

MTConnect® Standard Part 5.0 – Interface Interaction Model Version 2.0.0

Prepared for: MTConnect Institute

Prepared from: MTConnectSysMLModel.xml

Prepared on: May 24, 2022

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The normative XMI is located at the following URL: MTConnectSysMLModel.xml

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1 1 Purpose of This Document

- 2 This document, MTConnect Standard: Part 5.0 Interface Interaction Model of the MT-
- 3 Connect Standard, defines a structured data model used to organize information required
- 4 to coordinate inter-operations between pieces of equipment.
- 5 This data model is based on an *interaction model* that defines the exchange of information
- 6 between pieces of equipment and is organized in the MTConnect Standard by Inter-
- 7 faces.
- 8 Interfaces is modeled as an extension to the Device Information Model and Observa-
- 9 tion Information Model. Interfaces leverages similar rules and terminology as those
- used to describe a component in the *Device Information Model*. Interfaces also uses
- similar methods for reporting data to those used in the MTConnectStreams Response Doc-
- 12 ument.
- 13 As defined in MTConnect Standard: Part 2.0 Device Information Model, Interfaces
- organizes the Interface types (see Figure 3). Each individual Interface contains
- data associated with the corresponding interface.
- Note: See MTConnect Standard: Part 2.0 Device Information Model and
- 17 MTConnect Standard: Part 3.0 Observation Information Model of the MT-
- 18 Connect Standard for information on how Interfaces is structured in the
- 19 response documents which are returned from an agent in response to a probe
- 20 request, sample request, or current request.

21 **Terminology and Conventions**

- 22 Refer to MTConnect Standard Part 1.0 Fundamentals for a dictionary of terms, reserved
- language, and document conventions used in the MTConnect Standard.

24 2.1 MTConnect References

25	[MTConnect Part 1.0]	MTConnect Standard Part 1.0 - Fundamentals. Version 2.0.
26	[MTConnect Part 2.0]	MTConnect Standard: Part 2.0 - Device Information Model. Ver-
27		sion 2.0.
28	[MTConnect Part 3.0]	MTConnect Standard: Part 3.0 - Observation Information Model.
29		Version 2.0.
30	[MTConnect Part 5.0]	MTConnect Standard: Part 5.0 - Interface Interaction Model. Ver-
31		sion 2.0.

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33 Interface Interaction Model

- In many manufacturing processes, multiple pieces of equipment must work together to
- perform a task. The traditional method for coordinating the activities between individual
- 36 pieces of equipment is to connect them using a series of wires to communicate equipment
- 37 states and demands for action. These interactions use simple binary ON/OFF signals to
- 38 accomplished their intention.
- 39 In the MTConnect Standard, *interfaces* provides a means to replace this traditional method
- 40 for interconnecting pieces of equipment with a structured interaction model that provides
- a rich set of information used to coordinate the actions between pieces of equipment. Im-
- plementers may utilize the information provided by this data model to (1) realize the inter-
- action between pieces of equipment and (2) to extend the functionality of the equipment
- 44 to improve the overall performance of the manufacturing process.
- The interaction model used to implement interfaces provides a lightweight and efficient
- protocol, simplifies failure recovery scenarios, and defines a structure for implementing a
- Plug-And-Play relationship between pieces of equipment. By standardizing the informa-
- 48 tion exchange using this higher-level semantic information model, an implementer may
- more readily replace a piece of equipment in a manufacturing system with any other piece
- of equipment capable of providing similar interaction model functions.
- Two primary functions are required to implement the interaction model for an interfaces
- and manage the flow of information between pieces of equipment. Each piece of equip-
- ment needs to have the following:
- An *agent* which provides:
- The data required to implement the *interaction model*.
- Any other data from a piece of equipment needed to implement the *interface* operating states of the equipment, position information, execution modes, process information, etc.
- A client software application that enables the piece of equipment to acquire and interpret information from another piece of equipment.

61 3.1 Interfaces Architecture

- 62 MTConnect Standard is based on a communications method that provides no direct way
- for one piece of equipment to change the state of or cause an action to occur in another

- piece of equipment. The *interaction model* used to implement *interfaces* is based on a publish and subscribe type of communications as described in MTConnect Standard Part 1.0 Fundamentals and utilizes a request and response information exchange mechanism. For *interfaces*, pieces of equipment must perform both the publish (agent) and subscribe (client) functions.
 - Note: The current definition of *interfaces* addresses the interaction between two pieces of equipment. Future releases of the MTConnect Standard may address the interaction between multiple (more than two) pieces of equipment.

