EC2 nodes, as shown in Figure 17. The *Master Node* hosts the *ActiveMQ Server* which runs the JMS queue containing the billing events, the *Billing Route*, which implements the processing flow of the prototype and the *MySQL Database* containing the *Costed Event Database*. The *Mediation Node* and

Table 3: Measuring points of the messaging prototype

| 9 01            | 0 01 71   |
|-----------------|---|
| Measuring point | Description   |
| PROC_START      | Timestamp denoting the start of processing an event   |
| PROC_END        | Timestamp denoting the end of processing an event     |
| JMS_CONSUMER    | Elapsed time processing a single event                |
| UNMARSHALL      | Elapsed time for unmar-<br>shalling an event          |
| MEDIATION_PROC  | Elapsed time needed for calling the mediation service |
| MEDIATION       | Elapsed time used by the mediation component          |
| RATING_PROC     | Elapsed time needed for calling the rating service    |
| RATING          | Elapsed time used by the rating component             |
| DB              | Elapsed time for writing event to the database        |

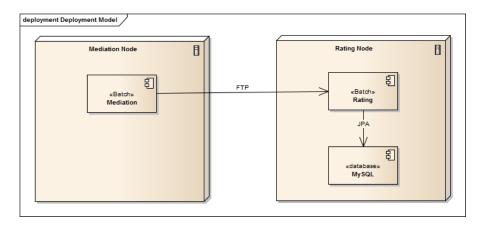


Figure 16: Batch prototype deployment on EC2 instances

Rating Node are containing the Mediation Service and Rating Service, respectively, with each service running inside an Apache Tomcat container.

# 4.3.4 Clock Synchronization

The clocks of the *Mediation Node* and *Rating Node* are synchronized with the clock of the *Master Node* using PTPd (*PTP daemon (PTPd)*, 2013), an implementation of the Precision Time Protocol (PTP) (IEEE, 2008). The clock of the *Master Node* itself is synchronised with a public timeserver using the Network Time Protocol (NTP). Using this approach, a sub-millisecond precision is achieved.

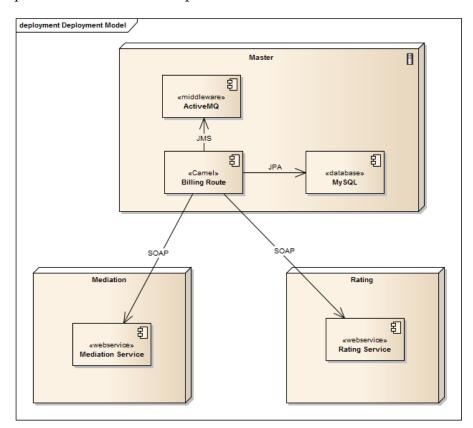


Figure 17: Messaging prototype deployment on EC2 instances

# 4.3.5 Preparation and execution of the performance tests

For running the performance tests, the Master Data DB has been set up with a list of customers, accounts, products and tariffs with each prototype using the same database and data. While part of the testdata like the products and tariffs have been created manually, the relationship between the customers and the products have been generated by a test data generator.

| Instance type          | M1 Extra Large (EBS optimized)          |
|------------------------|---|
| Memory                 | 15 GiB                                  |
| Virtual Cores          | 8 (4 cores x 2 units)                   |
| Architecture           | 64-bit                                  |
| EBS Volume             | 10 GiB (100 IOPS)                       |
| Instance Store Volumes | 1690 GB (4x420 GB<br>Raid 0)            |
| Operating System       | Ubuntu 12.04 LTS                        |
|                        | (GNU/Linux 3.2.0-<br>25-virtual x86_64) |
| Database               | MySQL 5.5.24                            |
| Messaging Middleware   | Apache ActiveMQ 5.6.0                   |

Table 4: Amazon EC2 instance configuration

After setting up the master data, a number of test runs have been executed using different sizes of test data (1.000, 5.000, 10.000, 50.000, 100.000, 500.000, 1.000.000 records). To get reliable results, each test configuration has been run three times. Out of the three runs for each configuration, the run having the median processing time has been used for the evaluation.

For each test run, the following steps have been executed:

# 1. Generating test data

In case of the batch prototype, the event generator writes the test data to file. In case of the messaging prototype, the event generator writes the test data to a JMS queue.

# 2. Running the test

Each prototype listens on the file system and the JMS queue, respectively. Using the batch prototype, the processing starts when the input file is copied to the input folder of the mediation batch application by the event genarotor. Using the messaging prototype, the processing starts when the first event is written to the JMS queue by the test generator.

# 3. Validating the results

Processsing the log files written during the test run

#### 4. Cleaning up

Deleting the created costed events from the DB.

Before running the tests, each prototype has been warmed up by processing 10.000 records.

# 4.3.6 Results

The performance evaluation yields the following results.

# 4.3.6.1 Throughput

The throughput per second for a test run with N records is defined as

$$TP/s_N = N/PT_N$$

with  $PT_N$  being the total processing time for N records. Figure 18 shows the measured throughput of the batch and messaging prototypes. The messaging prototype is able to process about 70 events per second. The maximum throughput of the batch prototype is about 383 records per second which is reached with an input of 1.000.000 records.

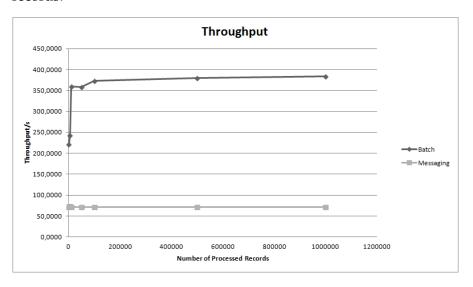


Figure 18: Throughput

# 4.3.6.2 *Latency*

Figure 19 shows the measured latencies of the batch and messaging prototypes. To rule out peaks, the 95th percentile has been used, that is, 95% of the measured latencies are below this value. In case of the batch prototype, the 95th percentile latency is a linear function of the amount of data. The latency increases proportionally to the number of processed records. In case of the messaging prototype, the 95th percentile latency is approximately a constant value which is independant of the number of processed records.

