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Executive Summary



Goal

• Predict SpaceX Falcon 9 first stage landing success rate by using historic launching data.



Data Source

- Data requested from spacexdata.com using API.
- Falcon 9 launching data obtained from Wikipedia using web scraping.



Methodology

- Data processing: pandas, numpy, sql, BeautifulSoup, requests.
- Visualization and machine learning: matplotlib, seaborn, folium, dash, plotly, scikit-learn.



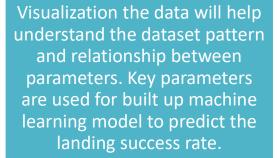
Results

• The model can predict the landing successful rate with high accuracy using testing data.

Introduction

SpaceY, a new born competitor of SapceX, provide the space launching service to the market. In order to further reduce the cost due to the potential failure of the first stage of landing. **SpaceY** determined to use SpaceX Falcon 9 historical launching data to predict the success rate of landing.

Falcon 9 historical data will be collected from Wikipedia and spacexdata.com. Applying data science technique to clean and process the raw data to understand dataset and launching parameters.



A. Factors influencing the landing outcome are identified.

B. The ideal models are developed to predict results which will be applied for future launching services.



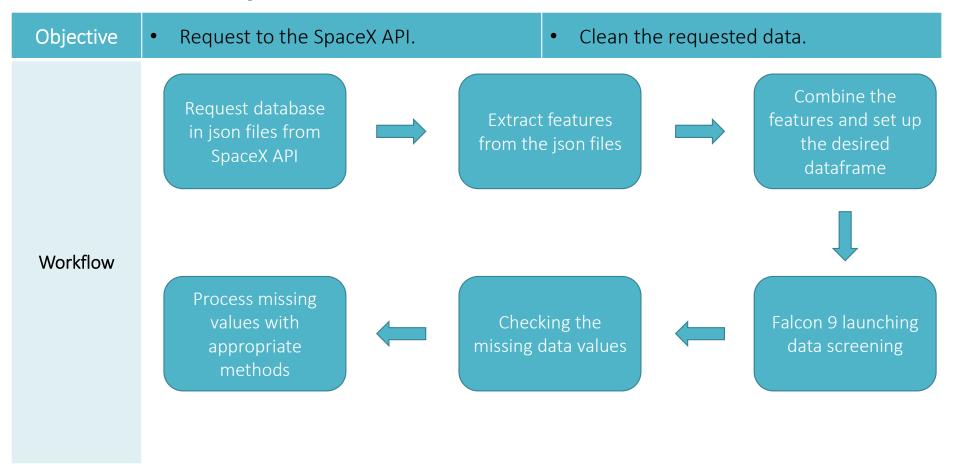
Data Collection and Data Wrangling Methodology

Data Source	spacexdata	https://api.spacexdata.com/v4/rockets/ https://api.spacexdata.com/v4/launchpads/ data https://api.spacexdata.com/v4/payloads/ https://api.spacexdata.com/v4/cores/ https://api.spacexdata.com/v4/launches/past		
	Wikipedia	https://en.wikipedia.org/wiki/List_of_Falcon_9_and_Falcon_Heavy_launches		
	Data Collection		Da	ta Wrangling
Tools	Requests http 60t huans	Beautifuloup	NumPy pandas	
Key methods	requests.get().json() pandas.json_normalize(json_file) BeautifulSoup(data, 'html')		panda.read_csv() df.insnull().sum() df['feature'].value	

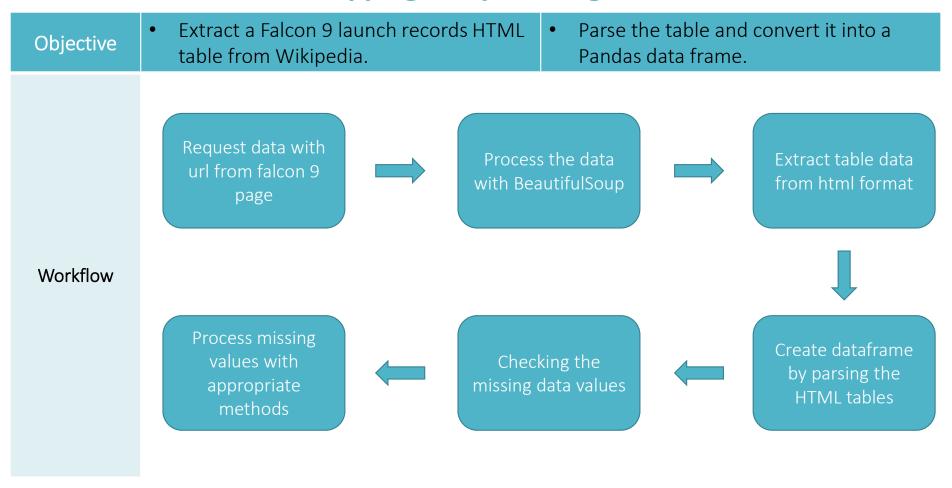
Data Collection

technique	tools	sources	contents
json file decoding	Requests	spacexdata.com API	Contains the information of Falcon 9, launching pads, payloads, cores, and historical launching records.
Web scarping	Beautifuloup	Wikipedia Falcon 9 launching	Falcon 9 historical launch records including features.