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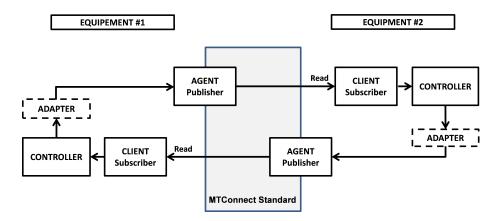


Figure 1: Data Flow Architecture for Interfaces

- Note: The data flow architecture illustrated in Figure 1 was historically referred to in the MTConnect Standard as a read-read concept.
- In the implementation of the *interaction model* for *interfaces*, two pieces of equipment 74 can exchange information in the following manner. One piece of equipment indicates a 75 request for service by publishing a type of request using a data item provided through 76 an agent as defined in Section 4.3 - DataItem Types for Interface. The client associated with the second piece of equipment, which is subscribing to data from the first machine, 78 detects and interprets that request. If the second machine chooses to take any action to 79 fulfill this request, it can indicate its acceptance by publishing a response using a data 80 item provided through its agent. The client on the first piece of equipment continues to 81 monitor information from the second piece of equipment until it detects an indication that 82 83 the *response* to the *request* has been completed or has failed.
- An example of this type of interaction between pieces of equipment can be represented by a machine tool that wants the material to be loaded by a robot. In this example, the machine tool is the *requester*, and the robot is the *responder*. On the other hand, if the robot wants the machine tool to open a door, the robot becomes the *requester* and the machine tool the *responder*.

89 3.2 Request and Response Information Exchange

- 90 The DataItem elements defined by the interaction model each have a REQUEST and
- 91 RESPONSE subtype. These subtypes identify if the data item represents a request or a
- 92 response. Using these data items, a piece of equipment changes the state of its request or
- 93 response to indicate information that can be read by the other piece of equipment. To aid
- in understanding how the *interaction model* functions, one can view this *interaction model*
- 95 as a simple state machine.
- The interaction between two pieces of equipment can be described as follows. When the
- 97 requester wants an activity to be performed, it transitions its request state from a READY
- 98 state to an ACTIVE state. In turn, when the client on the responder reads this information
- 99 and interprets the request, the responder announces that it is performing the requested
- task by changing its response state to ACTIVE. When the action is finished, the responder
- changes its response state to COMPLETE. This pattern of request and response provides
- the basis for the coordination of actions between pieces of equipment. These actions are
- implemented using EVENT category data items. (See Section 4.3 DataItem Types for
- 104 Interface for details on the Event type data items defined for interfaces.)
- Note: The implementation details of how the *responder* piece of equipment
- reacts to the *request* and then completes the requested task are up to the im-
- plementer.
- The initial condition of both the *request* and *response* states on both pieces of equipment
- is READY. The dotted lines indicate the on-going communications that occur to monitor
- the progress of the interactions between the pieces of equipment.
- 111 The interaction between the pieces of equipment as illustrated in Figure 2 progresses
- 112 through the sequence listed below.
- The *request* transitions from READY to ACTIVE signaling that a service is needed.
- The *response* detects the transition of the *request*.
- The *response* transitions from READY to ACTIVE indicating that it is performing
- the action.
- Once the action has been performed, the *response* transitions to COMPLETE.
- The *request* detects the action is COMPLETE.
- The *request* transitions back to READY acknowledging that the service has been
- performed.

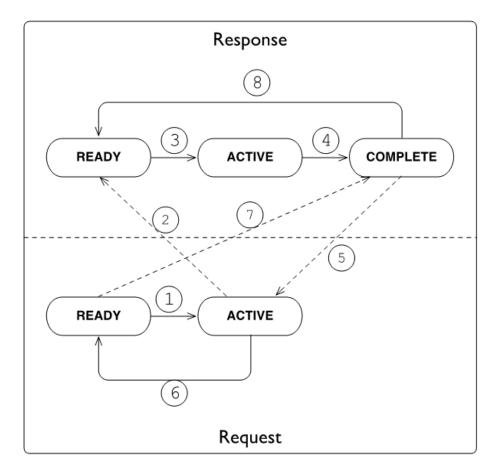


Figure 2: Request and Response Overview

- The *response* detects the *request* has returned to READY.
- In recognition of this acknowledgement, the *response* transitions back to READY.
- 123 After the final action has been completed, both pieces of equipment are back in the READY
- state indicating that they are able to perform another action.

125 3.3 Interface

abstract Component that coordinates actions and activities between pieces of equipment.

127 3.3.1 Commonly Observed DataItem Types for Interface

128 Table 1 lists the Commonly Observed DataItem Types for Interface.

Commonly Observed DataItem Types	Multiplicity
InterfaceState	1

 Table 1: Commonly Observed DataItem Types for Interface

129 4 Interfaces for Device and Observation Information Mod-130 els

- 131 The interaction model for implementing interfaces is defined in the MTConnect Standard
- as an extension to the Device Information Model and Observation Information Model.
- 133 A piece of equipment MAY support multiple different *interfaces*. Each piece of equipment
- supporting interfaces MUST model the information associated with each interface as an
- 135 Interface component. Interface is an abstract Component and is realized by
- 136 Interface component types.
- 137 The Figure 3 illustrates where an Interface is modeled in the Device Information
- 138 *Model* for a piece of equipment.