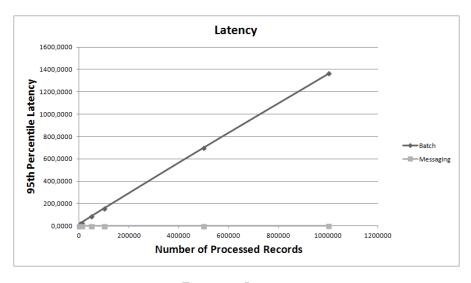


Figure 19: Latency

# 4.3.6.3 Processing overhead

The overhead of the batch prototype is about 7% of the total processing time, independant of the number of processed records, as shown in Figure 20. This overhead contains file operations, such as opening, reading, writing and closing of input files, the file transfer between the Mediation and Rating Nodes and the database transactions to write the the processed event to the Costed Events DB.

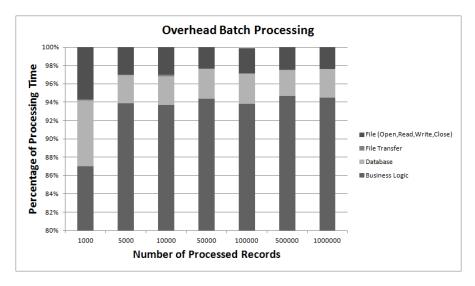


Figure 20: Overhead batch prototype

On the contrary, the overhead of the messaging prototype is about 84% of the total processing time (see Figure 21). In case of the messaging prototype, the overhead contains the JMS overhead, that is the overhead for reading events from the message queue, the webservice overhead needed for calling the Mediation and Rating services including marshalling and unmarshalling of input data and the overhead

caused the database transactions to write the processed events to the Costed Events DB. Most of the overhead is induced by the webservice overhead and the database overhead. Since every event is written to the database in its own transaction, the database overhead of the messaging prototype is much larger than the database overhead of the batch prototype.

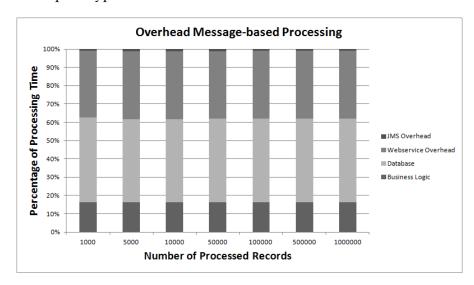


Figure 21: Overhead messaging prototype

# 4.3.6.4 System utilisation

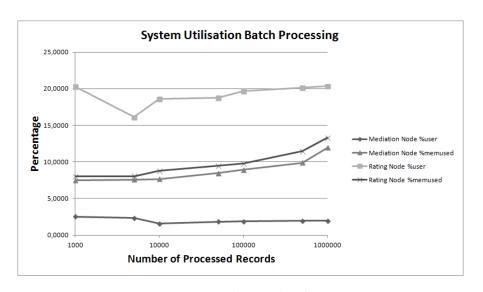


Figure 22: System utilisation batch prototype

The system utilisation has been measured using the sar (System Activity Report) command while running the performance tests. Figure 22 shows the mean percentage of CPU consumption at the user level (%user) and the mean percentage of used memory (%memused) for the Mediation node and Rating node of the Batch prototype. The

CPU utilisation of Medation Node and Ratig Node is about 2% and 19%, respectively. The memory utilisation increases slowly with the number of processed records.

Figure 23 shows the mean CPU consumption and mean memory usage for the nodes of the Messaging prototype. The CPU utilisation of the Master Node, Mediation Node and Rating Node is about 9%, 1% and 6%, respectively. As the same with the batch prototye, the memory utilisation of the messaging prototype increases with the number of processed records. The memory utilisation of the master node peaks at about 38% with 500000 processed records. With 1000000 processed records, the memory utilisation is only about 25%, which presumably can be accounted to the garbage collector.

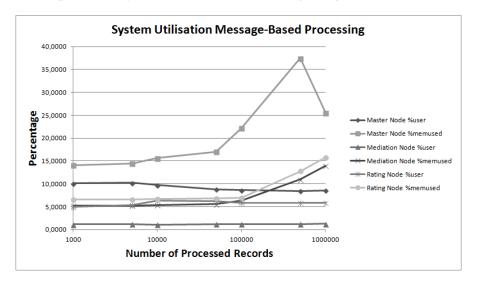


Figure 23: System utilisation messaging prototype

# 4.4 IMPACT OF DATA GRANULARITY ON THROUGHPUT AND LATENCY

The results presented in Section 4.3.6 suggest that the throughput of the messaging prototype can be increased by increasing the granularity of the data that is beeing processed. Data granularity relates to the amount of data that is processed in a unit of work, for example in a single batch run or an event. In order to examine this approach, we have repeated the performance tests using different package sizes for processing the data.

For this purpose, the messaging prototype has been extended to use an aggregator in the messaging route. The aggregator is a stateful filter which stores correlated messages until a set of messages is complete and sends this set to the next processing stage in the messaging route. In case of the messaging prototype, messages are not corelated to each other and also the messages can be processed in an arbitrary order. A set of messages is complete when it reaches the

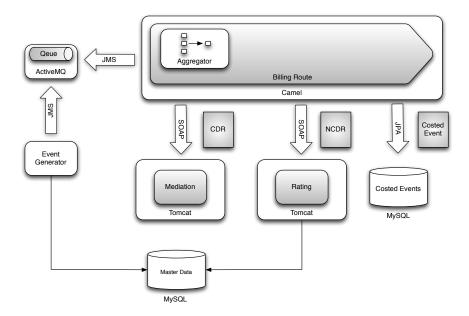


Figure 24: The data granularity is controlled by an aggregator

configured package size. In other scenarios, it is possible to corelate messages by specific data, for example an account number or by a business rule.