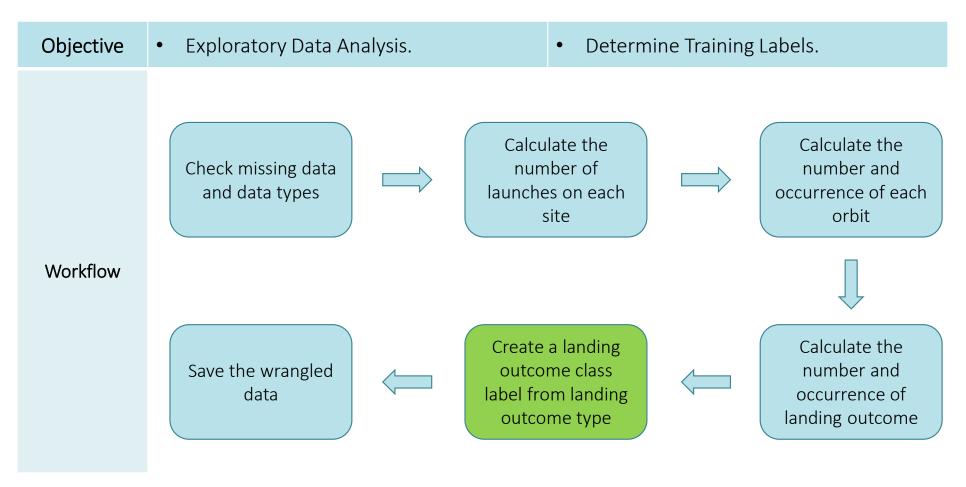
Data Collection: SpaceX API



Data Collection: Web Scrapping Wikipedia Page



Data Wrangling



SQL Request Objectives

Understand Dataset Understand dataset features such as launching site, payload.

Load Dataset into a Bb2 database

Learn how to use db2 UI and

Store dataset into the database

Change the data/time format

Execute sql query

Learn how to use magic sql query

Explore the dataset with sql query

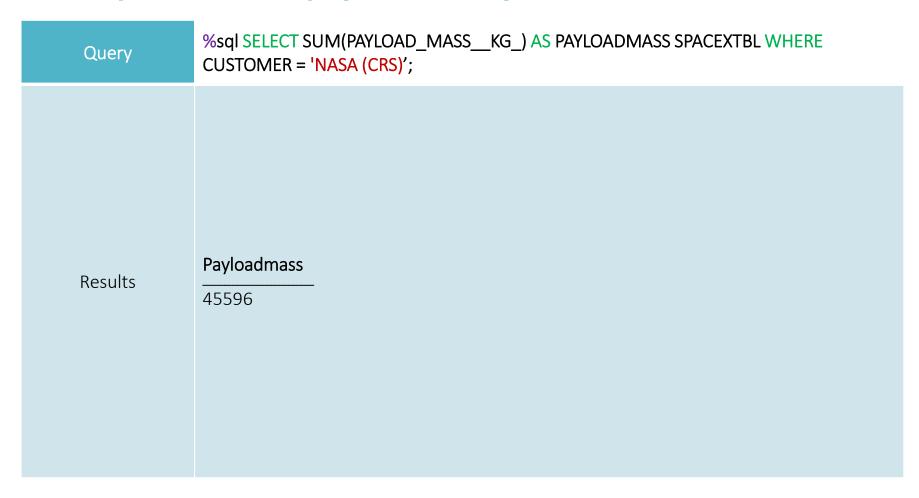
SQL Request Result: Display Launch Sites

Query	%sql SELECT DISTINCT LAUNCH_SITE FROM SPACEXTBL ORDER BY 1;
Results	launch_site CCAFS LC-40 CCAFS SLC-40 KSC LC-39A VAFB SLC-4E

SQL Request Result: Display 5 Records of Launch Site of "KSC"

%sql SELECT * FROM SPACEXTBL WHERE LAUNCH_SITE LIKE 'KSC%' LIMIT 5; Query payload landing__ time_utc launch_si mission_ DATE payload mass_kg orbit customer r_versi outcome outcome on F9 FT Success KSC LC-SpaceX **NASA** B1031. 2017-02-19 14:39:00 2490 LEO (ISS) Success (ground (CRS) 39A CRS-10 1 pad) KSC LC-F9 FT EchoStar No 2017-03-16 06:00:00 5600 **GTO** EchoStar Success B1030 39A 23 attempt F9 FT Success Results KSC LC-2017-03-30 22:27:00 B1021. SES-10 5300 **GTO SES** (drone Success 39A 2 ship) F9 FT Success KSC LC-2017-05-01 11:15:00 B1032. NROL-76 5300 LEO **NRO** Success (ground 39A 1 pad) F9 FT KSC LC-Inmarsat-No 6070 2017-05-15 23:21:00 **GTO** Inmarsat Success B1034 39A 5 F4 attempt

