# **Topic 3: Generalized Linear Models for Longitudinal Data**

### Marginal Models -

Assumptions:

(a)  $E[Y_{ij} | x_{ij}] = h(x_{ij}^T \beta)$ , where  $h(\cdot)$  is a known link function.

(b)  $Var(Y_{ij} | x_{ij}) = \phi \upsilon(h(x_{ij}^T \beta))$ , where  $\phi$  is a scale parameter and  $\upsilon(\cdot)$  is a known function.

 $Corr(Y_{ij}, Y_{ik} | x_{ij}, x_{ik}) = \rho(h(x_{ij}^T \beta), h(x_{ik}^T \beta); \alpha)$ , where  $\rho$  is a known function and  $\alpha$  is a parameter vector.

Example: Binary response  $(Y_{ij} = 0 \text{ or } 1)$ 

Logistic regression model:

$$E[Y_{ij} \mid x_{ij}] = \frac{e^{\beta^T x_{ij}}}{1 + e^{\beta^T x_{ij}}}, Var(Y_{ij} \mid x_{ij}) = E[Y_{ij} \mid x_{ij}](1 - E[Y_{ij} \mid x_{ij}]), Corr(Y_{ij}, Y_{ik} \mid x_{ij}, x_{ik}) = \alpha.$$

Another way for modeling the association among binary data using the odds ratio:

$$OR(Y_{ij}, Y_{ik}) = \frac{P(Y_{ij} = 1, Y_{ik} = 1)P(Y_{ij} = 0, Y_{ik} = 0)}{P(Y_{ii} = 1, Y_{ik} = 0)P(Y_{ii} = 0, Y_{ik} = 1)}$$
, not constrained by the means.

Random Effects Models - (Given the actual coefficients for a subject, the random effects model further assumes that the repeated measurements for each individual are independent.)

Assumptions:

Assumptions: (a) Given 
$$(U_i, X_{i1}, \dots, X_{im_i}) = (u_i, x_{i1}, \dots, x_{im_i})$$
,  $Y_{ij}$ 's are mutually independent and follow

a GLM with a density function  $f(y_{ij} | u_i, x_{ij}) = \exp(\frac{y_{ij}\theta_{ij} - \psi(\theta_{ij})}{\phi} + c(y_{ij}, \phi))$ .

(b) 
$$U_i$$
's  $\sim F_u(\cdot)$ .

Facts:

 $\mu_{ij} = E[Y_{ij} \mid u_i, x_{ij}] = \psi'(\theta_{ij}) \text{ and } \upsilon_{ij} = Var(Y_{ij} \mid u_i, x_{ij}) = \phi \psi''(\theta_{ij}) \text{ satisfy } h(\mu_{ij}) = x_{ij}^T \beta + d_{ij}^T u_i \text{ and } \upsilon_{ij} = \phi \upsilon(\mu_{ij}), \text{ where } h(\cdot) \text{ and } \upsilon(\cdot) \text{ are known link functions, and } d_{ij} \text{ is a subset}$  of  $x_{ij}$ .

# Transition (Markov) models -

Assumptions:

(a) 
$$E[Y_{ij} \mid x_{ij}, H_{ij}] = h(x_{ij}^T \beta + \sum_{r=1}^s f_r(H_{ij}; \alpha))$$
, where  $H_{ij} = \{y_{i1}, \dots, y_{ij-1}\}$ .

(b) 
$$Var(Y_{ii} | x_{ii}, H_{ii}) = \phi \upsilon(E[Y_{ii} | x_{ii}, H_{ii}])$$
.

#### **Statistical Inferences:**

#### Random effects model -

The likelihood function is  $L(\beta, \phi, \alpha \mid y) = \prod_{i=1}^{n} \int (\prod_{j=1}^{m_i} f(y_{ij} \mid u_i, \beta, \phi)) dF_U(u_i; \alpha)$ .

Find a maximizer of the likelihood function  $L(\beta, \phi, \alpha \mid y)$ .

### **Transition model -**

Facts: 
$$f(y_{i1}, \dots, y_{im_i}) = f(y_{im_i} | y_{im_i-1}, \dots, y_{i1}) f(y_{im_i-1} | y_{im_i-2}, \dots, y_{i1}) \dots f(y_{i2} | y_{i1}) f(y_{i1})$$
.

