

Topic 6. Transition Models

t_{ij} 's are assumed to be equally spaced.

Let $H_{ij} = \{y_{ik}, k = 1, \dots, j-1\}$.

Consider $f(y_{ij} | H_{ij}, \alpha, \beta) = \exp\{\frac{y_{ij}\theta_{ij} - \psi(\theta_{ij})}{\phi} + c(y_{ij}, \phi)\}$, where $\psi(\theta_{ij})$ and $c(y_{ij}, \phi)$ are

known functions. One has $\mu_{ij}^c = E[y_{ij} | H_{ij}] = \psi'(\theta_{ij})$ and $\nu_{ij}^c = V[y_{ij} | H_{ij}] = \psi''(\theta_{ij})\phi$ with

$$h(\mu_{ij}^c) = x_{ij}^T \beta + \sum_{r=1}^s f_r(H_{ij}; \alpha) \text{ for suitable functions } f_r(\cdot) \text{'s and } \nu_{ij}^c = \nu(\mu_{ij}^c)\phi.$$

Examples:

(1) Linear link - linear regression with autoregressive errors for Gaussian data.

$$Y_{ij} = x_{ij}^T \beta + \sum_{r=1}^s \alpha_r (Y_{i,j-r} - x_{i,j-r}^T \beta) + z_{ij}, \text{ where } z_{ij} \stackrel{iid}{\sim} N(0, \phi).$$

$$h(\mu_{ij}^c) = \mu_{ij}^c, \nu(\mu_{ij}^c) = 1, \text{ and } f_r = \alpha_r (Y_{i,j-r} - x_{i,j-r}^T \beta)$$

(2) Logit link -

$$\log it P(Y_{ij} | H_{ij}) = x_{ij}^T \beta + \sum_{r=1}^q \alpha_r Y_{i,j-r}.$$

$$h(\mu_{ij}^c) = \ln\left(\frac{\mu_{ij}^c}{1 - \mu_{ij}^c}\right), \nu(\mu_{ij}^c) = \mu_{ij}^c(1 - \mu_{ij}^c), \text{ and } f_r = \alpha_r Y_{i,j-r}.$$

(3) Log link -

$$\ln Y_{ij} = x_{ij}^T \beta + \alpha \{\ln(Y_{i,j-1}^*) - x_{i,j-1}^T \beta\}, Y_{ij}^* = \max\{Y_{ij}, d\} \text{ with } 0 < d < 1. \text{ (Note that the}$$

constant d is set to prevent $Y_{ij} = 0$.

$$\mu_{ij}^c = e^{x_{ij}^T \beta} \left(\frac{Y_{i,j-1}^*}{\exp(x_{i,j-1}^T \beta)} \right)^\alpha$$

Fitting transition models: (A markov model of order q)

By $L_i(y_{i1}, \dots, y_{im_i}) = f(y_{i1}, \dots, y_{iq}) \prod_{j=q+1}^{m_i} f(y_{ij} | y_{i,j-1}, \dots, y_{i,j-q})$, $i = 1, \dots, n$, one can get the likelihood function

$$L(\alpha, \beta) = \prod_{i=1}^n f(y_{i1}, \dots, y_{iq}) \prod_{j=q+1}^{m_i} f(y_{ij} | H_{ij}, \alpha, \beta), \quad \text{where } H_{ij} = \{y_{i,j-1}, \dots, y_{i,j-q}\}.$$

Since the term $f(y_{i1}, \dots, y_{iq})$ is always unavailable, the estimators of (α, β) are obtained via maximizing the conditional likelihood $\prod_{i=1}^n \prod_{j=q+1}^{m_i} f(y_{ij} | H_{ij}, \alpha, \beta)$.

Let $\delta = (\alpha, \beta)$. The log-conditional likelihood or conditional score function has the form $S^c(\delta) = \sum_{i=1}^n \sum_{j=(q+1)}^{m_i} \frac{\partial \mu_{ij}^c}{\partial \delta} v_{ij}^{c-1} (y_{ij} - \mu_{ij}^c) = 0$.

