

- EM wave as special soln to Maxwell Equations
  - Properties derived from wave nature & polarization
  - Energy of EM waves
- 

### Soln. to Maxwell Equation without sources

In vacuum, there is no charge ( $\rho = 0$ ) or current ( $\vec{J} = 0$ )

$\Rightarrow$  The system of equations become simple.

No need to be solved through converting to  $V/\vec{A}$

### Getting an equation with $\vec{E}$ only

$$\begin{aligned} \nabla \times (\nabla \times \vec{E}) &= \nabla \times \left( -\frac{\partial \vec{B}}{\partial t} \right) && \text{(Take Curl to Faraday's Law)} \\ \xrightarrow{\text{by vector identity}} \nabla(\nabla \cdot \vec{E}) - \nabla^2 \vec{E} &= -\frac{\partial}{\partial t} (\nabla \times \vec{B}) \\ \xrightarrow{\substack{\text{Gauss's Law,} \\ \text{but charge } \rho = 0}} 0 - \nabla^2 \vec{E} &= -\frac{\partial}{\partial t} (0 + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}) && \text{Ampere's Law} \\ &\boxed{\nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}} \end{aligned}$$

### Getting an equation with $\vec{B}$ only

$$\begin{aligned} \xrightarrow{\text{by vector identity}} \nabla \times (\nabla \times \vec{B}) &= \nabla \times \left( 0 + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) && \text{current } \vec{J} = 0 \quad \text{(Take curl to Ampere's Law)} \\ \nabla(\nabla \cdot \vec{B}) - \nabla^2 \vec{B} &= \mu_0 \epsilon_0 \frac{\partial}{\partial t} (\nabla \times \vec{E}) \\ \xrightarrow{\substack{\text{Gauss Law for } B \text{ field} \\ \text{Faraday's Law}}} 0 - \nabla^2 \vec{B} &= \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left( -\frac{\partial \vec{B}}{\partial t} \right) \\ &\boxed{\nabla^2 \vec{B} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2}} \end{aligned}$$

Therefore in vacuum,  $\vec{E}$  &  $\vec{B}$  exist as solutions of a 3D wave equation

i.e. Solution to the equation of the form  $\nabla^2 \varphi = \frac{1}{v^2} \frac{\partial^2 \varphi}{\partial t^2}$

with wave speed  $v = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = c = \text{speed of light}$

(In linear material, we replace by  $\epsilon_0 \rightarrow \epsilon$ ,  $\mu_0 \rightarrow \mu$ )  
and have  $v = \frac{1}{\sqrt{\mu \epsilon}} = \frac{c}{n}$

### Analytical soln. & interpretation

Recall the general soln to 1D wave Eq. looks like

$$\varphi(x, t) = \underbrace{f(x - vt)}_{\substack{\text{wave travelling in} \\ +x \text{ direction}}} + \underbrace{g(x + vt)}_{\substack{\text{wave travelling in} \\ -x \text{ direction}}}$$

In the 3D case, we promote the position  $x$  to vector  $\vec{r}$

$$\varphi(\vec{r}, t) = \underbrace{f(\vec{k} \cdot \vec{r} - \omega t)}_{\substack{\text{wave travelling in} \\ \vec{k} \text{ direction}}} + \underbrace{g(\vec{k} \cdot \vec{r} + \omega t)}_{\substack{\text{wave travelling in} \\ -\vec{k} \text{ direction}}}$$

which  $\vec{k} = (k_x, k_y, k_z)$  and  $\omega$  are parameters that we

are free to choose, as long as  $v = \frac{\omega}{|\vec{k}|}$  is satisfied.

### Review from 1D wave Eq.

Recall in 1D case, we can express the general soln

as a combination of sine & cosine after separating  $x$  &  $t$  part

$$\varphi(x, t) = \sum_{\substack{\text{all } k \text{ allowed} \\ \text{by boundary condition}}} [A_k \cos kvt + B_k \sin kvt] [C_k \cos kx + D_k \sin kx]$$

But it is usually easier to do calculation in the complex exponential form

$$\text{i.e. Make } C_1 e^{i\theta} + C_2 e^{-i\theta} = A \cos \theta + B \sin \theta$$

$$\Rightarrow \begin{cases} C_1 + C_2 = A \\ i(C_1 - C_2) = B \end{cases} \quad \text{or} \quad \begin{cases} C_1 = \frac{A - iB}{2} \\ C_2 = \frac{A + iB}{2} \end{cases}$$

( We will always use exponential form from now on )

So the solution is simplified into

$$\begin{aligned} \psi(x, t) &= \sum_{\text{all allowed } k} [A'_k e^{ikvt} + B'_k e^{-ikvt}] [C'_k e^{ikx} + D'_k e^{-ikx}] \\ &= \sum_{k \pm \pm} C_k e^{i(\pm kx \pm kvt)} \end{aligned}$$

- the terms will be in this form, so we can always start from it.

### Promotion to 3D

The solution to 3D wave equation is similar, except that

there are now 3 spatial parts:

$$\psi(x, y, z, t) = \sum_{\text{all } k_x k_y k_z w} C e^{\pm i k_x x} \cdot e^{\pm i k_y y} \cdot e^{\pm i k_z z} \cdot e^{\pm i w t}$$

with  $\sqrt{k_x^2 + k_y^2 + k_z^2} = \frac{\omega}{v}$  ← try to show this yourself.  
and allowed by boundary condition

$$= \sum_{\vec{k}} C_{\vec{k}} e^{i(\vec{k} \cdot \vec{r} \pm \omega t)}$$

By writing  $\vec{k} = (k_x, k_y, k_z)$  &  $\vec{r} = (x, y, z)$

$$\text{s.t. } \vec{k} \cdot \vec{r} = k_x x + k_y y + k_z z$$

All the terms will be in this form, so we only need to continue

with  $C_{\vec{k}} e^{i(\vec{k} \cdot \vec{r} - \omega t)}$  and generalize the result to all  $\vec{k}$

