

Detector Challenges For $\mu^+ \mu^-$

A. Mazzacane



Snowmass on the Mississippi August 1, 2013

Muon Collider Motivations

➤ PRECISION PHYSICS

Lepton colliders provide elementary interactions at known initial state.

$$\text{i.e. } e^+e^- \rightarrow Z^0 h^0 \quad (Z^0 \rightarrow l^+l^-) \Rightarrow M_{h^0}^2 = s + M^2 Z^0 - 2 E_{z^0} \sqrt{s} \quad (g^2 \propto \sigma = N/\mathcal{L}\epsilon),$$

“Higgs recoil mass technique”.

➤ COMPACT

Synchrotron radiation ($1/\text{mass}^4$) does not limit muon circular acceleration, a circular machine with multi-TeV beams can be realized and it fits on laboratory site.

➤ NARROW ENERGY SPREAD

The beam energy resolution is not limited by beamstrahlung smearing, precision scans, kinematic constraints.

➤ TWO DETECTORS (2 IPs)

No need for “push-pull”.

➤ $\Delta T(\text{BUNCH}) \sim 10 \mu\text{s}$... (e.g. 4 TeV collider)

Lots of time for readout.

Backgrounds don't pile up.

➤ ENHANCED S-CHANNEL HIGGS PRODUCTION

Higgs coupling is proportional to mass and $(m_\mu/m_e)^2 = \sim 40000$

Muon Collider Challenges

- **MUONS ARE PRODUCED AS TERTIARY PARTICLES**

To make enough of them we must start with a MW scale proton source & target facility.

- **MUONS DECAY**

Everything must be done fast and we must deal with the decay electrons (& neutrinos).

- **MUONS ARE BORN WITHIN A LARGE 6D PHASE-SPACE**

For a MuC we must cool them before they decay.

New cooling technique (ionization cooling) must be demonstrated, and it requires components with demanding performance (NCRF in magnetic channel, high field solenoids.)

- **AFTER COOLING, BEAMS STILL HAVE LARGE EMITTANCE**



S. Geer- Accelerator Seminar
SLAC 2011

Main Detector Challenges: Muons Decay!

- The Muon Collider will be a precision machine: the detector performance must be very demanding.
- One of the most serious technical issues in the design of a Muon Collider experiment is the background.
- The major source come from muon decays:
for 750 GeV muon beam with $2*10^{12}$ muons/bunch
 $\sim 4.3*10^5$ decays/m/bunchX.
- Large background is expected into the detector from interactions of decay products with the beamline components and accelerator tunnel.
- The background affects the detector performance and can spoil the physics program.
- The Muon Collider physics program and the background will guide the choice of technology and parameters for the design of the detector.

Extensive and Detailed Simulation Studies: MARS and ILCroot Frameworks

- **MARS** – is the framework for simulation of particle transport and interactions in accelerator, detector and shielding components.
 - New release of MARS15 is available since February 2011 at Fermilab (N. Mokhov, S. Striganov, see www-ap.fnal.gov/MARS).
 - Background simulation in the studies shown in this presentation is provided at the surface of MDI (10° nozzle + walls).
-
- **ILCroot** – is a software architecture based on ROOT, VMC & Aliroot:
 - All ROOT tools are available (I/O, graphics, PROOF, data structure, etc).
 - Extremely large community of ROOT users/developers.
 - It is a simulation framework and an offline system:
 - Single framework, from generation to reconstruction and analysis!!
 - Six MDC have proven robustness, reliability and portability
 - VMC allows to select G3, G4 or Fluka at run time (no change of user code).
 - Widely adopted within HEP community (4th Concept, LHeC, T1015, SiLC, ORKA, MuC)
 - Detailed detector simulation, full simulation and physics studies are presented in this presentation.
 - It is available at Fermilab since 2006.

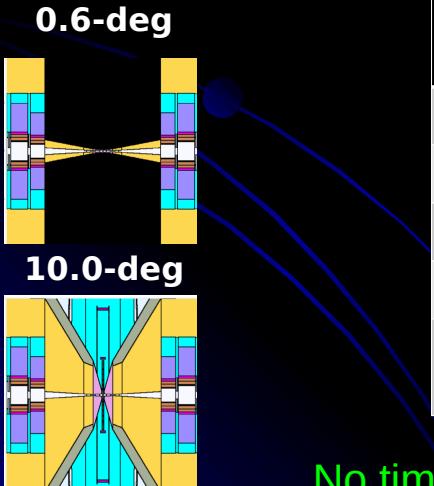
Part of the Solution: Shieldings

- Extensive studies (Mokhov et al., Fermilab) show a reduction of the background up to three order of magnitude using sophisticated shielding.
- Tungsten nozzle to stop gammas (generate neutrons), in Borated Polyetilene shell to absorb neutrons (and concrete walls outside the detector region)
- Detailed magnet geometry, materials, magnetic fields maps, tunnel, soil outside and a simplified experimental hall plugged with a concrete wall are simulated in MARS framework.



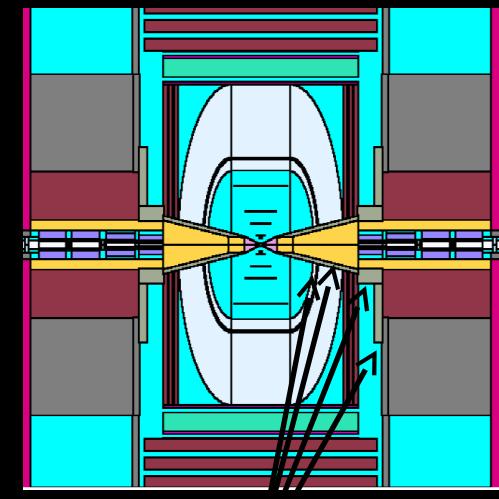
Number and species of particles per bunch crossing entering the detector,
starting from $S_{\max} = 75\text{m}$ for a 1.5 TeV collider.

N.V. Mokhov



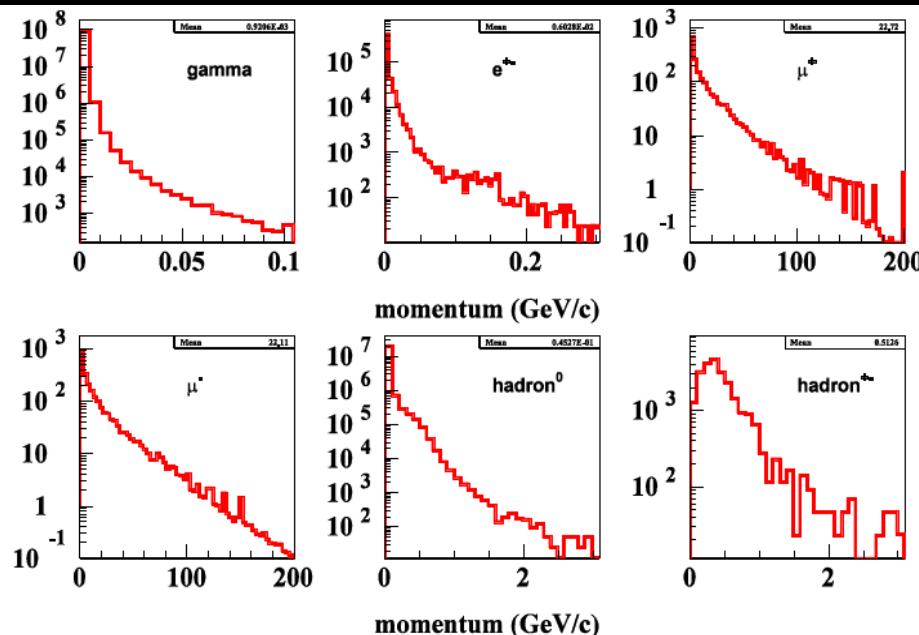
Particle	0.6-deg	10-deg
Photon	1.5×10^{11}	1.8×10^8
Electron	1.4×10^9	1.2×10^6
Muon	1.0×10^4	8.0×10^3
Neutron	5.8×10^8	4.3×10^7
Charged hadron	1.1×10^6	2.4×10^4

No time cut applied, can help substantially (see next)
All results below are presented
for a 1.5 TeV collider and a 10° nozzle



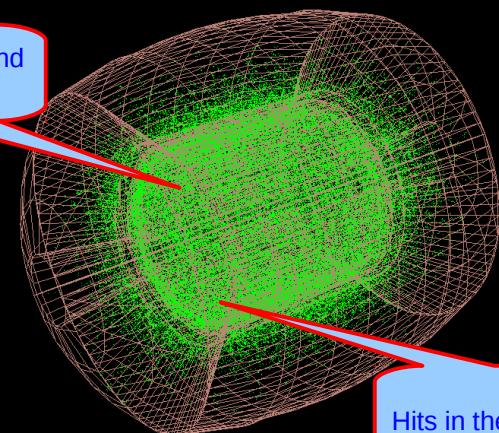
Sophisticated shielding:
W, iron, concrete & BCH_2

The Background Entering the Detector



Only 4% background pictured

S. Striganov



Hits in the calorimeter

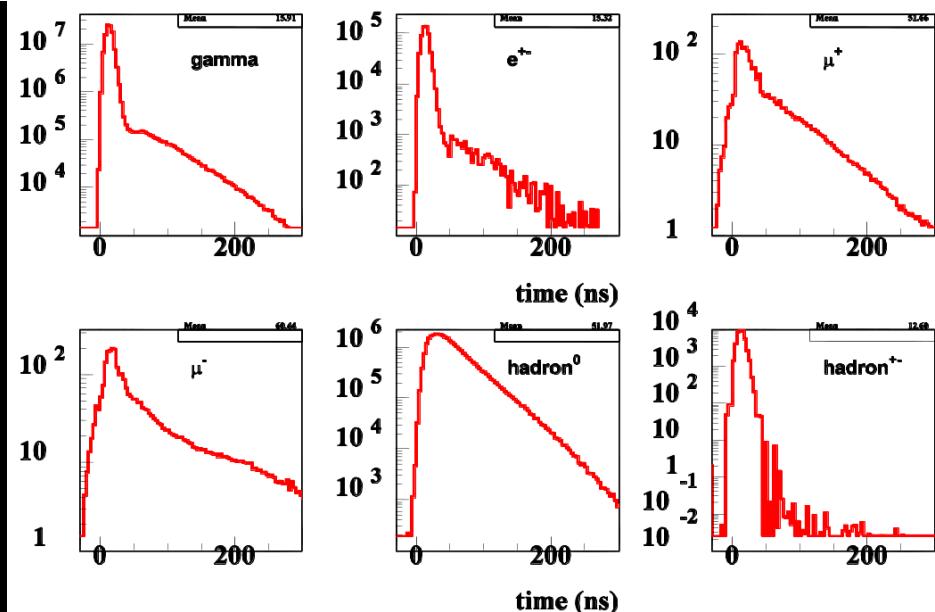
Most of the background is out of time
Timing cut can further reduce the background

Most of the background are low momenta photons and neutrons

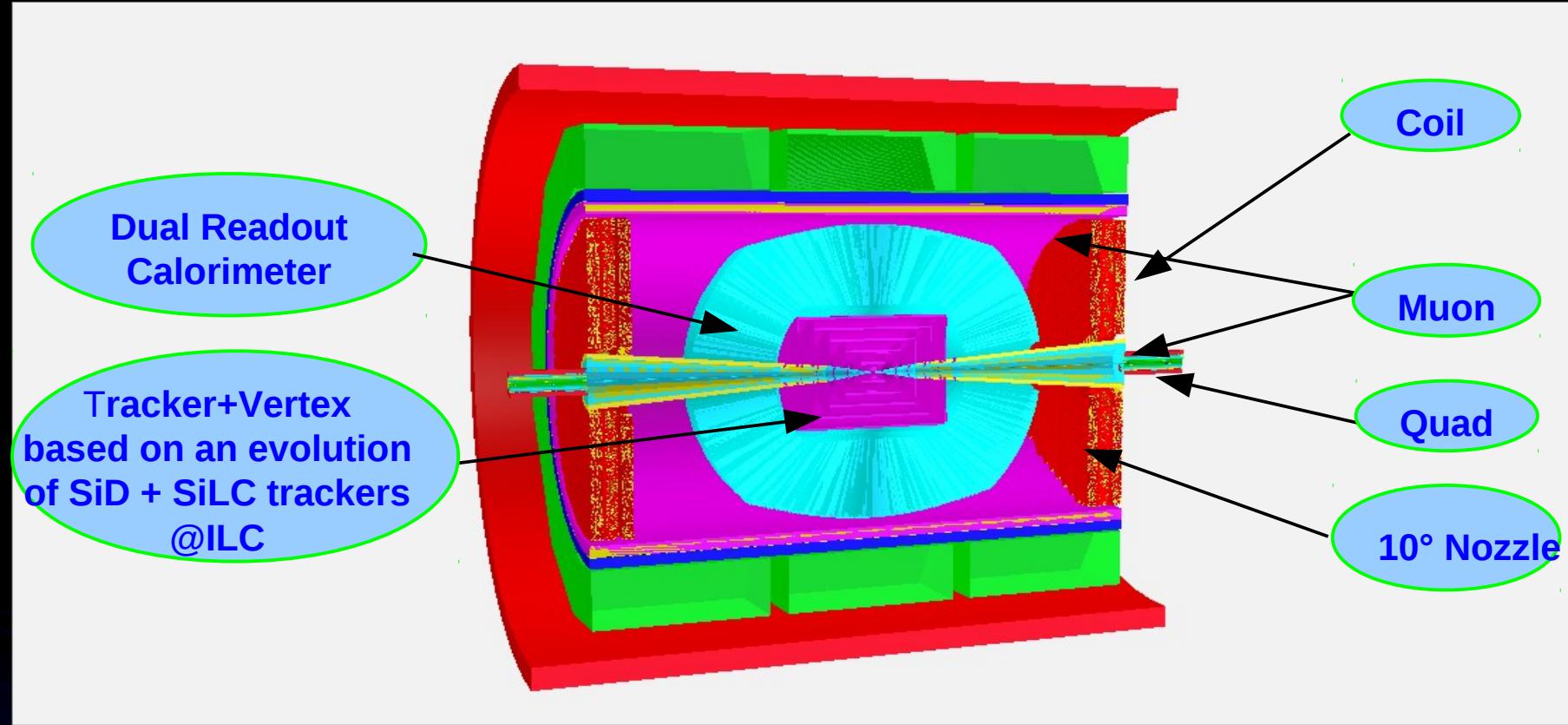


Still a lot of background!!!!!!

