

Attention mechanisms in deep neural networks

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1 Original attention mechanism and its variants

Essentially, the attention mechanism is a way to find an answer to a query. The query in this problem is a vector of real numbers, while the answer is a linear re-combination of values produced by encoding an input sequence. The attention mechanism is supposed to find the *best* linear re-combination for a given query.

- Query: $q \in \mathbb{R}^{d_q}$
- Keys: $K \in \mathbb{R}^{T \times d_k}$
- Values: $V \in \mathbb{R}^{T \times d_v}$

Where T is the time dimension (variable over different input instances), and $d_{|\cdot|}$ are the dimensions of respective embeddings. Keys and values are mapped one-to-one.

We define the *energy* as a result of a function f mapping from a key and query onto \mathbb{R} .

$$e_i = f(q, k_i)$$

The energy values are then normalized with a softmax function to produce a probability distribution over all keys

$$a_i = \text{softmax}(e_i)$$

We then use these values as the coefficients of a linear combination over the values

$$att = \sum_i a_i h_i$$

1.1 Usage

Initially (Bahdanau, Cho, and Bengio 2014), the attention mechanism was introduced in a machine translation (sequence to sequence) problem to mitigate the problem of learning long dependencies. After a RNN encoder encoded the input sequence into a sequence of hidden states, we use the current decoder state as the query and the encoder hidden states as both the keys and the values.

Essentially, we find relevant information for the word we are currently translating in the encoded input sequence. For this to work, it is essential that the embedding spaces of the input and output vocabularies are somewhat aligned (similar words in languages should be close together).

Other examples of usage include self-attention and multi-head attention, referenced in a later chapter.

1.2 Variants

1.2.1 MLP attention

(Bahdanau, Cho, and Bengio 2014) f is *parametrized* by a feed-forward neural network (multi-layer perceptron)

$$a_i(q, k) = w_2^T \tanh(W_1[q; k_i])$$

- $[q; k]$ are the concatenated query and key
- W_1 is a linear operator
- w_2 is a parameter vector

1.2.2 Bilinear attention

(Luong, Pham, and Manning 2015)

f is parametrized by a matrix $W \in \mathbb{R}^{d_q \times d_k}$ (a bilinear operator)

$$a(q, k) = q^T W k$$

1.2.3 Dot product attention

(Luong, Pham, and Manning 2015)

f is *parameter-free*, however d_q **must** be equal to d_k .

$$a(q, k) = q^T \cdot k$$

2 Extensions

2.1 Self-attention (inter-attention)

(Cheng, Dong, and Lapata 2016) : The LSTMN model “uses attention to induce relations between tokens”

Idea: use attention over previous LSTM states (keys, values) with the current LSTM state as the query.

$$a_i^{(t)} = v^T \tanh(W_h h_i + W_x x^{(t)} + W_{\hat{h}} \hat{h}^{(t-1)})$$
$$s_i^{(t)} = \text{softmax}(a_i^{(t)})$$

Where x^t is the current input, $\hat{h}^{(t-1)}$ the hidden state in the **previous timestep**, v a parameter vector and h_i the previous hidden states ($i < t - 1$).

Note: only the hidden state h is used in the computation, and not the cell state c !

Then the state vectors (c, h) are updated:

$$\begin{bmatrix} \hat{h}^t \\ \hat{c}^t \end{bmatrix} = \sum_{i=1}^{t-1} s_i^{(t)} \begin{bmatrix} h_i \\ c_i \end{bmatrix} \quad (1)$$

and then replace the un-altered state vectors in further LSTM computations.

Attention fusion: how to use self-attention in a sequence-to-sequence task where a decoder network, along with using self-attention, queries the encoder network (intra-attention).

- **Shallow attention fusion** treats the LSTMN model as a standard LSTM and uses intra-attention on top of it.
- **Deep attention fusion** adds an additional gating mechanism into the LSTM cell update based on intra-attention. Formula in chapter 4 of paper.