Listing 5 shows the definition of the billing route using the aggregator processor, which is provided by Apache Camel (line 7). The aggregator is configured using the correlation expression constant (true), which simply aggregates messages in order of their arrival and the aggregation strategy UsageEventsAggrationStrategy, which implements the merging of incoming messages with already merged messages. The aggregation size is set by completionSize. The specific value is set in a configuration file. As a fallback, completionTimeout defines a timeout in milliseconds to send the set of aggregated messages to the next processing stage before it has reached the defined aggregation size. parallelProcessing indicates that the aggregator should use multiple threads (default is 10) to process the finished sets of aggregated messages.

Listing 5: Billing route definition with an additional aggregator

```
public void configure() {

errorHandler(deadLetterChannel("activemq:queue:BILLING.ERRORS")
    );

from("activemq:queue:BILLING.USAGE_EVENTS")
    .unmarshal("jaxbContext")
    .aggregate(constant(true), new UsageEventsAggrationStrategy()
          ).completionSize(completionSize).completionTimeout(
          completionTimeout).parallelProcessing()
```

Figure 25 shows the impact of different aggregatation sizes on the throughput of the messaging prototype. For each test 100.000 events have been processed. The throughput increases constantly for

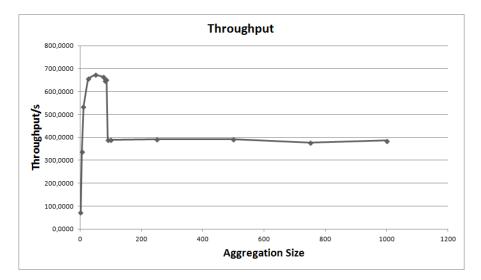


Figure 25: Impact of different aggregation sizes on throughput

1 < aggregation\_size <= 50 with a maximum of 673 events per second with aggregation\_size = 50. Higher aggregation sizes than 50 do not further increase the throughput, it stays around 390 events per second. Surprisingly, the maximum throughput of 673 events per second even outperforms the throughput of the batch prototype which is about 383 records per second. This is presumably a result of the better multithreading capabilities of the camel framework.

Increasing the aggregation size also decreases the processing overhead, as shown in Figure 26. An aggregate size of 10 decreases the overhead by more than 50% compared to an aggregate size of 1. Of course, the integration of the aggregator adds an additional overhead which is insignificant for aggregation\_size > 50.

The increased throughput achieved by increasing the aggregation size comes with the cost of a higher latency. Figure 27 shows the impact of different aggregation sizes on the 95th percentile latency of the messaging prototype.

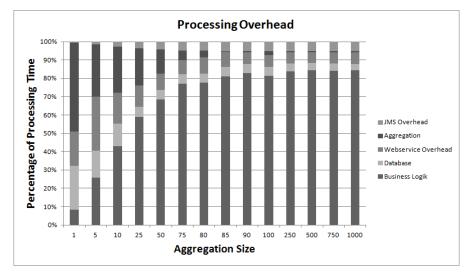


Figure 26: Impact of different aggregation sizes on processing overhead

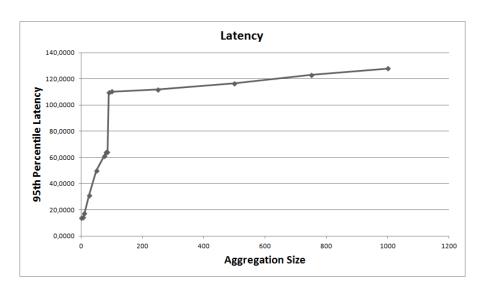


Figure 27: Impact of different aggregation sizes on latency

An aggregation size of 50, resulting in the maximum throughput of 673 events per seconds, shows a 95th percentile latency of about 68 seconds. This latency is significantly higher than the latency of the messaging system without message aggregation, which is about 0,15 seconds (see Section 4.3.6.2).

The results indicate that there is an optimal range for the aggregation size to control the throughput and latency of the system. Setting the aggregation size higher than a certain threshold leads to a throughput drop and latency gain. In case of our prototype, this threshold is between an aggregation size of 85 and 90. The observed throughput drop and latency gain is caused by a congestion in the aggregator. Messages are read faster from the queue than they are getting processed by the aggregator.

Figure 28 shows the impact of different aggregation sizes on the system utilisation. The CPU utilisation of the Master node shows a maximum of 30% with an aggregation size of 25. An aggregation\_size >= 90 results in a CPU utilisation of about 15%. The maximum memory utilisation of the Master node is 41% with an aggregation size of 100.

The maximum system utilisation of the Rating node is 25% with an aggregation size of 80. The memory utilisation is between 7-8% irrespective of aggregation size. Maximum system and memory utilisation of the Mediation node are also irrespective of aggregation size, beeing less than 2% and 8%, respectively.

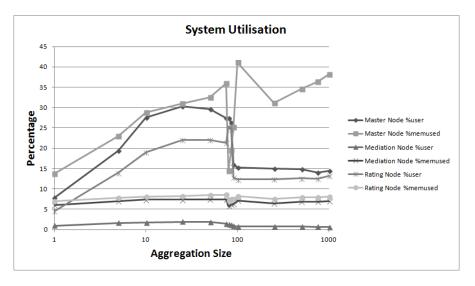


Figure 28: Impact of different aggregation sizes on system utilisation

When using high levels of data granularity, the messaging system is essentially a batch processing system, providing high throughput with high latency. To provide near-time processing an optimum level of data granularity would allow having the lowest possible latency with the lowest acceptable throughput.

