For ros installation use this vido

https://www.youtube.com/watch?v=zF7Pbq4Puvg

```
conda create -n ROS python=3.9

conda activate ROS

conda config --add channels conda-forge

conda config --add channels robostack

conda config --set channel_priority strict

conda install ros-noetic-desktop-full

conda install compilers cmake pkg-config make ninja catkin_tools

roscore

İn another terminal

conda activate ROS

rviz
```