# $\ensuremath{\mathsf{ELEC\text{-}E8103}}$ - Modelling, Estimation and Dynamic Systems

Assignment 5

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November 21, 2020

#### 1 System 1: model oe323

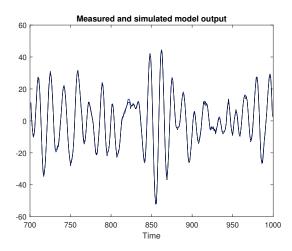


Figure 1: oe323 output

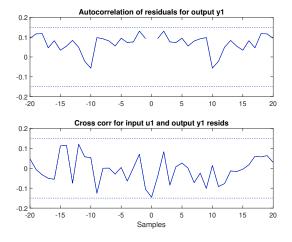


Figure 2: oe323 residual

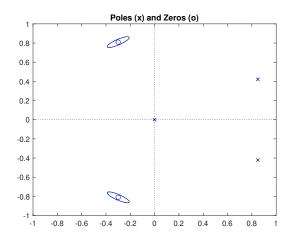


Figure 3: oe323 poles and zeros

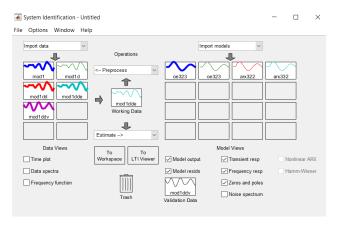


Figure 4: System 1 tried models

```
Discrete-time OE model: y(t) = [B(z)/F(z)]u(t) + e(t)
B(z) = 1.245 z^-3 + 0.7452 z^-4 + 0.9271 z^-5

F(z) = 1 - 1.699 z^-1 + 0.8988 z^-2

Name: oe323
Sample time: 1 seconds
```

Figure 5: oe323 model

#### 2 System 2: model arx224

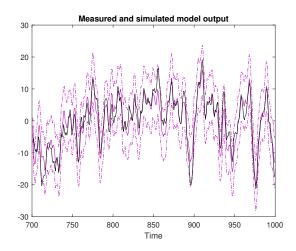


Figure 6: arx224 output

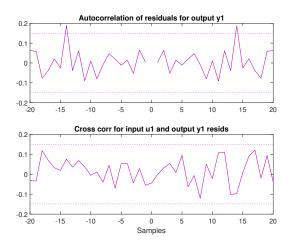


Figure 7: arx224 residual

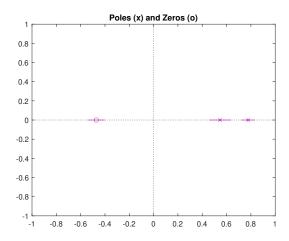


Figure 8: arx224 poles and zeros

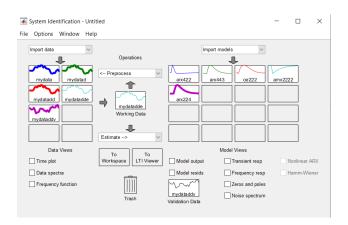


Figure 9: System 2 tried models

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Discrete-time ARX model: A(z)y(t) = B(z)u(t) + e(t)
A(z) = 1 - 1.325 z^-1 + 0.4253 z^-2
B(z) = 1.969 z^-4 + 0.9272 z^-5

Name: arx224
Sample time: 1 seconds
```

Figure 10: arx224 model

## 3 System 3: model armax2222

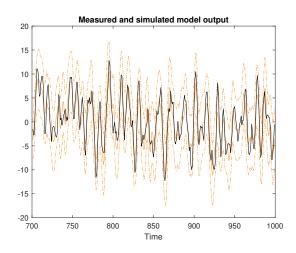


Figure 11: armax2222 output

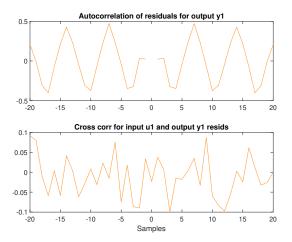


Figure 12: armax2222 residual

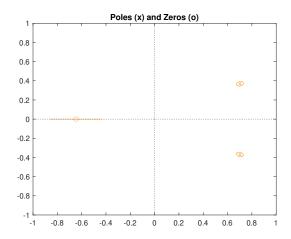


Figure 13: armax22224 poles and zeros

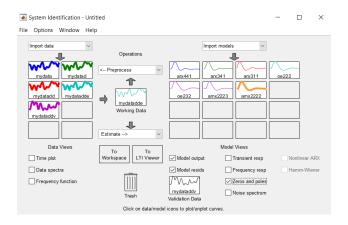


Figure 14: System 3 tried models