#### 4.5 RELATED WORK

This section gives an overview of work related to the research presented in this paper. Related work can be categorised in two different topics, performance measuring and performance optimisation of messaging systems. Performance measuring is applied to evaluate if an implemented system meets its performance requirements and to spot possible performance problems. Performance optimisation aims to improve the performance of a system to meet certain requirements such as throughput or latency.

# 4.5.1 Performance Measuring

Her et al. (Her et al., 2007) propose the following set of metrics for measuring the performance of a service-oriented system:

# • Service response time

Elapsed time between the end of request to service and the beginning of the response of the service. This metric is further split in 20 sub-metrics such as message processing time, service composition time and service discovery time.

#### Think time

Elapsed time between the end of a response generated by a service and the beginning of a response of an end user.

# • Service tournaround time

Time needed to get the result from a group of related activities within a transaction.

# • Throughput

Number of requests served at a given period of time. The authors distinguish between the throughput of a service and the throughput of a business process.

In their work, Henjes et al. (2006)Menth et al. (2006b) investigated the throughput performance of the JMS server FioranaMQ, SunMQ and WebsphereMQ. The authors came to the following conclusion:

- Message persistence reduces the throughput significantly.
- Message replication increases the overall throughput of the server.
- Throughput is limited either by the processing logic for small messages or by the transmission capacity for large messages.
- Filtering reduces the throughput significantly.

Chen and Greenfield (2004) propose that the following performance metrics should be used to evaluate a JMS server:

- Maximum sustainable throughput
- Latency
- Elapsed time taken to send batches messages
- Persistent message loss after recovery

The authors state that "although messaging latency is easy to understand, it is difficult to measure precisely in a distributed environment without synchronised high- precision clocks." They discovered that latencies increase with increasing message sizes.

SPECjms2007 is a standard benchmark for the evaluation of Message-Oriented Middleware platforms using JMS (Sachs et al., 2009). It provides a flexible performance analysis framework for tailoring the workload to specific user requirements. According to Sachs et al. (2007), the workload of the SPECjms2007 benchmark has to meet the following requirements:

# • Representativeness

The workload should reflect how the messaging platform is used in typical user scenarios.

# Comprehensiveness

The workload should incorporate all platform features typically used in JMS application including publish/subscript and point-to-point messaging.

#### Focus

The workload should focus on measuring the performance of the messaging middleware and should minimize the impact of other components and services.

#### Configurability

It should be possible to configure the workload to meet the requirements of the user.

# Scalability

It should be possible to scale the workload by the number of destinations with a fixed traffic per destination or by increasing the traffic with a fixed set of destinations.

Ueno and Tatsubori (2006) propose a methodology to evaluate the performance of an ESB in an early stage of development that can be used for capacity planning. Instead of using a performance model for performance prediction, they run the ESB on a real machine with a pseudo-environment using lightweight web service providers and clients. The authors state that model-based approaches "often require elemental performance measurements and sophisticated modeling of the entire system, which is usuable not feasible for complex systems".

# 4.5.2 *Performance Optimisation*

Various approaches have been proposed to optimise the performance of webservices, in particular SOAP, the standard protocol for Web Service communication. This includes approaches for optimising the processing of SOAP messages (see for example Abu-Ghazaleh and Lewis (2005), Suzumura et al. (2005) and Ng (2006)), compression of SOAP messages (see for example Estrella et al. (2008) and Ng et al. (2005)) and caching (see for example Andresen et al. (2004) and Devaram and Andresen (2003)). A survey of the current approaches to improve the performance of SOAP can be found in Tekli et al. (2012).

Wichaiwong and Jaruskulchai (2007) propose an approach to transfer bulk data between web services per FTP. The SOAP messages transferred between the web services would only contain the necessary details how to download the corresponding data from an FTP server since this protocol is optimized for transferring huge files. This approach solves the technical aspect of efficiently transferring the input and output data but does not pose any solutions how to implement loose coupling and how to integrate heterogeneous technologies, the fundamental means of an SOA to improve the flexibility of an application landscape.

Data-Grey-Box Web Services are an approach to transfer bulk data between Web Services (Habich, Richly and Grasselt, 2007). Instead of transferring the data wrapped in SOAP messages, it is transferred using an external data layer. For example when using database systems as data layer, this facilitates the use of special data transfer methods such Extract, Transform, Load (ETL) to transport the data between the database of the service requestor and the database of the Web service. The data transfer is transparent for both service participants in this case. The approach includes an extension of the Web service interface with properties describing the data aspects. Compared to the SOAP approach, the authors measured a speedup of up to 16 using their proposed approach. To allow the composition and execution of Data-Grey-Box Web services, Habich, Richly, Preissler, Grasselt, Lehner and Maier (2007) developed BPEL data transitions to explicitly specify data flows in BPEL processes.

Zhuang and Chen (2012) propose three tuning strategies to improve the performance of JMS for cloud-based applications.

- 1. When using persistent mode for reliable messaging the storage block size should be matched with the message size to maximise message throughput.
- 2. Applying distributed persistent stores by configuring multiple JMS destinations to achieve parallel processing
- 3. Choosing appropriate storage profiles such as RAID-1

MPAB (Massively Parallel Application Bus) is an ESB-oriented messaging bus used for the integration of business applications (Benosman et al., 2012). The main principle of MPAB is to fragment an application into parallel software processing units, called SPU. Every SPU is connected to an Application Bus Multiplexor (ABM) through an interface called Application Bus Terminal (ABT). The Application Bus Multiplexor manages the resources shared across the host system and communicates with other ABM using TCP/IP. The Application Bus Terminal contains all the resources needed by SPU to communicate with its ABM. A performance evaluation of MPAB shows that it achieves a lower response time compared to the open source ESBs Fuse, Mule and Petals.