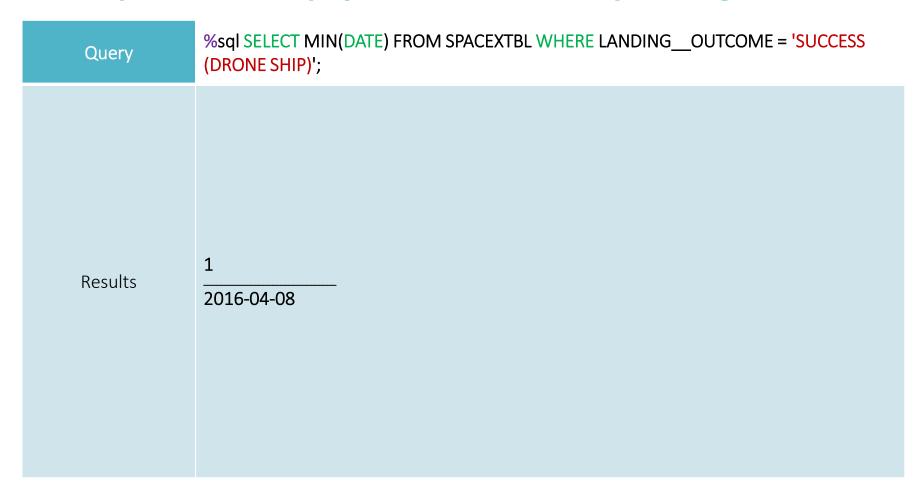
SQL Request Result: Display the Total Payload Mass from NASA



SQL Request Result: Display Average Payload Carried by F9 v1.1

Query	%sql SELECT AVG(PAYLOAD_MASSKG_) AS PAYLOADMASS SPACEXTBL WHERE BOOSTER_VERSION = 'F9 V1.1';
Results	Averagepayload 2928

SQL Request Result: Display Successful Drone Ship Landing Date



SQL Request Result: Display Boosters with Specific Constraints

Query	%sql SELECT_BOOSTER_VERSION FROM SPACEXTBL WHERE ((LANDINGOUTCOME = 'SUCCESS (GROUND PAD)') & (PAYLOAD_MASSKG_ BETWEEN 4000 AND 6000));
Results	booster_version F9 FT B1032.1 F9 B4 B1040.1 F9 B4 B1043.1

SQL Request Result: Display the Total Number of Different Outcomes

Query	%sql SELECT COUNT(MISSION_OUTCOME) AS OUTCOME FROM SPACEXTBL GROUP BY MISSION_OUTCOME;
Results	Outcome 1 99 1

SQL Request Result: Display the Booster Which Carried The Max. Payload

Query	•	-	ASSKG_ FROM SPACEXTBL WHERE D_MASSKG_) FROM SPACEXTBL)
Results	booster_version F9 B5 B1048.4 F9 B5 B1049.4 F9 B5 B1051.3 F9 B5 B1056.4 F9 B5 B1048.5 F9 B5 B1049.5 F9 B5 B1060.2 F9 B5 B1051.6 F9 B5 B1060.3 F9 B5 B1049.7	payload_masskg_ 15600 15600 15600 15600 15600 15600 15600 15600 15600 15600 15600 15600	

SQL Request Result: Display Record with Multiple Features and Constraints

Query

Results

%sql SELECT SUBSTR(DATE, 1, 4) AS YEAR, SUBSTR(DATE, 6, 2) AS MONTH, MISSION_OUTCOME, BOOSTER_VERSION, LAUNCH_SITE FROM SPACEXTBL WHERE ((SUBSTR(DATE, 1, 4)='2017') & (LANDING OUTCOME = 'SUCCESS (GROUND PAD)'));

Booster Versio

F9 FT B1031.1

F9 FT B1032.1

F9 FT B1035.1

F9 B4 B1039.1

F9 B4 B1040.1

F9 FT B1035.2

Success

Launch_Site

KSC LC-39A

KSC LC-39A

KSC LC-39A

KSC LC-39A

KSC LC-39A

CCAFS SLC-40

year	month	Mission_Outco me
2017	02	Success
2017	01	Success
2017	03	Success
2017	08	Success
2017	07	Success
2017	12	Success