In the rth-order Markov model,

$$f(y_{i1}, \dots, y_{im_i}; \beta, \alpha^*) = f(y_{i1}; \beta, \alpha_1) \dots f(y_{ir} \mid y_{ir-1}, \dots, y_{i1}; \beta, \alpha_r)$$

$$\cdot \prod_{i=r+1}^{m_i} f(y_{ij} \mid y_{ij-1}, \dots, y_{ij-r}; \beta, \alpha), \text{ where } \alpha^* = (\alpha_1, \dots, \alpha_r, \alpha).$$

Find the maximizer of  $\prod_{i=1}^{n} \left[\prod_{j=r+1}^{m_i} f(y_{ij} \mid y_{ij-1}, \dots, y_{ij-r}; \beta, \alpha)\right]$ ,

where 
$$\prod_{j=r+1}^{m_i} f(y_{ij} | y_{ij-1}, \dots, y_{ij-r}; \beta, \alpha) = f(y_{ir+1}, \dots, y_{im_i} | y_{i1}, \dots, y_{ir})$$

#### Marginal model -

Generalized Estimating Equations (GEE), which is a multivariate analogue of

quasi-likelihood.

# **Generalized Estimating Equations (GEE):**

$$S_{\beta}(\beta,\alpha) = \sum_{i=1}^{n} \left( \frac{\partial \mu_{i}}{\partial \beta} \right)^{T} [Var(Y_{i})]^{-1} (Y_{i} - \mu_{i}), \text{ where } \mu_{i} = h(x_{ij}^{T}\beta), Var(Y_{i}) = Var(Y_{i}; \beta, \alpha)$$

.

$$\begin{split} S_{\alpha}(\beta,\alpha) &= \sum\nolimits_{i=1}^{n} \left(\frac{\partial \eta_{i}}{\partial \alpha}\right)^{T} H_{i}^{-1}(\omega_{i} - \eta_{i}) \;\; , \quad \text{where} \;\; \omega_{i} = (R_{i1}R_{i2}, \cdots, R_{i1}R_{im_{i}}, \cdots, R_{i1}^{2}, \cdots, R_{im_{i}}^{2}) \;\; , \\ \eta_{i} &= E[\omega_{i} \big| (\beta,\alpha) \big] \;, \quad H_{i} = Var(\omega_{i}) \; \text{and} \; \text{with} \; R_{ij} = \frac{Y_{ij} - \mu_{ij}}{\sqrt{Var(Y_{ii})}} \; . \end{split}$$

The estimator,  $\operatorname{say}_{\mathbf{X}}(\hat{\beta}, \hat{\alpha})$  of  $(\beta, \alpha)$  is defined to be the solution of the above equations, i.e.  $S_{\beta}(\hat{\beta}, \hat{\alpha}) = 0$  and  $S_{\alpha}(\hat{\beta}, \hat{\alpha}) = 0$ .

**Theorem 3.1.** Under the regularity conditions,  $n^{\frac{-1}{2}} \begin{bmatrix} \begin{pmatrix} \hat{\beta} \\ \hat{\alpha} \end{pmatrix} - \begin{pmatrix} \beta \\ \alpha \end{pmatrix} \end{bmatrix} \xrightarrow{d} N(0, \Sigma)$ , where  $\Sigma$ 

can be estimated by  $(\frac{1}{n}\sum_{i=1}^{n}C_{i}^{T}B_{i}^{-1}D_{i})^{-1}(\frac{1}{n}\sum_{i=1}^{n}C_{i}^{T}B_{i}^{-1}V_{0i}D_{i}B_{i}^{-1}C_{i})(\frac{1}{n}\sum_{i=1}^{n}D_{i}^{T}B_{i}^{-1}C_{i})^{-1}$ ,

$$\text{where } C_i = \begin{pmatrix} \frac{\partial \mu_i}{\partial \beta} & 0 \\ 0 & \frac{\partial \eta_i}{\partial \alpha} \end{pmatrix}, B_i = \begin{pmatrix} Var(Y_i) & 0 \\ 0 & H_i \end{pmatrix}, D_i = \begin{pmatrix} \frac{\partial \mu_i}{\partial \beta} & \frac{\partial \mu_i}{\partial \alpha} \\ \frac{\partial \eta_i}{\partial \beta} & \frac{\partial \eta_i}{\partial \alpha} \end{pmatrix}, \text{ and } V_{0i} = \begin{pmatrix} y_i - \mu_i \\ \omega_i - \eta_i \end{pmatrix}^{\otimes 2}.$$

