Tricks

- All functions that are followed by a _ are in-place, e.g: uniform_(0, 1), add_(x), etc
 - In-place functions are usually more efficient
 - += is also in-place
- You can't use view() if you have a transposed matrix!!! (requires contiguous memory)
- z = x.view(batch, -1) this flattens the whole thing out
- Transposing is a special case of the permute function

Maths

```
torch.empty(shape) - uninitialized memory - whatever was in the memory at the time
```

torch.rand(shape), torch.zeros(shape), torch.eye(shape), torch.ones(shape), torch.arange(s,e,s) torch.tensor(arr, dtype=_, device=_, requires_grad=_) - This tells us if the tensor needs gradients torch.linspace(start, end, steps) - arange defines step size but linspace the number of values, and has ++options

```
tensor_x.normal_(mean=0, std=1) - normalizes data (in place function)
tensor_x.uniform_(0,1) - uniform distribution (in place function)
torch.diag(torch.ones(3)) - creates a diagonal matrix from tensor ----
Conversion (works no matter the device you're on)
```



tensor: .bool(), .short(int16), .long(int64), .half(float16, only new gpus), .float(float32), .double(float64)

```
torch.from_numpy(np_arr)
np_arr = tensor.numpy()
```

Tensor Math and Comparison

- You can use the default + operators or explicit functions .add(), etc
- torch.true_divide(x, y)
 - If the two shapes are the same, element-wise division
 - o If **y** is an integer, it divides all elements by **y**
- x.pow(2) is the same as x ** 2
- z = x > 0 returns a boolean array
- Matrix Multiplication: x1.mm(x2) or torch.mm(x1, x2) (2x3 * 3x5 = 2x5)
- z = x * y is element-wise multiplication
- torch.dot(x, y) dot product is for vectors, matrix multiplication for matrices
- x1.matrix_power(3)
- torch.bmm(x1, x2) Batch Multiplication for two vectors of shape (batch, x, y). Inside dimensions must match

Broadcasting

```
x1 = torch.rand((5, 5))
x2 = torch.rand((1, 5))
z = x1 - x2
                z = x1 ** x2
```

If you do something like subtracting a vector from a matrix, **pyTorch** (and NumPy) broadcast the vector, i.e. copy it 5 identically 5 times to make the shapes match

Other useful things

torch.any(x) returns true for a boolean array if any value is true

torch.all(x) returns true for a boolean array if all values is true

```
Torch Indexing
x[0] == x[0,:]
Yaddy yadda same as numpy
Fancy Indexing
x[list_of_indices]
x[(x < 2) | (x > 8)]
Useful Operations
torch.where (x > 5, x, x*2) - condition, how to change true vals, and how to change false vals
x.ndimension() - length of shape
x.numel() - total number of elements in tensor
Reshaping Tensors
x.arange(9)
x_3x3 = x.view(3, 3) - this needs the tensor to be in contiguous memory, superior performance
   This means you can't use view() if you have a transposed matrix!!!
x_3x3 = x.reshape(3, 3) - this doesn't, if it isn't it just makes a copy, safer but performance loss
z = x.view(-1) - this flattens the whole thing out
z = x.view(batch, -1) - this flattens the whole thing out
torch.cat((x1, x2), dim=0)
z = x.permute(0, 2, 1) - If you want to switch the order of axes (i.e. (batch, x, y) -> (batch, y, x))
```

• Transposing is a special case of the permute function

x.unsqueeze(0) - adds a dimension in the 0th spotx.squeeze(0)

torch.nn.Embedding -