# Analyzing Quantum Many-Body Systems with ITensor and PastaQ

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https://mtfishman.github.io/

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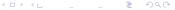
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- ► We are hiring postdocs, full-time scientists, part-time and full-time software developers, interns, etc.





# SIMONS FOUNDATION

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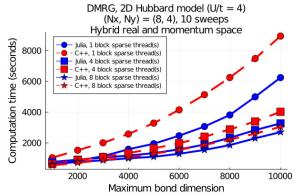


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- Great numerical libraries, code ended up faster.





# What is PastaQ?



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  - ▶ Built-in and easily extendable circuit definitions.
  - Approximate circuit evolution and optimization with MPS/MPO, etc.
- Find out more: github.com/GTorlai/PastaQ.jl  $_{\tiny \square}$



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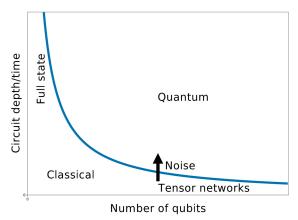
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  - ► ITensor and PastaQ handle this seamlessly.
  - ► This is not the focus of ITensor and PastaQ at the moment, specialized libraries like Yao.jl may be faster.
- ➤ Tensor networks are a common, general language for reasoning about quantum many-body systems (for example, quantum circuits).

▶ In my opinion, tensor networks are the best general purpose tool we have right now for studying quantum many-body systems (while we wait for a general purpose quantum computer).



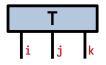
## What are tensor networks?



Matrix  $M_{ij}$ Order-2 tensor



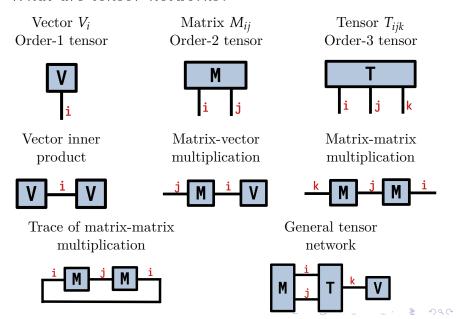
Tensor  $T_{ijk}$ Order-3 tensor



## What are tensor networks?

Vector  $V_i$ Matrix  $M_{ij}$ Tensor  $T_{ijk}$ Order-1 tensor Order-2 tensor Order-3 tensor Vector inner Matrix-vector Matrix-matrix multiplication multiplication product

## What are tensor networks?



1. Download Julia: julialang.org/downloads

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- 2. Launch Julia:
  - 1 \$ julia

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```
1 $ julia
```

3. Type the following commands:

```
julia> using Pkg
julia> Pkg.add("ITensors")
julia> Pkg.add("ITensors")
julia> Pkg.add("PastaQ")
julia> Pkg.add("PastaQ")
```

Now you can use ITensors and PastaQ:

```
julia> using ITensors
    julia > i = Index(2);
 4
    julia > A = ITensor(i);
 6
    julia > using PastaQ
 8
    julia > gates = [("X", 1), ("CX", (1, 3))];
 9
10
    julia> = runcircuit(gates);
```

```
1  using ITensors
2
3  i = Index(2)
4
5
```

#### Load ITensor

2-dimensional labeled Hilbert space (dim=2|id=510)

```
1     using ITensors
2
3     i = Index(2)
4
5
```



```
1     using ITensors
2
3     i = Index(2)
4
5
```

$$\begin{array}{ccc}
1 & \text{Zp} & = & \text{ITensor}(i) \\
2 & & & & & & & & & & & & & & & & & & \\
\end{array}$$

$$2 \text{ Zp}[i=>1] = 1$$

4 
$$Zp = ITensor([1, 0], i)$$

i

$$|Z+\rangle = \begin{bmatrix} 1\\0 \end{bmatrix}$$

Construct from a Vector

```
using ITensors
   i = Index(2)
5
   Zp = ITensor(i)
   Zp[i=>1] = 1
   Zp = ITensor([1, 0], i)
```

i

1 
$$Zp = ITensor([1, 0], i)$$
  
2  $Zm = ITensor([0, 1], i)$   
3  $Xp = ITensor([1, 1]//2, i)$ 

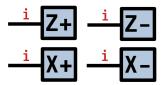
3 
$$Xp = ITensor([1, 1]/\sqrt{2}, i)$$

4 
$$\operatorname{Xm} = \operatorname{ITensor}([1, 1]/\sqrt{2}, 1)$$

$$|Z+\rangle = \begin{bmatrix} 1\\0 \end{bmatrix}, |Z-\rangle = \begin{bmatrix} 0\\1 \end{bmatrix}$$
$$|X+\rangle = \begin{bmatrix} 1\\1 \end{bmatrix} / \sqrt{2}, |X-\rangle = \begin{bmatrix} 1\\-1 \end{bmatrix} / \sqrt{2}$$

```
Zp = ITensor([1, 0], i)
Zm = ITensor([0, 1], i)
```

- $Xp = ITensor([1, 1]/\sqrt{2}, i)$
- $Xm = ITensor([1, -1]/\sqrt{2}, i)$



```
1 Zp = ITensor([1, 0], i)
    Zm = ITensor([0, 1], i)
    Xp = ITensor([1, 1]/\sqrt{2}, i)
    Xm = ITensor([1, -1]/\sqrt{2}, i)
1 (Zp + Zm)/\sqrt{2}
2 \quad dag(Zp) * Xp
3 \left( \frac{\operatorname{dag}(\mathrm{Zp}) * \mathrm{Xp}}{\mathrm{Im}} \right)
4 inner(Zp, Xp)
   norm(Xp)
```

