Controlling Test-Time Compute in Autoregressive Image Generation with Next-Detail Prediction

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Abstract

Autoregressive models have recently become competitive with diffusion-based approaches for image generation. However, these models remain computationally expensive, and fail to surpass the fastest approaches for image generation, such as GANs and distilled diffusion. We present Next-Detail Prediction (NDP), a method for precisely controlling the compute spent generating an image by focusing on difficult-to-predict regions. We achieve this by predicting sequentially higherresolution patch maps of an image, choosing to upsample difficult patches first. We compare and evaluate several strategies for estimating the difficulty of image patches, and propose a masked architecture that predicts both patches and their difficulty in a single step. We show that this method can generate high-quality images with significantly less compute than previous approaches. On the ImageNet 256x256 Generation benchmark, we achieve state-of-the-art FID and IS 2x faster than baseline AR approaches, and demonstrate desirable scaling with higher resolutions.

1. Introduction

Much has been made of the potential for large language models (LLMs) to generalize to visual data modalities, such as images and video. Vision LLMs, such as GPT-4V, Gemini 1.0, Claude 3 and their derivatives, have shown impressive capabilities in understanding visual data. Advances in image tokenization, particular VQ-VAEs, allow discrete LLM token vocabularies to span text and images.

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However, in deployment, these models do not use their native image tokenizers to generate images. State-of-the-art diffusion-based approaches such as DDPM and DiT remain widely used for image generation, and can be accelerated with methods such as LCM and sCM to generate images in less than a second. Diffusion is aesthetically less desirable than a general multimodal system, and seems not to benefit from the scalability and simplicity of self-supervised next-token prediction, so a high-quality autoregressive (AR) image generation paradigm is desirable.

Until recently, autoregressive models have been less competitive than diffusion for image generation. However, the recent work VAR showed that AR models can generate high-quality images, if asked to predict images in hierarchical scales rather than in raster order. VAR uses a hierarchical VQ-VAE to tokenize images into a sequence of increasingly-large token maps, and predicts these token maps autoregressively.

VAR cites inspiration from the fact that "humans percieve or create images in a hierarchical manner, first capturing the global structure and then local details". We add that humans percieve different parts of images preferentially – for example, an artist may focus on critical details such as eyes and faces, and spend less effort on background details. Many images in practice contain large regions of low-entropy single colors or patterns, which can be decoded easily. Therefore, we demonstrate that compute-efficiency of AR image models can be improved when they are allowed to focus on difficult-to-predict regions of an image first.

Our NDP model, following VAR, is trained on increasingly large token maps, however it follows a masked upsampling objective - given a $K \times K$ patch, it predicts the $4 \frac{K}{2} \times \frac{K}{2}$ child patches in the following scale. We train our model to predict these next tokens, and also to predict a difficulty scalar, which is an estimation of the difficulty of each visible patch. We then use this difficulty map to choose which patches to upsample next. We show that this method can generate high-quality images with significantly less compute than previous approaches. We contribute:

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- A novel method for precisely controlling the compute spent generating an image by focusing on difficult-to-predict regions.
- A comparison of methods for evaluating the difficulty of image patches.
- A novel objective that predicts patches and difficulty simultaneously.
- A novel tokenizer that decodes tokens of various scales into a single coherent image

Our code is open-sourced at https://github.com/next-detail-prediction/next-detail-prediction.

2. Related Work

2.1. Image Tokenization

As mentioned, we use a vector-quantized autoencoder to tokenize images similar to VQ-GAN, which is itself derived from VQ-VAE. Additionally, we adopt some architectural ideas from LlamaGen's tokenizer, namely normalizing the embedding space.

2.2. Image Generation

2.3. Abstract

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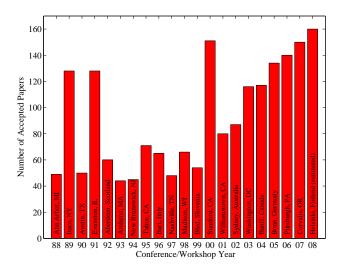


Figure 1. Historical locations and number of accepted papers for International Machine Learning Conferences (ICML 1993 – ICML 2008) and International Workshops on Machine Learning (ML 1988 – ML 1992). At the time this figure was produced, the number of accepted papers for ICML 2008 was unknown and instead estimated.

¹Footnotes should be complete sentences.

²Multiple footnotes can appear in each column, in the same order as they appear in the text, but spread them across columns and pages if possible.

Algorithm 1 Bubble Sort Input: data x_i , size mrepeat Initialize noChange = true. for i = 1 to m - 1 do if $x_i > x_{i+1}$ then Swap x_i and x_{i+1} noChange = falseend if end for until noChange is true

2.5. Figures

You may want to include figures in the paper to illustrate your approach and results. Such artwork should be centered, legible, and separated from the text. Lines should be dark and at least 0.5 points thick for purposes of reproduction, and text should not appear on a gray background.

Label all distinct components of each figure. If the figure takes the form of a graph, then give a name for each axis and include a legend that briefly describes each curve. Do not include a title inside the figure; instead, the caption should serve this function.

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2.6. Algorithms

If you are using LATEX, please use the "algorithm" and "algorithmic" environments to format pseudocode. These require the corresponding stylefiles, algorithm.sty and algorithmic.sty, which are supplied with this package. Algorithm 1 shows an example.

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You may also want to include tables that summarize material. Like figures, these should be centered, legible, and numbered consecutively. However, place the title above the table with at least 0.1 inches of space before the title and the same after it, as in Table 1. The table title should be set in 9 point type and centered unless it runs two or more lines, in which case it

Table 1. Classification accuracies for naive Bayes and flexible Bayes on various data sets.

Data set	Naive	Flexible	Better?
Breast	95.9 ± 0.2	96.7 ± 0.2	
Cleveland	83.3 ± 0.6	80.0 ± 0.6	×
Glass2	61.9 ± 1.4	83.8 ± 0.7	
Credit	74.8 ± 0.5	78.3 ± 0.6	
Horse	73.3 ± 0.9	69.7 ± 1.0	×
Meta	67.1 ± 0.6	76.5 ± 0.5	
Pima	75.1 ± 0.6	73.9 ± 0.5	
Vehicle	44.9 ± 0.6	61.5 ± 0.4	$\sqrt{}$

should be flush left.

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2.8. Theorems and such

The preferred way is to number definitions, propositions, lemmas, etc. consecutively, within sections, as shown below.

Definition 2.1. A function $f: X \to Y$ is injective if for any $x, y \in X$ different, $f(x) \neq f(y)$.

Using Definition 2.1 we immediate get the following result:

Proposition 2.2. If f is injective mapping a set X to another set Y, the cardinality of Y is at least as large as that of X

Proof. Left as an exercise to the reader. \Box

Lemma 2.3 stated next will prove to be useful.

Lemma 2.3. For any $f:X\to Y$ and $g:Y\to Z$ injective functions, $f\circ g$ is injective.

Theorem 2.4. If $f: X \to Y$ is bijective, the cardinality of X and Y are the same.

An easy corollary of Theorem 2.4 is the following:

Corollary 2.5. If $f: X \to Y$ is bijective, the cardinality of X is at least as large as that of Y.

Assumption 2.6. The set X is finite.

Remark 2.7. According to some, it is only the finite case (cf. Assumption 2.6) that is interesting.

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The above statement can be used verbatim in such cases, but we encourage authors to think about whether there is content which does warrant further discussion, as this statement will be apparent if the

paper is later flagged for ethics review.

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