## $\vec{E}$ & $\vec{B}$ in pairs

Now we have the wave Eq. solution of  $E$  &  $B$  individually

For convenience we only examine the term with  $\vec{k} = (0, 0, k)$

$$\left\{ \begin{array}{l} \vec{E}(\vec{r}, t) = \vec{E}_k e^{i(kz - \omega t)} \\ \vec{B}(\vec{r}, t) = \vec{B}_k e^{i(kz - \omega t)} \end{array} \right.$$

$\vec{E}$  &  $\vec{B}$  are vector field, so the coefficient  $E_k, B_k$  should also be vectors

$$\vec{E}(\vec{r}, t) = \vec{E}_k e^{i(kz - \omega t)} = \begin{pmatrix} E_{k,x} \\ E_{k,y} \\ E_{k,z} \end{pmatrix} e^{i(kz - \omega t)}$$

a vector with 3 constants

$$\vec{B}(\vec{r}, t) = \vec{B}_k e^{i(kz - \omega t)} = \begin{pmatrix} B_{k,x} \\ B_{k,y} \\ B_{k,z} \end{pmatrix} e^{i(kz - \omega t)}$$

a vector with 3 constants

- Gauss Law for  $\vec{E}$  &  $\vec{B}$  :

$$\vec{\nabla} \cdot \vec{E} = \frac{\partial}{\partial x} (E_{k,x} e^{i(kz - \omega t)}) + \frac{\partial}{\partial y} (E_{k,y} e^{i(kz - \omega t)}) + \frac{\partial}{\partial z} (E_{k,z} e^{i(kz - \omega t)})$$

there is no  $x$  inside                            there is no  $y$  inside

$$0 = E_{k,z} \cdot i k e^{i(kz - \omega t)}$$

$\Rightarrow$  require  $E_{k,z} = 0$ . Similarly we also have  $B_{k,z} = 0$

- Faraday's Law (Will get same results from Ampere's Law)

$$\nabla \times \vec{E} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_{k,x} e^{i(kz - \omega t)} & E_{k,y} e^{i(kz - \omega t)} & 0 \end{vmatrix}$$

$$= ik(E_{k,x} \hat{y} - E_{k,y} \hat{x}) e^{i(kz-\omega t)}$$

$$- \frac{\partial \vec{B}}{\partial t} = i\omega(B_{k,x} \hat{x} + B_{k,y} \hat{y}) e^{i(kz-\omega t)}$$

By comparing coefficient, we have

$$\begin{cases} kE_{k,x} = \omega B_{k,y} \\ -kE_{k,y} = \omega B_{k,x} \end{cases}$$

Finally, we find that only 2 of the coefficients are free variables.

$$\vec{E}(\vec{r}, t) = \begin{pmatrix} E_{k,x} \\ E_{k,y} \\ 0 \end{pmatrix} e^{i(kz-\omega t)}, \quad \vec{B}(\vec{r}, t) = \frac{k}{\omega} \begin{pmatrix} -E_{k,y} \\ E_{k,x} \\ 0 \end{pmatrix} e^{i(kz-\omega t)}$$

(In fact, we can check that  $\vec{B} = \frac{k \times \vec{E}}{\omega}$ )

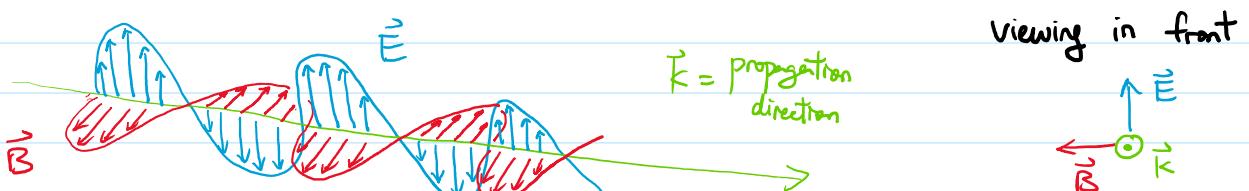
From the solutions we can observe 2 properties :

①  $\vec{E}/\vec{B}/\vec{k}$  are all  $\perp$  to one another

$$(\vec{E} \cdot \vec{k} = \vec{B} \cdot \vec{k} = \vec{E} \cdot \vec{B} = 0)$$

②  $\vec{E}$  &  $\vec{B}$ 's magnitude are related by  $|\vec{B}| = \left| \frac{\vec{k} \times \vec{E}}{\omega} \right| \sim \frac{1}{\nu} |\vec{E}|$

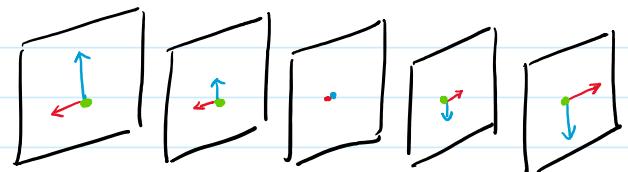
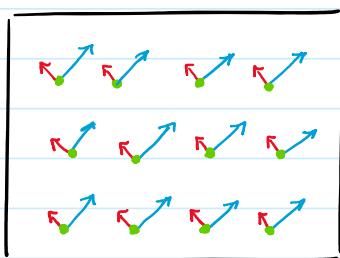
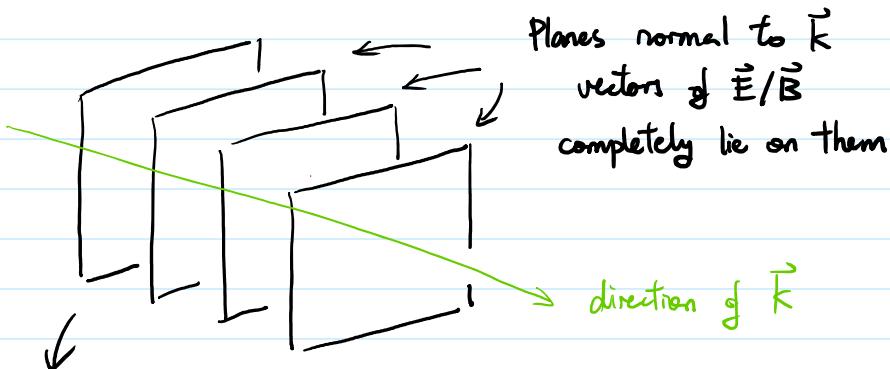
Therefore, a EM wave is usually depicted as follow in textbook