```
\approx ITensor(1/\sqrt{2})
\approx 1/\sqrt{2}
\approx 1/\sqrt{2}
```

 $\approx Xp$ 

 $\approx 1$ 

```
1 Zp = ITensor([1, 0], i)

2 Zm = ITensor([0, 1], i)

3 Xp = ITensor([1, 1]/\sqrt{2}, i)

4 Xm = ITensor([1, -1]/\sqrt{2}, i)

1 (Zp + Zm)/\sqrt{2}

2 dag(Zp) * Xp

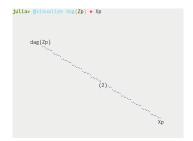
3 (dag(Zp) * Xp)

4 inner(Zp, Xp)

5 norm(Xp)
```

$$\frac{\mathbf{i}}{\mathbf{Z}} = \frac{\mathbf{i}}{\mathbf{X}} + \frac{\mathbf{i}}{\mathbf{Z}} = \frac{\mathbf{i}}{\mathbf{Z}} + \frac{\mathbf{i}}{\mathbf{Z}} = \frac{\mathbf{i}}{\sqrt{2}}$$

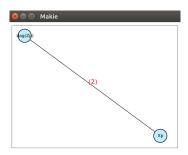
$$\mathbf{Z} + \frac{\mathbf{i}}{\mathbf{X}} + \mathbf{Z} = \frac{1}{\sqrt{2}}$$



- 1 **using**ITensorUnicodePlots
- $\overline{3}$  @visualize dag(Zp) \* Xp

- 1 using ITensorGLMakie
- 2
- 3 @visualize dag(Zp) \* Xp





### Tutorial: One-site states

"S=1/2" defines an operator basis

Additionally: "Qubit", "Qudit", "Electron", ...

### Tutorial: One-site states

```
1     i = Index(2, "S=1/2")
2
3
4
5
6
```

```
1 Zp = state("Z+", i)

2 Zm = state("Z-", i)

3 Xp = state("X+", i)

4 Xm = state("X-", i)
```

```
"S=1/2" defines an operator basis
```

```
Additionally: "Qubit", "Qudit", "Electron", . . .
```

```
1 ITensor([1 0], i)
2 ITensor([0 1], i)
3 (Zp + Zm)/\sqrt{2}
4 (Zp - Zm)/\sqrt{2}
```

#### Tutorial: Custom one-site states

```
import ITensors: state

function state(
::StateName"iX-",
::SiteType"S=1/2"

return [im -im]/√2
end
```

Overload ITensors.jl behavior

Define a state with the name "iX-"

#### Tutorial: Custom one-site states

```
import ITensors: state

function state(
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return [im -im]/√2
end
```

```
1 iXm = state("iX-", i)
2
3 inner(Zp, iXm)
4 inner(Zm, iXm)
```

Overload ITensors.jl behavior

Define a state with the name "iX-"

 $\approx$  im \* Xm

 $\approx \text{im}/\sqrt{2}$  $\approx -\text{im}/\sqrt{2}$ 

#### Tutorial: Custom one-site states

```
import ITensors: state

function state(
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return [im -im]/√2
end
```

Overload ITensors.jl behavior

Define a state with the name "iX-"

$$iX+ = (iX+)*i$$

## Tutorial: Priming

```
1 i = Index(2) (dim=2|id=837)

2 j = Index(2) (dim=2|id=837)

3 (dim=2|id=899)

4 i == j false
```

## Tutorial: Priming

```
1 i = Index(2)
2 j = Index(2)
3
4 i == j
```

## Tutorial: Priming

```
1 i = Index(2)
2 j = Index(2)
3
4 i == j
```

```
1  i = Index(2)
2
3  prime(i)
4  i'
5  i == i'
6  noprime(i')
```

# Tutorial: Priming

```
1 i = Index(2)
2 j = Index(2)
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4 i == j
```

```
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```

$$\frac{\underline{i}}{\text{prime}\left(\underline{i}\right) = \underline{i'}}$$

$$\frac{\underline{i}}{\underline{j'}} \neq \underline{i'}$$

- $1 \quad Z = ITensor(i', i)$
- Z[i'=>1, i=>1] = 1
- Z[i'=>2, i=>2] = -1

$$Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

- $1 \quad Z = ITensor(i', i)$
- 2 Z[i'=>1, i=>1] = 1
- Z[i'=>2, i=>2] = -1



```
1 Z = ITensor(i', i)
2 Z[i'=>1, i=>1] = 1
3 Z[i'=>2, i=>2] = -1
```

```
1 z = [
2 10
3 0-1
4 ]
5
6 Z = ITensor(z, i', dag(i))
7
8 Z = op("Z", i)
```



Matrix representation Z

Convert to ITensor

Use predefined definition

```
 \begin{array}{lll} 1 & Z = op(\mbox{"}\mbox{Z"}, i) & Z \\ 2 & X = op(\mbox{"}\mbox{X"}, i) & X \\ 3 & & Zp = state(\mbox{"}\mbox{Z+"}, i) & |Z+\rangle \\ 5 & Zm = state(\mbox{"}\mbox{Z-"}, i) & |Z-\rangle \\ \end{array}
```

```
1 Z = op("Z", i)

2 X = op("X", i)

3 Zp = state("Z+", i)

5 Zm = state("Z-", i)
```