Some research has been done to add real-time capabalities to ESB or messaging middleware. Garces-Erice (2009) proposes an architecture for a real-time messaging middleware based on an Enterprise Service Bus. It consists of an event scheduler, a JMS-like API and a communication subsystem. While fulfilling real-time requirements, the middleware also supports already deployed infrastructure.

In their paper, Xia and Song (2011) suggest a real-time ESB model by extending the JBI specification with semantics for priority and time restrictions and modules for flow control and bandwith allocation. The proposed system is able to dynamically allocate bandwidth according to business requirements.

Tempo is a real-time messaging system written in Java that can be used on either a real-time or non-real-time architecture (Bauer et al., 2008). The authors, Bauer et al., state that existing messaging systems are designed for transactional processing and therefore not appropriate for applications with with stringent requirements of low latency with high throughtput. The main principle of Tempo is to use an independent queuing system for each topic. Ressources are partitioned between these queueing systems by a messaging scheduler using a time-base credit scheduling mechanism. In a test environment, Tempo is able to process more than 100.000 messages per second with a maximum latency of less than 120 milliseconds.

Haesen et al. (2008) distinguishes between two types of data granularity:

- Input data granularity

  Data that is sent to a component
- Output data granularity

  Data that is returned by a component

The authors state that a coarse-grained data granularity reduces the communication overhead, since the number of network transfers is decreased. "Especially in the case of Web services, this overhead is high since asynchronous messaging requires multiple queuing operations and numerous XML transformations".

#### 4.6 SUMMARY

Near-time processing of bulk data is hard to achieve. As shown in Section 2.3, latency and throughput are opposed performance metrics of a system for bulk data processing. Batch processing, while providing high throughput, leads to high latency, which impedes near-time processing. Message-base processing delivers low latency but cannot provide the throughput for bulk data processing due to the additional overhead for each processed message.

While it is technically possible to minimise the overhead of a messaging system by implementing a lightweight marshalling system and not use JMS or other state-of-the-art technologies such as XML, SOAP or REST, it would hurt the ability of the messaging middle-ware to integrate heterogenous systems or services and thus limiting its flexibility, which is one the main selling propositions of such a middleware. Furthermore, batch processing enables optimizations by partitioning and sorting the data appropriately which is not possible when each record is processed independently as a single message.

In order to compare throughput and latency of batch and messageoriented systems, a prototype for each processing type has been built. A performance evaluation has been conducted with the following results:

- The throughput of the batch prototype is 4 times the throughput of the messaging prototype.
- The latency of the messaging prototype is only a fraction of the latency of the batch prototype.
- The overhead of the messaging prototype is about 84% of the total processing time, which is mostly induced by the webservice overhead and the database transactions.
- The overhead of the batch prototype is only about 7% of the total processing time.

The results presented in Section 4.4 show that throughput and latency depend on the granularity of data that is being processed.

- The throughput increases constantly for an aggreation size > 1 and <= 50 with a maximum of 673 events per second with an aggregation size = 50.
- The increased throughput achieved by increasing the aggregation size comes with the cost of a higher latency. An aggregation size of 50, resulting in the maximum throughput of 673 events per seconds, shows a 95th percentile latency of about 68 seconds. This latency is significantly higher than the latency of the messaging system without message aggregation, which is about 0,15 seconds.

- Increasing the aggregation size also decreases the processing overhead of the messaging prototype. An aggregate size of 10 decreases the overhead by more than 50% compared to an aggregation size of 1.
- There is an optimal range for the aggregation size to control the throughput and latency of the system. Setting the aggregation size higher than a certain threshold leads to a throughput drop and latency gain cause by a congestion in the aggregator.

The performance tests that have been run for the evaluation described in section 4.3 are static tests, in the sense that they do not take different load scenarios of the system into account. In a real situation, the current throughput and latency also depend on the current load of the system. If the system is not able to handle the current load, messages are congested in the input queue which increases the latency of the system. A higher maximum throughput would decrease the latency in this case.

Therefore, the aggregation size used by the messaging system should depend on the current load of the system. It is not feasible to find a static aggregation size that works under all load conditions resulting in an optimum latency.

The next chapter presents a solution for this problem. It describes an adaptive middleware that is able to adjust the data aggregation size at runtime, depending on the current load of the system.

# AN ADAPTIVE MIDDLEWARE FOR NEAR-TIME PROCESSING OF BULK DATA

#### 5.1 INTRODUCTION

This section introduces the concept of an adaptive middleware which is able to adapt its processing type fluently between batch processing and single-event processing. It continuously monitors the load of the system and controls the message aggregation size. Depending on the current aggregation size, the middleware automatically chooses the appropriate service implementation and transport mechanism to further optimize the processing.

In this chapter, a solution to this problem is proposed:

 The concept of a middleware is presented that is able to adapt its processing type fluently between batch processing and singleevent processing. By adjusting the data granularity at runtime, the system is able to minimize the end-to-end latency for different load scenarios.

The remainder of this chapter is organized as follows. Section 5.10 gives an overview of other work related to this research. Finally, Section 5.11 concludes the chapter.

# 5.2 MIDDLEWARE COMPONENTS

Table 5 shows the components of the middleware, that are based on the Enterprise Integration Patterns described by Hohpe and Woolf (2003).