SQL Request Result: Display Record with Multiple Features and Constraints

Query

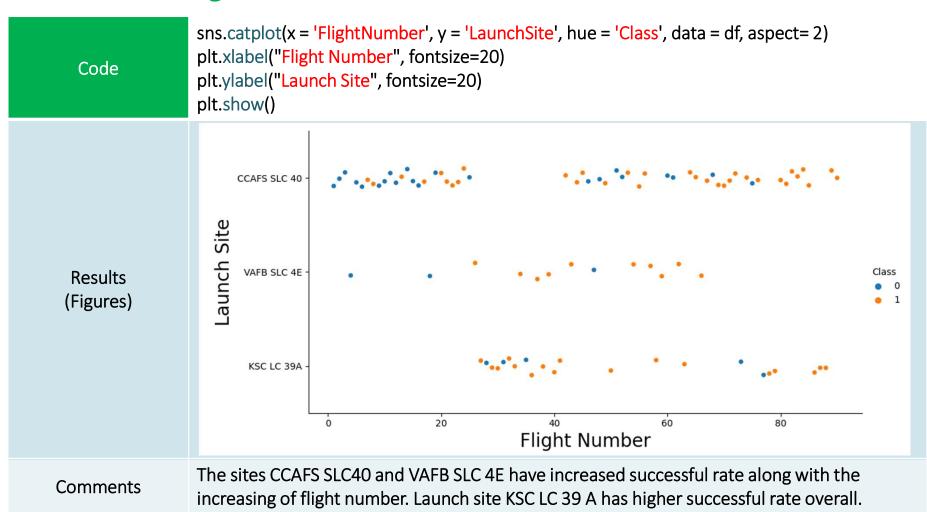
%sql SELECT LANDING__OUTCOME, COUNT(*) AS COUNT_LAUNCHES FROM SPACEXTBL WHERE DATE BETWEEN '2010-06-04' AND '2017-03-20' GROUP BY LANDING OUTCOME ORDER BY COUNT LAUNCHES DESC;

	landing_outcome	count_launches
	No attempt	10
	Failure (drone ship)	5
	Success (drone ship)	5
Results	Controlled (ocean)	3
	Success (ground pad)	3
	Failure (parachute)	2
	Uncontrolled (ocean)	2
	Precluded (drone ship)	1

EDA with Visualization Objectives

Objectives	Exploratory Data Analysis Visualization		Preparing Data Feature Engineering
	pandas	NumPy	Use the pandas function get_dummies and features
Tools	matpl	%tlib	dataframe to apply OneHotEncoder to the column Orbits LaunchSite LandingPad
	sea	born	Serial

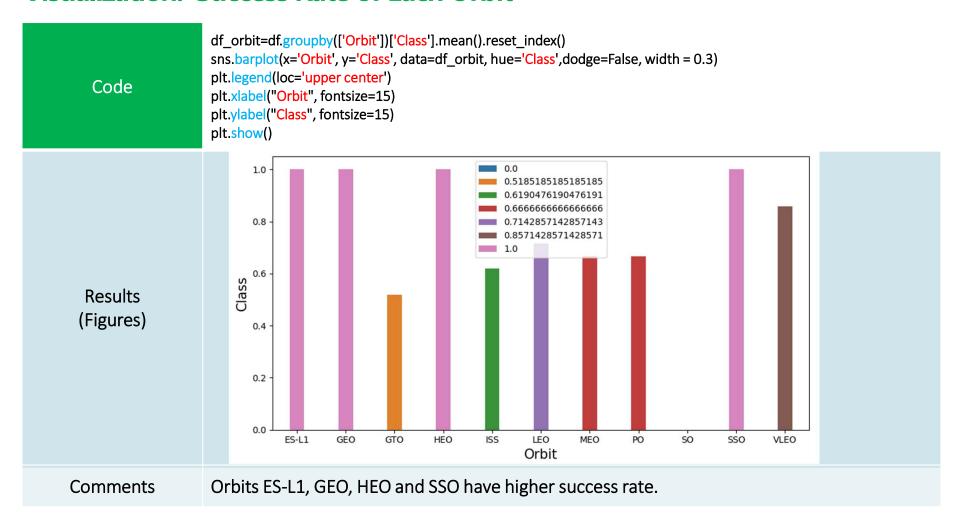
Visualization: Flight Number Vs Launch Site