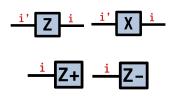
```
1  Z = op("Z", i)

2  X = op("X", i)

3  

4  Zp = state("Z+", i)

5  Zm = state("Z-", i)
```



$$X|Z+\rangle = |Z-\rangle$$
 false true true

$$\begin{array}{ll} 1 & XZp = X*Zp \\ 2 & XZp == Zm \\ 3 & XZp == Zm' \\ 4 & \text{noprime}(XZp) == Zm \end{array}$$

$$i'$$
  $X$   $i$   $Z+ =  $i'$   $Z-$$ 

```
\begin{array}{lll} 1 & XZp = X*Zp & X|Z+\rangle = |Z-\rangle \\ 3 & inner(Zm, XZp) & error: not a scalar value \\ 5 & inner(Zm', XZp) & \approx 1 \\ 6 & inner(Zp', XZp) & \approx 0 \end{array}
```

```
1  XZp = X * Zp

2  inner(Zm, XZp)

4  inner(Zm', XZp)

6  inner(Zp', XZp)
```

```
1 (dag(Zm)' * X * Zp)[]
2 inner(Zm', X, Zp)
3
4 XZp = apply(X, Zp)
5 inner(Zm, XZp)
```

 $\approx 1$ 

```
XZp = X * Zp
   inner(Zm, XZp)
4
   inner(Zm', XZp)
   inner(Zp', XZp)
   (dag(Zm)' * X * Zp)[]
   inner(Zm', X, Zp)
   XZp = \frac{apply}{X}(X, Zp)
   inner(Zm, XZp)
```

$$\frac{\mathbf{i}'}{\mathbf{Z} - \mathbf{Z} - \mathbf{i}}$$

$$\frac{\mathbf{Z} - \mathbf{i}'}{\mathbf{X} - \mathbf{Z} + \mathbf{i}'} = 1$$

$$\mathbf{Z} + \mathbf{i}' \times \mathbf{Z} + \mathbf{Z} + \mathbf{I}$$

$$\mathbf{Z} + \mathbf{I} \times \mathbf{Z} + \mathbf{I}$$

$$\mathbf{Z} + \mathbf{Z} + \mathbf{I}$$

$$\mathbf{Z} + \mathbf{I} \times \mathbf{Z} + \mathbf{I}$$

$$\mathbf{Z} + \mathbf{$$

```
import ITensors: op
    function op(
     ::OpName"iX",
    ::SiteType"S=1/2"
6
     return [
      0 \text{ im}
    im 0
10
```

Overload ITensors.jl behavior

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import ITensors: op
    function op(
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     return [
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$$\frac{i'}{X} = \frac{i'}{X} \times i$$

```
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    end
```

$$\frac{\mathbf{i'} \quad \mathbf{iX} \quad \mathbf{i}}{\mathbf{iX} \quad \mathbf{i}} = \left( \frac{\mathbf{i'} \quad \mathbf{X} \quad \mathbf{i}}{\mathbf{X}} \right) * \mathbf{i}$$

```
1 op("iX", i)
```

```
import ITensors: op
   function op(
     ::OpName"iX",
    ::SiteType"S=1/2"
 6
    return
    0 \text{ im}
    im 0
10
    end
```

$$\frac{\mathbf{i}' \mathbf{i} \mathbf{X} \cdot \mathbf{i}}{\mathbf{1} \cdot \mathbf{i} \mathbf{m} * \mathbf{X}} = \left(\frac{\mathbf{i}' \mathbf{X} \cdot \mathbf{i}}{\mathbf{X}}\right) * \mathbf{i}$$

```
1 op("iX", i)
```

```
1  i1 = Index(2, "S=1/2")
2  i2 = Index(2, "S=1/2")
3
4  i1 == i2
5
6  ZpZm = ITensor(i1, i2)
7  ZpZm[i1=>1, i2=>2] = 1
```

$$(dim=2|id=505|"S=1/2")$$
  
 $(dim=2|id=576|"S=1/2")$   
false

$$|Z+\rangle_1|Z-\rangle_2 = |Z+Z-\rangle$$

```
1 i1 = Index(2, "S=1/2")

2 i2 = Index(2, "S=1/2")

3

4 i1 == i2

5

6 ZpZm = ITensor(i1, i2)

7 ZpZm[i1=>1, i2=>2] = 1
```

```
1 i1 = Index(2, "S=1/2")

2 i2 = Index(2, "S=1/2")

3

4 i1 == i2

5

6 ZpZm = ITensor(i1, i2)

7 ZpZm[i1=>1, i2=>2] = 1
```

Z+ 1<sub>2</sub> Z-

```
1  Zp1 = state("Z+", i1)
2  Zp2 = state("Z+", i2)
3
4  Zm1 = state("Z-", i1)
5  Zm2 = state("Z-", i2)
6
7  ZpZm = Zp1 * Zm2
8  ZmZp = Zm1 * Zp2
```

$$|Z+\rangle_1$$
  
 $|Z+\rangle_2$ 

$$|Z-\rangle_1$$
  
 $|Z-\rangle_2$ 

$$|Z+Z-\rangle = |Z+\rangle_1|Z-\rangle_2$$
  
 $|Z-Z+\rangle = |Z-\rangle_1|Z+\rangle_2$ 

```
1 i1 = Index(2, "S=1/2")

2 i2 = Index(2, "S=1/2")

3

4 i1 == i2

5

6 ZpZm = ITensor(i1, i2)

7 ZpZm[i1=>1, i2=>2] = 1
```

```
1  Zp1 = state("Z+", i1)
2  Zp2 = state("Z+", i2)
3
4  Zm1 = state("Z-", i1)
5  Zm2 = state("Z-", i2)
6
7  ZpZm = Zp1 * Zm2
8  ZmZp = Zm1 * Zp2
```