MARS Simulation



Baseline Detector for Muon Collider Studies



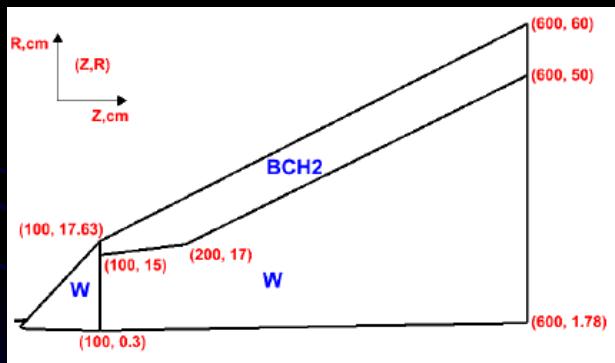
- Detailed geometry (dead materials, pixels, fibers ...)
- Full simulation: hits-sdigits-digits. Includes noise effect, electronic threshold and saturation, pile up...
- Tracking Reconstruction with parallel Kalman Filter.
- Light propagation and collection.
- Jet reco

Vertex Detector (VXD)

10°Nozzle and Beam Pipe

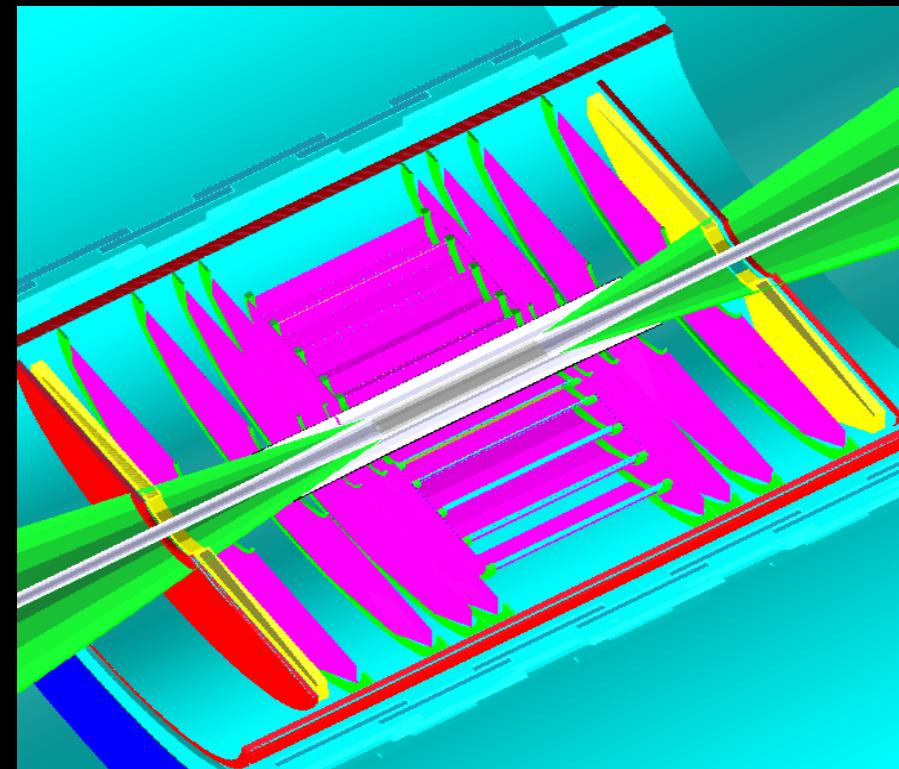
VXD

- 75 μm thick Si layers in the barrel
- 100 μm thick Si layers in the endcap
- 20 $\mu\text{m} \times 20 \mu\text{m}$ Si pixel
- Barrel : 5 layers subdivided in 12-30 ladders
- $R_{\min} \sim 3 \text{ cm}$ $R_{\max} \sim 13 \text{ cm}$ $L \sim 13 \text{ cm}$
- Endcap : 4 + 4 disks subdivided in 12 ladders
- Total length 42 cm



NOZZLE

- W - Tungsten
- BCH2 – Borated Polyethylene
- Starting at $\pm 6 \text{ cm}$ from IP with $R = 1 \text{ cm}$ at this z



PIPE

- Be – Beryllium 400 μm thick
- 12 cm between the nozzles

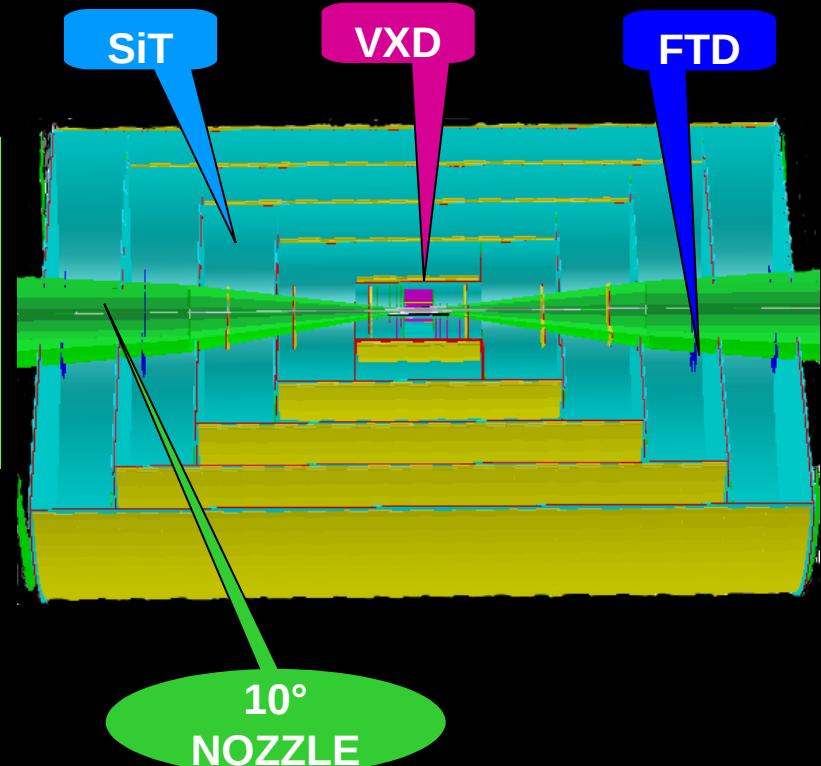
Silicon Tracker (SiT) and Forward Tracker Detector (FTD)

SiT

- 200 μm thick Si layers
- 50 $\mu\text{m} \times 50 \mu\text{m}$ Si pixel (or Si strips or double Si strips available)
- Barrel : 5 layers subdivided in staggered ladders
- Endcap : (4+3) + (4+3) disks subdivided in ladders
- $R_{\min} \sim 20 \text{ cm}$ $R_{\max} \sim 120 \text{ cm}$ $L \sim 330 \text{ cm}$

FTD

- 200 μm thick Si layers
- 50 $\mu\text{m} \times 50 \mu\text{m}$ Si pixel
- Endcap : 3 + 3 disks
- Distance of last disk from IP = 190 cm

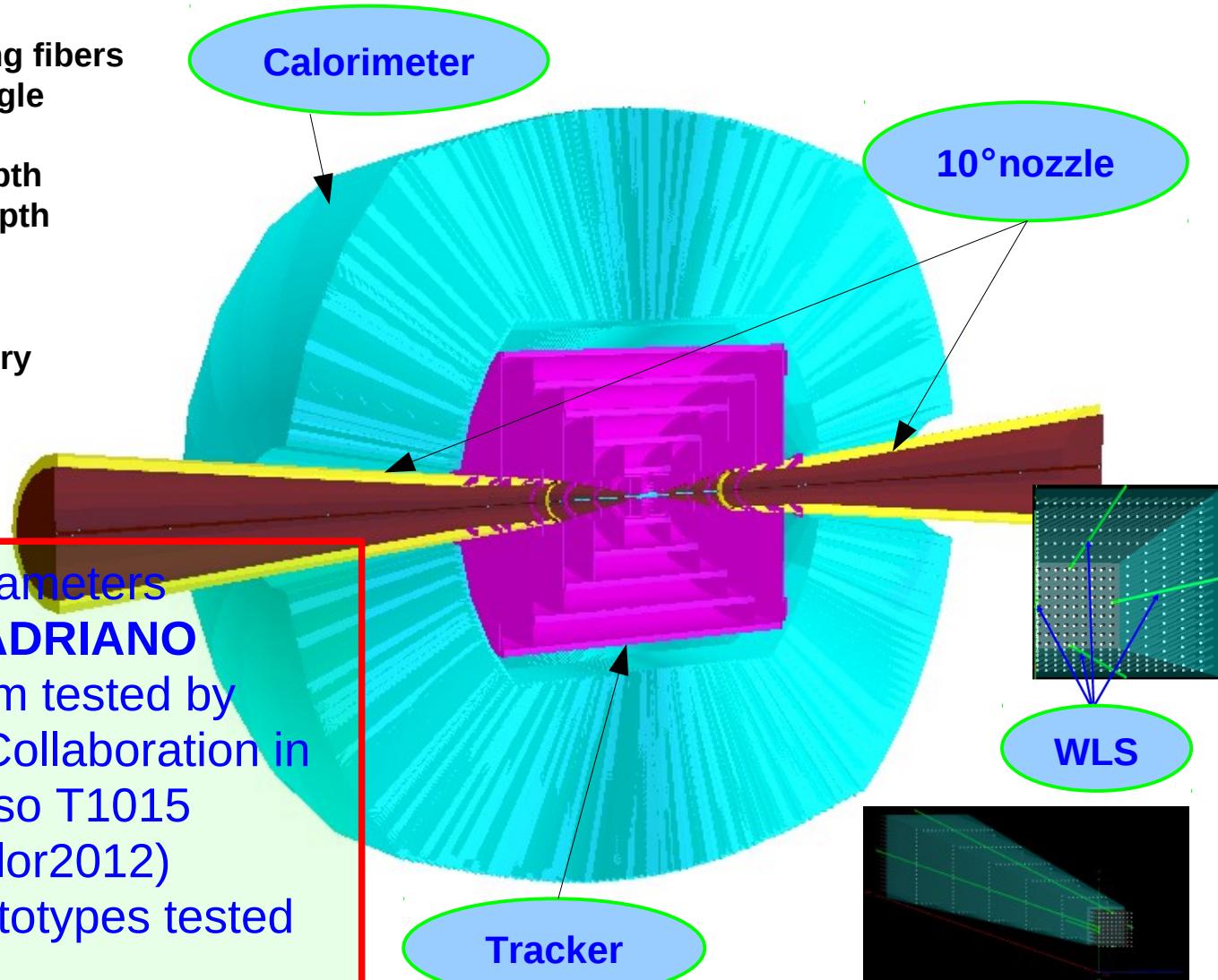


- Silicon pixel for precision tracking amid up to 10^5 hits
- Tungsten nozzle to suppress the background

Dual-Readout Projective Calorimeter

- Lead glass + scintillating fibers
- $\sim 1.4^\circ$ tower aperture angle
- Split in two sections
- Front section 20 cm depth
- Rear section 160 cm depth
- $\sim 7.5 \lambda_{\text{int}}$ depth
- $>100 X_0$ depth
- Fully projective geometry
- Azimuth coverage down to $\sim 8.4^\circ$ (Nozzle)
- Barrel: 16384 towers
- Endcaps: 7222 towers

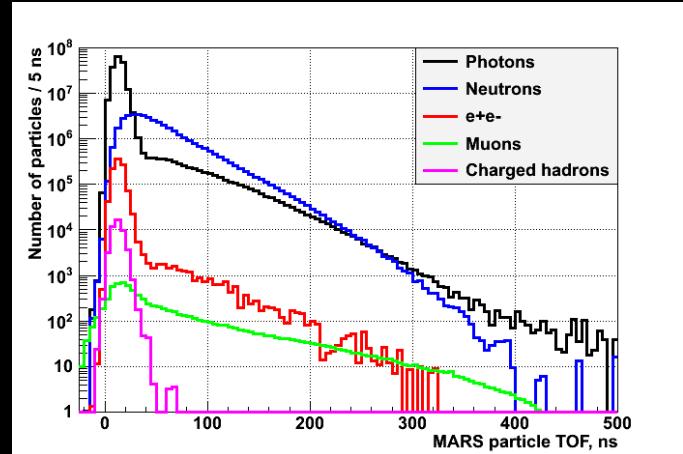
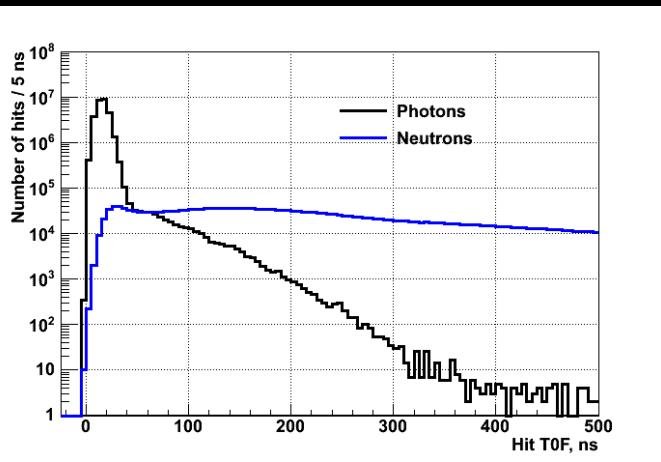
- All simulation parameters corresponds to **ADRIANO** prototype #9 beam tested by Fermilab T1015 Collaboration in Aug 2012 (see also T1015 Gatto's talk at Calor2012)
- Several more prototypes tested with real beam.