However, this is not entirely accurate because, remember,

$\vec{E}$  and  $\vec{B}$  are a distribution of vectors in space

It is more accurate to visualize by cross sections in the space



On each plane, there is a constant distribution of  $\vec{E}/\vec{B}$

$$\text{with } \vec{E} \perp \vec{B} \text{ & } |\vec{B}| = \left| \frac{\vec{k} \times \vec{E}}{\omega} \right|$$

On consecutive planes, the magnitudes vary sinusoidally

## Polarization

The general solution of  $\vec{E}/\vec{B}$  in vacuum appears with 2 independent coefficients  $E_{k,x}, E_{k,y}$  suggests there to be freedom of polarization

Note that the coefficients can be complex number without

losing any physical meaning, because  $a+bi = \sqrt{a^2+b^2} e^{i \tan^{-1}(b/a)}$

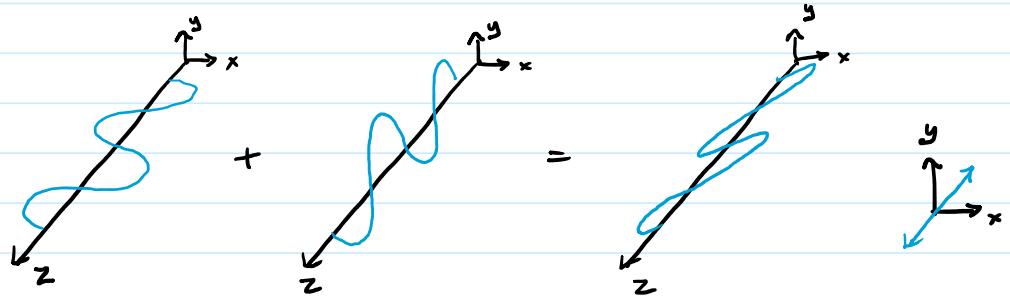
$$\vec{E} = \begin{pmatrix} E_{k,x} \\ E_{k,y} \\ 0 \end{pmatrix} e^{i(kz-wt)} = \begin{pmatrix} |E_{k,x}| e^{i(kz-wt+\phi_x)} \\ |E_{k,y}| e^{i(kz-wt+\phi_y)} \\ 0 \end{pmatrix}$$

The phase difference in the x/y results in different polarization.

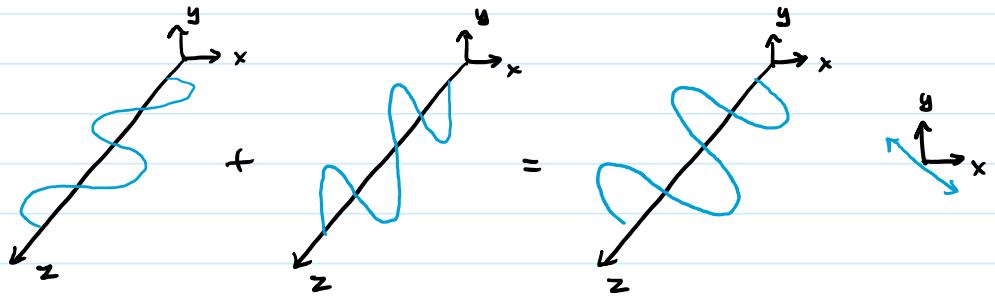
Let  $\phi_x = 0$  so  $\phi_y$  is exactly the phase difference.

Plane polarization :  $\phi_y = 0$  or  $\phi_y = \pi$

$\phi_y = 0$   
In phase

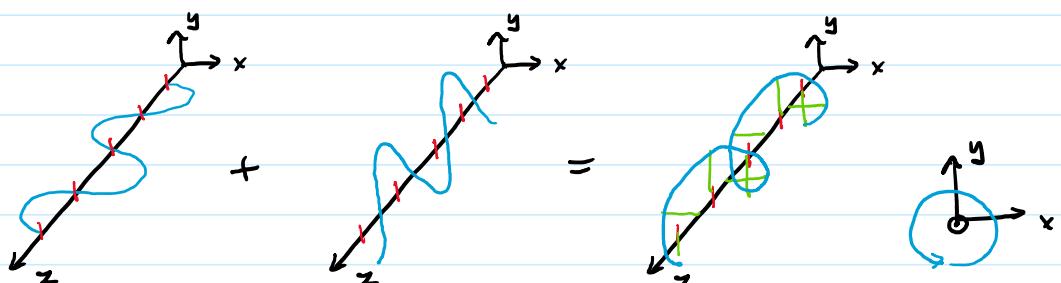


$\phi_y = \pi$   
Out of phase

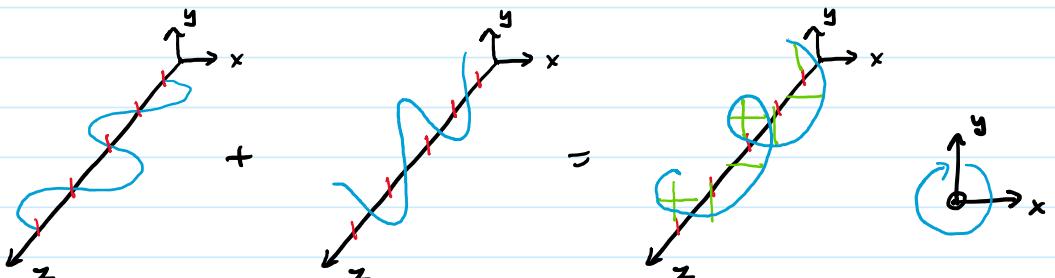


Circular Polarization :  $\phi_y = \pm \frac{\pi}{2}$

$\phi_y = -\frac{\pi}{2}$   
left - circular  
(counter-clockwise)  
from +z

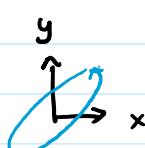


$\phi_y = \frac{\pi}{2}$   
right circular  
(clockwise)  
from +z



For other values of  $\phi_y$ , they are called

elliptic polarization

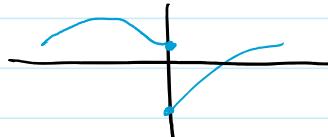


## Boundary Condition

When a wave travel onto the boundary between materials  
the wave needs to satisfy certain constraints