1 = ITensor(i1, i2)  
2 [i1=>1, i2=>2] = 
$$1/\sqrt{2}$$
  
3 [i1=>2, i2=>1] =  $1/\sqrt{2}$   
4  
5 =  $(\text{Zp1} * \text{Zm2} + \text{Zm1} * \text{Zp2})/\sqrt{2}$ 

$$(|Z+\rangle|Z-\rangle + |Z-\rangle|Z+\rangle)/\sqrt{2}$$

From single-site states

```
1 = ITensor(i1, i2)

2 [i1=>1, i2=>2] = 1/\sqrt{2}

3 [i1=>2, i2=>1] = 1/\sqrt{2}

4

5 = (\text{Zp1} * \text{Zm2} + \text{Cm1} * \text{Zp2})/\sqrt{2}
```

```
1 = ITensor(i1, i2)

2 [i1=>1, i2=>2] = 1/\sqrt{2}

3 [i1=>2, i2=>1] = 1/\sqrt{2}

4

5 = (\text{Zp1} * \text{Zm2} + \text{Zm1} * \text{Zp2})/\sqrt{2}
```

```
\begin{array}{ll} & inner(\;,\;) \\ 2 & inner(ZpZm,\;) \\ 3 & \\ 4 & U,\,S,\,V = svd(ZmZp,\,i1) \\ 5 & s = diag(S) \\ 6 & \\ 7 & U,\,S,\,V = svd(\;,\,i1) \\ 8 & s = diag(S) \\ \end{array}
```

### v = 11 Z4 + 11 Z1 √2

$$\approx 1$$
 $\approx 1/\sqrt{2}$ 

$$\approx [1, 0]$$

$$\approx [1/\sqrt{2},\,1/\sqrt{2}]$$

```
1 = ITensor(i1, i2)

2 [i1=>1, i2=>2] = 1/\sqrt{2}

3 [i1=>2, i2=>1] = 1/\sqrt{2}

4

5 = (\text{Zp1} * \text{Zm2} + \text{Zm1} * \text{Zp2})/\sqrt{2}
```

```
inner(, )
inner(ZpZm, )

U, S, V = svd(ZmZp, i1)

s = diag(S)

U, S, V = svd(, i1)

s = diag(S)
```

```
1 H = ITensor(i1', i2', i1, i2)
2 H[i1'=>2, i2'=>1,
3 i1=>2, i2=>1] = -1
4 # ...
```

Make a Hamiltonian: Transverse field Ising n=2 sites  $H=-\sum_{j}^{n-1}Z_{j}Z_{j+1}+h\sum_{j}^{n}X_{j}$ 

```
\begin{array}{ll} 1 & H = ITensor(i1',\,i2',\,i1,\,i2) \\ 2 & H[i1'=>2,\,i2'=>1, \\ 3 & i1=>2,\,i2=>1] = -1 \\ 4 & \# \ ... \end{array}
```

```
1 Id1 = op("Id", i1)
2 Z1 = op("Z", i1)
3 X1 = op("X", i1)
4 # ...
5
6 ZZ = Z1 * Z2
7 XI = X1 * Id2
8 IX = Id1 * X2
9
10 h = 0.5
11 H = -ZZ + h * (XI + IX)
```

Make a Hamiltonian: Transverse field Ising n=2 sites  $H = -\sum_{j}^{n-1} Z_{j}Z_{j+1} + h\sum_{j}^{n} X_{j}$  Alternative: Build from single-site operators. Less error-prone.

```
\begin{array}{ll} 1 & H = {\bf ITensor}(i1',\,i2',\,i1,\,i2) \\ 2 & H[i1'=>2,\,i2'=>1, \\ 3 & i1=>2,\,i2=>1] = -1 \\ 4 & \# \dots \end{array}
```

```
1 Id1 = op("Id", i1)
2 Z1 = op("Z", i1)
3 X1 = op("X", i1)
4 # ...
5
6 ZZ = Z1 * Z2
7 XI = X1 * Id2
8 IX = Id1 * X2
9
10 h = 0.5
11 H = -ZZ + h * (XI + IX)
```

Make a Hamiltonian: Transverse field Ising n=2 sites  $H = -\sum_{j}^{n-1} Z_{j}Z_{j+1} + h\sum_{j}^{n} X_{j}$ 

### [TODO: Add visualization of $\langle H \rangle$ ]

```
1 ZpZp = Zp1 * Zp2  # Expectation value:

2 # \langle H \rangle = \langle Z+Z+|H|Z+Z+ \rangle

3 | 4 | 5 (dag(ZpZp)' * H * ZpZp)[]

6 inner(ZpZp', H, ZpZp)  # \approx -1

7 inner(ZpZp, apply(H, ZpZp))
```

### [TODO: Add visualization of $\langle H \rangle$ ]

```
1 ZpZp = Zp1 * Zp2  # Expectation value:

2 # \langle H \rangle = \langle Z+Z+|H|Z+Z+\rangle

3 # \langle H \rangle = \langle Z+Z+|H|Z+Z+\rangle

5 (dag(ZpZp)' * H * ZpZp)[]

6 inner(ZpZp', H, ZpZp)  # \approx -1

7 inner(ZpZp, apply(H, ZpZp))
```

$$\begin{array}{ll} 1 & D, \, U = \operatorname{eigen}(H) \\ 2 & \operatorname{diag}(D) \end{array}$$

$$\# \approx [-\sqrt{2}, -1, 1, \sqrt{2}]$$

```
import ITensors: op
2
    function op(
     ::OpName"CRy",
     ::SiteType"S=1/2";
 6
     c = \cos(\theta/2)
     s = \sin(\theta/2)
   return
10
11
   1 \ 0 \ 0
  0 1 0 0
12
  0 0 c -s
13
14 	 0.0 s c
15
16
    end
```

```
# Controlled—Ry (CRy)
# rotation gate
\# \operatorname{CRy}(\theta)
```