2.2 A structured self-attentive sentence embedding

(Lin et al. 2017)

1. Run embedded sentence through BiLSTM
2. Self-attention over the BiLSTM hidden states
3. Use a MLP for a downstream task

Attention:

- (1) a MLP attention with a tanh hidden layer as in (1.2.1)

- (2) *Matrix attention* – the second weight of the attention MLP is a matrix instead of a vector, resulting in a matrix aggregation instead of a vector

$$A = \text{softmax}(W_2 \tanh(W_1 H^T))$$

Where the softmax is applied along the second dimension of the input. The MLP has no bias! The matrix A is then multiplied with the matrix of hidden states (of dim $T \times H$), resulting in a sentence embedding matrix $M = AH$

We expect (hope) that the sentence embedding matrix will capture different aspects, however this is not necessary the case since the matrix M can “*suffer from redundancy problems*”. The authors attempt to mitigate this by introducing a regularization penalty term P .

$$P = \|(AA^T - I)\|_F^2$$

Intermezzo: Frobenius norm:

The Frobenius or Hilbert-Schmidt norm of the matrix A is defined as:

$$\begin{aligned} \|A\|_F &= \sqrt{\sum_i^m \sum_j^n |a_{ij}|^2} \\ &= \sqrt{\text{trace}(A^T A)} \\ &= \sqrt{\sum_i^{\min\{m,n\}} \sigma_i^2(A)} \end{aligned} \tag{2}$$

where σ_i is a singular value of A .

Effect of regularization:

The matrix A is row-normalized (each out of r rows should focus on one aspect), and each row represents one module of attention. The matrix AA^T contains the dot products of \mathbf{a}_i and \mathbf{a}_j on the location i, j . Obviously, the matrix AA^T is a square matrix with diagonal elements equal to one (since $i = j$), therefore the subtraction of the identity matrix.

The remainder of the dot products can be seen as a measure of similarity between two discrete probability distributions over the same discrete space (the input sequence). The dot product of the pdfs produces a number between 0 and 1, 0 meaning the distributions are completely different, and 1 meaning they are

equal. Therefore, the larger the overlap between the distributions, the higher the penalty is going to be.

Experiments: Yelp dataset, Age dataset, SNLI (* SNLI model described)

2.3 Incorporating Structural Alignment Biases into an Attentional Neural Translation Model

(Cohn et al. 2016)

Fertility: each instance of source word is translated to a consistent number of tokens in the target language (IBM Models 3, 4, 5)

Absolute positional bias: word order is similar in source and target

Relative position bias, alignment consistency.

Note: Good description of attention in NMT.

Attention used: MLP attention (1.2.1), but with different notation

$$f_{ji} = \mathbf{v}^T \tanh(W^{ae} \mathbf{e}_i + W^{ah} g_{j-1})$$

Where f_{ji} is the **energy** (before) between g_{j-1} , the target hidden state and e_i , the source encoding. The MLP has size A , and the dimensions of the parameters are: $W^{ae} \in \mathbb{R}^{A \times 2h}$, $W^{ah} \in \mathbb{R}^{A \times h}$ (decoder is unidirectional) and $\mathbf{v} \in \mathbb{R}^A$.

Standard attention follows:

$$\alpha_j = \text{softmax}(\mathbf{f}_j)$$

$$c_j = \sum_i \alpha_{ji} \mathbf{e}_i$$

Incorporating position bias:

a word at a relative position in the source aligns to a similar relative position at the target (A: obviously dependent on language pairs): $\frac{i}{I} \approx \frac{j}{J}$ (Dyer, Chahuneau, and Smith 2013).

$$f_{ji} = \mathbf{v}^T \tanh(W^{ae} \mathbf{e}_i + W^{ah} g_{j-1} + \underbrace{W^{ap} \psi_{j,i,I}}_{\text{pos bias}})$$

$$\psi_{j,i,I} = [\log(1+j), \log(1+i), \log(1+I)]$$

where, obviously, $W^{ap} \in \mathbb{R}^{A \times 3}$

- Target length J is excluded as it is unknown during encoding.
- $\log 1p$ “*avoids numerical instabilities*”

Incorporating Markov condition:

Add another parameter to the already known MLP attention equation:

$$f_{ji} = \mathbf{v}^T \tanh(W^{ae} \mathbf{e}_i + W^{ah} g_{j-1} + W^{ap} \psi_{j,i,I} + \underbrace{W^{am} \xi(\alpha_{j-1}; i)}_{\text{markov param}})$$

Where α_{j-1} is the **previous** attention vector. Since the length of that vector is dynamic (and therefore can't be fit by a single parameter matrix), the authors restrict themselves to using only local offset by $\pm k$ positions:

$$\xi(\alpha_{j-1}; i) = [\alpha_{j-1, i-k}, \dots, \alpha_{j-1, i}, \dots, \alpha_{j-1, i+k}]$$

where, $W^{am} \in \mathbb{R}^{A \times (2k+1)}$

Fertility:

- the propensity for a word to be translated as a consistent number of words in the other language

Bidirectional translation:

Idea: attention should be roughly similar in forward and backward directions – train so that there's a bonus for the trace of the product of attention matrices (which is bounded above by $\min(I, J)$ and ≥ 0)

$$B = -\text{tr}(A_{X \rightarrow Y}^T A_{Y \rightarrow X})$$

the total loss is then the sum of two unidirectional translations reduced by the attentional bonus:

$$\mathbb{L} = -\log p(\mathbf{t}|\mathbf{s}) - \log p(\mathbf{s}|\mathbf{t}) + \gamma B$$

2.4 Attention is off-by-one

Six Challenges for Neural Machine Translation, chapter 3.5 (Koehn and Knowles 2017)

Challenge 5. *The attention model for NMT does not always fulfill the role of a word alignment model, but may in fact dramatically diverge.*

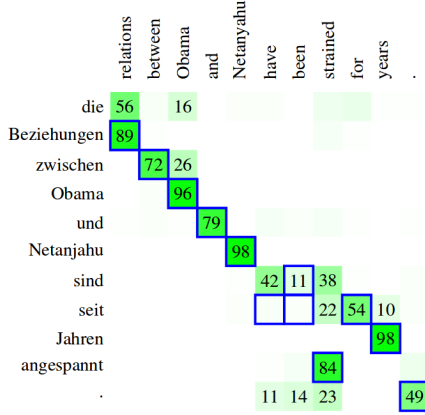


Figure 8: Word alignment for English–German: comparing the attention model states (green boxes with probability in percent if over 10) with alignments obtained from fast-align (blue outlines).

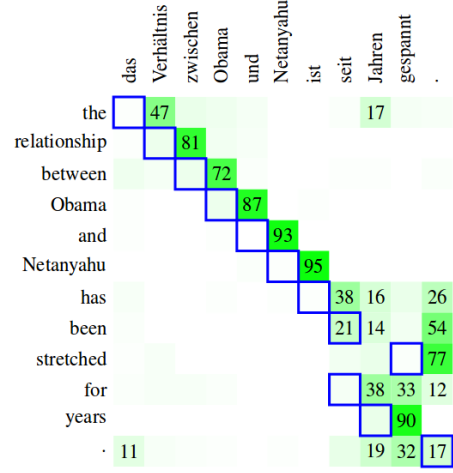


Figure 9: Mismatch between attention states and desired word alignments (German–English).

However, as mentioned in the paper, this **misalignment is an outlier unique to German–English** translation to a larger scale and to a lesser scale otherwise.

2.5 Hard attention

Show, Attend and Tell: Neural Image Caption Generation with Visual Attention, chapters 3 and 4 (Xu et al. 2015)

Add a parameter $Z_{|\cdot|}\hat{z}_t$ to the standard LSTM formulation which is a dynamic representation of the relevant part of the image input at timestep t .

LSTM Reformulation

$$a_{|\cdot|} = \sigma(W_{|\cdot|}y_{t-1} + U_{|\cdot|}h_{t-1} + Z_{|\cdot|}\hat{z}_t)$$

$$f, i, \hat{c}, o = a_{|\cdot|}(y_{t-1}, h_{t-1}, \hat{z}_t)$$

$$c_t = f_t \odot c_{t-1} + i_t \odot \hat{c}_t$$

$$h_t = o_t \odot \tanh(c_t)$$

\hat{z}_t is computed via an attention mechanism from a set of *annotation vectors* $a_1, \dots, a_L, a_i \in \mathbb{R}^D$ obtained as a result of a CNN embedding different regions of the input image. y_t are the output words which constitute a caption.

Computing attention

At each timestep of generating the output caption, we attend to a certain region of the image a_i .

$$\begin{aligned}
e_{ti} &= f_{att}(a_i, h_{t-1}) \\
\alpha_{ti} &= \text{softmax}(e_{ti}) \\
\hat{z}_t &= \phi(\{\mathbf{a}_i\}, \{\alpha_i\})
\end{aligned}$$

e.g. in classic attention, ϕ is a linear combination.

Note: LSTM cell states are initialized to an average of the annotation vectors, passed through two MLPs (one for c_0 , one for h_0)

Note: when generating the next word, instead of a classifier on top of the output state, a deep output layer (Pascanu et al. 2013) is used as follows:

$$p(y_t|a, y_t^{t-1}) \propto \exp(L_o(Ey_{t-1} + L_h h_t + L_z \hat{z}_t))$$

Learning hard attention

When the probabilities for attention over each region $\{\alpha_i^n\}$ are computed, sample a concrete location \hat{s}_t^n to focus on from a Multinoulli distribution parametrized by α .