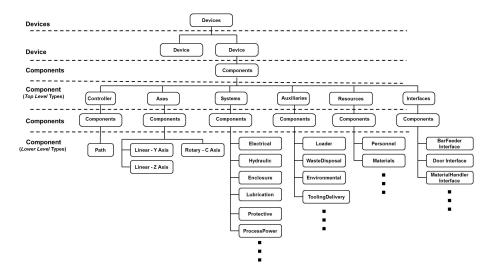


Figure 3: Interfaces in Entity Hierarchy

139 4.1 Interface Types

- 140 The abstract Interface is realized by the following types listed in this section.
- 141 In order to implement the *interaction model* for *interfaces*, each piece of equipment asso-
- ciated with an interface MUST provide the corresponding Interface type. A piece of
- equipment **MAY** support any number of unique *interfaces*.

144 4.1.1 BarFeederInterface

- 145 Interface that coordinates the operations between a bar feeder and another piece of
- 146 equipment.
- Bar feeder is a piece of equipment that pushes bar stock (i.e., long pieces of material of
- 148 various shapes) into an associated piece of equipment most typically a lathe or turning
- 149 center.

150 4.1.2 ChuckInterface

- 151 Interface that coordinates the operations between two pieces of equipment, one of
- which controls the operation of a chuck.
- 153 The piece of equipment that is controlling the chuck MUST provide the data item Chuck-
- 154 State as part of the set of information provided.

155 4.1.3 DoorInterface

- 156 Interface that coordinates the operations between two pieces of equipment, one of
- which controls the operation of a door.
- The piece of equipment that is controlling the door MUST provide data item DoorState
- as part of the set of information provided.

160 4.1.4 MaterialHandlerInterface

- 161 Interface that coordinates the operations between a piece of equipment and another
- associated piece of equipment used to automatically handle various types of materials or
- services associated with the original piece of equipment.
- 164 A material handler is a piece of equipment capable of providing any one, or more, of a
- variety of support services for another piece of equipment or a process like:
- Loading/unloading material or tooling
- Part inspection

- 168 Testing
- Cleaning
- 170 A robot is a common example of a material handler.

171 4.2 Data for Interface

- Each interface MUST provide the data associated with the specific interface to implement
- the interaction model and any additional data that may be needed by another piece of
- equipment to understand the operating states and conditions of the first piece of equipment
- as it applies to the *interface*.
- Details on data items specific to the *interaction model* for each type of *interface* are pro-
- vided in Section 4.3 DataItem Types for Interface.
- An implementer may choose any other data available from a piece of equipment to describe
- the operating states and other information needed to support an *interface*.

180 4.2.1 References for Interface

- Some of the data items needed to support a specific *interface* may already be defined
- elsewhere in the MTConnectDevices Response Document for a piece of equipment. How-
- ever, the implementer may not be able to directly associate this data with the *interface*
- since the MTConnect Standard does not permit multiple occurrences of a piece of data to
- be configured in an MTConnectDevices Response Document. References provides a
- mechanism for associating information defined elsewhere in the information model for a
- piece of equipment with a specific *interface*.
- 188 References organizes Reference elements.
- 189 Reference is a pointer to information that is associated with another entity defined
- 190 elsewhere for a piece of equipment.
- 191 References is an economical syntax for providing interface specific information with-
- out directly duplicating the occurrence of the data. It provides a mechanism to include all
- 193 necessary information required for interaction and deterministic information flow between
- 194 pieces of equipment.

- 195 For more information on the References model, see MTConnect Standard: Part 2.0 -
- 196 Device Information Model.

197 4.3 DataItem Types for Interface

- 198 Each Interface contains data items which are used to communicate information re-
- quired to execute the *interface*. When these data items are read by another piece of equip-
- 200 ment, that piece of equipment can then determine the actions that it may take based upon
- 201 that data.
- 202 InterfaceState is a data item specifically defined for interfaces. It defines the op-
- 203 erational state of the *interface*. This is an indicator identifying whether the *interface* is
- functioning or not. See Section 4.3.4 InterfaceState for complete semantic details.
- 205 Some data items MAY be directly associated with the Interface element and others
- 206 will be organized by a References element. It is up to an implementer to determine
- which additional data items are required for a particular *interface*.

208 4.3.1 Specific Data Items for the Interaction Model for Interface

- 209 A special set of data items have been defined to be used in conjunction with Interface.
- 210 They provide information from a piece of equipment to request a service to be performed
- 211 by another associated piece of equipment; and for the associated piece of equipment to
- indicate its progress in performing its response to the request for service. .
- 213 Many of the data items describing the services associated with an *interface* are paired to
- 214 describe two distinct actions one to request an action to be performed and a second to
- 215 reverse the action or to return to an original state. For example, a DoorInterface will
- 216 have two actions OpenDoor and CloseDoor. An example of an implementation of this
- 217 would be a robot that indicates to a machine that it would like to have a door opened so
- 218 that the robot could extract a part from the machine and then asks the machine to close
- 219 that door once the part has been removed.
- 220 When these data items are used to describe a service associated with an *interface*, they
- 221 MUST have one of the following two subType elements: REQUEST or RESPONSE.
- These MUST be specified to define whether the piece of equipment is functioning as the
- 223 requester or responder for the service to be performed. The requester MUST specify the
- 224 REQUEST subType for the data item and the responder MUST specify a corresponding
- 225 RESPONSE subType for the data item to enable the coordination between the two pieces
- 226 of equipment.