**Proof:** (Hint)

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} S_{\beta}(\hat{\beta}, \hat{\alpha}) \\ S_{\alpha}(\hat{\beta}, \hat{\alpha}) \end{pmatrix} = \begin{pmatrix} S_{\beta}(\beta, \alpha) \\ S_{\alpha}(\beta, \alpha) \end{pmatrix} + \begin{pmatrix} \frac{\partial S_{\beta}(\beta, \alpha)}{\partial \beta} & \frac{\partial S_{\beta}(\beta, \alpha)}{\partial \alpha} \\ \frac{\partial S_{\alpha}(\beta, \alpha)}{\partial \beta} & \frac{\partial S_{\alpha}(\beta, \alpha)}{\partial \alpha} \end{pmatrix}_{\begin{pmatrix} \hat{\beta}^{*} \\ \hat{\alpha}^{*} \end{pmatrix}} \begin{pmatrix} \begin{pmatrix} \hat{\beta} \\ \hat{\alpha} \end{pmatrix} - \begin{pmatrix} \beta \\ \alpha \end{pmatrix} \end{pmatrix},$$

where  $\begin{pmatrix} \hat{\beta}^* \\ \hat{\alpha}^* \end{pmatrix}$  lies on the line segment between  $\begin{pmatrix} \beta \\ \alpha \end{pmatrix}$  and  $\begin{pmatrix} \hat{\beta} \\ \hat{\alpha} \end{pmatrix}$ .

# **Appendix:**

### 1. Structure of the generalized linear model (GLM) -

GLM consists of three components:

- a. The random component, which specifies the p.d.f. of the response  $Y_i$ ,  $i = 1, \dots, n$ .
- b. The systematic component, which specifies a linear function of the explanatory variables  $x_i$ , i.e.  $\mathbf{x}_i^T \boldsymbol{\beta}$ .
- c. The link function, which describes a function relationship between the systematic component  $x_i^T \beta$  and the expectation of the random component, i.e.,  $E[Y_i]$

 $f(y_i|\theta_i,\phi) = \exp\{\frac{y_i\theta_i - b(\theta_i)}{a(\phi)} + c(y_i;\phi)\}$ , where  $\phi$  is called the scaling parameter (or the dispersion parameter) and  $\theta_i$  is called the natural parameter.

Remark: When  $\phi$  is known, the above model represents a linear exponential family. If  $\phi$  is unknown, the above model is called an exponential dispersion model.

Example:  $Gamma(\alpha, \beta)$  and  $Normal(\mu, \sigma^2)$ 

#### **Properties:**

$$\operatorname{Let} L(\underline{\theta}, \phi) = \prod_{i=1}^{n} f(y_i | \theta_i, \phi) = \exp\left\{\frac{\sum_{i=1}^{n} y_i \theta_i - b(\theta_i)}{a(\phi)} + \sum_{i=1}^{n} c(y_i; \phi)\right\}, \underline{\theta} = (\theta_1, \dots, \theta_n),$$

and 
$$l(\theta, \phi) = \frac{\sum_{i=1}^{n} y_i \theta_i - b(\theta_i)}{a(\phi)} + \sum_{i=1}^{n} c(y_i; \phi) \text{ with } l_i = \frac{y_i \theta_i - b(\theta_i)}{a(\phi)} + c(y_i; \phi).$$

(a) 
$$\frac{\partial l_i}{\partial \theta_i} = \frac{y_i - b'(\theta_i)}{a(\phi)}$$
 and  $\frac{\partial^2 l_i}{\partial \theta_i^2} = \frac{-b''(\theta_i)}{a(\phi)}$ .

(b) Under the regularity conditions, 
$$E\left[\frac{\partial l_i}{\partial \theta_i}\right] = 0$$
 and  $-E\left[\frac{\partial^2 l_i}{\partial \theta_i^2}\right] = E\left[\left(\frac{\partial l_i}{\partial \theta_i}\right)^2\right]$ 

From (a) and (b), one has

(c) 
$$E[Y_i] = b'(\theta_i) \triangleq \mu_i$$
 and  $\frac{Var(Y_i)}{a^2(\phi)} = \frac{b''(\theta_i)}{a(\phi)}$ , i.e.,  $Var(Y_i) = b''(\theta_i)a(\phi) = \frac{\partial \mu_i}{\partial \theta_i}a(\phi)$ .