Timing Is The Key

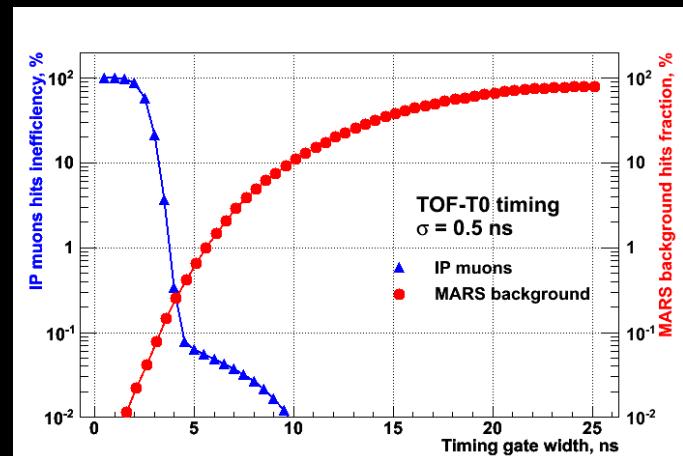
➤ Timing for MARS background particles

- MARS background (on a surface of the shielding cone) up to ~ 1000 ns of TOF (time of flight w.r.t. BX)



➤ Timing of ILCRoot MARS background hits in VXD and Tracker

- TOF for neutron hits has long tail up to a few ms (due to “neutron gas”)



N. Terentiev

With layer dependent time gate (TOF-T0)
several times gain in MARS background rejection compared with global time gate (TOF)

Strategies To Reduce Clusters In The Tracking System Produced By The Machine Background

	Kalman Reconstruction	Clusters
Physics: 100μ (0.2-200) GeV/c	92 (include geom. eff.)	1166
Machine Background	-	4×10^7

Simulated in ILCroot 4 detectors with different timing capabilities:

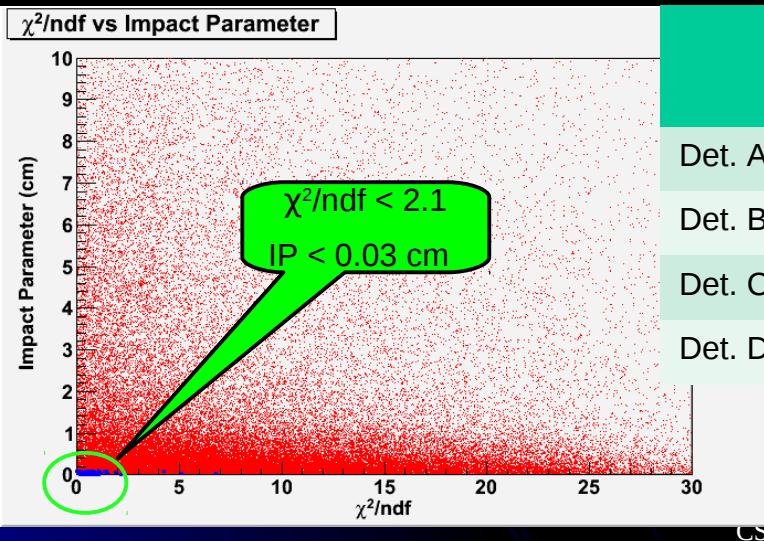
- **Det. A** – No time information (integrates all hits).
- **Det. B** – Acquires data in a fixed 7 ns time gate (minimal timing capabilities).
- **Det. C** - Acquires data in a 3 ns time gate tuned to distance from IP (advanced timing capabilities).
- **Det. D** - Acquires data in a 1 ns time gate tuned to pixel distance from IP (extreme timing capabilities.)

Reconstructed Background Tracks (from Kalman filter)

Full vs Fast simulation
of the bkg

Detector type	Reconstructed Tracks (full simu)	Reconstructed Tracks (fast simu)
Det. A (no timing)	Cannot calculate	Cannot calculate
Det. B (7 ns fixed gate)	75309	64319
Det. C (3 ns adjustable gate)	6544	4639
Det. D (1 ns adjustable gate)	1459	881

After χ^2 and IP cuts



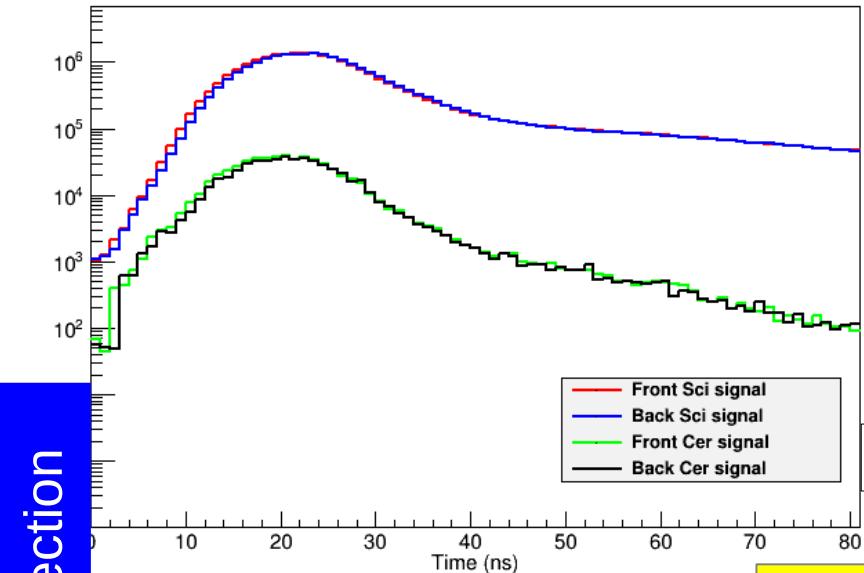
Detector type	Reconstructed Tracks (full simu)	Reconstructed Tracks (fast simu)
Det. A (no timing)	Cannot calculate	Cannot calculate
Det. B (7 ns fixed gate)	475	405
Det. C (3 ns adjustable gate)	11	8
Det. D (1 ns adjustable gate)	3	1

Full reconstruction is paramount when combinatorics is relevant

Timing Is Also The Key For Calorimetry

Time Waveform generated by MuC background (Calorimeter front section)

Time Waveform generated by MuC background (Calorimeter rear section)



Background

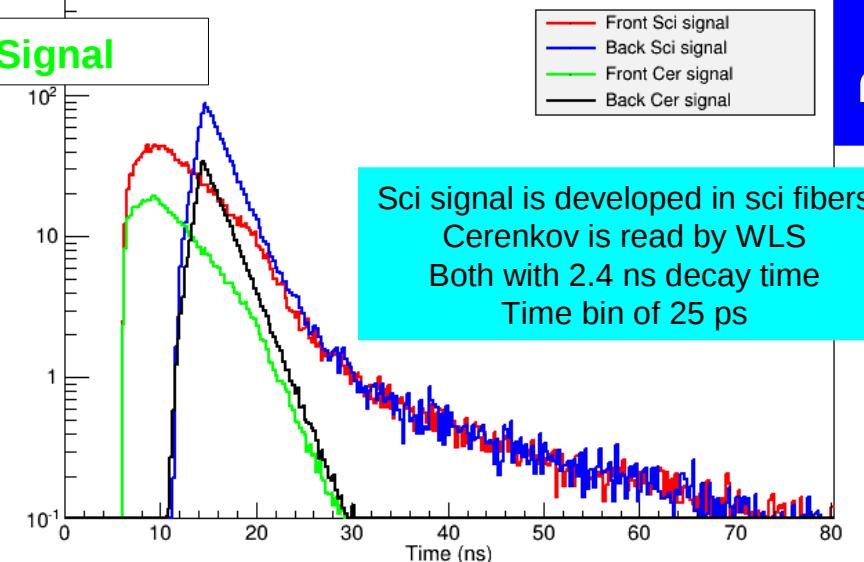
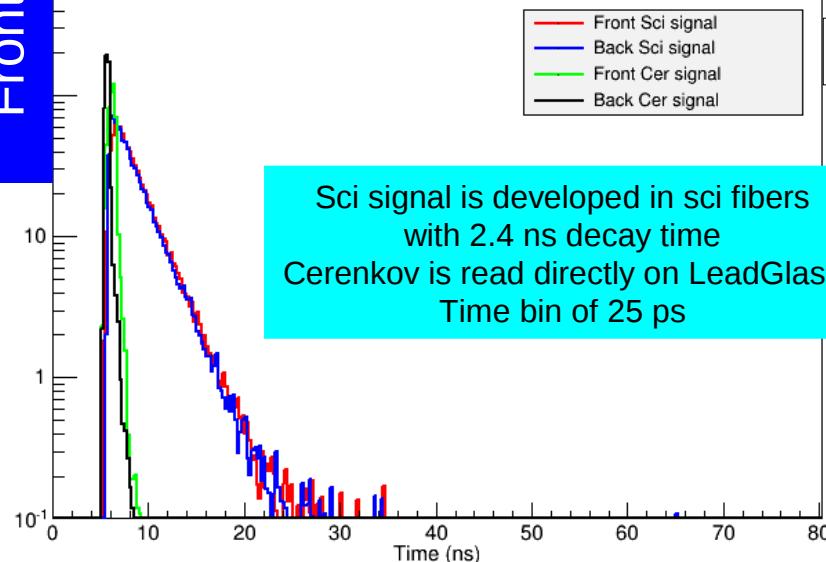
V. Di Benedetto

Average Time Waveform generated by Physics (Calorimeter front section)

Average Time Waveform generated by Physics (Calorimeter rear section)

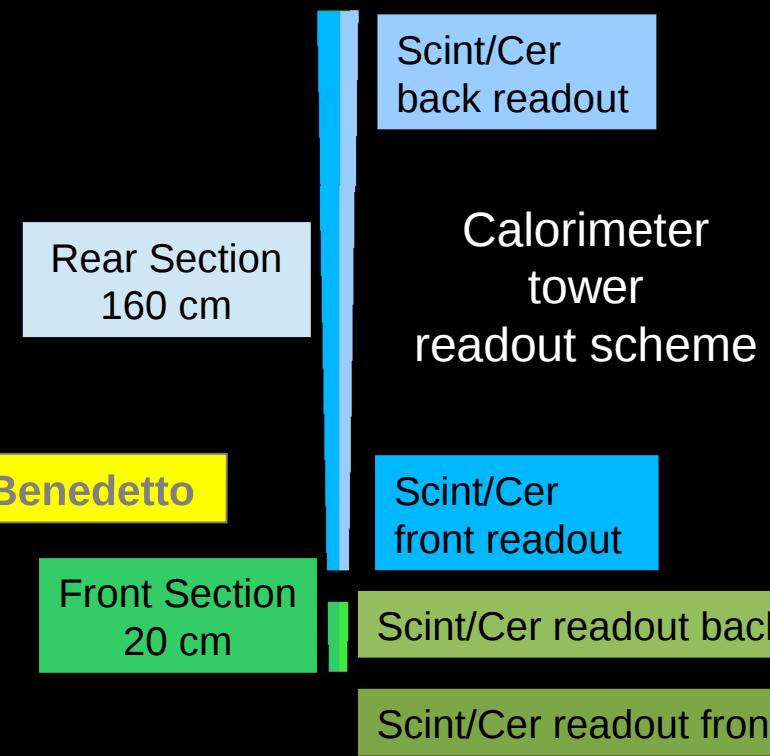
Rear Section

Signal



Background Rejection In The Calorimeter

Time gate for each section				
	Front Section		Rear Section	
	Scint	Cer	Scint	Cer
Front readout	6.3 ns	1.5 ns	12.8 ns	10.3 ns
Back readout	5.7 ns	0.8 ns	8.5 ns	7.0 ns
Signal efficiency	83%		76%	
BG suppression	98.5%		97.3%	



BG energy	Front Section		Rear Section
	Total	After time cut	
	228 TeV	3 TeV	155 TeV
			4 TeV

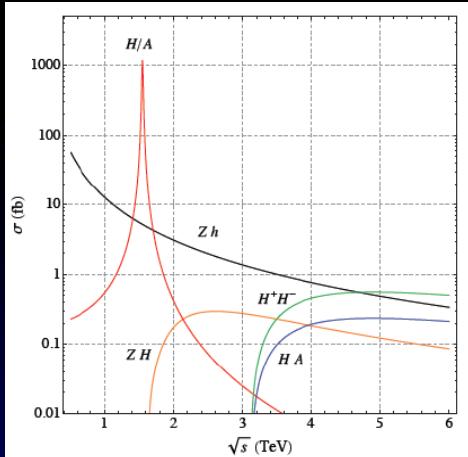
Approach to reject machine background.

- Apply time cut.
- Individuate Region of Interest (RoI), i.e. regions where the energy is 2.5σ above the background level in that region.
- In the RoI apply soft energy subtraction, i.e. subtract the mean value of the background in that region.
- In the other regions apply hard energy cut, i.e. subtract 4σ of the background.

Preliminary

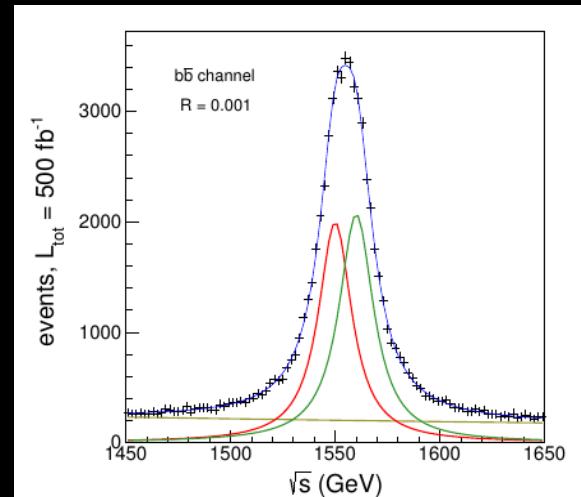
The Muon Collider as a H/A factory: Theory

- Heavy Neutral Higgses (H/A) and charged Higgses (H^\pm) are a simple possibility of New Physics beyond the Standard Model.
- H/A are likely to be difficult to find at the LHC, and at e+ e- colliders are produced in association with other particles, such as Z, since the electron Yukawa coupling is too small for s-channel production.
- The H and A can be produced as s-channel resonances at a Muon Collider.
(Eichten and Martin arXiv:1306.2609).