- These data items and their associated subType provide the basic structure for implement-
- 228 ing the *interaction model* for an *interface* and are defined in the following sections.
- Figure 4 and Figure 5 show possible state transitions for a request and response respec-
- 230 tively. The state machine diagrams provide the permissible values of the observations for
- 231 the DataItem types listed in this section.

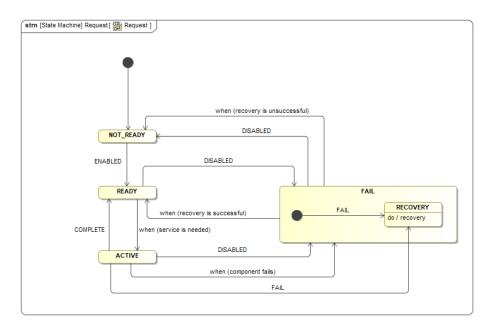


Figure 4: Request State Machine

232 4.3.2 CloseChuck

233 A subType **MUST** always be specified.

234 4.3.2.1 Subtypes of CloseChuck

- 235 REQUEST
- operating state of the *request* to close a chuck.
- 237 RequestStateEnum Enumeration:
- 238 ACTIVE
- requester has initiated a request for a service and the service has not yet been completed by the responder.
- MTConnect Part 5.0: Interface Interaction Model Version 2.0.0

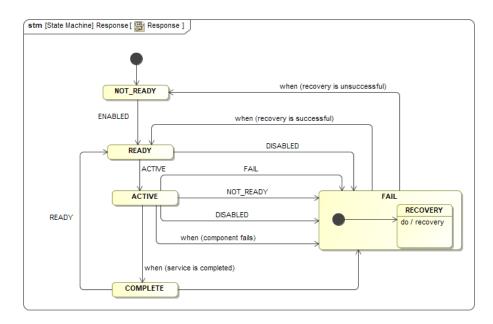


Figure 5: Response State Machine

- FAIL

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requester has detected a failure condition. 242 - NOT READY 243 244 requester is not ready to make a request. - READY 245 246 requester is prepared to make a request, but no request for service is required. • RESPONSE 247 operating state of the *response* to a *request* to close a chuck. 248 ResponseStateEnum Enumeration: 249 250 - ACTIVE responder has detected and accepted a request for a service and is in the process 251 of performing the service, but the service has not yet been completed. 252 253 - COMPLETE responder has completed the actions required to perform the service. 254 - FAIL 255 responder has detected a failure condition. 256 257 - NOT_READY responder is not ready to perform a service. 258

- **–** READY
- responder is prepared to react to a request, but no request for service has been
- detected.

262 4.3.3 CloseDoor

263 A subType **MUST** always be specified.

264 **4.3.3.1 Subtypes of CloseDoor**

- 265 REQUEST
- operating state of the *request* to close a door.
- The value of CloseDoor MUST be one of the RequestStateEnum enumera-
- 268 tion.
- 269 RESPONSE
- operating state of the *response* to a *request* to close a door.
- The value of CloseDoor MUST be one of the ResponseStateEnum enumer-
- ation.

273 4.3.4 InterfaceState

- When the InterfaceState is DISABLED, the state of all data items that are specific
- for the *interaction model* associated with that Interface MUST be set to NOT_READY.
- 276 InterfaceStateEnum Enumeration:
- 277 DISABLED
- 278 Interface is currently not operational.
- 279 ENABLED
- Interface is currently operational and performing as expected.

281 4.3.5 MaterialChange

282 A subType MUST always be specified.

283 4.3.5.1 Subtypes of MaterialChange

- 284 REOUEST
- operating state of the *request* to change the type of material or product being loaded
- or fed to a piece of equipment.
- The value of MaterialChange MUST be one of the RequestStateEnum
- enumeration.
- 289 RESPONSE
- operating state of the *response* to a *request* to change the type of material or product
- being loaded or fed to a piece of equipment.
- The value of MaterialChange MUST be one of the ResponseStateEnum
- enumeration.

294 4.3.6 MaterialFeed

295 A subType MUST always be specified.

296 4.3.6.1 Subtypes of MaterialFeed

- 297 REQUEST
- operating state of the *request* to advance material or feed product to a piece of equip-
- ment from a continuous or bulk source.
- The value of MaterialFeed MUST be one of the RequestStateEnum enu-
- meration.
- 302 RESPONSE
- operating state of the response to a request to advance material or feed product to a
- piece of equipment from a continuous or bulk source.
- The value of MaterialFeed MUST be one of the ResponseStateEnum enu-
- meration.

307 4.3.7 MaterialLoad

308 A subType MUST always be specified.

309 4.3.7.1 Subtypes of MaterialLoad

- 310 REQUEST
- operating state of the *request* to load a piece of material or product.
- The value of MaterialLoad MUST be one of the RequestStateEnum enu-
- 313 meration.
- 314 RESPONSE
- operating state of the *response* to a *request* to load a piece of material or product.
- The value of MaterialLoad MUST be one of the ResponseStateEnum enu-
- 317 meration.

