Machine Learning 101 ~ Unsupervised Learning schusters > Supervised Learning no "right oursur" ("right ourswers" given can find structure in data tasks estimate more "light answers Regression Problem : continuous value answer L Classification Problems descrete valued output 1 Lincor Regression Notation Training set as dottaset for given problem

m as number of examples in training set - xin "input" variables y's ~ "output"/ "torget" variable = (x(i), y(i)) = ith training example L hypothesis as function given by learning algorithm
Ls maps From x's to y's given: Shypothesis Is parameters Lost Function 1 Gradient Descent * Con reach different local min depending on starting parameters

Lowerks best in cores in which there is only one min point

(elliptic paraboloid)

Algorithms

while (convergence) learning rate

Oj:= Oj - (D) J J (Oo, OL), univariate have

Je columbited and stored into temp values all at once, then updated all at once or well

as Learning Rate (x) too small & gradient descent is too slow - too big & "big steps", may lead to overshooting and failure to converge ND Goodient Descent for Linear Regression woodel $\{h_0(x) = \theta_0 + \theta_1 x \}$ $\{J(\theta_0,\theta_1) = \frac{1}{2} \sum_{m=1}^{\infty} (h_0(x^{(i)}) - y^{(i)})^2 \Rightarrow apply (b) \text{ to get lowest cost parameter}$ $\theta_{j} = \theta_{j} - \alpha \frac{1}{2} \frac{1}{3} (\theta_{0}, \theta_{1})$ $\theta_{j} = 1 \times \frac{1}{2} \frac{1}{2} (h_{0}(x^{(i)}) - y^{(i)}), x^{(i)}$ JO0 = 00 - a T = (NO (x0) - y0) * Batch" Gradient Descent each iteration goes through (P1:= AT = (40 (x(,) - A(,)) x(,) the entire training set Week 2 ND Multivosiate Linear regression - Xn feature contribute to output value Y - Notation & X(i) is vector containing all features in i-eth example - Hypothesis: ho(x)= Po+ PgX1+ P2X2+...+ OnXn Ly Xo = 1 ~ ho(x) = \(\int \times \tau \) = ATX vector with all Xs Gradient Descent : θj:= θj = α / [he(x(i)) - y(i)) x(i) ~) Feature Scaling Freature boing and similar scale con make gradient descent work fanter Leget every feature in range [-1,1] and divide by maximum value. Mean Normalization of $x_i = \frac{x_i - y_i}{x_i}$ overage value. ~ Convergence method establish a threshold E and it I (8) decrease by less than E in one iteration it has converged * hord to determine E Le plot in terotions x 5(b) -> helpful when choosing of X It's possible to create new featurer that enable the ofitting of polynomial functions to the date

D Normal Equations . Sower for optimum value directly - Take derivative and equal to zero Defining X as a matrix containing all feature and I as the solution vel 0 = (x x) - X 4 No need to choose or or to iterate Doer not scale well to a large number of featurer Week 3 ND Logistic Reglession Used in classification problems ~> Lincor regression is ineffective - Model (Binary cone) I he will output the probability of the conect prediction being I Decision Boundary [Pt x can represent all kinds of polynomials by adding extra featurer - Original cost function is not concex in logist regression or gradient descent wouldn't $J(\theta) = \frac{1}{m} \sum_{i=1}^{m} Cost(h_{\theta}(x^{i}), y^{(i)})$ ione = - log(h_{\theta}(x)) Cost () y=0 = - log (1-ho (x)) cost zero when prediction correct In LR, We have cost blows up when prediction in correct Cost (horx), y) = - y log (horx) - 16(1-y) log (L-ho(x)) Simplified. Gradient Descent Same update rule. 8; = 0, - x = (ho(xii) - yi) xi L Vectorizedo 0:= 8- x (1(0x)-y) Advanced Optimization Algorithms . Conjugate Gradient ? provided by language * Eminune () Multiclan Classification Lo One-Vs-all : find no for each Clan and predict whichever maximize the regul