### [TODO: Add visualization of CH|ZpZm>]

1 CH = op("CRy", i1, i2;  
2 
$$\theta = \pi/2$$
)

```
# Controlled—Hadamard gate # CH = CRy(\theta=\pi/2)
```

### [TODO: Add visualization of CH|ZpZm>]

1 CH = op("CRy", i1, i2;  
2 
$$\theta = \pi/2$$
)

# Controlled—Hadamard gate # CH = 
$$CRy(\theta=\pi/2)$$

$$2pZm = Zp1 * Zm2$$

4

$$3 \text{ CH\_Xm} = \frac{\text{apply}(\text{CH, ZpZm})}{\text{CH}}$$

$$5 \text{ CH}_X\text{m} \approx \text{Zp1} * \text{Xm2}$$

$$\#~|\mathrm{Z+Z-}\rangle = |\mathrm{Z+}\rangle_1|\mathrm{Z-}\rangle_2$$

$$\# \text{ CH}|\text{Z}+\text{Z}-\rangle = |\text{Z}+\text{X}-\rangle$$

### [TODO: Add visualization of minimizing <v|H|v>]

```
1 function E(\psi)

2 \psi H \psi = inner(\psi', H, \psi)

3 \psi \psi = inner(\psi, \psi)

4 return \psi H \psi / \psi \psi

5 end
```

```
# Function to minimize:

# Expectation value of the

# energy.

#

# E(\psi) = \langle \psi | H | \psi \rangle / \langle \psi | \psi \rangle
```

function  $E(\psi)$ 

### [TODO: Add visualization of minimizing $\langle v|H|v\rangle$ ]

```
\psi H \psi = inner(\psi', H, \psi)
                                                  # Expectation value of the
\psi\psi = \operatorname{inner}(\psi, \psi)
                                                  \# energy.
return ψHψ / ψψ
end
                                                  \# E(\psi) = \langle \psi | H | \psi \rangle / \langle \psi | \psi \rangle
function minimize(f, \partial f, x;
                                                  # Simple gradient descent.
 nsteps, \gamma)
                                                  # Must provide function f(x)
for n in 1:nsteps
                                                  # to minimize and \partial f(x),
  x = x - \gamma * \partial f(x)
                                                  # the gradient of f at x.
end
return x
                                                  # \gamma is the gradient
 end
                                                  # descent step size.
```

# Function to minimize:

### [TODO: Add visualization of minimizing $\langle v|H|v\rangle$ ]

```
1 \psi_0 = (\mathrm{Zp1} * \mathrm{Zm2} + \mathrm{Zm1} * \mathrm{Zp2})/\sqrt{2}
3
4 \mathrm{E}(\psi_0)
5
6 \mathrm{using} Zygote: gradient
7 \partial \mathrm{E}(\psi) = \mathrm{gradient}(\mathrm{E}, \psi)[1]
8
9 \mathrm{norm}(\partial \mathrm{E}(\psi_0))
```

# 
$$|\psi_0\rangle = (|Z+Z+\rangle +$$
#  $|Z-Z-\rangle)/\sqrt{2}$ 
#  $\approx -1$ 
# Using Zygote for automatic # differentation of the energy.
#  $\approx 2$ 

### [TODO: Add visualization of minimizing <v|H|v>]

```
\# |\psi_0\rangle = (|Z+Z+\rangle +
     \psi_0 = (\text{Zp1} * \text{Zm2} +
                                                                  \# |Z-Z-\rangle)/\sqrt{2}
               Zm1 * Zp2)/\sqrt{2}
3
     \mathbf{E}(\psi_0)
                                                                  \# \approx -1
5
     using Zygote: gradient
                                                                  # Using Zygote for automatic
     \partial \mathbf{E}(\psi) = \mathbf{gradient}(\mathbf{E}, \psi)[1]
                                                                  # differentiation of the energy.
8
     \operatorname{norm}(\partial \mathbf{E}(\psi_0))
                                                                  \#\approx 2
```

## Tutorial: Two-site circuit optimization

```
# Circuit as a vector of gates:
     U(\theta, i1, i2) = [
      op("Ry", i1; \theta = \theta[1]),
      op("Ry", i2; \theta = \theta[2]),
     op("CX", i1, i2),
      op("Ry", i1; \theta = \theta[3]),
       op("Ry", i2; \theta = \theta[4]),
 8
10
11
```

```
# PastaQ notation:  u(\theta, j1, j2) = [ \\ ("Ry", j1, (; \theta = \theta[1])), \\ ("Ry", j2, (; \theta = \theta[2])), \\ ("CNOT", j1, j2), \\ ("Ry", j1, (; \theta = \theta[3])), \\ ("Ry", j2, (; \theta = \theta[4])), \\ ] \\ U(\theta, i1, i2) = \\ buildcircuit(u(\theta, 1, 2), [i1, i2])
```