318 4.3.8 MaterialRetract

319 A subType MUST always be specified.

320 **4.3.8.1 Subtypes of MaterialRetract**

- 321 REQUEST
- operating state of the *request* to remove or retract material or product.
- The value of MaterialRetract MUST be one of the RequestStateEnum
- 324 enumeration.
- 325 RESPONSE
- operating state of the *response* to a *request* to remove or retract material or product.
- The value of MaterialRetract MUST be one of the ResponseStateEnum
- 328 enumeration.

329 4.3.9 MaterialUnload

330 A subType MUST always be specified.

331 4.3.9.1 Subtypes of MaterialUnload

- 332 REQUEST
- operating state of the *request* to unload a piece of material or product.
- The value of MaterialUnload MUST be one of the RequestStateEnum
- enumeration.
- 336 RESPONSE
- operating state of the *response* to a *request* to unload a piece of material or product.
- The value of MaterialUnload MUST be one of the ResponseStateEnum
- enumeration.

340 4.3.10 OpenChuck

341 A subType MUST always be specified.

342 **4.3.10.1 Subtypes of OpenChuck**

- 343 REQUEST
- operating state of the *request* to open a chuck.
- The value of OpenChuck MUST be one of the RequestStateEnum enumera-
- 346 tion.
- 347 RESPONSE
- operating state of the *response* to a *request* to open a chuck.
- The value of OpenChuck MUST be one of the ResponseStateEnum enumer-
- ation.

351 4.3.11 OpenDoor

352 A subType MUST always be specified.

353 **4.3.11.1 Subtypes of OpenDoor**

- 354 REQUEST
- operating state of the *request* to open a door.
- The value of OpenDoor MUST be one of the RequestStateEnum enumera-
- 357 tion.
- 358 RESPONSE
- operating state of the *response* to a *request* to open a door.
- The value of OpenDoor MUST be one of the ResponseStateEnum enumera-
- 361 tion.

362 4.3.12 PartChange

363 A subType **MUST** always be specified.

364 **4.3.12.1 Subtypes of PartChange**

- 365 REQUEST
- operating state of the *request* to change the part or product associated with a piece
- of equipment to a different part or product.
- The value of PartChange MUST be one of the RequestStateEnum enumer-
- 369 ation.
- 370 RESPONSE
- operating state of the *response* to a *request* to change the part or product associated
- with a piece of equipment to a different part or product.
- The value of PartChange MUST be one of the ResponseStateEnum enu-
- meration.

5 Operation and Error Recovery

- The request and response state model implemented for interfaces may also be represented
- by a graphical model. The scenario in Figure 6 demonstrates the state transitions that occur
- during a successful request for service and the resulting response to fulfill that service
- 379 request.

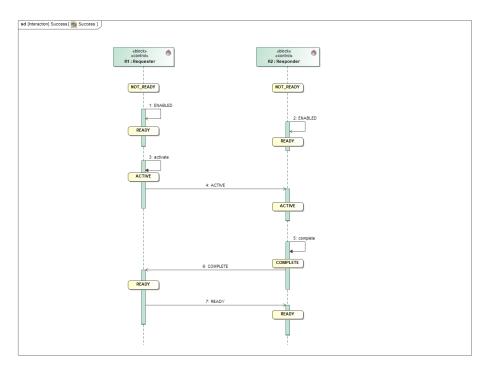


Figure 6: Success Scenario

380 5.1 Request and Response Failure Handling and Recovery

- 381 A significant feature of the request and response interaction model is the ability for ei-
- ther piece of equipment to detect a failure associated with either the request or response
- actions. When either a failure or unexpected action occurs, the request and the response
- portion of the *interaction model* can announce a FAIL state upon detecting a problem. The
- following are graphical models describing multiple scenarios where either the *requester*
- to the state of th
- or responder detects and reacts to a failure. In these examples, either the requester or
- responder announces the detection of a failure by setting either the request or the response
- 388 state to FAIL.
- Once a failure is detected, the *interaction model* provides information from each piece of
- equipment as they attempt to recover from a failure, reset all of their functions associated

- with the *interface* to their original state, and return to normal operation.
- The following sections are scenarios that describe how pieces of equipment may react to
- 393 different types of failures and how they indicate when they are again ready to request a
- 394 service or respond to a request for service after recovering from those failures:

395 5.1.1 Responder Fails Immediately

- In this scenario, a failure is detected by the responder immediately after a request for
- service has been initiated by the *requester*.

