```
//Thirumalainambi
                     Maharaja
//TE-D
//EXP8
//304D074
 #include<p18f4550.h>
 void timerInit(void)
 TOCON = 0b00000111;
 TMROH = OxED;
 TMROL = 0xB0;
 void Interrupt_Init(void)
 IPEN = 1;
 INTCON = 0b11100000;
 TMR0IP = 0;
 }
 void interrupt low_priority timerinterrupt(void) {
 if(TMROIF == 1)
 TMROON = 0;
 TMROIF = 0;
 LATB =~LATB;
 TMROH = OxED;
 TMROL = 0xB0;
 TMROON = 1;
 }
 void main(void)
 TRISB = 0x00;
 LATB = 0xFF;
 Interrupt_Init();
 timerInit();
 TMROON = 1;
 while(1);
 }
```