#### 5.2.1 Aggregator

The Aggregator is a stateful filter which stores correlated messages until a set of messages is complete and sends this set to the next processing stage in the messaging route.

There are different options to aggregate messages, which can be implemented by the Aggregator:

- No correlation: Messages are aggregated in the order in which they are read from the input message queue. In this case, an optimized processing is not simply possible.
- **Technical correlation:** Messages are aggregated by their technical properties, for example by message size or message format.

Table 5: Components of the Adaptive Middleware. We are using the notation defined by Hohpe and Woolf (2003)

| Symbol              | Component            | . 2  |
|---------------------|----------------------|--|
| Q <sub>0</sub>      | Message              | A single message representing a business event.  |
| Q 000               | Message<br>Aggregate | A set of messages aggregated by the Aggregator component.  |
|                     | Queue                | Storage component which stores messages using the First In, First Out (FIFO) principle.  |
|                     | Aggregator           | Stateful filter which stores correlated messages until a set of messages is complete and sends this set to the next processing stage in the messaging route. |
|                     | Router               | Routes messages to the appropriate service endpoint.   |
| Service<br>Endpoint | Service<br>Endpoint  | Represents a business service.   |

• **Business correlation**: Messages are aggregated by business rules, for example by customer segments or product segments.

# 5.2.2 Feedback Loop

To control the level of message aggregation at runtime, the middleware uses a closed feedback loop with the following properties (see Figure 29):

- Input (u): Current aggregation size
- Output (y): Change of queue size measured between sampling intervals
- Set point (r): The change of queue size should be zero.

Ultimately, we want to control the average end-to-end latency depending on the current load of the system. The change of queue size seems to be an appropriate quantity because it can be directly measured without a lag at each sampling interval, unlike the average end-to-end latency.

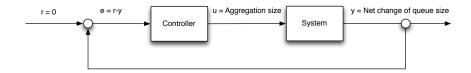


Figure 29: Feedback loop to control the aggregation size

The concrete architecture and tuning of the feedback loop and the controller is subject to our ongoing research.

# 5.2.3 Router

- static router
- dynamic router

Depending on the size of the aggregated message, the Router routes the message to the appropriate service endpoint, which is either optimized for batch or single event processing.

When processing data in batches, especially when a batch contains correlated data, there are multiple ways to speed up the processing:

- To reduce I/O, data can be pre-loaded at the beginning of the batch job and held in memory.
- Storing calculated results for re-use in memory
- Use bulk database operations for reading and writing data

With high levels of message aggregation, it is not preferred to send the aggregated message payload itself over the message bus using Java Message Service (JMS) or SOAP. Instead, the message only contains a pointer to the data payload, which is transferred using File Transfer Protocol (FTP) or a shared database.

#### 5.3 USAGE SCENARIOS

- different usage scenarios
- single aggregator, request/response integration pattern

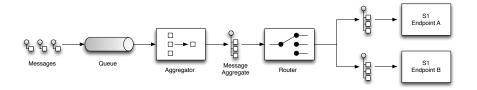


Figure 30: single aggregator, request/response integration pattern

• single aggregator, point to point channel

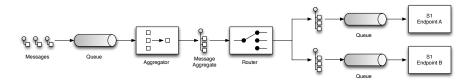


Figure 31: single aggregator, point to point channel

• system consisting of multiple subsystems, with each subsystem having an input queue, aggregator, router

# 5.4 SERVICE DESIGN

- Services that implement the business functionality of the system need to be designed properly to support the runtime adaption between single and batch processing
- Service needs to support operations with a list interface
- Different processing algorithms for different single and batch processing
- Different options for service design:
  - Single Service offering multiple operations for single and batch processing

- Single Service with a single operation for both single and batch processing
- Using different services for single and batch processing (or different aggregation sizes)
- Examples of Java interfaces

Listing 6: Java interface of a web service offering different operations for single and batch processing.

```
@WebService
     @SOAPBinding(style=Style.DOCUMENT, use=Use.LITERAL,
2
         parameterStyle=ParameterStyle.WRAPPED)
    public interface RatingPortType {
3
       @WebMethod(operationName="processCallDetails")
4
       @WebResult(name="costedEvents")
6
       public Costedevents processCallDetails(@WebParam(name="
           callDetailRecords") SimpleCDRs callDetailRecords) throws
           ProcessingException, Exception;
       @WebMethod(operationName="processCallDetail")
8
       @WebResult(name="costedEvent")
       public Costedevent processCallDetail(@WebParam(name="
           simpleCDR") SimpleCDR callDetailRecord) throws
           ProcessingException, Exception;
     }
11
```

# 5.5 CONTROLLER DESIGN

# 5.5.1 Control Problem

- Control problem: minimise the end-to-end latency of the system by controlling the message aggregation size
- aggregation size used by the messaging system should depend on the current load of the system
- when system faces high load, aggregation sizes should be increased
- when sytem faces low load, aggregation sizes could be decreases

# 5.5.2 Input/Output Variables

- **Input (u):** Current aggregation size
- Output (y): Change of queue size measured between sampling intervals
- **Set point (r):** The change of queue size should be zero.

• advantage of queue size as output variable: queue size can be directly measured whithout a delay

# 5.5.3 Control Strategy

- Simple controller strategy
  - A simple control strategy could be implemented as follows:
  - change queue > 0: Increase the aggregation size by a certain amount
  - change queue = o: Do nothing

# • PID Controller

Another option would be to use a standard PID-Controller instead, which calculates the output value  $u_k$  at time step k of the controller depending on the current (proportional part), previous (integral part) and expected future error (differential part):

$$u_k = K_p * e_k + K_i * T_a \sum_{i=0}^k e_i + \frac{K_d}{T_a} (e_k - e_{k-1})$$

with  $K_p$  being the controller gain of the proportional part,  $e_k$  being the error (r-y) at step k,  $K_i$  being the controller gain of the integral part,  $T_a$  being the sampling interval and  $K_d$  being the controller gain of the differential part.