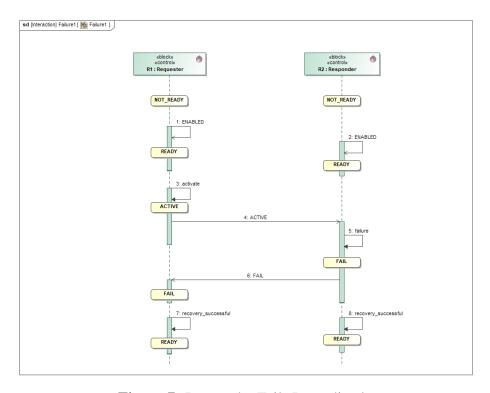


Figure 7: Responder Fails Immediately

- 398 In this case, the request transitions to ACTIVE and the responder immediately detects
- 399 a failure before it can transition the response state to ACTIVE. When this occurs, the
- 400 responder transitions the response state to FAIL.
- After detecting that the responder has transitioned its state to FAIL, the requester MUST
- 402 change its state to FAIL.
- The requester, as part of clearing a failure, resets any partial actions that were initiated and
- attempts to return to a condition where it is again ready to request a service. If the recovery

- is successful, the requester changes its state from FAIL to READY. If for some reason
- 406 the requester cannot return to a condition where it is again ready to request a service, it
- 407 transitions its state from FAIL to NOT_READY.
- The responder, as part of clearing a failure, resets any partial actions that were initiated
- and attempts to return to a condition where it is again ready to perform a service. If the
- 410 recovery is successful, the responder changes its response state from FAIL to READY. If
- 411 for some reason the responder is not again prepared to perform a service, it transitions its
- 412 state from FAIL to NOT_READY.

413 5.1.2 Responder Fails While Providing a Service

- This is the most common failure scenario. In this case, the *responder* will begin the actions
- required to provide a service. During these actions, the responder detects a failure and
- 416 transitions its response state to FAIL.

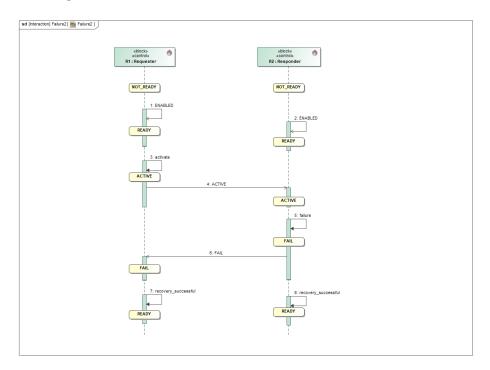


Figure 8: Responder Fails While Providing a Service

- When a requester detects a failure of a responder, it transitions it state from ACTIVE to
- 418 FAIL.
- 419 The requester resets any partial actions that were initiated and attempts to return to a
- condition where it is again ready to request a service. If the recovery is successful, the

- requester changes its state from FAIL to READY if the failure has been cleared and it is
- again prepared to request another service. If for some reason the requester cannot return
- 423 to a condition where it is again ready to request a service, it transitions its state from FAIL
- 424 to NOT_READY.
- 425 The responder, as part of clearing a failure, resets any partial actions that were initiated
- and attempts to return to a condition where it is again ready to perform a service. If the
- recovery is successful, the responder changes its response state from FAIL to READY if
- 428 it is again prepared to perform a service. If for some reason the responder is not again
- prepared to perform a service, it transitions its state from FAIL to NOT_READY.

430 5.1.3 Requester Failure During a Service Request

- In this scenario, the *responder* will begin the actions required to provide a service. During
- these actions, the *requester* detects a failure and transitions its *request* state to FAIL.

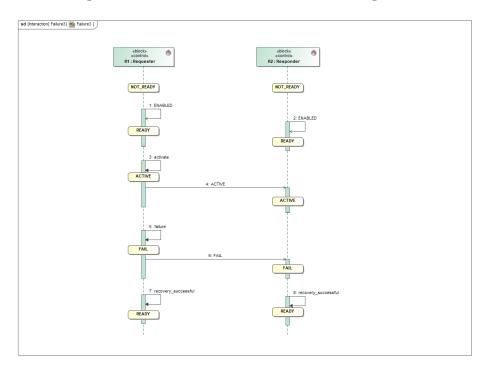


Figure 9: Requester Fails During a Service Request

- When the responder detects that the requester has transitioned its request state to FAIL,
- 434 the responder also transitions its response state to FAIL.
- The requester, as part of clearing a failure, resets any partial actions that were initiated and
- attempts to return to a condition where it is again ready to request a service. If the recovery

- is successful, the requester changes its state from FAIL to READY. If for some reason
- 438 the requester cannot return to a condition where it is again ready to request a service, it
- 439 transitions its state from FAIL to NOT_READY.
- The responder, as part of clearing a failure, resets any partial actions that were initiated
- and attempts to return to a condition where it is again ready to perform a service. If the
- recovery is successful, the responder changes its response state from FAIL to READY. If
- for some reason the *responder* is not again prepared to perform a service, it transitions its
- 444 state from FAIL to NOT READY.

445 5.1.4 Requester Changes to an Unexpected State While Responder is 446 Providing a Service

- In some cases, a requester may transition to an unexpected state after it has initiated a
- 448 request for service.
- 449 As demonstrated in Figure 10, the requester has initiated a request for service and its
- 450 request state has been changed to ACTIVE. The responder begins the actions required to
- provide the service. During these actions, the requester transitions its request state back
- 452 to READY before the responder can complete its actions. This **SHOULD** be regarded as a
- 453 failure of the requester.
- 454 In this case, the *responder* reacts to this change of state of the *requester* in the same way
- 455 as though the requester had transitioned its request state to FAIL (i.e., the same as in
- 456 Scenario 3 above).
- 457 At this point, the *responder* then transitions its *response* state to FAIL.
- 458 The responder resets any partial actions that were initiated and attempts to return to its
- original condition where it is again ready to perform a service. If the recovery is successful,
- 460 the responder changes its response state from FAIL to READY. If for some reason the
- responder is not again prepared to perform a service, it transitions its state from FAIL to
- 462 NOT READY.
- Note: The same scenario exists if the *requester* transitions its *request* state to
- NOT_READY. However, in this case, the *requester* then transitions its *request*
- state to READY after it resets all of its functions back to a condition where it
- is again prepared to make a *request* for service.