Remark.

Let $X_i^* = \left(\frac{\partial \mu_{ij}^c}{\partial \delta} \right)_{(m_i+q) \times (p+s)}$ with $\dim(\beta) = p$ and $\dim(\alpha) = s$, $W_i = \text{diag}(v_{i(q+1)}^{c-1}, \dots, v_{im_i}^{c-1})$,

and $Z_i = X_i^* \hat{\delta} + (Y_i - \hat{\mu}_i^c)$.

Updated $\hat{\delta}$ can be obtained by iteratively regression Z_i on X_i^* using weight W_i as below.

$$\begin{aligned} \hat{\delta}^{(k+1)} &= \sum_{i=1}^n (X_i^{*T} W_i X_i)^{-1} \left(\sum_{i=1}^n X_i^{*T} W_i Z_i^{(k)} \right) \\ &= \hat{\delta}^{(k)} + \left(\sum_{i=1}^n X_i^{*T} W_i X_i \right)^{-1} \left(\sum_{i=1}^n X_i^{*T} W_i \right) (Y_i - \hat{\mu}_i^{(k)}) \end{aligned}$$

One has $(\hat{\delta} - \delta) \xrightarrow{d} N(0, V_\delta)$,

where V_δ is the robust variance with

$$V_R = \left(\sum_{i=1}^n X_i^{*T} W_i X_i \right)^{-1} \left(\sum_{i=1}^n X_i^{*T} W_i V_i W_i X_i^* \right) \left(\sum_{i=1}^n X_i^{*T} W_i X_i \right)^{-1}.$$

Note that δ is still consistent even the conditional variance is not specified correctly.

Transition models for binary response -

Examples:

(1) First-order binary Markov chain -

The transition matrix is $\begin{pmatrix} \pi_{00} & \pi_{01} \\ \pi_{10} & \pi_{11} \end{pmatrix}$ with $\pi_{ab} = P(Y_{ij} = b | Y_{i,j-1} = a)$, $a, b = 0, 1$.

Assume that $\log itP(Y_{ij} = 1 | Y_{i,j-1} = 0) = x_{ij}^T \beta_0$ and $\log itP(Y_{ij} = 1 | Y_{i,j-1} = 1) = x_{ij}^T \beta_1$,

where $x_{ij} = (1, x_{ij1}, \dots, x_{ijp})^T$. One has $\log itP(Y_{ij} = 1 | Y_{i,j-1} = y_{i,j-1}) = x_{ij}^T \beta_0 + y_{i,j-1} x_{ij}^T \alpha$,

where $\beta_1 = \beta_0 + \alpha$.

(2) Second-order binary Markov chain -

$Y_{i,j-2} \quad Y_{i,j-1}$		Y_{ij}	
		0	1
0	0	π_{000}	π_{001}
0	1	π_{010}	π_{011}
1	0	π_{100}	π_{101}
1	1	π_{110}	π_{111}

The transition probabilities can be modeled as below.

$$\log itP(Y_{ij} = 1 | Y_{i,j-2} = y_{i,j-2}, Y_{i,j-1} = y_{i,j-1}) = x_{ij}^T \beta + x_{ij}^T (y_{i,j-1} \alpha_1 + y_{i,j-2} \alpha_2 + y_{i,j-1} y_{i,j-2} \alpha_3).$$

(3) The mixture of random effects and transition model -

$$\log itP(Y_{ij} = 1 | Y_{i,j-1} = y_{i,j-1}, U_i = u_i) = u_i + x_{ij}^T \beta + \alpha y_{i,j-1}, \text{ where } U_i \stackrel{iid}{\sim} N(0, \sigma^2).$$

Ordered Categorical data -

Y : ordinal response with categories labeled $1, 2, \dots, k$.

Let $F(a | x) = P(Y \leq a | x)$, where $a = 1, \dots, (k-1)$, $x = (x_1, \dots, x_p)^T$.