### Tutorial: Two-site circuit optimization

#### [TODO: Add visualization of minimizing <0|UHU|0>]

```
1 \psi_0 = \mathrm{Zp1} * \mathrm{Zp2}
2
3
4 function \mathrm{E}(\theta)
5 \psi_\theta = \mathrm{apply}(\mathrm{U}(\theta), \psi_0)
6 return \mathrm{inner}(\psi_\theta, \mathrm{H}, \psi_\theta)
7 end
```

```
# References state:

# |0\rangle = |Z+Z+\rangle

# Find \theta that minimizes:

# E(\theta) = \langle 0|U(\theta)^{\dagger} H U(\theta)|0\rangle

# = \langle \theta|H|\theta\rangle
```

# Tutorial: Two-site circuit optimization

#### [TODO: Add visualization of minimizing $<0|\mathrm{UHU}|0>$ ]

```
1 \psi_0 = \mathrm{Zp1} * \mathrm{Zp2} # References state:

2 # |0\rangle = |\mathrm{Z} + \mathrm{Z} + \rangle

3 function \mathrm{E}(\theta) # Find \theta that minimizes:

5 \psi_\theta = \mathrm{apply}(\mathrm{U}(\theta), \psi_0) # \mathrm{E}(\theta) = \langle 0|\mathrm{U}(\theta)^\dagger \; \mathrm{H} \; \mathrm{U}(\theta)|0\rangle

6 return inner(\psi_\theta), H, \psi_\theta) # = \langle \theta|\mathrm{H}|\theta\rangle

7 end
```

```
1 \theta_0 = [0, 0, 0, 0]

2 \theta = \underset{\text{minimize}}{\text{minimize}}(E, \partial E, \theta_0;

3 \text{nsteps}=40, \gamma=0.5)

4 E(\theta_0), \underset{\text{norm}}{\text{norm}}(\partial E(\theta_0))

6 E(\theta), \underset{\text{norm}}{\text{norm}}(\partial E(\theta))
```

```
# (-1, \sqrt{3}/2)
# (-1.4142077, 0.0017584116)
# \approx (-\sqrt{2}, 0)
```

## Tutorial: Two-site fidelity optimization

#### [TODO: Add visualization of minimizing $\langle v|U|v0\rangle$ ]

```
1 \psi_0 = \mathrm{Zp1} * \mathrm{Zp2}

2 \psi = (\mathrm{ZpZp} + \mathrm{ZmZm}) / \sqrt{2}

3 4 5 6 function F(\theta)

7 \psi_\theta = \mathrm{apply}(\mathrm{U}(\theta, \mathrm{i1}, \mathrm{i2}), \psi_0)

8 return -abs(inner(\psi, \psi_\theta))^2

9 end
```

```
# Reference state:

# |0\rangle = |Z+Z+\rangle

# Target state:

# |\psi\rangle = (|Z+Z+\rangle + |Z-Z-\rangle)/\sqrt{2}

# Find \theta that minimizes:

# F(\theta) = -|\langle \psi | U(\theta) | 0 \rangle|^2
```

# Tutorial: Two-site fidelity optimization

#### [TODO: Add visualization of minimizing $\langle v|U|v0\rangle$ ]

```
1 \psi_0 = \operatorname{Zp1} * \operatorname{Zp2} # Reference state:

2 \psi = (\operatorname{ZpZp} + \operatorname{ZmZm}) / \sqrt{2} # Target state:

5 # |\psi\rangle = |\operatorname{Z}+\operatorname{Z}+\rangle

6 function \operatorname{F}(\theta) # |\operatorname{Z}-\operatorname{Z}-\rangle)/\sqrt{2}

7 \psi_\theta = \operatorname{apply}(\operatorname{U}(\theta, \operatorname{i1}, \operatorname{i2}), \psi_0)

8 \operatorname{return} \operatorname{-abs}(\operatorname{inner}(\psi, \psi_\theta))^2 # Find \theta that minimizes:

9 end # \operatorname{F}(\theta) = -|\langle \psi|\operatorname{U}(\theta)|0\rangle|^2
```

```
1 \theta_0 = [0, 0, 0, 0]

2 \theta = \underset{\text{minimize}}{\text{minimize}}(F, \partial F, \theta_0;

3 \text{nsteps} = 50, \gamma = 0.1)

4 

5 F(\theta_0), \underset{\text{norm}}{\text{norm}}(\partial F(\theta_0))

6 F(\theta), \underset{\text{norm}}{\text{norm}}(\partial F(\theta))
```

#### [TODO: Add visualization of $\langle \text{Zp}| \rangle$ ]

```
1  n = 30

2  i = [Index(2, "S=1/2")]

3  for j in 1:n]

4  Zp = MPS(i, "Z+")

6  Zm = MPS(i, "Z-")

7  = (Zp + Zm)/\sqrt{2}
```

```
# n-site state

# |Z+Z+...Z+\rangle

# |Z-Z-...Z-\rangle

# (|Z+Z+...Z+\rangle + 

# |Z-Z-...Z-\rangle)/\sqrt{2}
```