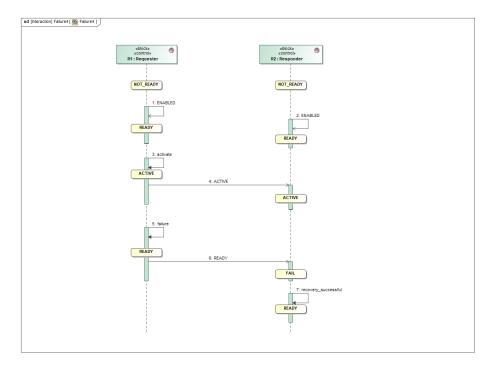


Figure 10: Requester Makes Unexpected State Change

5.1.5 Responder Changes to an Unexpected State While Providing a Service

- Similar to Scenario 5, a responder may transition to an unexpected state while providing
- 470 a service.
- 471 As demonstrated in Figure 11, the *responder* is performing the actions to provide a service
- 472 and the response state is ACTIVE. During these actions, the responder transitions its state
- 473 to NOT_READY before completing its actions. This should be regarded as a failure of the
- 474 responder.
- 475 Upon detecting an unexpected state change of the *responder*, the *requester* transitions its
- 476 state to FAIL.
- The requester resets any partial actions that were initiated and attempts to return to a
- 478 condition where it is again ready to request a service. If the recovery is successful, the
- 179 requester changes its state from FAIL to READY. If for some reason the requester cannot
- return to a condition where it is again ready to request a service, it transitions its state from
- 481 FAIL to NOT READY.
- Since the responder has failed to an invalid state, the condition of the responder is un-

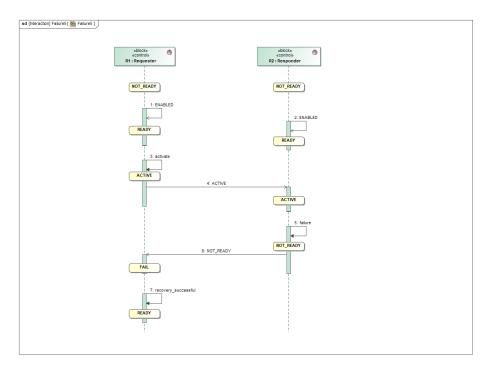


Figure 11: Responder Makes Unexpected State Change

- known. Where possible, the *responder* should try to reset to an initial state.
- 484 The responder, as part of clearing the cause for the change to the unexpected state, should
- attempt to reset any partial actions that were initiated and then return to a condition where
- it is again ready to perform a service. If the recovery is successful, the responder changes
- 487 its response state from the unexpected state to READY. If for some reason the responder is
- 488 not again prepared to perform a service, it maintains its state as NOT_READY.

Responder or Requester Become UNAVAILABLE or Experience a Loss of Communication

- 491 In this scenario, a failure occurs in the communications connection between the responder
- and requester. This failure may result from the InterfaceState from either piece of
- 493 equipment returning a value of UNAVAILABLE or one of the pieces of equipment does
- not provide a heartbeat within the desired amount of time (See MTConnect Standard Part
- 495 1.0 Fundamentals for details on heartbeat).
- When one of these situations occurs, each piece of equipment assumes that there has been
- a failure of the other piece of equipment.

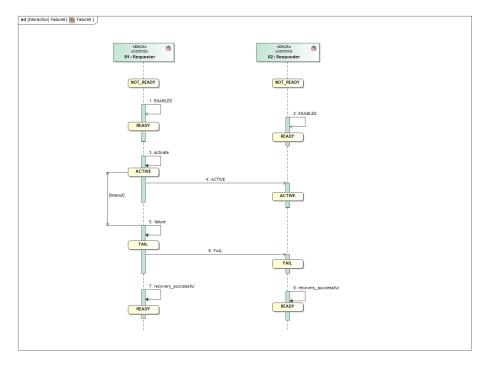


Figure 12: Requester - Responder Communication Failure 1

- When normal communications are re-established, neither piece of equipment should as-
- sume that the request and response state of the other piece of equipment remains valid.
- Both pieces of equipment should set their state to FAIL.
- 501 The requester, as part of clearing its FAIL state, resets any partial actions that were ini-
- 502 tiated and attempts to return to a condition where it is again ready to request a service.
- 503 If the recovery is successful, the requester changes its state from FAIL to READY. If for
- 504 some reason the requester cannot return to a condition where it is again ready to request a
- service, it transitions its state from FAIL to NOT_READY.
- The responder, as part of clearing its FAIL state, resets any partial actions that were initi-
- ated and attempts to return to a condition where it is again ready to perform a service. If
- 508 the recovery is successful, the responder changes its response state from FAIL to READY.
- 509 If for some reason the *responder* is not again prepared to perform a service, it transitions
- 510 its state from FAIL to NOT_READY.