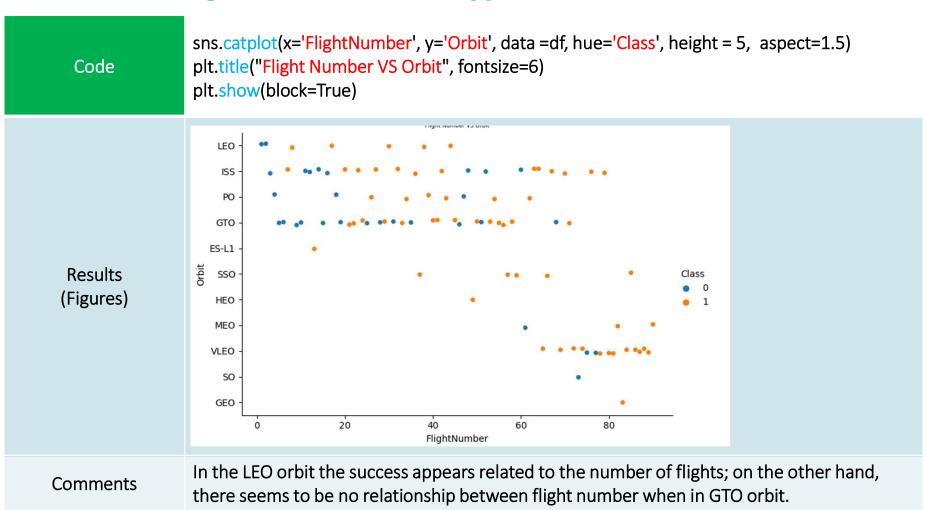
Visualization: Payload and Launch Site

sns.catplot(x='PayloadMass', y='LaunchSite', data=df, hue='Class', aspect=2) plt.xlabel("PayloadMass", fontsize=20) Code plt.ylabel("Launch Site", fontsize=20) plt.show() . CCAFS SLC 40 Launch Site VAFB SLC 4E Results (Figures) KSC LC 39A 8000 2000 4000 6000 10000 12000 14000 16000 **PayloadMass** Comments There are no rockets launched for heavy payload mass(greater than 10000) on VAFB SLC 4E.

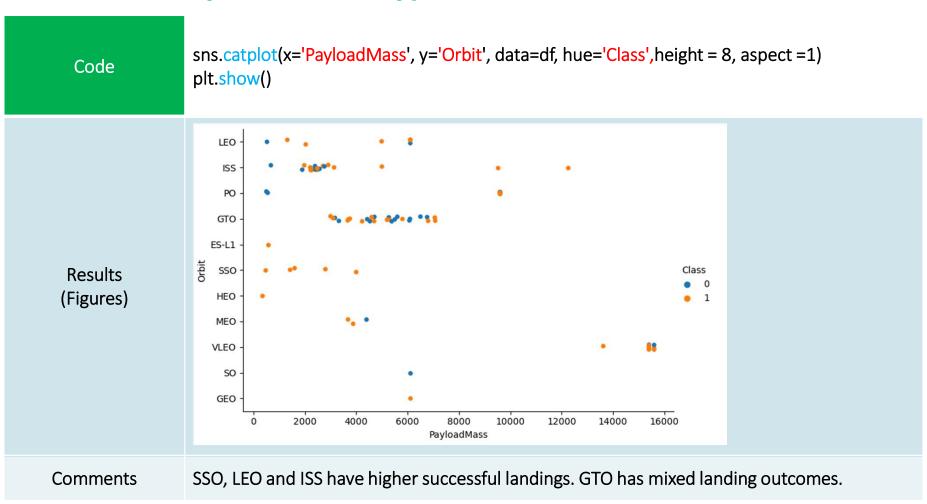
Visualization: Success Rate of Each Orbit



Visualization: FlightNumber VS Orbit type



Visualization: Payload VS Orbit type

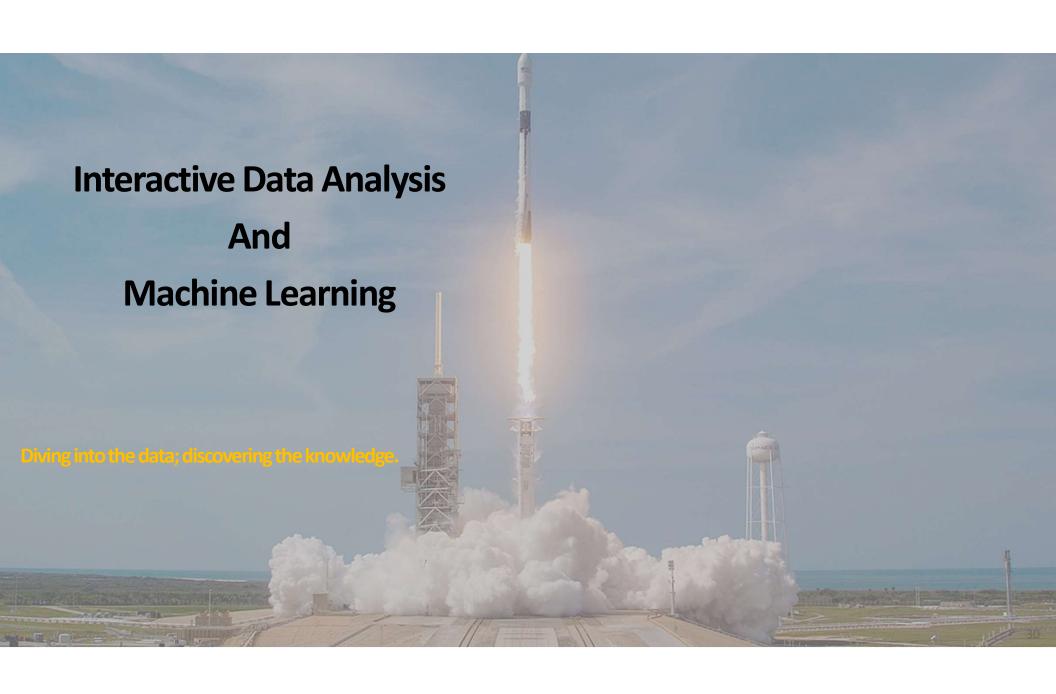


Visualization: Launch Success Yearly Trend

sns.lineplot(x='Date', y='Class', data=df, color='green') plt.xlabel("Launch Year", fontsize=15) Code plt.ylabel("Success Rate", fontsize=15) plt.show() 1.0 0.8 Success Rate Results (Figures) 0.2 0.0 2010 2012 2013 2014 2015 2016 2017 2018 2019 2020 Launch Year Comments The success rate since 2013 kept increasing till 2020.