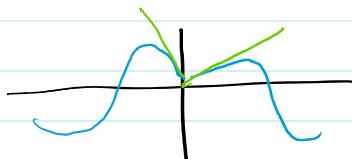
E.g. Constraints on 1D mechanical wave

(1) Amplitude is continuous



or else the string  
is broken

(2) Curve is smooth (i.e. slope is continuous)



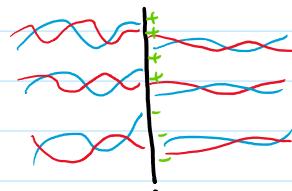
or else tension on both sides  
are unequal  
⇒ momentum not conserved.

Because EM waves are just solutions to the Maxwell's Equations

They should follow the boundary conditions of  $\vec{E}/\vec{B}$ . i.e.

$$\left\{ \begin{array}{l} D_{\perp}^{\text{left}} - D_{\perp}^{\text{right}} = \zeta_f \\ B_{\perp}^{\text{left}} - B_{\perp}^{\text{right}} = 0 \\ E_{\parallel}^{\text{left}} - E_{\parallel}^{\text{right}} = 0 \\ H_{\parallel}^{\text{left}} - H_{\parallel}^{\text{right}} = K_f \end{array} \right.$$

material 1      material 2



↑ may have charge/current  
on the boundary.

But for usages in optics, we normally only consider the case

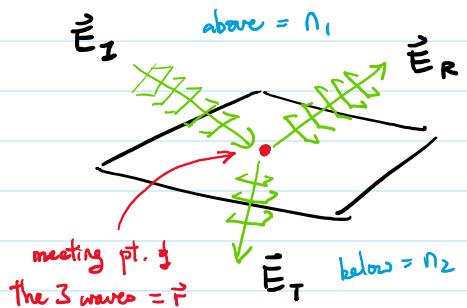
- Materials on both sides are linear
- No charge / current on the boundary

Then the boundary conditions are reduced to :

$$\left\{ \begin{array}{l} \varepsilon_{\text{left}} E_{\perp}^{\text{left}} - \varepsilon_{\text{right}} E_{\perp}^{\text{right}} = 0 \\ B_{\perp}^{\text{left}} - B_{\perp}^{\text{right}} = 0 \\ E_{\parallel}^{\text{left}} - E_{\parallel}^{\text{right}} = 0 \\ \frac{1}{\mu_{\text{left}}} B_{\parallel}^{\text{left}} - \frac{1}{\mu_{\text{right}}} B_{\parallel}^{\text{right}} = 0 \end{array} \right.$$

Now we can start deriving for the 3D case of EM wave

We can identify these 3 waves :



$$\text{Incident wave } \vec{E}_I = \vec{E}_I e^{i(\vec{k}_I \cdot \vec{r} - \omega_I t)}$$

$$\text{Reflected wave } \vec{E}_R = \vec{E}_R e^{i(\vec{k}_R \cdot \vec{r} - \omega_R t)}$$

$$\text{Transmitted wave } \vec{E}_T = \vec{E}_T e^{i(\vec{k}_T \cdot \vec{r} - \omega_T t)}$$

(No need to write  $\vec{B}$  since  $\vec{B} = \frac{\vec{k} \times \vec{E}}{\omega}$  for each wave)

## ① Time & Position symmetry

The waves' relations should be independent of whatever  $\vec{r}, t$  we

choose. Therefore it must require

$$e^{i(\vec{k}_I \cdot \vec{r} - \omega_I t)} = e^{i(\vec{k}_R \cdot \vec{r} - \omega_R t)} = e^{i(\vec{k}_T \cdot \vec{r} - \omega_T t)}$$

(The parts that depend on  $\vec{r}/t$  must equal)

which then lead to the following :

## ② Positional symmetry : free to take $\vec{r} = 0$

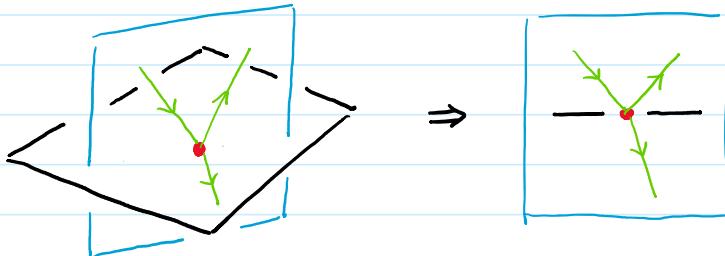
$\Rightarrow \omega_I = \omega_R = \omega_T$  i.e. They must have the same frequency