[TODO: Add visualization of  $\langle \text{Zp}| \rangle$ ]

```
n = 30
                                        # n-site state
i = [Index(2, "S=1/2")]
     for j in 1:n
Zp = MPS(i, "Z+")
                                        \# |Z+Z+...Z+\rangle
Zm = MPS(i, "Z-")
                                        \# |Z-Z-...Z-\rangle
  = (\mathrm{Zp} + \mathrm{Zm})/\sqrt{2}
                                        \# (|Z+Z+...Z+) +
                                        # |Z-Z-...Z-\rangle)/\sqrt{2}
```

```
\begin{array}{lll} 1 & \underset{}{\text{maxlinkdim}(Zp)} & \# \ 1 \ (product \ state) \\ 2 & \underset{}{\text{maxlinkdim}(} \ ) & \# \ 2 \ (entangled \ state) \\ 3 & \underset{}{\text{inner}(Zp, Zp)} & \# \ \langle Z+|Z+\rangle \approx 1 \\ 4 & \underset{}{\text{inner}(Zm, Zp)} & \# \ \langle Z-|Z+\rangle \approx 0 \\ 5 & \underset{}{\text{norm}(} \ ) & \# \ (\langle Z+|+\langle Z-|)(|Z+\rangle +|Z+\rangle)/2 \\ 6 & \# \ \approx 1 \end{array}
```

#### [TODO: Add visualization of minimizing <psi|H|psi>]

```
1          j = n ÷ 2

2          X<sub>j</sub> = op("X", i[j])

3          X<sub>j</sub>Zp = apply(X<sub>j</sub>, Zp)

5          state = [k == j ? "Z-" : "Z+" for k in 1:n]

9          X<sub>j</sub>Zp = MPS(i, state)
```

#### [TODO: Add visualization of minimizing <psi|H|psi>]

```
# j = n ÷ 2

# X_j

# X_j | Z+Z+...Z+ \rangle =

# | Z+Z+...Z-...Z+ \rangle

# | Z+Z+...Z-...Z+ \rangle
```

```
 \begin{array}{ll} 1 & \operatorname{maxlinkdim}(\mathbf{X}_{j}\mathbf{Z}\mathbf{p}) \\ 2 & \operatorname{inner}(\mathbf{Z}\mathbf{p},\,\mathbf{X}_{j}\mathbf{Z}\mathbf{p}) \\ 3 & \operatorname{inner}(\mathbf{X}_{j}\mathbf{Z}\mathbf{p},\,\operatorname{apply}(\mathbf{X}_{j},\,\mathbf{Z}\mathbf{p})) \end{array}
```

```
# 1 (product state)
# \approx 0
# \approx 1
```

```
# n sites
    function ising(n; h)
                                           \# H = -\sum_{j=1}^{n-1} Z_{j}Z_{j+1} + h\sum_{j=1}^{n} X_{j}
     H = OpSum()
     for j in 1:(n - 1)
     H = "Z", j, "Z", j + 1
    end
     for j in 1:n
     H += h, "X", j
8
    end
    return H
    end
10
```

# Tutorial: n-site states with MPS [TODO: Add visualization of H]

```
function ising(n; h)
                                             # n sites
                                             \# H = -\sum_{i=1}^{n-1} Z_{i}Z_{j+1} + h\sum_{j=1}^{n} X_{j}
      H = OpSum()
      for j in 1:(n - 1)
       H = "Z", j, "Z", j + 1
      end
 6
      for j in 1:n
      H += h, "X", i
      end
     return H
10
    end
```

3 maxlinkdim(H)
 4 Zp = MPS(i, "Z+")
 5 inner(Zp', H, Zp)

H = MPO(ising(n; h=h), i)

h = 0.5

# \langle Z+Z+...Z+ \rangle H \rangle Z+Z+...Z+ \rangle

# = 3 (local Hamiltonian)

```
1 \psi_0 = \text{MPS}(i, \text{"Z+"})  # |0\rangle = |\text{Z}+\text{Z}+...\text{Z}+\rangle

2 # Minimize over \psi:

4 nsteps=50, \gamma=0.1, # \langle \psi | \text{H} | \psi \rangle / \langle \psi | \psi \rangle

5 maxdim=10, cutoff=1e-5)

6 E_{dmrg}, \psi_{dmrg} = \text{dmrg}(\text{H}, \psi_0; # DMRG solves:

8 nsweeps=10, # H | \psi \rangle \approx | \psi \rangle

9 maxdim=10, cutoff=1e-5)
```

# Tutorial: n-site states with MPS [TODO: Add visualization of H]

```
\psi_0 = MPS(i, "Z+")
                                                                \# |0\rangle = |Z+Z+...Z+\rangle
     \psi = \text{minimize}(E, \partial E, \psi_0;
                                                                # Minimize over \psi:
            nsteps=50, \gamma=0.1,
                                                                \# \langle \psi | H | \psi \rangle / \langle \psi | \psi \rangle
            maxdim=10, cutoff=1e-5)
6
     \mathbf{E}_{dmrg}, \, \psi_{dmrg} = \mathrm{dmrg}(\mathbf{H}, \, \psi_0;
                                                                # DMRG solves:
            nsweeps=10,
                                                                \# H|\psi\rangle \approx |\psi\rangle
8
9
            maxdim=10, cutoff=1e-5)
```

```
\begin{array}{lll} & \max (\psi_0) & \# = 1 \text{ (product state)} \\ & \max (\psi) & \# = 3 \text{ (entangled state)} \\ & \max (\psi) & \# = 2 \text{ (entangled state)} \\ & E(\psi_0), \operatorname{norm}(\partial(\psi_0)) & \# \approx (-29, 5.4772256) \\ & E(\psi), \operatorname{norm}(\partial E(\psi)) & \# \approx (-31.0317917, 0.06673780) \\ & E(\psi_{dmrg}), \operatorname{norm}(\partial E(\psi_{dmrg})) & \# \approx (-31.0356110, 0.02413237) \end{array}
```