Features Engineering: Create dummy variables to categorical columns

Task	Code
Create dummy variables to categorical columns	features_one_hot=pd.get_dummies(features, columns=['Orbit', 'LaunchSite', 'LandingPad', 'Serial']) features_one_hot.head()
Cast all numeric columns to float64	features_one_hot.astype('float64')

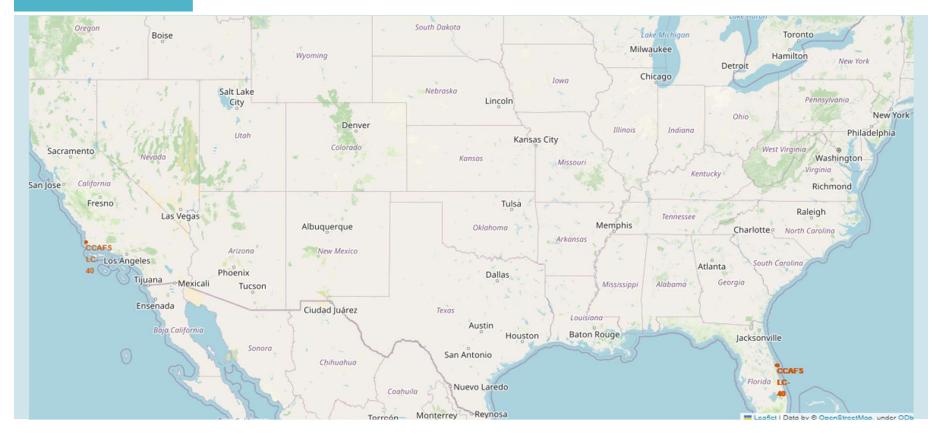


Interactive Visual Analytics Objectives and Methodology

Objective	Tools
 Mark all launch sites on a map. Mark the success/failed launches for each site on the map. Calculate the distances between a launch site to its proximities. 	Folium
Build an Interactive Dashboard with Ploty Dash	iii plotly Dash

Launch Sites Locations Analysis with Folium

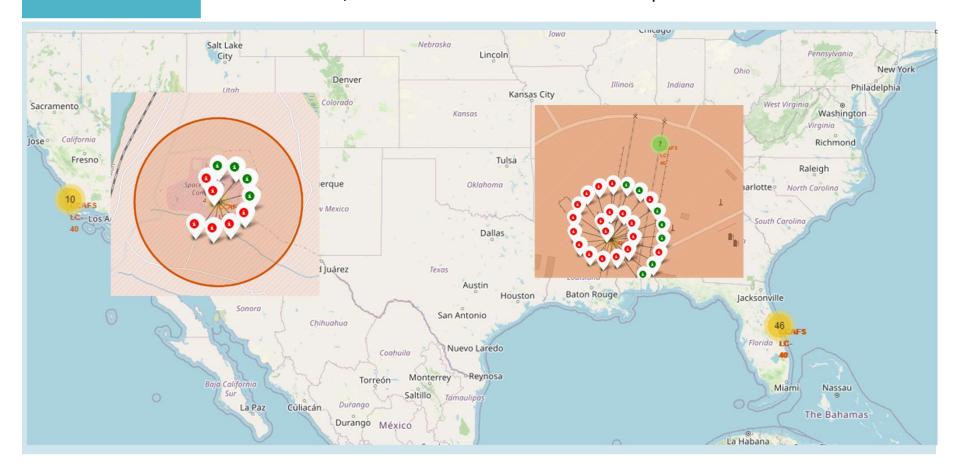
Task 1 Mark all launch sites on a map.



Launch Sites Locations Analysis with Folium

Task 2

Mark the success/failed launches for each site on the map.