② Time symmetry : free to take  $t = 0$

$$\Rightarrow \vec{k}_I \cdot \vec{r} = \vec{k}_R \cdot \vec{r} = \vec{k}_T \cdot \vec{r}$$

$$\text{or } (\vec{k}_I - \vec{k}_R) \cdot \vec{r} = (\vec{k}_I - \vec{k}_T) \cdot \vec{r} = 0$$

i.e. The 3 waves must be co-planar



We can draw all 3 waves on 1 plane

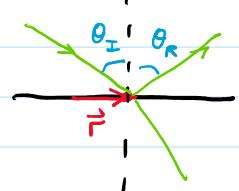
③ Law of reflection

$$\text{By } \vec{k}_I \cdot \vec{r} = \vec{k}_R \cdot \vec{r}$$

$$\Rightarrow |\vec{k}_I| |\vec{r}| \sin \theta_I = |\vec{k}_R| |\vec{r}| \sin \theta_R$$

$$\therefore \omega_I = \omega_R \text{ and } |\vec{k}_I| = \frac{\omega_I}{v} = \frac{\omega_R}{v} = |\vec{k}_R|$$

$$\text{We get } \boxed{\theta_I = \theta_R}$$



④ Law of refraction

$$\text{By } \vec{k}_I \cdot \vec{r} = \vec{k}_T \cdot \vec{r}$$

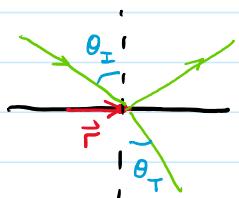
$$\Rightarrow |\vec{k}_I| |\vec{r}| \sin \theta_I = |\vec{k}_T| |\vec{r}| \sin \theta_T$$

$$\therefore \omega_I = \omega_T \text{ and } |\vec{k}_I| = \frac{\omega_I}{v_1} = \frac{n_1 \omega_I}{c}$$

$$|\vec{k}_T| = \frac{\omega_I}{v_2} = \frac{n_2 \omega_I}{c}$$

2 sides are of different materials.

$$\text{We get } \boxed{n_1 \sin \theta_I = n_2 \sin \theta_T}$$

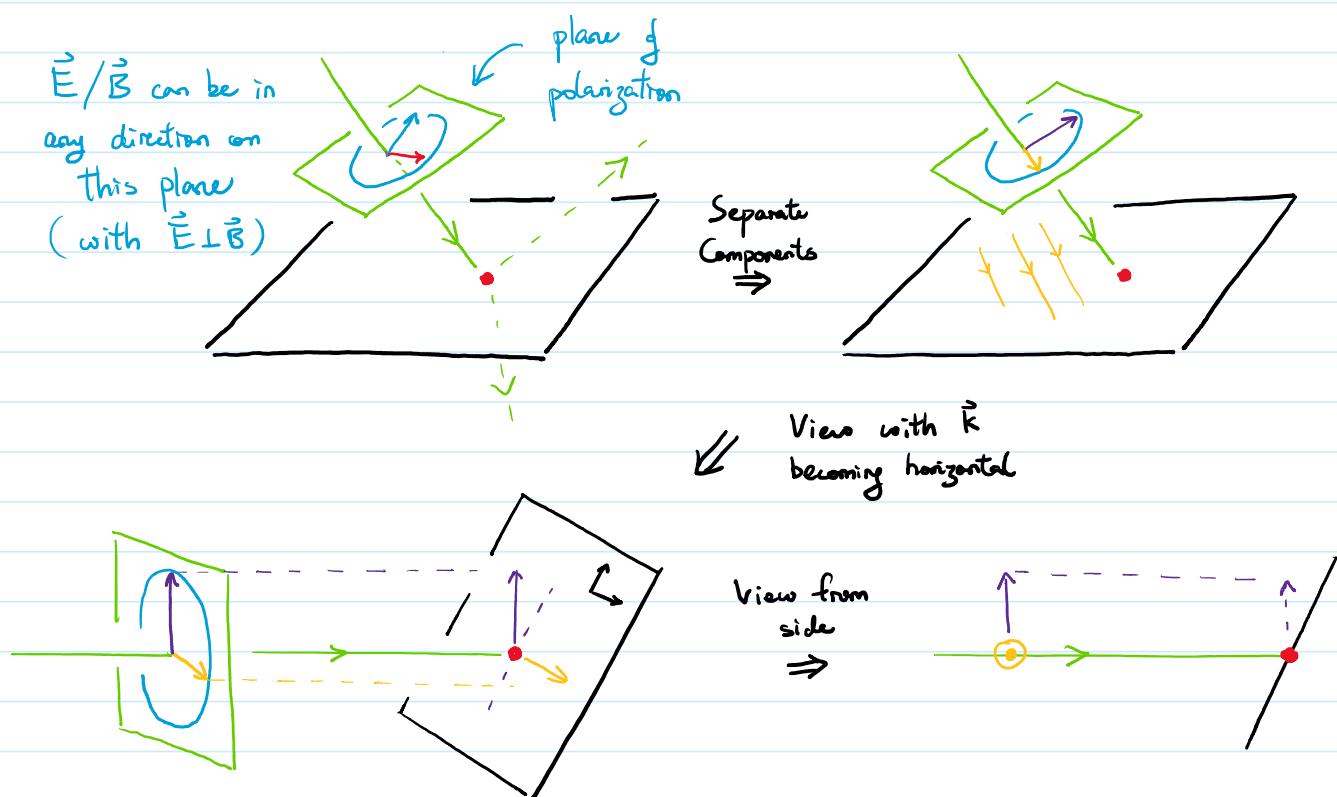


## ② Restriction from $\vec{E}/\vec{B}$ 's properties

After matching the  $e^{(kr-xt)}$  part, we can proceed to matching the amplitudes  $\vec{E}_I$ ,  $\vec{E}_R$  &  $\vec{E}_T$ .