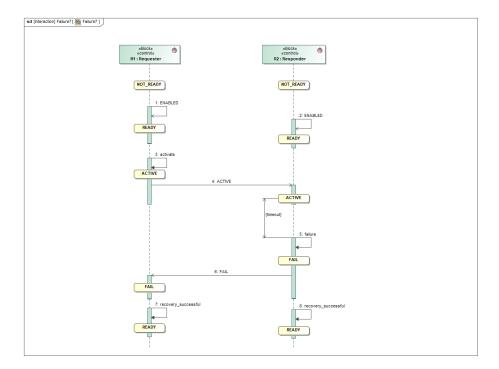


Figure 13: Requester - Responder Communication Failure 2

511 6 Profile

- 512 MTConnect Profile is a *profile* that extends the Systems Modeling Language (SysML)
- 513 metamodel for the MTConnect domain using additional data types and *stereotypes*.

514 6.1 DataTypes

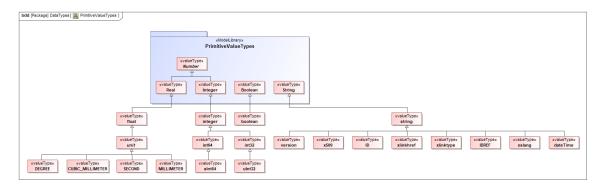


Figure 14: DataTypes

515 **6.1.1** boolean

516 primitive type.

517 **6.1.2** ID

518 string that represents an identifier (ID).

519 6.1.3 string

520 primitive type.

521 6.1.4 float

522 primitive type.

523 6.1.5 dateTime

string that represents timestamp in ISO 8601 format.

525 **6.1.6** integer

526 primitive type.

527 6.1.7 xlinktype

```
string that represents the type of an XLink element. See https://www.w3.org/TR/
```

529 xlink11/.

530 6.1.8 xslang

```
string that represents a language tag. See http://www.ietf.org/rfc/rfc4646.
```

532 txt.

533 **6.1.9 SECOND**

float that represents time in seconds.

535 6.1.10 IDREF

536 string that represents a reference to an ID.

537 **6.1.11** xlinkhref

- string that represents the locator attribute of an XLink element. See https://www.w3.
- 539 org/TR/xlink11/.

540 6.1.12 x509

string that represents an x509 data block. *Ref ISO/IEC 9594-8:2020*.

542 6.1.13 int32

543 32-bit integer.

544 **6.1.14** int64

545 **64-bit integer.**

546 6.1.15 version

- series of four numeric values, separated by a decimal point, representing a major, minor,
- and revision number of the MTConnect Standard and the revision number of a specific
- 549 schema.

550 6.1.16 uInt32

551 32-bit unsigned integer.

552 6.1.17 uInt64

553 64-bit unsigned integer.

554 6.2 Stereotypes

555 **6.2.1** organizer

556 element that *organizes* other elements of a type.

557 6.2.2 deprecated

element that has been deprecated.

559 6.2.3 extensible

560 enumeration that can be extended.

561 6.2.4 informative

562 element that is descriptive and non-normative.

563 6.2.5 valueType

extends SysML <<ValueType>> to include Class as a value type.

565 6.2.6 normative

566 element that has been added to the standard.

567 6.2.7 observes

association in which a Component makes Observations about an observable DataItem.

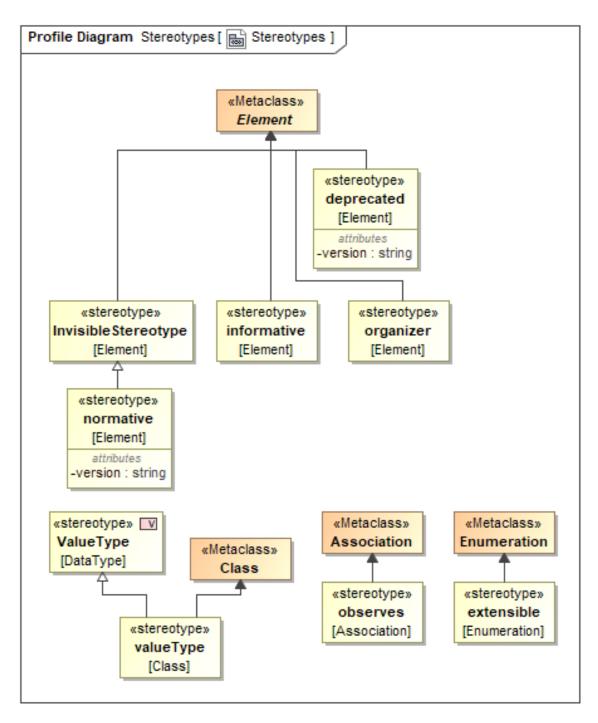


Figure 15: Stereotypes

569 Appendices

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