Launch Sites Locations Analysis with Folium

Task 3

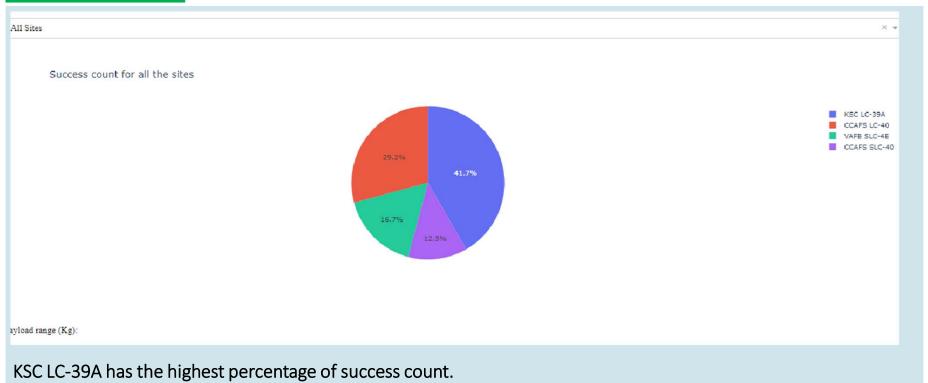
Calculate the distances between a launch site to its proximities.



Build an Interactive Dashboard with Ploty Dash

Task 1

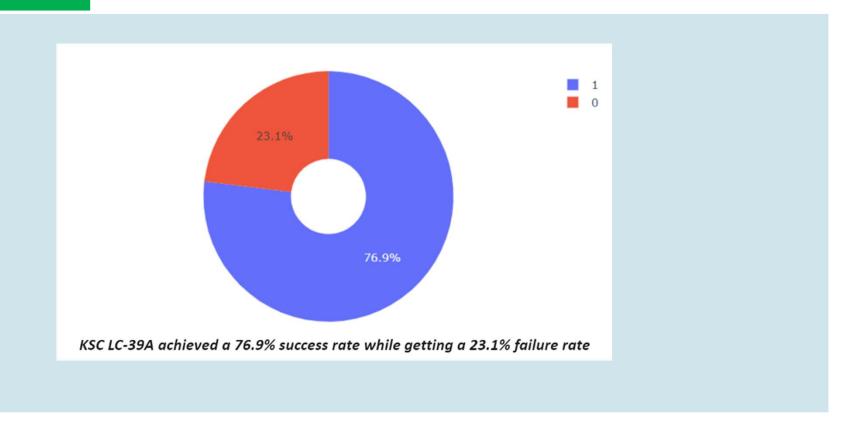
Display the success count achieved by each launch site.



Build an Interactive Dashboard with Ploty Dash

Task 2

Display the success percentage achieved by a single site.



Build an Interactive Dashboard with Ploty Dash

Task 3

Display success count on payload mass for all sites.



Predictive Analysis Objectives and Methodology

Objective	Tools
 Perform exploratory data analysis and determine training labels Create a column for the class Standardize the data Split into training data and test data 	pandas matpletlib
 Find best Hyperparameter for SVM, Classification Trees and Logistic Regression Find the method performs best using test data 	seaborn

Task 1

Create a logistic regression object then create a GridSearchCV object logreg_cv with cv = 10. Fit the object to find the best parameters from the dictionary parameters.

```
parameters ={"C":[0.01,0.1,1], 'penalty':['12'], 'solver':['lbfgs']}# L1 Lasso L2 ridge
           lr=LogisticRegression()
           # Create a GridSearchCV object Logreg cv
           logreg cv = GridSearchCV(lr, parameters, cv=10)
           #Fit the training data into the GridSearch object
           logreg cv.fit(X train, Y train)
           GridSearchCV(cv=10, estimator=LogisticRegression(),
                         param_grid={'C': [0.01, 0.1, 1], 'penalty': ['12'],
                                     'solver': ['lbfgs']})
Results
            print("tuned hpyerparameters :(best parameters) ",logreg cv.best params )
            print("accuracy :",logreg_cv.best_score_)
           tuned hpyerparameters :(best parameters) {'C': 0.01, 'penalty': '12', 'solver': 'lbfgs'}
            accuracy: 0.8464285714285713
            We output the GridSearchCV object for logistic regression. We display the best parameters using the data
            attribute best params and the accuracy on the validation data using the data attribute best score.
```

Calculate the accuracy on the test data using the method score. Task 2 Confusion Matrix did not land accuracy_logreg = logreg_cv.score(X_test, Y_test) print(f"The accuracy of logreg_cv on testing data is {accuracy_logreg}") The accuracy of logreg_cv on testing data is 0.83333333333333333 True labels yhat=logreg_cv.predict(X_test) plot_confusion_matrix(Y_test,yhat) Results 12 did not land Predicted labels

Task 3

Create a support vector machine object then create a GridSearchCV object svm_cv with cv - 10. Fit the object to find the best parameters from the dictionary parameters.

```
parameters = {'kernel':('linear', 'rbf', 'poly', 'rbf', 'sigmoid'),
                          'C': np.logspace(-3, 3, 5),
                          'gamma':np.logspace(-3, 3, 5)}
            svm = SVC()
            svm cv = GridSearchCV(svm, parameters, cv=10)
            svm cv.fit(X train, Y train)
            GridSearchCV(cv=10, estimator=SVC(),
                          param grid={'C': array([1.0000000e-03, 3.16227766e-02, 1.00000000e+00, 3.16227766e+01,
Results
                   1.00000000e+03]),
                                      'gamma': array([1.00000000e-03, 3.16227766e-02, 1.00000000e+00, 3.16227766e+01,
                    1.00000000e+03]),
                                      'kernel': ('linear', 'rbf', 'poly', 'rbf', 'sigmoid')})
            print("tuned hpyerparameters :(best parameters) ", svm cv.best params )
            print("accuracy :",svm_cv.best_score_)
            tuned hpyerparameters :(best parameters) {'C': 1.0, 'gamma': 0.03162277660168379, 'kernel': 'sigmoid'}
            accuracy: 0.8482142857142856
```