H/A production in the Natural Supersymmetry model compared with $Z^0 h$, $Z^0 H$ and heavy Higgs pair production.

One Resonance		
Mass(GeV)	Γ (GeV)	σ_{peak} (pb)
1555 ± 0.1 GeV	24.2 ± 0.2	1.107 ± 0.0076
$\chi^2/\text{ndf} = 363/96$		$c_1 = 0.0354 \pm 0.0006$
Two Resonances		
Mass(GeV)	Γ (GeV)	σ_{peak} (pb)
1550 ± 0.5 GeV	19.3 ± 0.7	0.6274 ± 0.0574
1560 ± 0.5 GeV	20.0 ± 0.7	0.6498 ± 0.0568
$\chi^2/\text{ndf} = 90.1/93$		$c_1 = 0.040 \pm 0.0006$



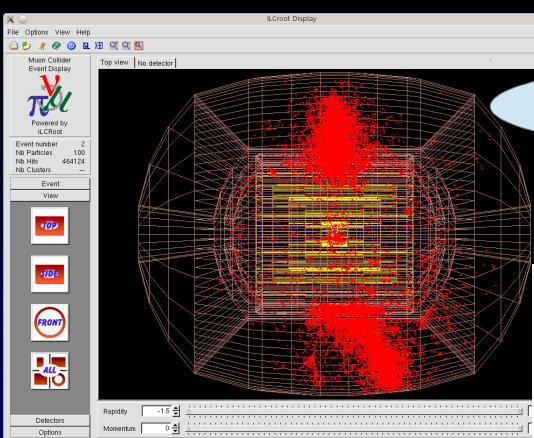
Pseudo-data (in black) along with the fit result in the $b\bar{b}$ channel. The peak signal is more than an order of magnitude larger than the physics background.

$$\sigma_B(\sqrt{s}) = c_1 \frac{(m_H m_A)}{s(\text{in TeV}^2)}$$

The Muon Collider as a H/A factory: “Reality”

- Fully simulated with track and calorimeter reconstruction in ILCroot framework 4000 H/A events generated by Pythia at $\sqrt{s} = 1550$ GeV with a Gaussian beam energy smearing ($R=0.001$) (A. Martin)
- In these preliminary studies, considered the $b\bar{b}$ decay of the H/A which is the channel with the largest BR (64%).
- Applied a perfect b-tagging (using information from MonteCarlo truth).
- Reconstructed 2 jets applying PFA-like jet reconstruction developed for ILC benchmark studies.

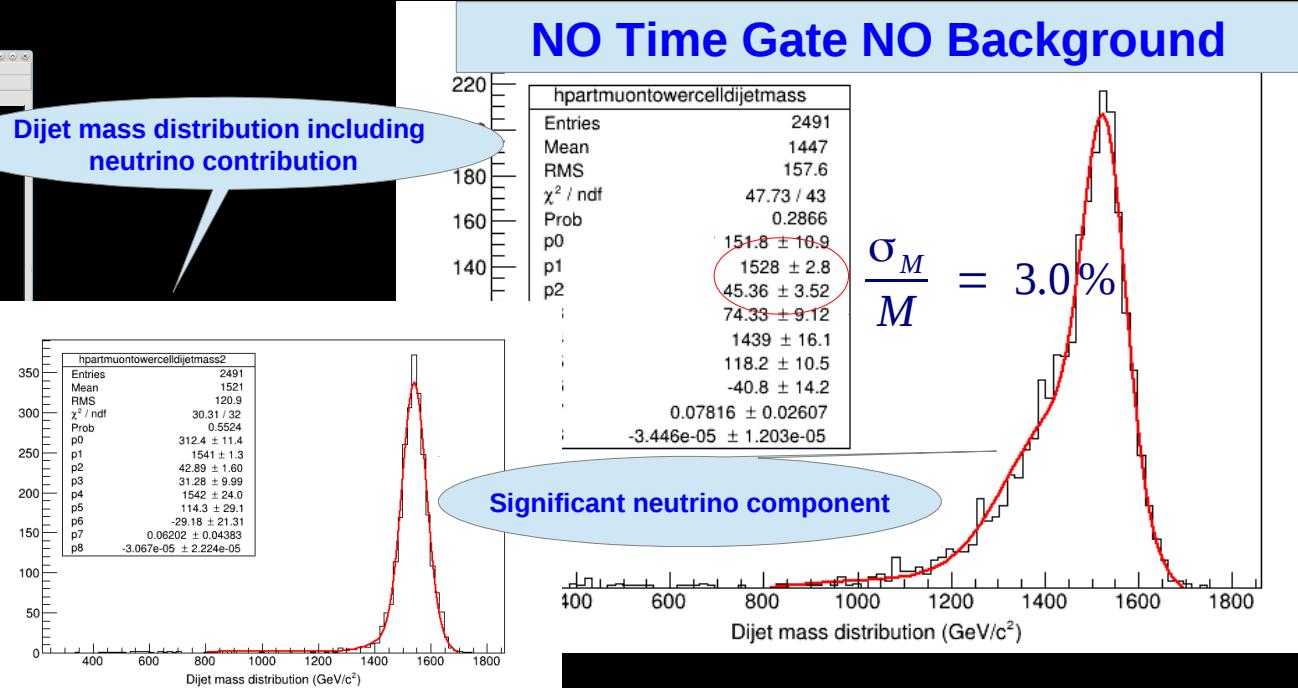
ILCroot Event Display



NO machine background

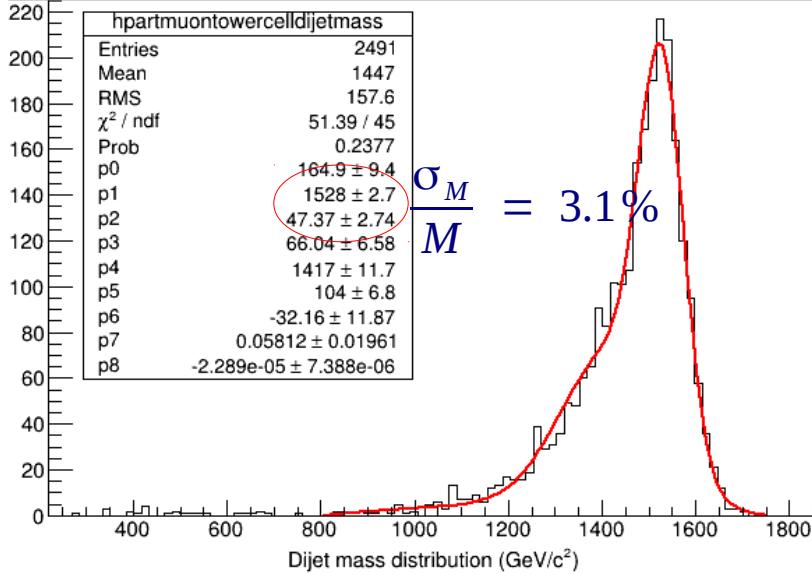
A. Mazzacane (Fermilab)

ILCroot Simulation



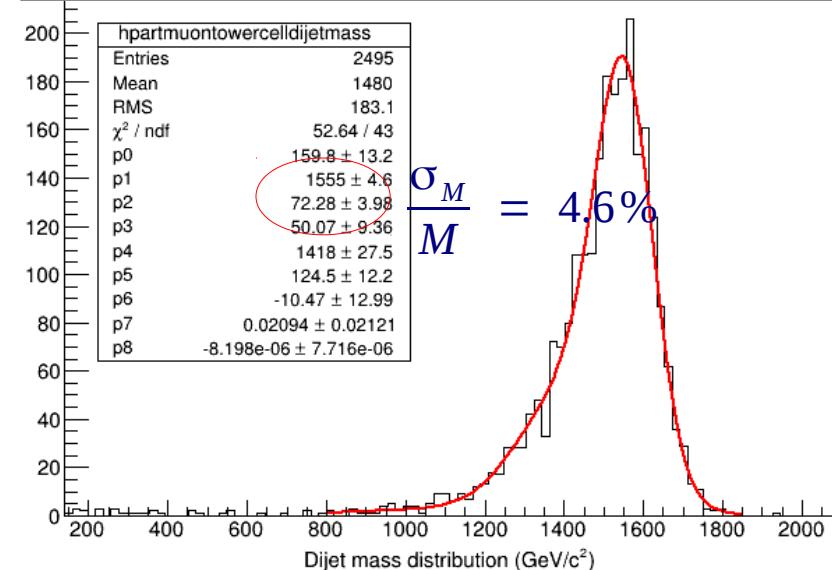
The Muon Collider as a H/A factory: “Reality” (cont'd)

YES Time Gate NO Background



- Applied 3 ns layer dependent time gate in the tracking system and the time gate shown in slide #16 in the calorimeter.

YES Time Gate YES Background



- Fully simulated signal and beam background
Applied 3ns time gate and energy cut theta dependent to further reject the background

A. Mazzacane (Fermilab)

Why MuC Detector R&D Is Important

- Background vs Physics rejection has unprecedented characteristics compared to previous HEP experiments.
 - The background is huge but out-of-time and enter in the detector with a quite uniform distribution.
 - The Machine Detector Interface (MDI) has an important role and has to be considered an integral part of the detector: i.e. the geometry changes as the shielding strategy evolves.
 - The MDI affects the physics program, especially Susy signals, by the presence of forward shielding and instrumentation.
- New detector technologies need to be exploited. Push for a new detector generation.

Tracking

- Simulations indicate the Si detectors are a good solution, but many issues have to be addressed.
- The inner radius of the vertex is set by the beam background and the shielding nozzle. But the impact parameter resolution and the physics reach are affected.
- High granularity is required to low occupancies. But charge sharing limits the pixel size.
- Fast timing is crucial. But power requirements need to be understood.

Calorimetry

- PFA would not probably work at multi-TeV energies and in a MuC environment.
- Fast Dual-Readout can be the best option, but the radiation hardness is crucial.
- LAPPD for picosecond-level resolution and excellent photon-counting capabilities.

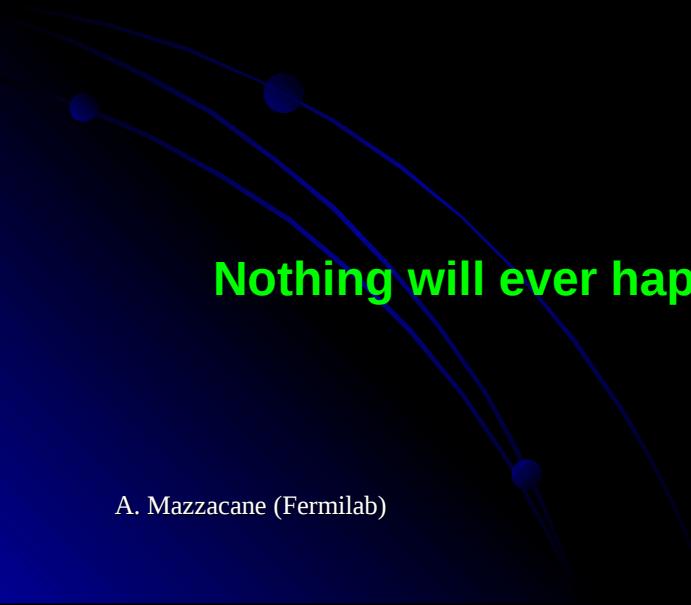
But Do Not Forget Software

- We understood many things since these studies began thanks to simulations. Therefore simulations are crucial:
 - to guide through technologies and help identifying the figure of merit for each subdetector.
 - to optimize parameters and to build prototypes to test.
- Established and already proved software architecture makes detector performance and physics studies possible in a realistic time scale and man power.

Conclusions

- Large background is expected in the detector for a Muon Collider experiment.
- Sophisticated shielding have been proposed to suppress the machine background.
- MARS15 simulation shows a reduction of the machine background ~ 3 orders of magnitude (depends on the nozzle angle).
- The baseline detector configuration for a Muon Collider has been developed in ILCroot framework and studies on the performance are well advanced.
- Full simulation and reconstruction of Si-tracking detectors and a dual-readout calorimeter are implemented in ILCroot framework (thanks to previous and detailed studies at ILC).
- Both tracking and calorimetry implemented
- The background is very nasty, even with a 10° nozzle , but it has been shown is not impossible to reach the physics goal at a Muon Collider experiment.
- Current studies show that timing cut is an effective tool to reducing the background to an acceptable level.
- However the needed timing for the Si detectors is at the limit of existing pixel devices (power consuption-cooling, material budget) and beyond the current calorimeter technology \Rightarrow Extensive R&D is needed.
- A second generation of detector and reconstruction algorithm under consideration:
 - - 3-D Si-pixel with precision timing
 - - 4-D Kalman filter
 - - segmented calorimeters with enhanced timing.

The Muon Collider is the opportunity to bring back collider physics to US soil.