$$\hat{s}_t^n \sim \text{Multinoulli}_L(\{\alpha_i^n\})$$

and use the REINFORCE (Williams 1992) learning rule to estimate the gradient. This results in the following gradient estimate:

$$\frac{\partial \mathbb{L}}{\partial W} \approx \frac{1}{N} \sum_{n=1}^N \left[\frac{\partial \log p(y|\hat{s}^n, a)}{\partial W} + \log p(y|\hat{s}^n, a) \frac{\partial \log p(\hat{s}^n|a)}{\partial W} \right]$$

Since the REINFORCE rule produces gradient estimates with high variance, a number of techniques are used to reduce the variance, such as Baselines (Weaver and Tao 2001) which uses a moving average of previously seen log likelihoods:

$$b_k = 0.9 \times b_{k-1} + 0.1 \times \log p(y|\hat{s}_k, a)$$

another technique to further reduce the estimator variance is adding the gradient of the entropy $E[\cdot]$ of the Multinoulli distribution to the REINFORCE loss expression, resulting in:

$$\frac{\partial \mathbb{L}}{\partial W} \approx \frac{1}{N} \sum_{n=1}^N \left[\frac{\partial \log p(y|\hat{s}^n, a)}{\partial W} + \underbrace{\lambda_r \log p(y|\hat{s}^n, a) \frac{\partial \log p(\hat{s}^n|a)}{\partial W}}_{\text{reinforce contribution}} + \underbrace{\lambda_e \frac{\partial H[\hat{s}^n]}{\partial W}}_{\text{entropy contribution}} \right]$$

λ_r and λ_e are learned by cross-validation.

another improvement to robustness of this training rule is that with $p = 0.5$, for a given image, the sampled location \hat{s} is set to the expected value α (equivalent to deterministic attention).

2.6 Dynamic coattention networks for QA

(Xiong, Zhong, and Socher 2016)

LSTM encoder (one!) for document and question Additional non-linear layer on top of question encoding

– Sentinel vectors! (Merity et al. 2016) added to end of each encoded sequence

$$d_t = LSTM_{enc}(d_{t-1}, x_t^D)$$

$$q_t = LSTM_{enc}(q_{t-1}, x_t^Q)$$

$$Q = \tanh(W^{(Q)}Q' + b^{(Q)})$$

Coattention encoder:

Attends to the document and the question simultaneously

1. Compute affinity matrix between document and question words

$$L = D^T Q \in \mathbb{R}^{(m+1) \times (n+1)}$$

After normalizing the affinity matrix row-wise, we get the attention weights A^Q for each word in the question, and when normalizing column-wise the attention weights for each word in the document A^D .

Summaries (attention contexts) are computed by multiplying the document representation with respect to each word in the question

$$C^Q = DA^Q \in \mathbb{R}^l \times (n+1)$$

Then, compute C^D , a co-dependent representation of the question and document as the coattention context. The query and the summary are concatenated horizontally.

$$C^D = [Q; C^Q]A^D \in \mathbb{R}^{2l \times (m+1)}$$

The last step: run a Bi-LSTM over the concatenated document and codependent representation:

$$u_t = BiLSTM(u_{t-1}, t_{t+1}, [d_t; c_t^D]) \in \mathbb{R}^{2l}$$

$U = [u_1, \dots, u_m] \in \mathbb{R}^{2l \times m}$ is then used as the foundation for selecting the span for the best possible answer.

Dynamic pointing decoder:

Producing the answer span in SQuAD:= predicting the start and end points of the span.

The dynamic decoder is a faux state machine whose state is maintained by a LSTM based model.

$$h_i = LSTM_{dec}(h_{i-1}, [u_{s_{i-1}}; u_{e_{i-1}}])$$

where u_s and u_e are the representations of the previous estimates of the start and end positions in the coattention encoding (U)

Then, two Highway Maxout Networks (maxout networks with highways) are used to compute the predicted start and end locations. The loss is the cumulative softmax cross-entropy of the start and end points across all iterations. The iterative LSTM-HMN procedure stops when both the start and end estimate don't change, or a maximum number of iterations is reached.

2.7 Attention-over-Attention

(Cui et al. 2016)

- Document, query $\in R^{|\mathbb{D}| \cdot 2h}, R^{|\mathbb{Q}| \cdot 2h}$
- D, Q are sequence lengths of document and query respectively
- Shared embedding spaces for query and document (uses one embedding matrix for their joined vocabulary)
- two BiGRU embed query and document ($h_{doc} \in D \cdot 2h, h_{query} \in Q \cdot wh$)
- matrix multiplication over the shared embedding dimension $2d$ produces the **pair-wise matching score**

$$M = h_{doc}^T \cdot h_{query} \in R^{D \times Q}$$

CONT

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