

run zephyr and runway World on gazebo

```
cd /home/halit/ardupilot_gazebo-master/worlds
```

```
cat > zephyr.world
```

copy zephyr_delta_wing_demo_world and past new .world file (zephyr.world)

change addres of model, there are two zephyr model on ardupilot_gazebo/models, old World file (zephyr_demo) use zephyr_delta_wing_ardupilot_demo.

Our new file zephyr.world use zephyr_delta_wing model.

End of files

Not Changed zephyr_delta_wing_demo_world

```
<model name="zephyr_delta_wing_demo">
  <pose>0 0 0.2 0 0 0</pose>
  <include>
    <uri>model://zephyr_delta_wing_ardupilot_demo</uri>
    <pose>0 0 0 0 0 0</pose>
  </include>
</model>
</world>
</sdf>
```

Changed zephyr.world

```
<model name="zephyr_delta_wing_demo">
  <pose>0 0 0.2 0 0 0</pose>
  <include>
    <uri>/home/halit/ardupilot_gazebo-master/models/zephyr_delta_wing</uri>
    <pose>0 0 0 0 0 0</pose>
  </include>
</model>
</world>
</sdf>
```