Proportional odds model: $\log itF(a | x) = \theta_a + x^T \beta$, $a = 1, \dots, (k-1)$.

Define $Y^* = (Y_1^*, \dots, Y_{k-1}^*)$ with $Y_a^* = 1_{(Y \leq a)}$. Then, $\log itF(a | x) = \log itP(Y_a^* = 1 | x)$.

Y	1	2	3	\dots	$k-1$	k
Y_1^*	1	0	0	\dots	0	0
Y_2^*	1	1	0	\dots	0	0
\vdots	\vdots	\vdots				\vdots
Y_{k-1}^*	1	1	1	\dots	1	0

Example:

Assume that $\text{logit}P(Y_{ij} \leq b | Y_{i,j-1} = a) = \theta_{ab} + x_{ij}^T \beta_a$, $a, b = 1, \dots, (k-1)$. It can be

derived that $\text{logit}P(Y_{ij} \leq b | Y_{ij-1}^* = y_{i,j-1}^*) = \theta_b + \sum_{l=1}^{k-1} \alpha_{ab} y_{i(j-1)l}^* + x_{ij}^T (\beta + \sum_{l=1}^{k-1} r_l y_{i(j-1)l}^*)$,

$$\text{where } \begin{cases} \theta_{kb} = \theta_b, \alpha_{ab} = \theta_{lb} - \theta_{k+1,b} \\ \beta_k = \beta, r_l = \beta_l - \beta_{l+1} \end{cases}.$$

Log-linear transition models for count data -

$$Y_{ij} | (H_{ij}, x_{ij}) \sim \text{Poisson}(\mu_{ij}^c).$$

Model 1. Wong (1986) proposed that $\mu_{ij}^c = \exp(x_{ij}^T \beta) \{1 + \exp(-\alpha_0 - \alpha_1 y_{i,j-1})\}$, α_0, α_1

> 0 , where β is the influence of x_{ij} as $y_{i,j-1} = 0$.

Remark. When $y_{i,j-1} > 0$, μ_{ij}^c decreases as $y_{i,j-1}$ increases. A negative association is implied between the prior and current responses.

Model 2. $\mu_{ij}^c = \exp(x_{ij}^T \beta + \alpha y_{i,j-1})$.

Properties: (1) μ_{ij}^c increases as an exponential function of time as $\alpha > 0$.

(2) When $\exp(x_{ij}^T \beta) = \mu$ and $\alpha < 0$, it leads to a stationary process.

Model 3. $\mu_{ij}^c = \exp(x_{ij}^T \beta + \alpha \{\ln(y_{i,j-1}^*) - x_{i,j-1}^T \beta\})$, where $y_{i,j-1}^* = \max\{y_{i,j-1}, d\}$, $0 < d < 1$.

Property: $\begin{cases} \alpha = 0: \text{ it reduces to an ordinary log-linear model.} \\ \alpha < 0: \text{ negative correlation between } y_{i,j-1} \text{ and } y_{ij}. \\ \alpha > 0: \text{ positive correlation between } y_{i,j-1} \text{ and } y_{ij}. \end{cases}$

Application to a size-independent branching process: $\exp(x_{ij}^T \beta) = \mu$

$\begin{cases} y_{ij} : \text{the number of individuals in the } i\text{th population at generation } j. \\ Z_k(y_{i(j-1)}) : \text{the number of offspring for person } k \text{ in generation } (j-1). \end{cases}$

For $y_{i(j-1)} > 0$, $y_{ij} = \sum_{k=1}^{y_{i(j-1)}} Z_k(y_{i(j-1)})$, where $Z_k \stackrel{iid}{\sim} \text{Poisson}((\frac{\mu}{y_{i(j-1)}})^{1-\alpha})$. One can get

$$\mu_{ij}^c = \mu \cdot \left(\frac{y_{i(j-1)}}{\mu} \right)^\alpha.$$

Property:

$\alpha < 0$: the sample paths oscillate back and forth about their long-term average level.

$\alpha > 0$: the sample paths have sharper peaks and broader valleys.