Because they are vectors, we need to match them components by components. But for convenience, we separate the components of  $\vec{E}/\vec{B}$  by :

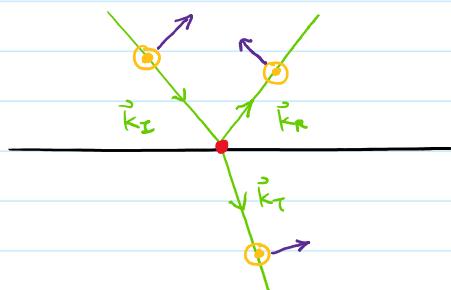
- The component parallel to boundary surface ( $\rightarrow$ )
- The remaining component on the polarization plane ( $\uparrow$ )



We do this to all

$\vec{E}_I$ ,  $\vec{E}_R$ ,  $\vec{E}_T$  and

arrive at this picture

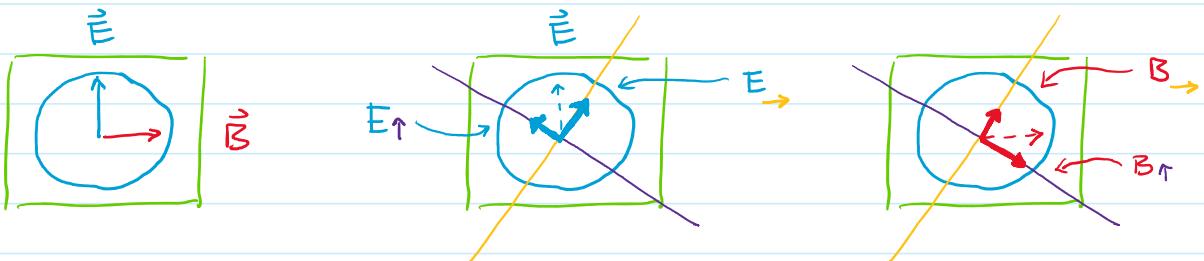


Then on the polarization plane, we can write  $\vec{E}/\vec{B}$  as

$$\left\{ \begin{array}{l} \vec{E} = \vec{E}_{\text{--}} + \vec{E}_{\uparrow} \\ \vec{B} = \vec{B}_{\text{--}} + \vec{B}_{\uparrow} \end{array} \right.$$

And because  $\vec{E} \perp \vec{B}$ , we must have

$$\vec{E}_{\text{--}} \perp \vec{B}_{\uparrow} \quad \& \quad \vec{E}_{\uparrow} \perp \vec{B}_{\text{--}}$$



Finally we can discuss the 2 special cases :

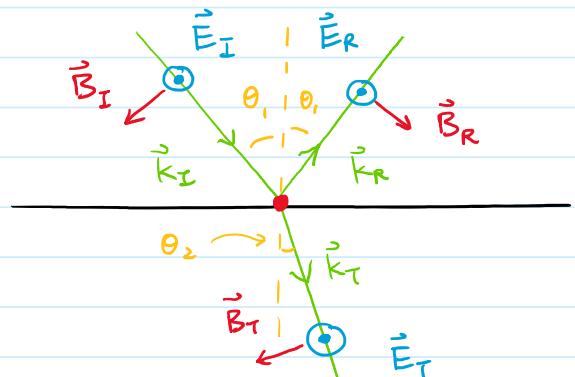
$$\left\{ \begin{array}{l} \text{TE mode} = \text{Transverse Electric, i.e. } \vec{E} = \vec{E}_{\text{--}} \text{ only} \\ \quad (\text{And so by } \vec{E} \perp \vec{B}, \vec{B} = \vec{B}_{\uparrow} \text{ only}) \\ \\ \text{TM mode} = \text{Transverse Magnetic, i.e. } \vec{B} = \vec{B}_{\text{--}} \text{ only} \\ \quad (\text{And so by } \vec{E} \perp \vec{B}, \vec{E} = \vec{E}_{\uparrow} \text{ only}) \end{array} \right.$$

## II TE mode

let  $\vec{E}_I, \vec{E}_R, \vec{E}_T$  all

be pointing out of paper

then get direction of  $\vec{B}$  by  $\vec{k} \times \vec{E}$



The boundary conditions due to Maxwell Equations write as

$$\varepsilon_1 E_{\perp}^{(1)} - \varepsilon_2 E_{\perp}^{(2)} = 0$$

$O = O \because$  no  $E$  field  $\perp$  boundary surface

$$B_{\perp}^{(1)} - B_{\perp}^{(2)} = 0$$

$$B_I \sin \theta_1 + B_R \sin \theta_1 - B_T \sin \theta_2 = 0$$

$$E_{||}^{(1)} - E_{||}^{(2)} = 0$$



$$E_I + E_R - E_T = 0$$

$$\frac{1}{\mu_1} B_{||}^{(1)} - \frac{1}{\mu_2} B_{||}^{(2)} = 0$$

$$\frac{1}{\mu_1} [B_I \cos \theta_1 - B_R \cos \theta_1] - \frac{1}{\mu_2} B_T \cos \theta_2 = 0 \quad (\star)$$

The 2 equations with  $(\star)$ , together with  $|B| = \frac{|E|}{\omega} = \frac{n}{c} |\vec{E}|$

is enough to solve the relationship between  $\vec{E}_I, \vec{E}_R, \vec{E}_T$

$$|\vec{E}_R| = \frac{\cos \theta_1 - \beta \cos \theta_2}{\cos \theta_1 + \beta \cos \theta_2} |\vec{E}_I|$$

(where  $\beta = \frac{n_2}{n_1} \cdot \frac{\mu_1}{\mu_2}$ )

$$|\vec{E}_T| = \frac{2 \cos \theta_1}{\cos \theta_1 + \beta \cos \theta_2} |\vec{E}_I|$$

These 2 relations are called "Fresnel Equation in TE mode"

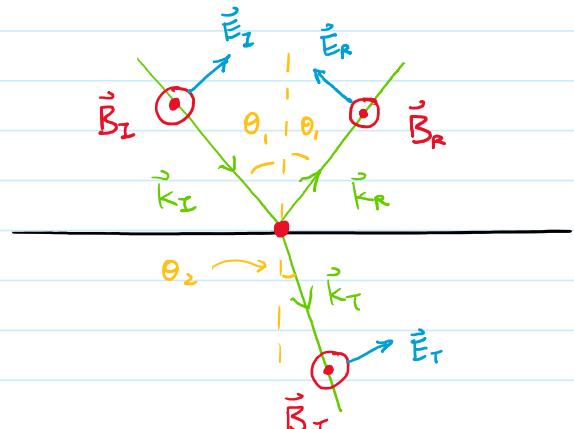
(Caution! : Most textbooks, including wiki, only write  $\beta = \frac{n_2}{n_1}$ )  
because  $\mu \approx \mu_0$  for most common materials