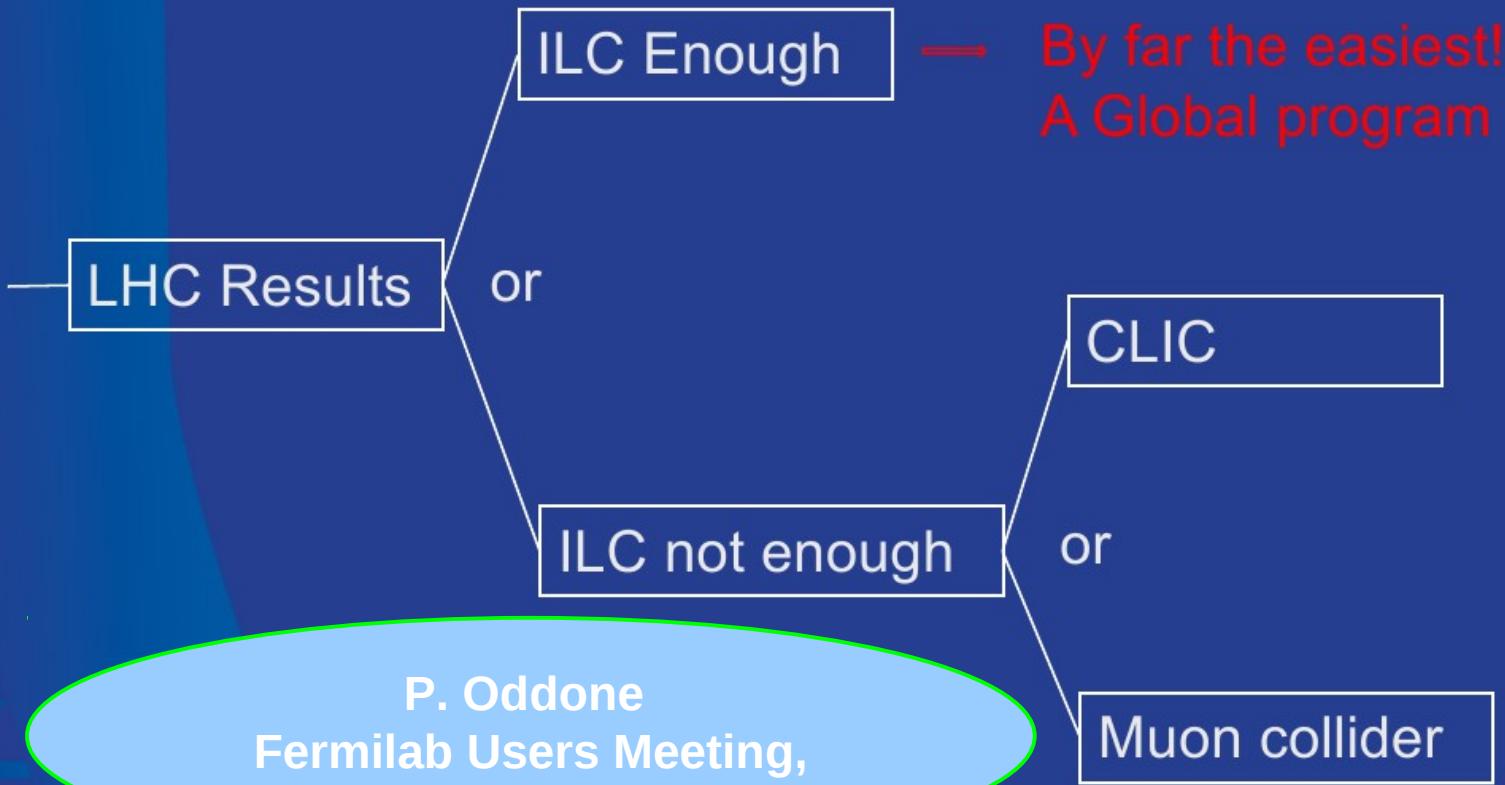


Nothing will ever happen in the future, if we don't start in the now.

Backup slides

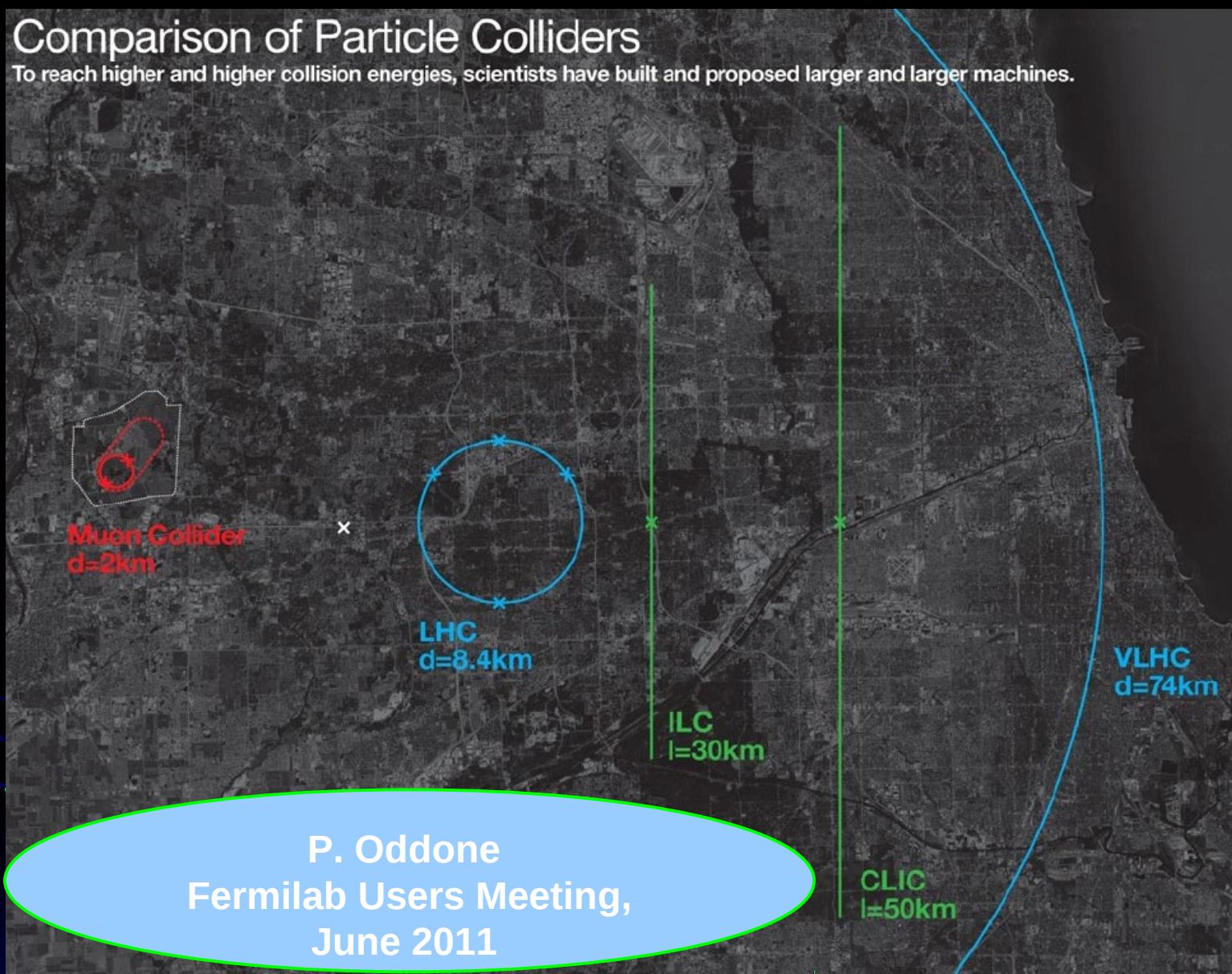


Biggest decision of the decade !



Comparison of Particle Colliders

To reach higher and higher collision energies, scientists have built and proposed larger and larger machines.



Introduction

Physics goals of a Muon Collider (MC) can only be reached with appropriate design of the ring, interaction region (IR), high-field superconducting magnets, machine-detector interface (MDI) and detector. All - under demanding requirements, arising from the short muon lifetime, relatively large values of the transverse emittance and momentum spread, unprecedented dynamic heat loads (0.5-1 kW/m) and background particle rates in collider detector.

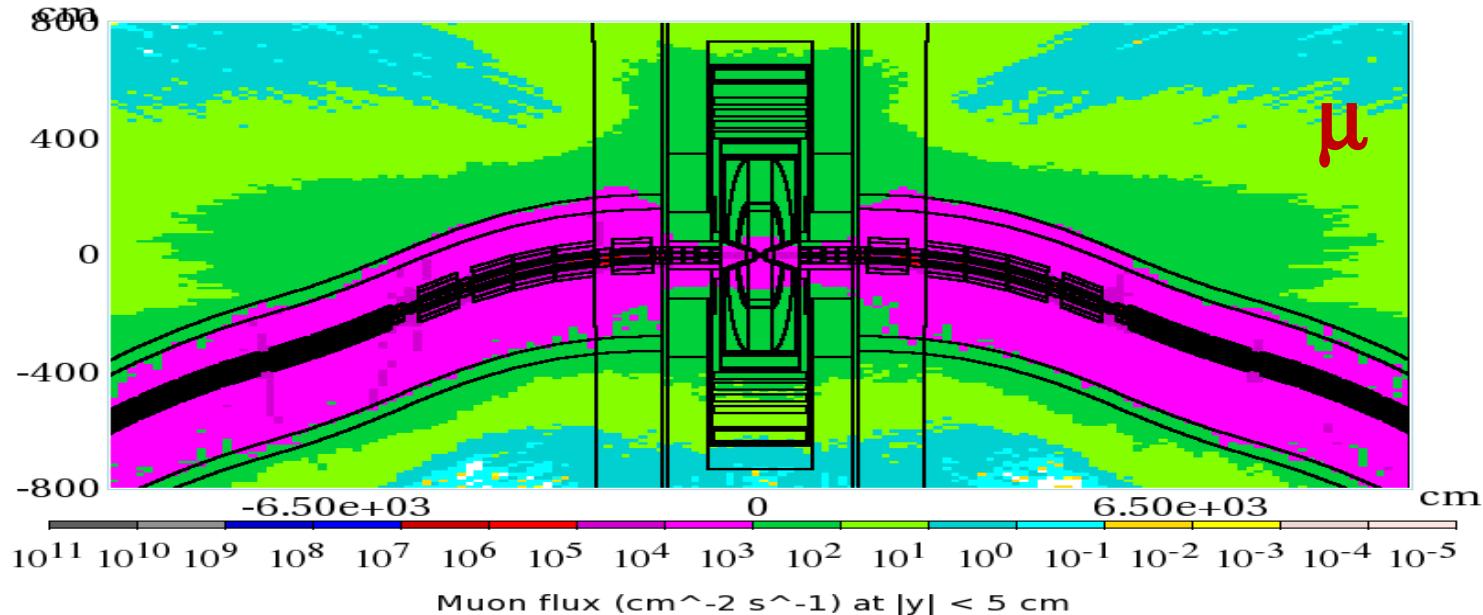
Sources of Background and Dynamic Heat Load

1. **IP $\mu^+\mu^-$ collisions:** Production x-section 1.34 pb at $\sqrt{S} = 1.5$ TeV (negligible compared to #3).
2. **IP incoherent e^+e^- pair production:** x-section 10 mb which gives rise to background of 3×10^4 electron pairs per bunch crossing (manageable with nozzle & detector B)
3. **Muon beam decays:** Unavoidable bilateral detector irradiation by particle fluxes from beamline components and accelerator tunnel - **major source** at MC: For 0.75-TeV muon beam of 2×10^{12} , 4.28×10^5 dec/m per bunch crossing, or 1.28×10^{10} dec/m/s for 2 beams; 0.5 kW/m.
4. **Beam halo:** Beam loss at limiting apertures; severe, can be taken care of by an appropriate collimation system far upstream of IP.

SUMMARY (1)

1. Backgrounds originated at IP are negligible compared to other sources: hadrons from $\mu^+\mu^-$ collisions; incoherent pairs are captured by nozzles in the solenoid field.
2. Backgrounds induced by beam halo losses exceed the limits by orders of magnitude, but can be suppressed with an appropriate collimation system.
3. Muon beam decays are the major source of backgrounds in the MC detectors. They can drastically be reduced by sophisticated collimating nozzles at IP, and sweep dipoles and collimators in a 100-m region upstream IP.

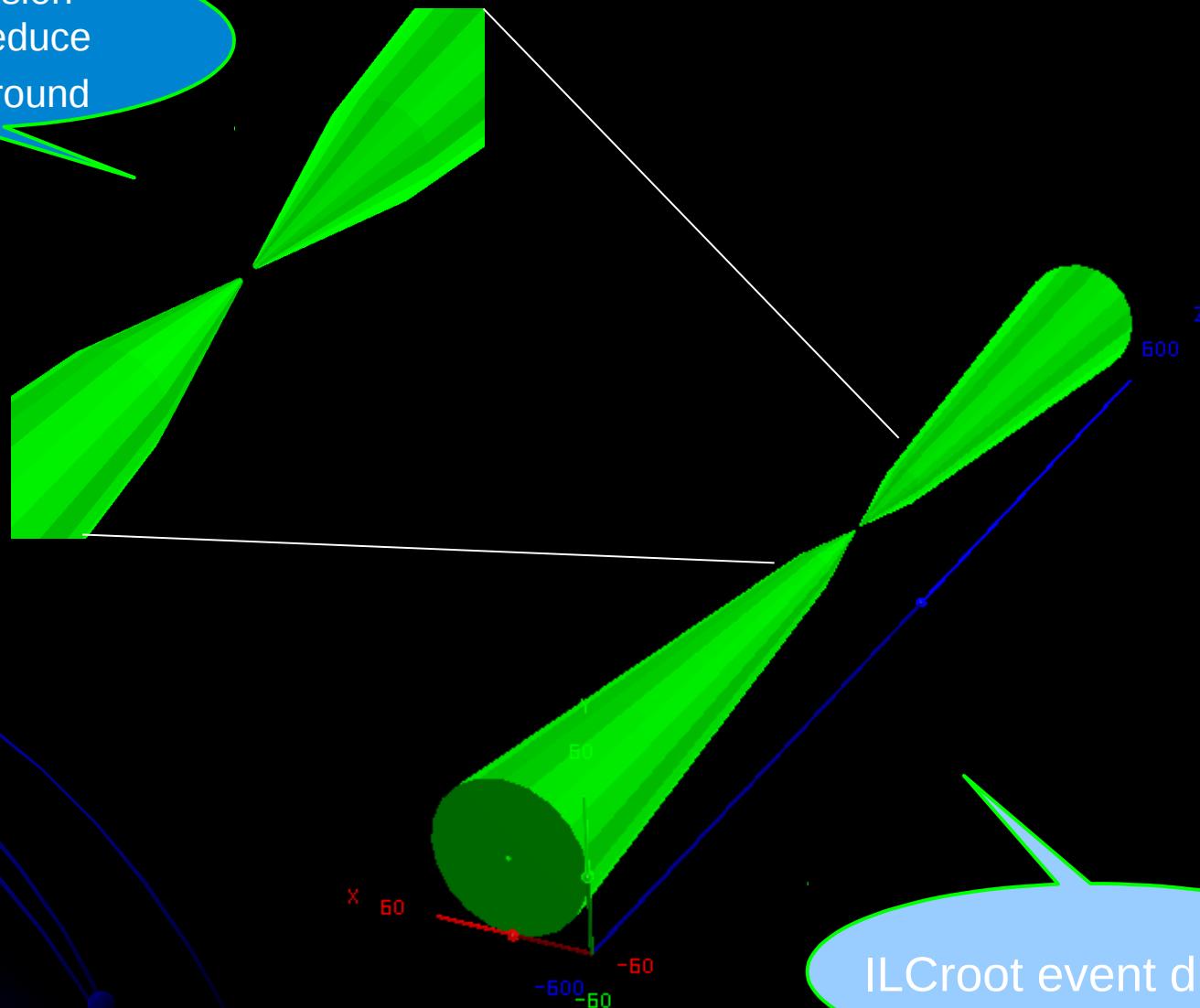
Background Suppression



Dipoles close to the IP and tungsten masks in each interconnect region help reduce background particle fluxes in the detector by a substantial factor. The tungsten nozzles, assisted by the detector solenoid field, trap most of the decay electrons created close to the IP as well as most of incoherent e^+e^- pairs generated in the IP. With additional MDI shielding, total reduction of background loads by more than three orders of magnitude is obtained.

