

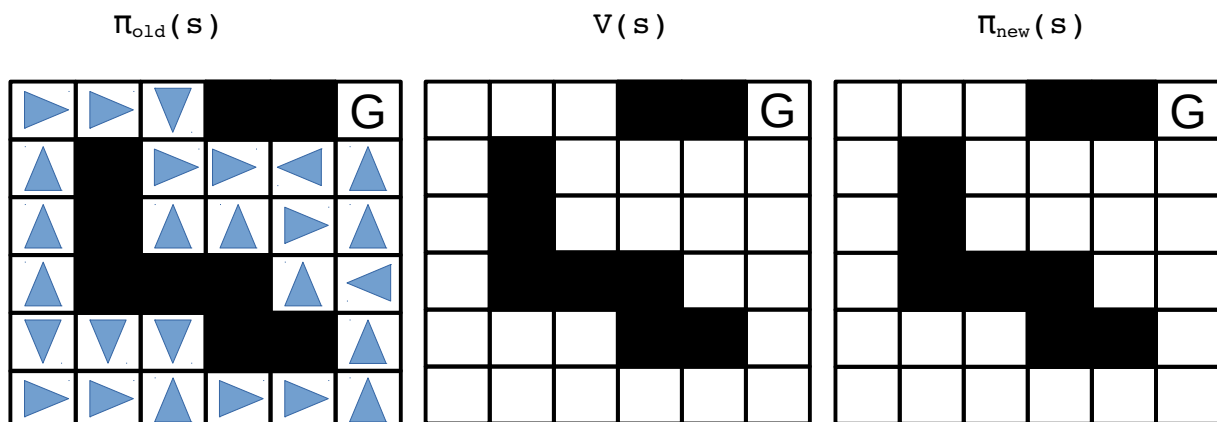
# CSCI 4350/5350

## Homework 10

Due: Tue. Dec. 4, 11:00 PM

1. Use *policy iteration* to determine the answers to the following questions. Note that the reward for reaching the goal state,  $G$ , is 1, and a reward of 0 is given for all other states [ $r(G) = 1$  and  $r(s) = 0$  for all  $s \neq G$ ] and the value of a state,  $V(s)$ , is the sum of all future rewards obtained starting from that state [ $V(s) = r(s) + r(s+1) + r(s+2) + \dots + r(s+n)$ ].

- a. (5 points) Determine the value of all states,  $V(s)$ , below and write their values in the grid provided, then calculate the new policy,  $\pi_{\text{new}}(s)$ , and indicate the **new** actions in the grid provided:

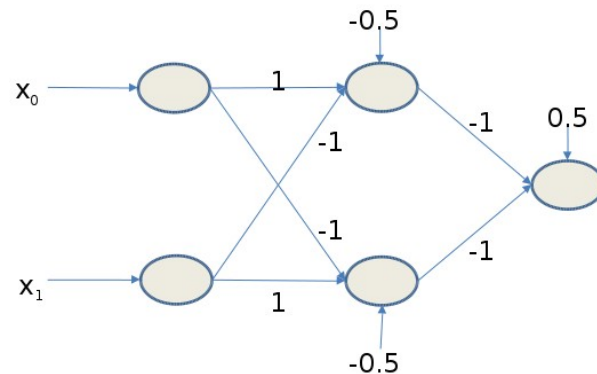


- b. (2 points) Will recalculating  $V(s)$  and  $\pi(s)$  (performing another iteration of the algorithm) result in additional changes to the policy? Why or why not?

- c. (2 points) Would this also be true if we defined  $V(s)$  using *discounted* future rewards [i.e.  $V(s) = \gamma^0 r(s) + \gamma^1 r(s+1) + \gamma^2 r(s+2) + \dots + \gamma^n r(s+n)$ ]? Why or why not?

2. (2 points) An \_\_\_\_\_ function is used to transform a neural units' *net input* into a corresponding *rate code* output.
3. (2 points) What is the most commonly used *learning algorithm* for updating weights in a feed-forward neural network?

4. Given the neural network architecture on the right which uses a *threshold* activation function ( $f(\text{net}_i) = 0$  if  $\text{net}_i \leq 0$  and  $f(\text{net}_i) = 1$  if  $\text{net}_i > 0$ ), answer the following questions:



- a. (1 point each) What is the output of the network for each of the four input patterns:
  - i. [0 0]
  - ii. [0 1]
  - iii. [1 0]
  - iv. [1 1]
- b. (1 point) What would be the output of the network for an input pattern of [1, 0.4]?
- c. (2 points) Does the input/output from question (b) make sense? Why or why not?