- 1 Ry\_layer( $\theta$ , i) = [op("Ry", i[j];  $\theta$ = $\theta$ [j]) for j in 1:n]
- 2  $CX_{ij} = [op("CX", i[j], i[j+1])$  for j in 1:2:(n-1)]

```
1 Ry_layer(\theta, i) = [op("Ry", i[j]; \theta=\theta[j]) for j in 1:n]
2 CX_layer(i) = [op("CX", i[j], i[j+1]) for j in 1:2:(n-1)]
```

```
1 function U(\theta, i; nlayers)
2 n = length(i)
3 U_{\theta} = Ry\_layer(\theta[1:n], i)
4 for l in l:(nlayers - 1)
5 \theta_{l} = \theta[(1:n) .+ l * n]
6 U_{\theta} = [U_{\theta}; CX\_layer(i)]
7 U_{\theta} = [U_{\theta}; Ry\_layer(\theta_{l}, i)]
8 end
9 return U_{\theta}
10 end
```

```
1 \psi_0 = \text{MPS}(i, "Z+")

2 \text{nlayers} = 6

3 \text{function E}(\theta)

4 \psi_\theta = \text{apply}(\text{U}(\theta, i; \text{nlayers}), \psi_0)

5 \text{return inner}(\psi_\theta', \text{H}, \psi_\theta)

6 \text{end}

7 \theta_0 = \text{zeros}(\text{nlayers} * \text{n})

9 \theta = \text{minimize}(\text{E}, \partial \text{E}, \theta_0; \text{nsteps} = 20, <math>\gamma = 0.1)
```

```
# |0\rangle = |Z+Z+...Z+\rangle

# Minimize over \theta:

# |\theta\rangle = U(\theta)|0\rangle

# E(\theta) = \langle \theta|H|\theta\rangle
```

```
1 \psi_0 = \text{MPS}(i, "Z+")

2 \text{nlayers} = 6

3 \text{function E}(\theta)

4 \psi_\theta = \text{apply}(\text{U}(\theta, i; \text{nlayers}), \psi_0)

5 \text{return inner}(\psi_\theta', \text{H}, \psi_\theta)

6 \text{end}

7 \theta_0 = \text{zeros}(\text{nlayers} * \text{n})

9 \theta = \text{minimize}(\text{E}, \partial \text{E}, \theta_0; \text{nsteps} = 20, \gamma = 0.1)
```

```
# |0\rangle = |Z+Z+...Z+\rangle

# Minimize over \theta:

# |\theta\rangle = U(\theta)|0\rangle

# E(\theta) = \langle \theta|H|\theta\rangle
```

```
1 \max_{\theta} (\psi_0)

2 \max_{\theta} (\psi_{\theta})

3 E(\theta_0), \text{ norm}(\partial E(\theta_0))

4 E(\theta), \text{ norm}(\partial E(\theta))
```

```
# 1 (product state)
# 2 (entangled state)
# (-29, 5.773335)
# (-31.017062, 0.000759)
```

```
1 \psi_0 = \mathrm{MPS}(\mathrm{i}, \text{"Z+"})

2 \mathrm{nlayers} = 6

3 \mathrm{function} \ \mathrm{F}(\theta)

4 \psi_\theta = \mathrm{apply}(\mathrm{U}(\theta, \mathrm{i}; \mathrm{nlayers}), \psi_0)

5 \mathrm{return} \ -\mathrm{abs}(\mathrm{inner}(\psi', \psi_\theta))^2

6 \mathrm{end}

7 \theta_0 = \mathrm{zeros}(\mathrm{nlayers} * \mathrm{n})

9 \theta = \mathrm{minimize}(\mathrm{F}, \partial \mathrm{F}, \theta_0; \mathrm{nsteps} = 20, \gamma = 0.1)
```

```
# |0\rangle = |Z+Z+...Z+\rangle

# Minimize over \theta:

# F(\theta) = -|\langle \psi | U(\theta) | 0 \rangle|^2

# = -|\langle \psi | \theta \rangle|^2
```

```
1 \psi_0 = \text{MPS}(i, "Z+") #
2 \text{nlayers} = 6
3 \text{function } F(\theta) #
4 \psi_\theta = \text{apply}(U(\theta, i; \text{nlayers}), \psi_0) #
5 \text{return -} abs(inner(\psi', \psi_\theta))^2 #
6 \text{end}
7
8 \theta_0 = \text{zeros}(\text{nlayers} * n)
9 \theta = \minimize(F, \partial F, \theta_0; \\ nsteps=20, \gamma=0.1)
```

```
# |0\rangle = |Z+Z+...Z+\rangle

# Minimize over \theta:

# F(\theta) = -|\langle \psi | U(\theta) | 0 \rangle|^2

# = -|\langle \psi | \theta \rangle|^2
```

```
1 \max \lim \dim(\psi_0)

2 \max \lim \dim(\psi_\theta)

3 F(\theta_0), \operatorname{norm}(\partial F(\theta_0))

4 F(\theta), \operatorname{norm}(\partial F(\theta))
```

```
# 1 (product state)
# 2 (entangled state)
# (-0.556066, 0.895717)
# (-0.995230, 0.048939)
```

▶ More AD, make ITensor fully differentiable (have some work to do, like tensor decompositions and general network contractions, more MPS/MPO functions. You will find bugs!).

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- Many ongoing projects and directions: quantum chemistry (for example UCC), real space parallel DMRG, TDVP, and TEBD, MPO compression tools, general approximate contraction techniques for unstructured networks, contracting and optimizing general tensor networks with AD, infinite MPS and tensor network tools like VUMPS and TDVP, trying out different network topologies for noisy circuit tomography, simulation and optimization.

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