### ③ TM mode

let  $\vec{B}_I, \vec{B}_R, \vec{B}_T$  all

be pointing out of paper

then get direction of  $\vec{E}$  by  $\vec{B} \times \vec{k}$



The boundary conditions due to Maxwell Equations write as

$$\begin{aligned} \varepsilon_1 E_{\perp}^{(1)} - \varepsilon_2 E_{\perp}^{(2)} &= 0 & \varepsilon_1 [E_I \sin \theta_1 + E_R \sin \theta_1] - \varepsilon_2 E_T \sin \theta_2 &= 0 \\ B_{\perp}^{(1)} - B_{\perp}^{(2)} &= 0 & 0 = 0 \because \text{no } B \text{ field } \perp \text{ boundary surface} \\ E_{||}^{(1)} - E_{||}^{(2)} &= 0 & E_I \cos \theta_1 - E_R \cos \theta_1 &= E_T \cos \theta_2 \quad (\star) \\ \frac{1}{\mu_1} B_{||}^{(1)} - \frac{1}{\mu_2} B_{||}^{(2)} &= 0 & \frac{1}{\mu_1} [B_I + B_R] - \frac{1}{\mu_2} B_T &= 0 \quad (\star) \end{aligned}$$

The 2 equations with  $(\star)$ , together with  $|B| = \frac{|k| |\vec{E}|}{\omega} = \frac{n}{c} |\vec{E}|$

we can find the relationship between  $\vec{E}_I, \vec{E}_R, \vec{E}_T$

$$\begin{aligned} |\vec{E}_R| &= \frac{\beta \cos \theta_1 - \cos \theta_2}{\beta \cos \theta_1 + \cos \theta_2} |\vec{E}_I| & \left( \text{where } \beta = \frac{n_2}{n_1} \frac{\mu_1}{\mu_2} \right) \\ |\vec{E}_T| &= \frac{2 \cos \theta_1}{\beta \cos \theta_1 + \cos \theta_2} |\vec{E}_I| \end{aligned}$$

These 2 relations are called "Fresnel Equation in TM mode"

(Caution 2 : TE & TM formulae are very similar but actually different)

## 2 Special Angles

### ① Critical Angle

This phenomenon appears due to law of refraction

$\Rightarrow$  Occur in all waves

From  $n_1 \sin \theta_1 = n_2 \sin \theta_2$ , what is happening to the transmitted

wave when  $\frac{n_1}{n_2} \sin \theta_1 = \sin \theta_2 > 1$  ?

This is totally fine if  $\theta_2 = a+ib$  is a complex no.

$$\text{By } e^{i\theta_2} = e^{i(a+ib)} = e^{-b} e^{ia}$$

$$= e^{-b} (\cos a + i \sin a) = \cos \theta_2 + i \sin \theta_2$$

$$\Rightarrow \text{If } e^{-b} > 1, \sin \theta_2 = e^{-b} \sin a > 1$$

So in the transmitted wave

$$\vec{k}_T \cdot \vec{r} = k_T^{(x)} \sin \theta_2 \cdot x + k_T^{(y)} \cos \theta_2 \cdot y$$

Angle is complex  $\leftarrow$

so we cannot use

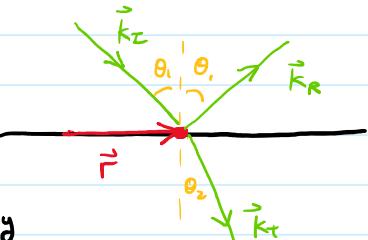
$$a \cdot b = |a||b| \cos \theta$$

$$= k_T^{(x)} \underbrace{\sin \theta_2 \cdot x}_{\text{real no.} > 1} + k_T^{(y)} \underbrace{(\sqrt{1 - \sin^2 \theta_2}) \cdot y}_{\text{complex no.}}$$

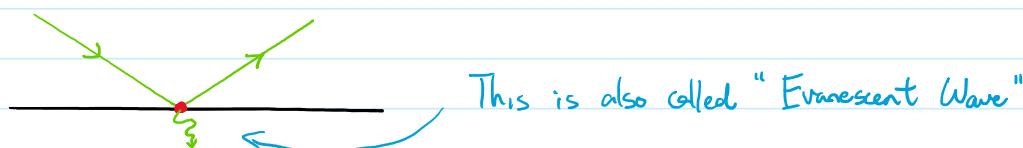
$$= k_T^{(x)} \cdot p \cdot x + k_T^{(y)} \cdot i g \cdot y$$

$$\vec{E}_T e^{i(\vec{k} \cdot \vec{r} - wt)} = \vec{E}_i e^{i(k_T^{(x)} p x - wt)} \cdot e^{-(k_T^{(y)} g y)}$$

*Sinusoidal wave*      *Decaying amplitude*



Therefore in total internal reflection, the transmitted wave does go through, but only decay very fast such that it is barely visible.



## ② Brewster Angle

This appear only due to the E/B boundary condition

$\Rightarrow$  Can only be found in light

The reflected wave's amplitude in TM mode is

$$|\vec{E}_R| = \frac{\beta \cos\theta_1 - \cos\theta_2}{\beta \cos\theta_1 + \cos\theta_2} |\vec{E}_I| \quad (\beta = \frac{n_2 \mu_1}{n_1 \mu_2})$$

Note that  $|\vec{E}_R| = 0$  when  $\beta \cos\theta_1 - \cos\theta_2 = 0$

Then by substituting Snell's Law  $\sin\theta_1 = n \sin\theta_2$

$$1 = \sin^2\theta_2 + \cos^2\theta_2 = \left(\frac{1}{n} \sin\theta_1\right)^2 + (\beta \cos\theta_1)^2$$

$$n^2 \sec^2\theta_1 = \tan^2\theta_1 + n^2 \beta^2$$

$$n^2 (\tan^2\theta_1 + 1) = \tan^2\theta_1 + n^2 \beta^2$$

$$\tan\theta_1 = \pm n \sqrt{\frac{\beta^2 - 1}{n^2 - 1}} \quad \begin{array}{l} \text{(Most textbook only} \\ \text{write } \tan\theta_1 = n \text{ by} \\ \text{taking } \mu_1 = \mu_2 = \mu_0 \end{array}$$