```
Discrete-time ARMAX model: A(z)y(t) = B(z)u(t) + C(z)e(t)

A(z) = 1 - 1.404 z^{-1} + 0.6288 z^{-2}

B(z) = 1.049 z^{-2} + 0.6789 z^{-3}

C(z) = 1 - 0.4808 z^{-1} - 0.3721 z^{-2}

Name: amx2222

Sample time: 1 seconds
```

Figure 15: armax2222 model

## 4 System 4: model bj12121

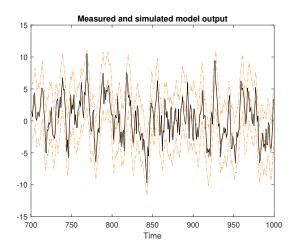


Figure 16: bj12121 output

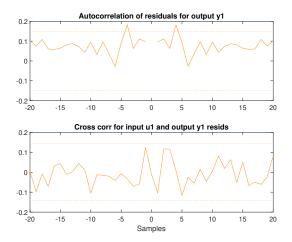


Figure 17: bj12121 residual

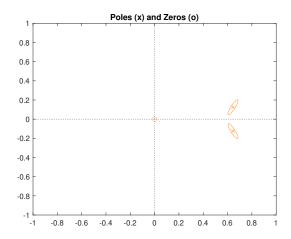


Figure 18: bj12121 poles and zeros

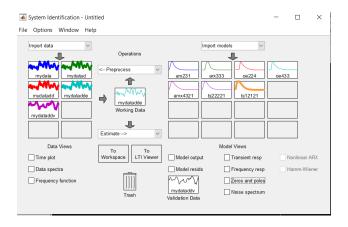


Figure 19: System 4 tried models

```
Discrete-time ARMAX model: A(z)y(t) = B(z)u(t) + C(z)e(t)
A(z) = 1 - 1.404 z^{-1} + 0.6288 z^{-2}
B(z) = 1.049 z^{-2} + 0.6789 z^{-3}
C(z) = 1 - 0.4808 z^{-1} - 0.3721 z^{-2}
Name: amx2222
Sample time: 1 seconds
```

Figure 20: bj12121 model

# 5 System 5: model bj11221

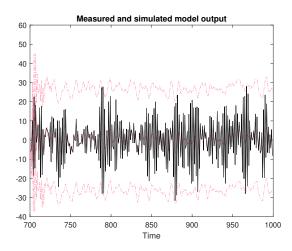


Figure 21: bj11221 output

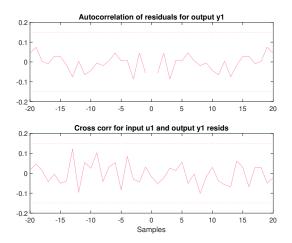


Figure 22: bj11221residual

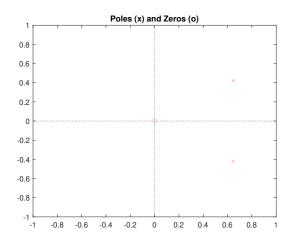


Figure 23: bj11221 poles and zeros

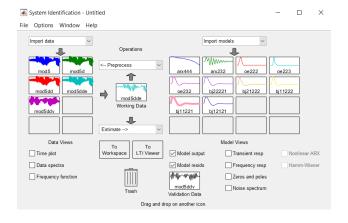


Figure 24: System 5 tried models

```
Discrete-time BJ model: y(t) = [B(z)/F(z)]u(t) + [C(z)/D(z)]e(t)
B(z) = 1.304 z^-1

C(z) = 1 - 0.814 z^-1

D(z) = 1 + 1.681 z^-1 + 0.7842 z^-2

F(z) = 1 - 1.295 z^-1 + 0.5958 z^-2

Name: bj11221
Sample time: 1 seconds
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Figure 25: bj11221 model