10° Nozzle

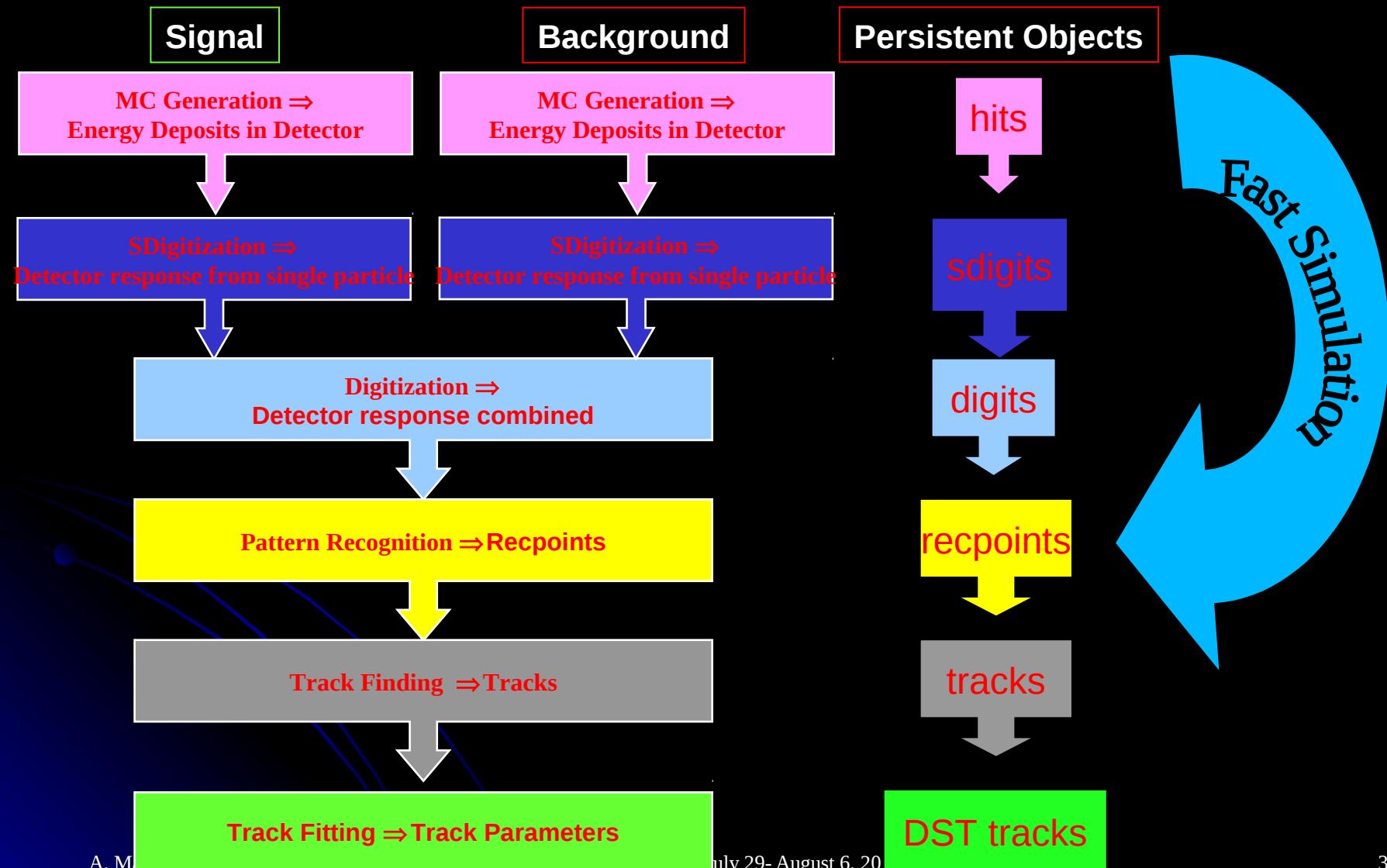
Newer version
to further reduce
MuC background



ILCroot: root Infrastructure for Large Colliders

- **Software architecture based on root, VMC & Aliroot**
 - All ROOT tools are available (I/O, graphics, PROOF, data structure, etc)
 - Extremely large community of users/developers
- **Re-allignment with latest Aliroot version every 1-2 years (v4.17 release)**
- **It is a simulation framework and an Offline Systems:**
 - Single framework, from generation to reconstruction through simulation. Don't forget analysis!!!
 - It is immediately usable for test beams
 - Six MDC have proven robustness, reliability and portability
- **Main add-ons Aliroot:**
 - Interface to external files in various format (STDHEP, text, etc.)
 - Standalone VTX track fitter
 - Pattern recognition from VTX (for si central trackers)
 - Parametric beam background (# integrated bunch crossing chosen at run time)
- Growing number of experiments have adopted it: Alice (LHC), Opera (LNGS), (Meg), CMB (GSI), Panda(GSI), 4th Concept, (SiLC ?) and LHeC
- **It is Publicly available at FNAL on ILCSIM since 2006**
- **Used for ILC, CLIC and Muon Collider studies**

Simulation steps in ILCroot: Tracking system



Fast simulation and/or fast digitization also available in ILCroot for tracking system

- Fast Simulation = hit smearing
- Fast Digitization = full digitization with fast algorithms
- Do we need fast simulation in tracking studies?

Yes!

- Calorimetry related studies do not need full simulation/digitization for tracking
- Faster computation for quick answer to response of several detector layouts/shielding

- Do we need full simulation in tracking studies?

Yes!

- Fancy detector and reconstruction needed to be able to separate hits from signal and background

Digitization and Clusterization of Si Detectors in Ilcroot: a description of the algorithms available for detailed tracking simulation and studies

Technologies Implemented

- 3 detector species:
 - Silicon pixels
 - Silicon Strips
 - Silicon Drift
- Pixel can have non constant size in different layers
- Strips can also be stereo and on both sides
- Dead regions are taken into account
- Algorithms are parametric: almost all available technologies are easily accomodated (MAPS, 3D, DEPFET, etc.)



Used for VXD SiT and
FTD
in present studies

SDigitization in Pixel Detector (production of summable digits)

- Summable digit = signal produced by each individual track in a pixel
- Loop over the hits produced in the layer and create a segment in Si in 3D
 - Step (from MC) along the line >1 μm increments
 - Convert GeV to charge and get bias voltage:
$$q = dE \cdot dt / 3.6e-9 \quad dV = \text{thick/bias voltage}$$
 - Compute charge spreading:
$$\sigma_{xy} = \sqrt{2k/e \cdot T^\circ \cdot dV \cdot L}, \quad \sigma_z = fda \cdot \sigma_{xy}$$
 - Spread charge across pixels using $\text{Erfc}(xy, z, \sigma_{xy}, \sigma_z)$
 - Charge pile-up is automatically taken into account

SDigitization in Pixels (2)

- Add coupling effect between nearby pixels row-wise and column-wise (constant probability)
- Remove dead pixels (use signal map)



Digitization in Pixels

Digit = sum of all sdigit corresponding to the same pixel

- Load SDigits from several files (signal or multiple background)
- Merge signals belonging to the same pixel
 - Non-linearity effects
 - Saturation
- Add electronic noise
- Save Digits over threshold

Clusterization in Pixel Detector

Cluster = a collection of nearby digit

Create a initial cluster from adjacent pixels (no for diagonal)

Subdivide the previous cluster in smaller NxN clusters

Reconstruct cluster and error matrix from coordinate average of the cluster

Kalman filter picks up the best cluster

Parameters used for the pixel tracking detectors in current MuX studies

Size Pixel X = 20 μm (VXD and FTD), 50 μm (SiT)

Size Pixel Z = 20 μm (VXD and FTD), 50 μm (SiT)

Eccentricity = 0.85 (fda)

Bias voltage = 18 V

cr = 0% (coupling probability for row)

cc = 4.7% (coupling probability for column)

threshold = 3000 electrons

electronics noise = 0 electrons

T° = 300 °K

Clusterization in Strip Detector

- Create a initial cluster from adjacent strips (no for diagonal)
- Separate into Overlapped Clusters
 - Look for through in the analog signal shape
 - Split signal of parent clusters among daugeter clusters
- Intersect stereo strips to get Recpoints from CoG of signals (and error matrix)
- Kalman filter picks up the best Clusters

SDigitization in Strips Detector

- Get the Segmentation Model for each detector (from `IlcVXDSegmentationSSD` class)
- Get Calibration parameters (from `IlcVXDCalibrationSSD` class)
- Load background hits from file (if any)
- Loop on the hits and create a segment in Si in 3D
 - Step along the line in equal size increments
 - Compute Drift time to p-side and n-side:

```
tdrift[0] = (y+(seg->Dy()*1.0E-4)/2)/GetDriftVelocity(0);  
tdrift[1] = ((seg->Dy()*1.0E-4)/2-y)/GetDriftVelocity(1);
```
 - Compute diffusion constant:

```
sigma[k] = TMath::Sqrt(2*GetDiffConst(k)*tdrift[k]);
```
 - integrate the diffusion gaussian from -3σ to 3σ
 - Charge pile-up is automatically taken into account

SDigitization in Strips (2)

- Add electronic noise per each side separately

```
// noise is gaussian  
noise = (Double_t) gRandom->Gaus(0,res->GetNoiseP().At(ix));
```

```
// need to calibrate noise  
noise *= (Double_t) res->GetGainP(ix);
```

```
// noise comes in ADC channels from the calibration database  
// It needs to be converted back to electronVolts  
noise /= res->GetDEvToADC(1.);
```

- Add coupling effect between nearby strips
 - different contribution from left and right neighbours
 - Proportional to nearby signals
- Remove dead pixels (use signal map)
- Convert total charge into signal (ADC count)

```
if(k==0) signal /= res->GetGainP(ix);  
else signal /= res->GetGainN(ix);  
// signal is converted in unit of ADC  
signal = res->GetDEvToADC(fMapA2->GetSignal(k,ix));
```

The Parameters for the Strips

- Strip size (p, n)
- Stereo angle (p-> 7.5 mrad, n->25.5 mrad)
- Ionization Energy in Si = 3.62E-09
- Hole diffusion constant (= 11 cm²/sec)
- Electron diffusion constant (= 30 cm²/sec)
- $v_{\text{drift}}^P (=0.86E+06 \text{ cm/sec})$, $v_{\text{drift}}^N (=2.28E+06 \text{ cm/sec})$
- Calibration constants
 - Gain
 - ADC conversion (1 ADC unit = 2.16 KeV)
- Coupling probabilities between strips (p and n)
- σ of gaussian noise (p AND n)
- threshold

Track Fitting in ILCRoot

Track finding and fitting is a global tasks: individual detector collaborate

It is performed after each detector has completed its local tasks (simulation, digitization, clusterization)

It occurs in three phases:

- Seeding in SiT and fitting in VXD+SiT+MUD
- Standalone seeding and fitting in VXD
- Standalone seeding and fitting in MUD

Two different seedings:

- Primary seeding with vertex constraint
- Secondary seeding without vertex constraint

Not yet implemented

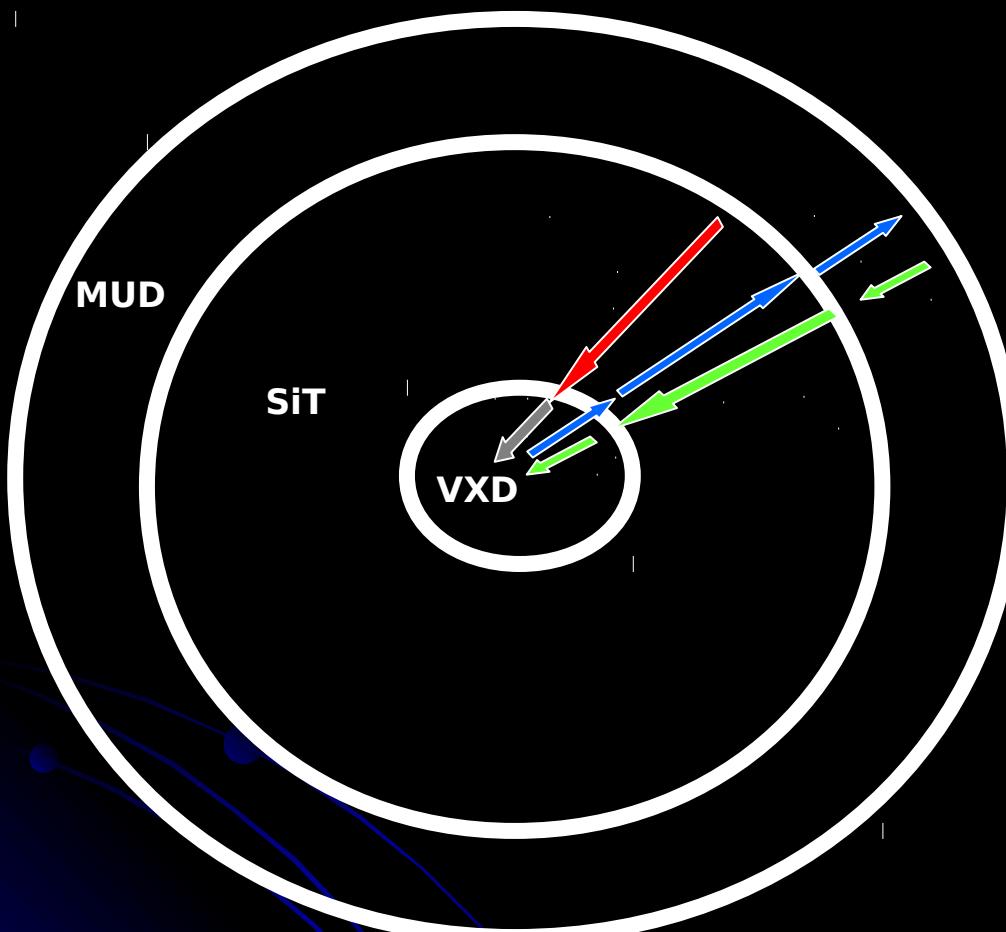
Kalman Filter (classic)