While this does not happen to the reflected wave in TE mode

$$|\vec{E}_R| = \frac{\cos\theta_1 - \beta \cos\theta_2}{\cos\theta_1 + \beta \cos\theta_2} |\vec{E}_I| \quad (\beta = \frac{n_2 \mu_1}{n_1 \mu_2})$$

Requiring  $\cos\theta_1 = \beta \cos\theta_2$  &  $\sin\theta_1 = n \sin\theta_2$  implies

$$1 = \cos^2\theta_1 + \sin^2\theta_1 = \beta^2 \cos^2\theta_2 + n^2 \sin^2\theta_2$$

$$\Rightarrow \tan\theta_1 = \pm \frac{\beta}{n} \sqrt{\frac{1 - \beta^2}{n^2 - 1}}$$

But if Brewster angle to exist in TM mode, require  $\beta^2 - 1 > 0$

$\therefore$  At the incident angle  $\theta_1 = \tan^{-1}\left(n \sqrt{\frac{\beta^2 - 1}{n^2 - 1}}\right)$ , there is no TM polarization reflected back from the boundary surface.

$\Rightarrow$  The reflected wave is purely of TE polarization.

We can use this to create polarized light source.

## Energy of EM Wave

Recall that energy of  $E/B \propto (\text{magnitude})^2 \left( \frac{1}{2} \epsilon E^2 + \frac{1}{2\mu} B^2 \right)$

The energy density carried by a light beam is therefore

$$\begin{aligned}
 U &= \frac{1}{2} \epsilon \left| \vec{E} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right|^2 + \frac{1}{2\mu} \left| \vec{B} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \right|^2 \\
 &= \frac{1}{2} \epsilon |\vec{E}|^2 + \frac{1}{2\mu} \left| \frac{\vec{k} \times \vec{E}}{\omega} \right|^2 \\
 &= \frac{1}{2} \epsilon |\vec{E}|^2 + \frac{1}{2\mu} \left( \frac{k}{\omega} \right)^2 |\vec{E}|^2 \quad \begin{matrix} \vec{k} \text{ always } \perp \vec{E} \\ \text{so can take out as factor} \end{matrix} \\
 &= \epsilon |\vec{E}|^2 \quad \begin{matrix} \frac{k}{\omega} = \frac{n}{c} = \sqrt{\mu\epsilon} \end{matrix}
 \end{aligned}$$

It is also common to see people taking time average and write

$$U_{\text{Avg}} = \frac{1}{2} \epsilon |\vec{E}|^2, \quad \text{with } \frac{1}{2} \text{ because } \frac{1}{T} \int_0^T \sin^2 \left( \frac{2\pi t}{T} \right) dt = \frac{1}{2}$$

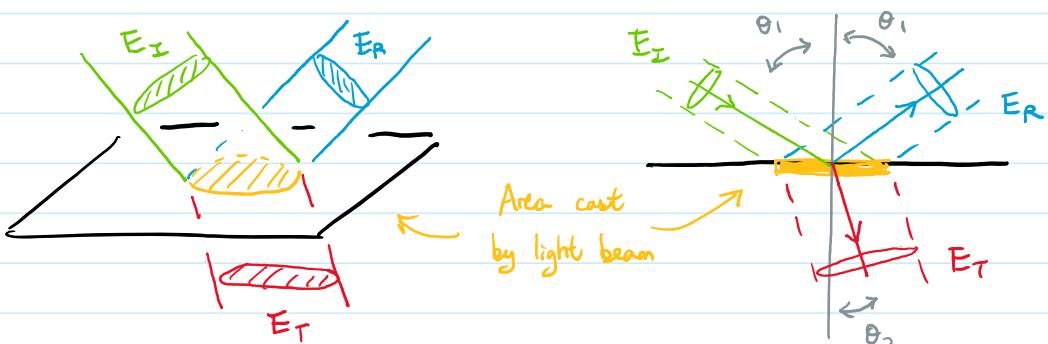
## Energy Flux in Reflection/Transmission

The Poynting vector of EM wave is calculated as

$$\vec{S} = \frac{1}{\mu} \vec{E} \times \vec{B} = \frac{1}{\mu} \vec{E} \times \left( \frac{\vec{k} \times \vec{E}}{\omega} \right) = \frac{1}{\mu} \frac{n}{c} |\vec{E}|^2 = \frac{\epsilon}{\mu} |\vec{E}|^2$$

Remind that Poynting vector is the "flux" of energy

So we also need to take of the area



Thus if no energy accumulate on the area, we must have

$$\vec{S}_I \cdot A \cos\theta_1 = \vec{S}_R \cdot A \cos\theta_1 + \vec{S}_T \cdot A \cos\theta_2$$

(in flux)    (out flux)

$$\int \frac{\epsilon_1}{\mu_1} |E_I|^2 \cos\theta_1 = \int \frac{\epsilon_1}{\mu_1} |E_R|^2 \cos\theta_1 + \int \frac{\epsilon_2}{\mu_2} |E_T|^2 \cos\theta_2$$

One can easily prove that this is true for both TE & TM mode.

Also it is common to see the following definition

Reflection Coefficient :  $R = \frac{|E_R|^2}{|E_I|^2}$

(Different for TE/TM)

Transmission Coefficient :  $T = \sqrt{\frac{\epsilon_2}{\epsilon_1} \frac{\mu_1}{\mu_2}} \frac{\cos\theta_2}{\cos\theta_1} \frac{|E_T|^2}{|E_I|^2}$

(Different for TE/TM)

So that energy conservation implies  $R + T = 1$