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Thus,

$$E[Y] = \frac{\partial b(\theta)}{\partial \theta} = \left(\frac{\partial b(\theta_1)}{\partial \theta}, \dots, \frac{\partial b(\theta_n)}{\partial \theta_n}\right)^T \text{ and } Cov(Y) = a(\phi) diag(b''(\theta_1), \dots, b''(\theta_n)), \text{ where } \theta$$

$$Y = (Y_1, \dots, Y_n)^T.$$

(d) 
$$\frac{\partial l_i}{\partial \theta_i} = \frac{y_i - \mu_i}{a(\phi)} = \frac{\partial \mu_i}{\partial \theta_i} \left( \frac{y_i - \mu_i}{Var(y_i)} \right), i = 1, \dots, n.$$

Let  $\eta_i = g(\mu_i)$  and  $\eta_i = x_i^T \beta$ , where  $g(\cdot)$  is a monotone and differentiable function. One has

$$\frac{\partial l_{i}}{\partial \beta_{j}} = \frac{\partial \eta_{i}}{\partial \beta_{j}} \frac{\partial \mu_{i}}{\partial \eta_{i}} \frac{\partial \theta_{i}}{\partial \mu_{i}} \frac{\partial l_{i}}{\partial \theta_{i}} = x_{ij} \cdot \frac{\partial \mu_{i}}{\partial \eta_{i}} \cdot \frac{\partial \theta_{i}}{\partial \mu_{i}} \cdot \left( \frac{\partial \mu_{i}}{\partial \theta_{i}} \left( \frac{y_{i} - \mu_{i}}{Var(y_{i})} \right) \right)$$

$$= x_{ij} \frac{\partial \mu_{i}}{\partial \eta_{i}} \left( \frac{y_{i} - \mu_{i}}{Var(y_{i})} \right), j = 1, \dots, p.$$

Note: 
$$\begin{cases} g(\mu) = \mu & \text{is called the identity link} \\ g(\mu) = Q(\theta_i) = x_i^T \beta & \text{is called the canonical(natural) link} \end{cases}$$

### 2. Quasi Loglikelihood –

$$Y = \begin{pmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{pmatrix} \sim (\mu, \phi \upsilon(\mu)), \text{ where } \mu = \begin{pmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_n \end{pmatrix} \text{ and } V = diag(\upsilon(\mu_1), \dots, \upsilon(\mu_n)).$$

$$Let U_i = \frac{y_i - \mu_i}{\phi \upsilon(\mu_i)}$$

#### **Properties:**

(a) 
$$E[U_i] = 0$$
 and  $Var(U_i) = \frac{1}{\phi \upsilon(\mu_i)}$ .

$$\frac{\partial U_i}{\partial \mu_i} = \frac{-\upsilon(\mu_i) - (y_i - \mu_i) \frac{\partial \upsilon(\mu_i)}{\partial \mu_i}}{\phi \upsilon^2(\mu_i)} \text{ and } -E\left[\frac{\partial U_i}{\partial \mu_i}\right] = \frac{1}{\phi \upsilon(\mu_i)} \left(=Var(U_i)\right).$$

(b) $U_i$  has the same property as the derivative of  $l_i$ .

Let  $Q(\mu; Y) = \sum_{i=1}^{n} Q_i(\mu_i; y_i)$ , where  $Q_i(\mu_i; y_i) = \int_{y_i}^{\mu_i} \left(\frac{y_i - t}{\phi v(t)}\right) dt$  is the analogue of the log-likelihood function.

 $Q(\mu; Y)$ : the qusi loglikelihood.

The quasi-score function is obtained by differentiating  $Q(\mu; Y)$  with  $\beta = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_p \end{pmatrix}$ , which

is equal to

$$U(\beta) = \phi^{-1}D^{T}V^{-1}(Y - \mu), \text{ where } D = \begin{pmatrix} \frac{\partial \mu_{1}}{\partial \beta_{1}} & \cdots & \frac{\partial \mu_{1}}{\partial \beta_{p}} \\ \frac{\partial \mu_{2}}{\partial \beta_{1}} & \cdots & \frac{\partial \mu_{2}}{\partial \beta_{p}} \\ \vdots & & \vdots \\ \frac{\partial \mu_{n}}{\partial \beta_{1}} & \cdots & \frac{\partial \mu_{n}}{\partial \beta_{p}} \end{pmatrix}.$$

The quasi-likelihood estimator  $\hat{\beta}$  is defined to be the solution of  $U(\hat{\beta})=0$  .