Calculate the accuracy on the test data using the method score: Task 4 **Confusion Matrix** did not land - 10 accuracy_svm = svm_cv.score(X_test, Y_test) - 8 print(f"The accuracy of svm_cv on testing data is {accuracy_svm}") True labels The accuracy of svm_cv on testing data is 0.8333333333333333 yhat=svm_cv.predict(X_test) Results plot_confusion_matrix(Y_test,yhat) 12 did not land land Predicted labels

Task 5

Create a decision tree classifier object then create a GridSearchCV object tree_cv with cv = 10. Fit the object to find the best parameters from the dictionary parameters.

```
parameters = {'criterion': ['gini', 'entropy'],
                    'splitter': ['best', 'random'],
                    'max depth': [2*n for n in range(1,10)],
                    'max_features': ['auto', 'sqrt'],
                    'min samples leaf': [1, 2, 4],
                    'min_samples_split': [2, 5, 10]}
               tree = DecisionTreeClassifier()
               tree cv = GridSearchCV(tree, parameters, cv=10)
               tree cv.fit(X train, Y train)
Results
               GridSearchCV(cv=10, estimator=DecisionTreeClassifier(),
                            param_grid={'criterion': ['gini', 'entropy'],
                                        'max_depth': [2, 4, 6, 8, 10, 12, 14, 16, 18],
                                        'max_features': ['auto', 'sqrt'],
                                        'min_samples_leaf': [1, 2, 4],
                                        'min_samples_split': [2, 5, 10],
                                        'splitter': ['best', 'random']})
               print("tuned hpyerparameters :(best parameters) ",tree_cv.best_params_)
               print("accuracy :",tree_cv.best_score_)
               tuned hpyerparameters :(best parameters) {'criterion': 'entropy', 'max depth': 8, 'max features': 'auto', 'min samples leaf':
               2, 'min_samples_split': 2, 'splitter': 'random'}
               accuracy : 0.9053571428571429
```

Calculate the accuracy of tree_cv on the test data using the method score: Task 6 **Confusion Matrix** did not land - 10 accuracy_tree = tree_cv.score(X_test, Y_test) print(f"The accuracy of tree_cv on testing data is {accuracy_tree}") - 8 The accuracy of tree_cv on testing data is 0.8333333333333333 True labels We can plot the confusion matrix Results yhat = tree_cv.predict(X_test) landed plot_confusion_matrix(Y_test,yhat) 12 did not land land Predicted labels

Task 7

Create a k nearest neighbors object then create a GridSearchCV object knn_cv with cv = 10. Fit the object to find the best parameters from the dictionary parameters.

Calculate the accuracy of knn_cv on the test data using the method score: Task 8 Confusion Matrix did not land - 10 accuracy_knn = knn_cv.score(X_test, Y_test) print(f"The accuracy of knn_cv on testing data is {accuracy_knn}") - 8 The accuracy of knn_cv on testing data is 0.8333333333333334 True labels We can plot the confusion matrix Results yhat = knn_cv.predict(X_test) plot_confusion_matrix(Y_test,yhat) 12 did not land land Predicted labels

Task 9

Find the method performs best:

method = ['LogisticRegression','svm','DecisionTree','KNN'] score = [accuracy_logreg, accuracy_svm, accuracy_tree, accuracy_knn] performation = pd.DataFrame(columns=['Method', 'Score']) performation['Method'] = method performation['Score'] = score performation Method Score Results **0** LogisticRegression 0.833333 svm 0.833333 1 2 DecisionTree 0.833333 KNN 0.833333 3



The success landing rate increased along with the flight number and the passed year, which implied that the technology became mature and reliable.

Conclusion

The four kinds of predictive models LogisticRegression, SVM, DecisionTree, and KNN have same and higher predictive accuracy.

Orbit type, payload mass, and launching site can also impact the landing outcomes.

Appendix

Notebook GitHub links:

- 1 1 Data collection API.ipynb
- 1 2 Data collection web-scraping.ipynb
- 1 3 Data collection data-wrangling.ipynb
- 2 1 EDA with SQL.ipynb
- 2 2 EDA with visualizations.ipynb
- 3 1 Interactive visual analytics with Folium.ipynb
- 3 2 Interactive dashboard with Ploty Dash.py
- 4 1 Machine Learning prediction.ipynb