# 5.6 TRANSPORTS

- with high aggregation sizes it is not feasible to use the same transport as with single event processing, such as JMS, SOAP etc.
- Instead a file based, using FTP, or database based transport should be used
- When using a messaging system, the payload of large messages (messages that have a high aggregation size) should not be transported over the messaging system.
- EIP Claim Check

# 5.7 ERROR HANDLING

- technical errors / business errors
- erroneous messages/events are written the an error queue for later processing

- multiple queues for different type of errors, perhaps some errors can be fixed automatically, while other errors need to be fixed manually.
- if the faulty message is part of an aggregated message, the faulty messages needs to be extracted from the aggregate.

# 5.8 PROTOTYPE IMPLEMENTATION

# 5.8.1 Aggregator

# 5.8.2 Load Generator

# 5.8.2.1 *Overview*

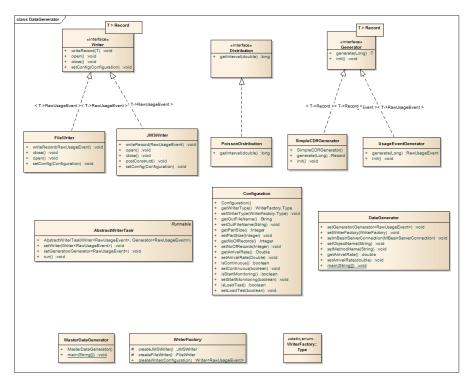


Figure 32: Datagenerator: Class diagram

• Description of main classes

# 5.8.2.2 Event Distribution

- Poisson Process
  - Events occur continuously and independently of each other
  - Exponentially distributed inter-arrival times

## 5.8.3 Sensors

## 5.8.3.1 QueueLenghtSensor

- Base class JmxSensor
- Reads the current queue length of the ActiveMQ instance using IMX

# 5.8.4 Controller

ControllerStrategy Interface

Listing 7: ControllerStrategy Interface

```
package com.jswiente.phd.performance.controller;

public interface ControllerStrategy {
   public Double getOutput(Double error);
}
```

5.8.4.1 Simple Controller

5.8.4.2 PID Controller

Listing 8: Implementation of PID Controller

```
public class PIDController implements ControllerStrategy {
2
     @Value("${controller.kp}")
3
     private Double kp;
4
5
     @Value("${controller.ki}")
6
     private Double ki;
7
     @Value("${controller.kd}")
     private Double kd;
10
11
     @Value("${controller.ta}")
12
     private Double ta;
13
14
     private Double errorSum = 0.0;
15
     private Double previousError = 0.0;
16
17
     public Double getOutput(Double error) {
18
       errorSum = errorSum + error;
19
       Double output = kp * error + ki * ta * errorSum + (kd * (
20
           error - previousError)/ta);
       previousError = error;
       return output;
22
```

```
23  }
24
25  //Setter methods removed for simplification...
26
27 }
```

## 5.8.5 Actuator

- Interface Actuator
- AggregateSizeActuator

Listing 9: Actuator Interface

```
package com.jswiente.phd.performance.actuator;

public interface Actuator<T> {

public void setValue(T value);
}
```

```
5.9 EVALUATION

5.9.1 Test Environment

5.9.2 Test Design

5.9.2.1 Static Tests

5.9.2.2 Step Tests

5.9.2.3 Dynamic Tests

5.9.3 Results

5.10 RELATED WORK
```

Adaptive Middleware

Research on messaging middleware currently focusses on Enterprise Services Bus (ESB) infrastructure. An ESB is an integration plattform that combines messaging, web services, data transformation and intelligent routing to connect multiple heterogeneous services (Chappell, 2004). It is a common middleware to implement the integration layer of an Service Oriented Architecture (SOA) and is available in numerous commercial and open-source packages.

Several research has been done to extend the static service composition and routing features of standard ESB implementations with

dynamic capabilities decided at run-time, such as dynamic service composition (Chang et al., 2007), routing (Bai et al., 2007) (Wu et al., 2008) (Ziyaeva et al., 2008) and load balancing (Jongtaveesataporn and Takada, 2010).

Work to manage and improve the Quality of Service (QoS) of ESB and service-based systems in general is mainly focussed on dynamic service composition and service selection based on monitored QoS metrics such as throughput, availability and response time (Calinescu et al., 2011). González and Ruggia (2011) propose an adaptive ESB infrastructure to adress QoS issues in service-based systems which provides adaption strategies for response time degradation and service saturation, such as invoking an equivalent service, using previously stored information, distributing requests to equivalent services, load balancing and deferring service requests.

## 5.10.2 Message Batching

The adaption strategy of our middleware is to change the message aggregation size based on the current load of the system. Aggregating or batching of messages is a common approach to increase the throughput of a messaging system, for example to increase the throughput of total ordering protocols (Friedman and Renesse, 1997) (Friedman and Hadad, 2006) (Romano and Leonetti, 2012) (Didona et al., 2012).

# 5.10.3 Dynamic Scaling

A different solution to handle infrequent load spikes is to automatically instantiate additional server instances, as provided by current Platform as a Service (PaaS) offerings such as Amazon EC2 (Amazon EC2 Auto Scaling, n.d.) or Google App Engine (Auto Scaling on the Google Cloud Platform, n.d.). While scaling is a common approach to improve the performance of a system, it also leads to additional operational and possible license costs. Of course, our solution can be combined with these auto-scaling approaches.