- Recursive least-squares estimation.
- Equivalent to global least-squares method including all correlations between measurements due to multiple scattering.
- Suitable for combined track finding and fitting
- Provides a natural way:
 - to take into account multiple scattering, magnetic field inhomogeneity
 - possibility to take into account mean energy losses
 - to extrapolate tracks from one sub-detector to another

Parallel Kalman Filter

- Seedings with constraint + seedings without constraint at different radii (necessary for kinks and V0) from outer to inner
- Tracking
 - Find for each track the prolongation to the next layer
 - Estimate the errors
 - Update track according current cluster parameters
 - (Possible refine clusters parameters with current track)
- Track several track-hypothesis in parallel
 - Allow cluster sharing between different track
- Remove-Overlap
- **Kinks and V0** fitted during the Kalman filtering

Tracking Strategy – Primary Tracks



- Iterative process
 - Seeding in SiT
 - Forward propagation towards to the vertex
 $\text{SiT} \rightarrow \text{VXD}$
 - Back propagation towards to the MUD
 $\text{VXD} \rightarrow \text{SiT} \rightarrow \text{MUD}$
 - Refit inward
 $\text{MUD} \rightarrow \text{SiT} \rightarrow \text{VXD}$
- Continuous seeding –track segment finding in all detectors

VXD Standalone Tracking

- Uses Clusters leftover in the VXD by Parallel Kalman Filter
- **Requires at least 4 hits to build a track**
- Seeding in VXD in two steps
 - Step 1: look for 3 Clusters in a narrow row or 2 Clusters + IP constraint
 - Step 2: prolongate to next layers each helix constructed from a seed
- After finding Clusters, all different combination of clusters are refitted with the Kalman Filter and the tracks with lowest χ^2 are selected
- Finally, the process is repeated attempting to find tracks on an enlarged row constructed looping on the first point on different layers and all the subsequent layers
- In 3.5 Tesla B-field $P_t > 20$ MeV tracks reconstructable

Tracking System Studies: Nozzle Effects on Tracking Performance

Reconstruction Efficiency & Resolutions

$$\epsilon_{tot} = \frac{\text{reconstructed tracks}}{\text{generated tracks}} = \epsilon_{geom} * \epsilon_{track}$$

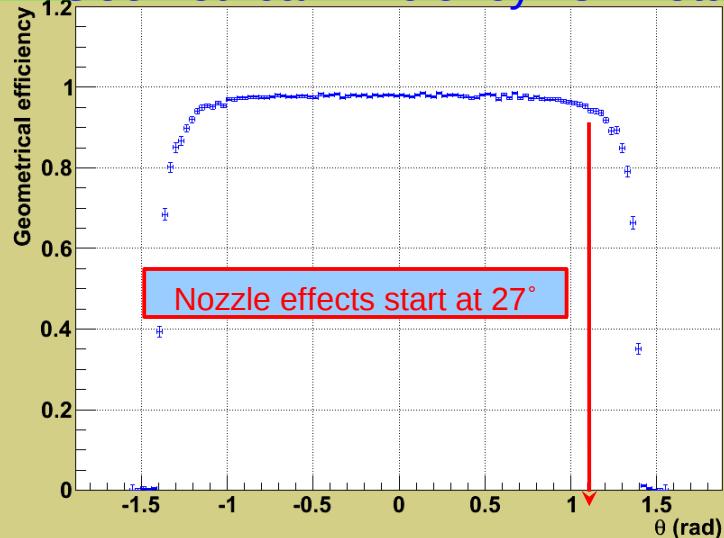
$$\epsilon_{geom} = \frac{\text{reconstructable tracks}}{\text{generated tracks}}$$

$$\epsilon_{track} = \frac{\text{reconstructed tracks}}{\text{reconstructable tracks}}$$

Defining “reconstructable tracks” (candidate for reconstruction)
tracks with $DCA(\text{true}) < 3.5 \text{ cm}$
AND
at least 4 hits in the detector

Reconstruction Efficiency for Single Muons

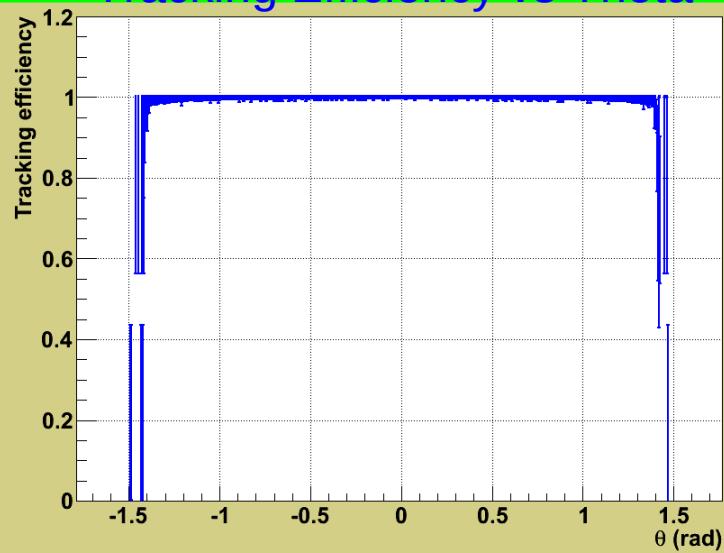
Geometrical Efficiency vs Theta



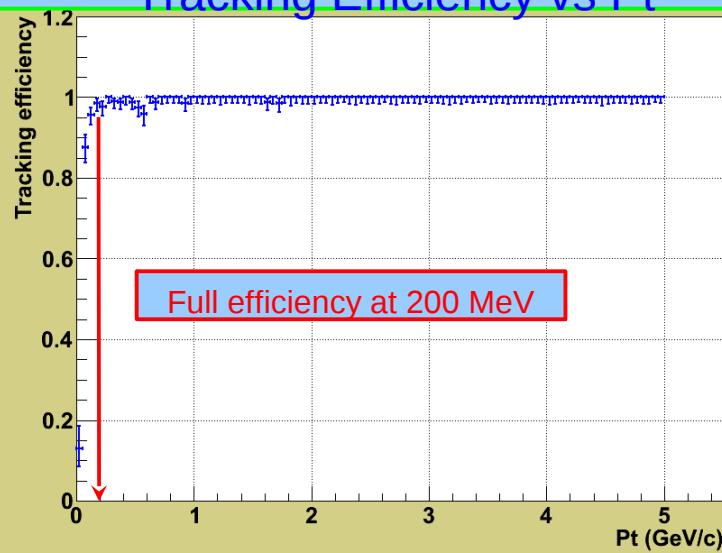
Geometrical Efficiency vs Pt



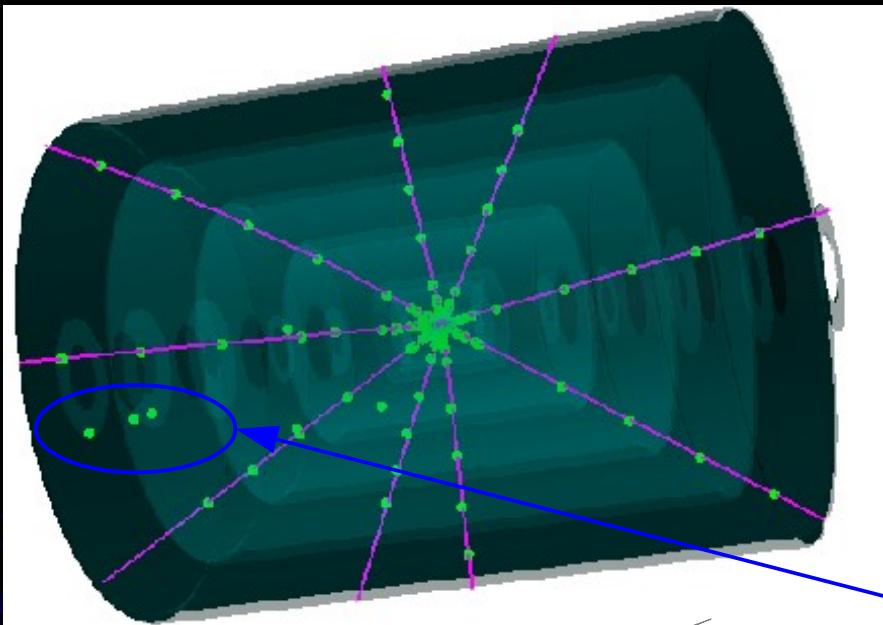
Tracking Efficiency vs Theta



Tracking Efficiency vs Pt



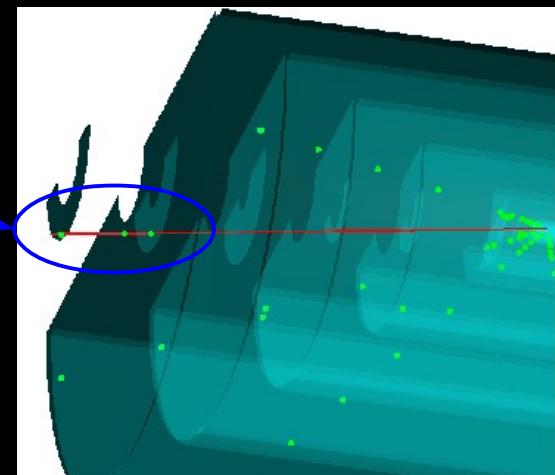
Effect of the 10° nozzle



10 generated muons
9 reconstructed tracks

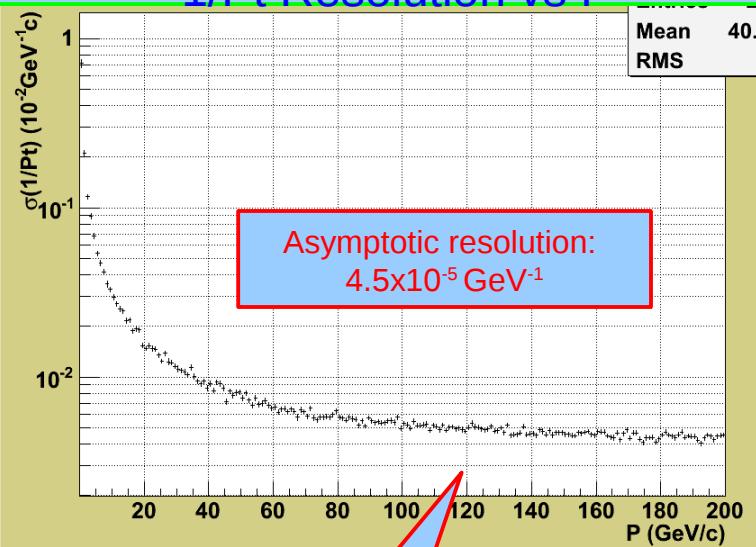
ILCroot event display
for 10 muons up to 200 GeV