## 5.10.4 Feedback Control of Computing Systems

#### 5.11 SUMMARY

In this paper, we have presented a middleware that is able to adapt itself to changing load scenarios by fluently shifting the processing type between single event and batch processing. The middleware uses a closed feedback loop to control the end-to-end latency of the system by adjusting the level of message aggregation depending on the current load of the system. Determined by the aggregation size of a messsage, the middleware routes a message to appropriate service endpoints, which are optimized for either single-event or batch processing.

To evaluate the proposed middleware concepts, we have implemented a prototype system and performed preliminary performance tests. The tests show that throughput and latency of a messaging system depend on the level of data granularity and that the throughput can be increased by increasing the granularity of the processed messages.

Next steps of our research are the implementation of the proposed middleware including the evaluation and tuning of different controller architectures, performance evaluation of the proposed middleware using the prototype and developing a conceptional framework containing guidelines and rules for the practitioner how to implement an enterprise system based on the adaptive middleware for near-time processing

# A CONCEPTUAL FRAMEWORK FOR HIGH-PERFORMANCE NEAR-TIME PROCESSING OF BULK DATA

Alternative title: A Conceptual Framework for Feedback-Controlled Computer Systems

Alternative title: A Process (Procedure) Model for ...

## 6.1 INTRODUCTION

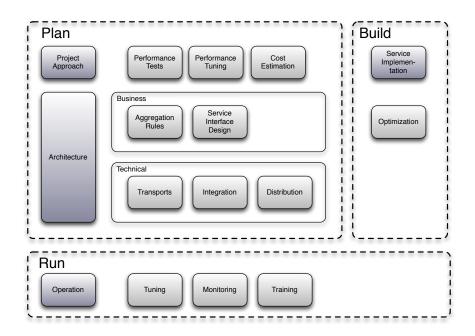


Figure 33: Overview of Conceptual Framework

## 6.2 METAMODEL

- View
- Role
- Task
- Deliverable
- Tool

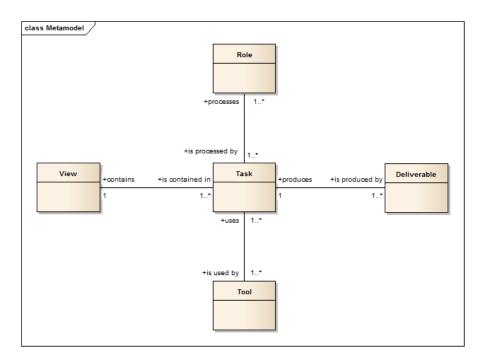


Figure 34: Metamodel

# 6.3 VIEWS

- Plan
- Build
- Run

# 6.4 ROLES

- System Architect
- Business Analyst
- Developer
- Tester
- Project Manager
- Operations Engineer
- Service Architect
- Service Developer

Table 6: System Architect

| Role        | System Architect           |
|-------------|----------------------------|
| Description | Lorem ipsum                |
| Tasks       | Define System Architecture |
| Artifacts   | System Architecture        |

- 6.4.1 System Architect
- 6.5 PROCESSES/TASKS
- 6.5.1 List of Tasks
  - Define System Architecture
  - Define Integration Architecture
    - Transports
    - Distribution
  - Define Controller Architecture
    - Define Control Problem
    - Define Input/Output Variables
  - Implement Controller / Feedback Loop
  - Perform Controller Tuning
    - System Model/System Identification
    - Static Tests
    - Step Tests
  - Define Service Interfaces
  - Implement Service Interfaces / Test / Deploy
  - Define Aggregation Rules
  - Implement Aggregation Rules
  - Define Performance Tests
  - Setup Monitoring infrastructure
  - Setup Test and Integration Environment
  - Deploy to Test and Integration Environment
  - Perform Performance Tests

- Evaluate Performance Test Results
- Define Training Concept

Table 7: Define System Architecture

| What           | Define System Architecture |  |  |
|----------------|----------------------------|--|--|
| Why            | Lorem ipsum                |  |  |
| Who            | System Architect           |  |  |
| Artifacts      | System Architecture        |  |  |
| Challenges     | Lorem Ipsum                |  |  |
| Best practises | Lorem ipsum                |  |  |

# 6.5.2 Task Dependencies

• Tasks depend on each other

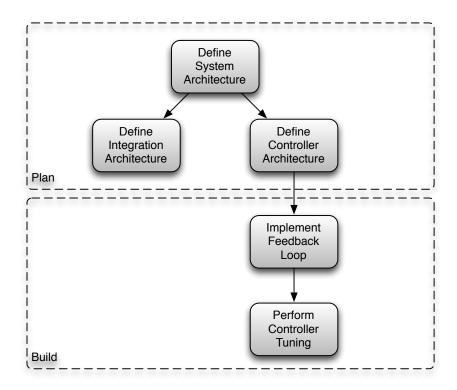


Figure 35: Tasks depend on each other

# 6.6 BUILDING BLOCKS/ARTIFACTS

• System Architecture

- Integration Architecture
- Controller Architecture
- System Model
- Performance Test Concept
- Training Concept

# 6.7 TOOLS

- Modeling Framework
  - Discrete Event Simulation
  - Matlab/Simulink
  - Scilab/Xcos
- Tools for Data Visualisation
  - Excel
  - Matlab
  - Gnuplot
  - matplotlib
- 6.8 REFERENCE ARCHITECTURE
- 6.9 RELATIONSHIP TO ARCHITECTURE FRAMEWORKS AND METHOD-OLOGIES
  - TOGAF
  - Agile (Scrum)
- 6.10 RELATED WORK
- 6.11 SUMMARY

# Part III CONCLUSION

# CONCLUSION

- 7.1 CONTRIBUTIONS
- 7.2 LIMITATIONS
- 7.3 FUTURE WORK

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