green - hits
purple - reconstructed tracks
red - MC particle

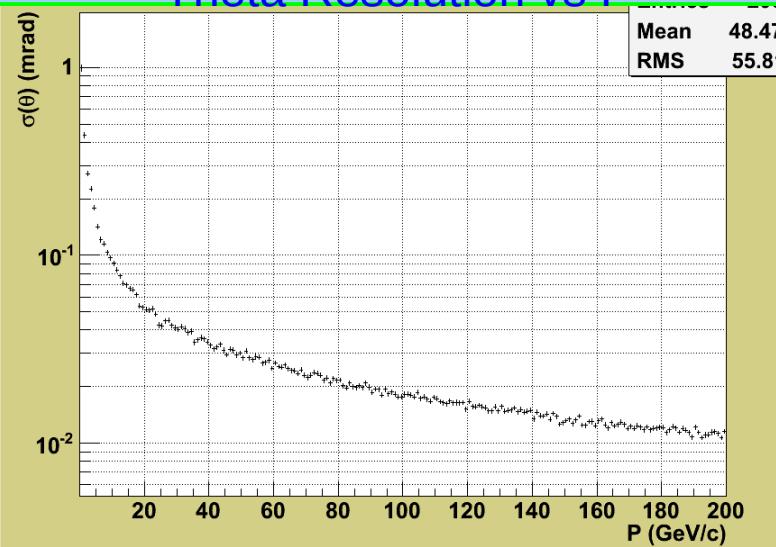


Resolutions for single muons

1/Pt Resolution vs P



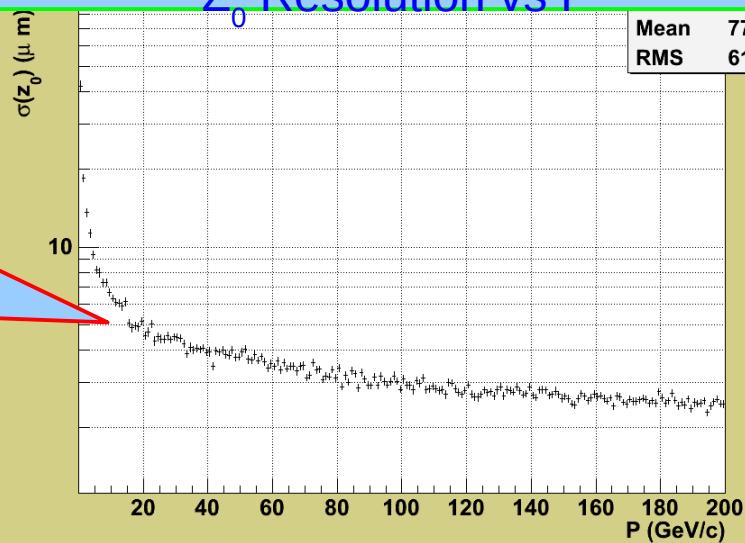
Theta Resolution vs P



Well within requirements for precision physics

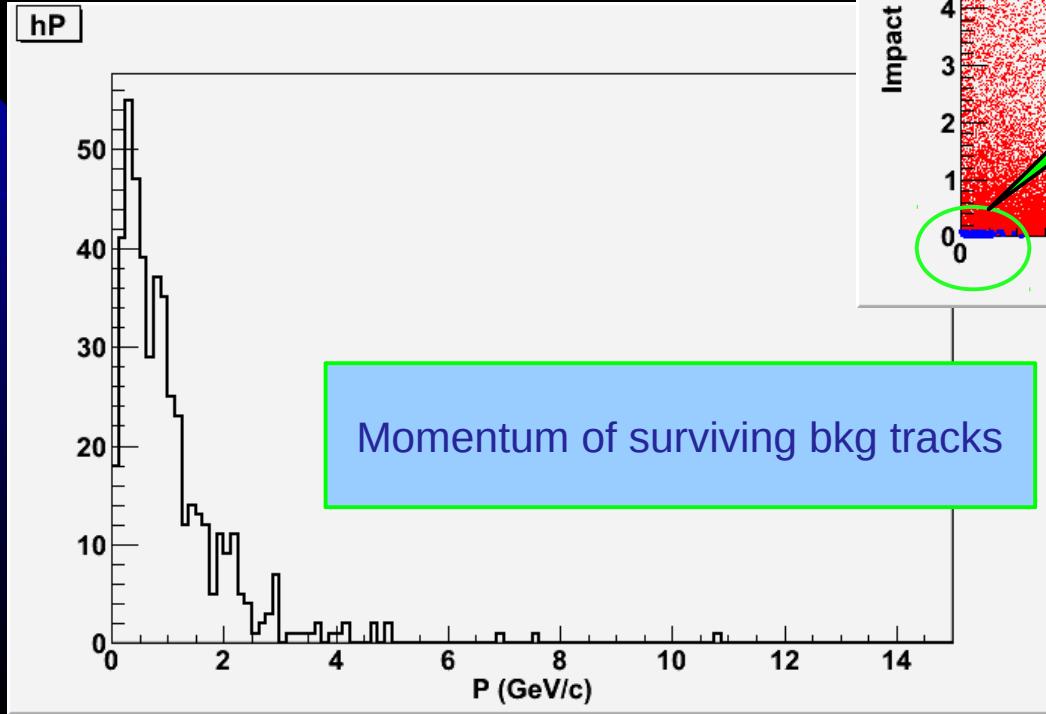
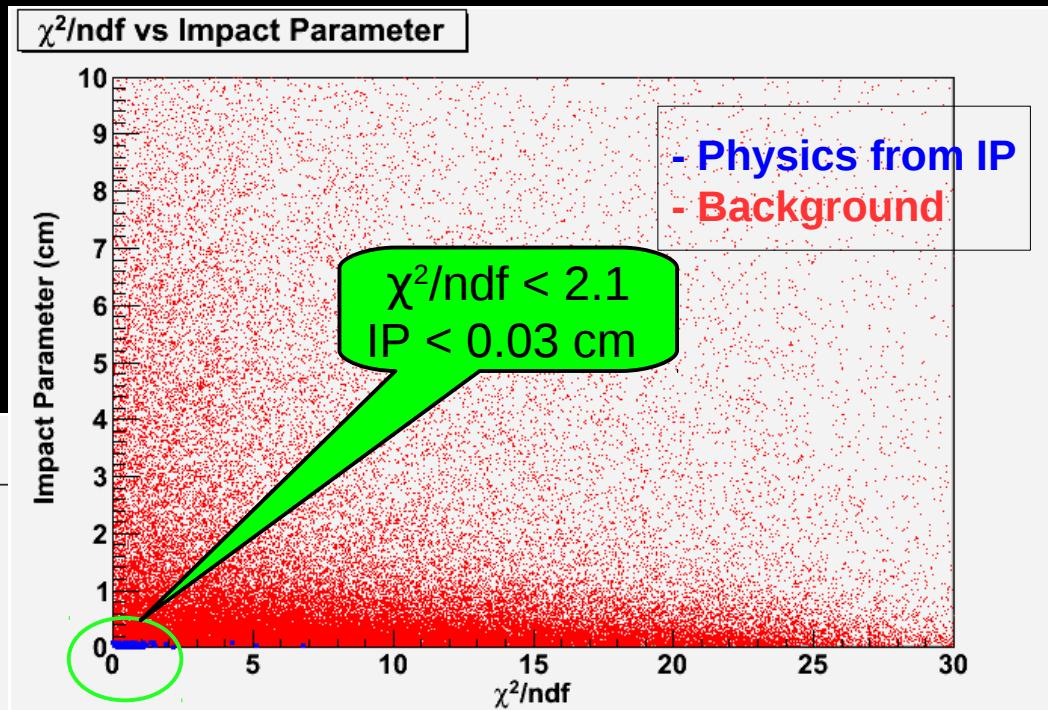
No background

Z_0 Resolution vs P



Physics vs Background in Det. B: A strategy to disentangle reconstructed tracks from IP

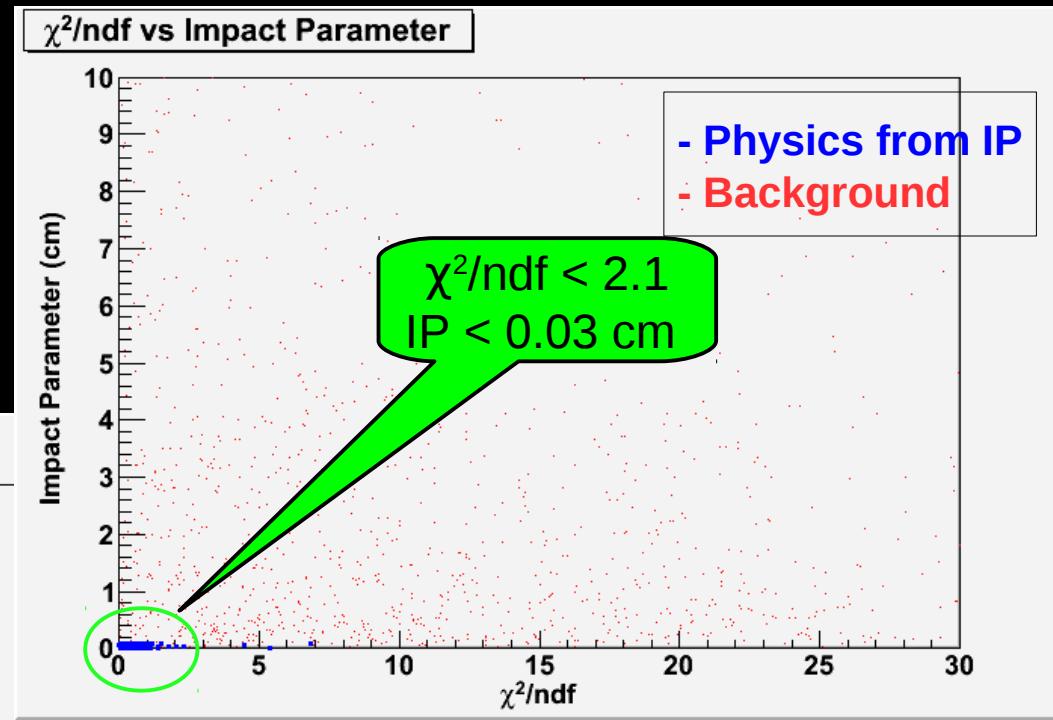
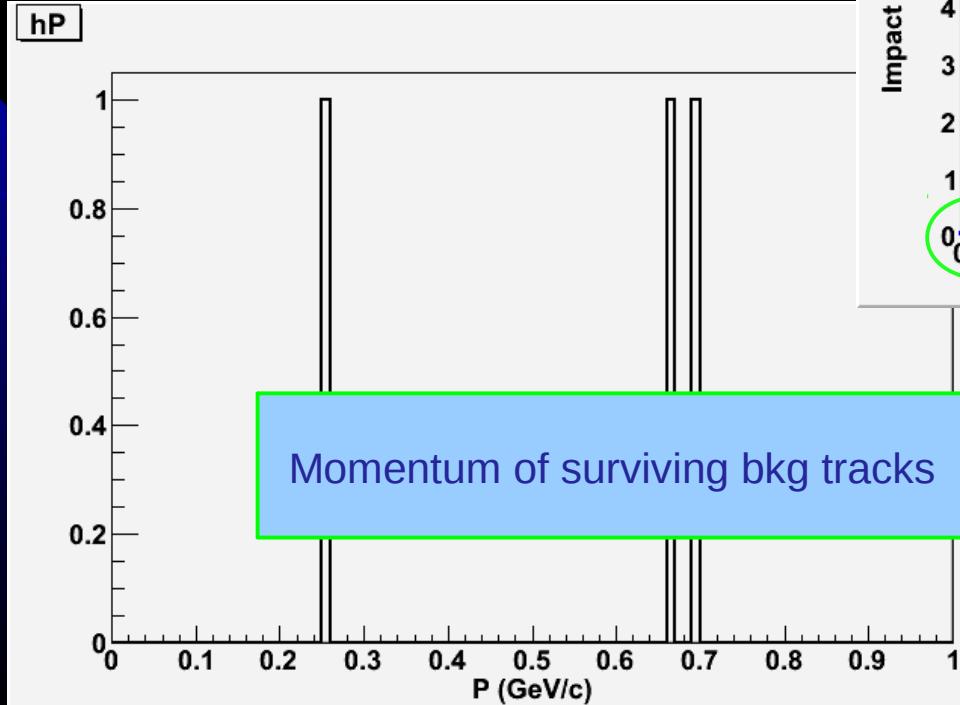
Full simulation of
physics + bkg



Det. B = Acquires data in a fixed 7 ns time gate

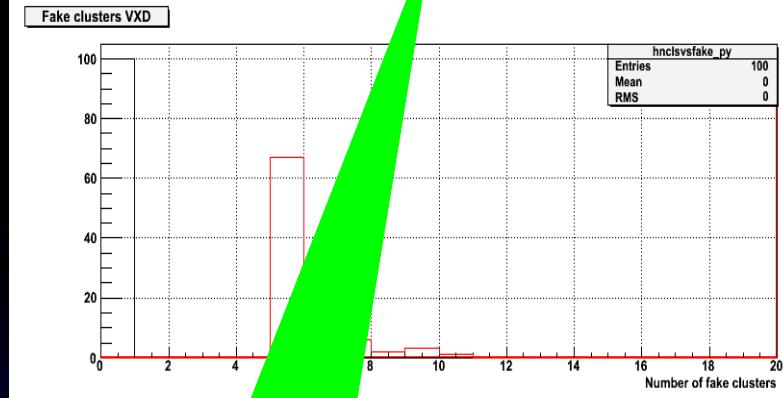
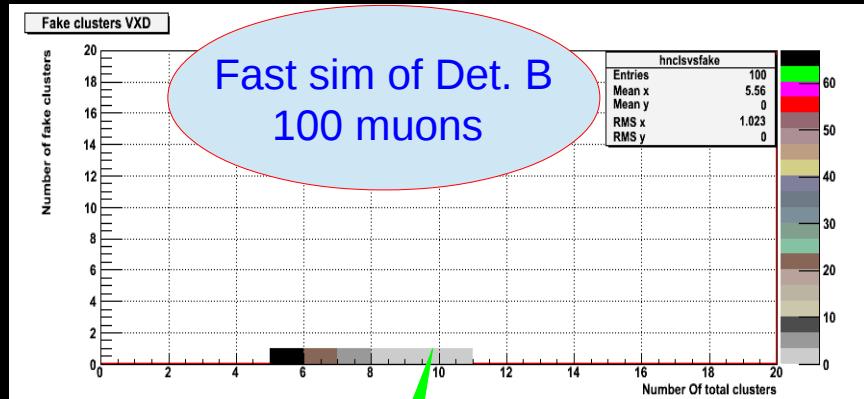
Physics vs Background in Det. D: A strategy to disentangle reconstructed tracks from IP

Full simulation of
physics + bkg

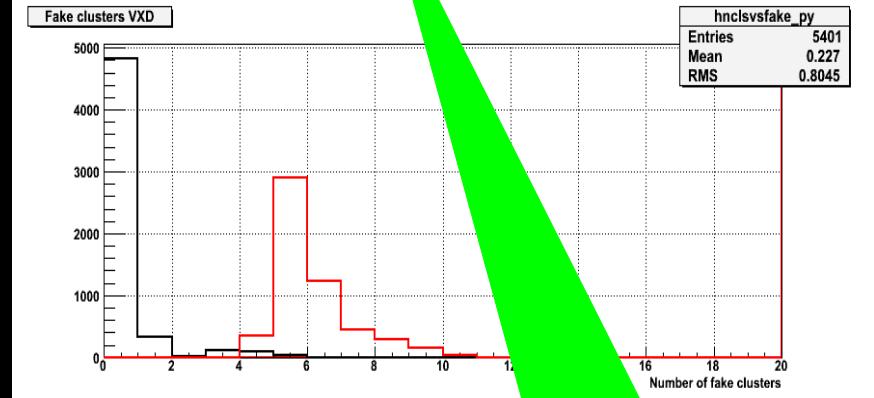
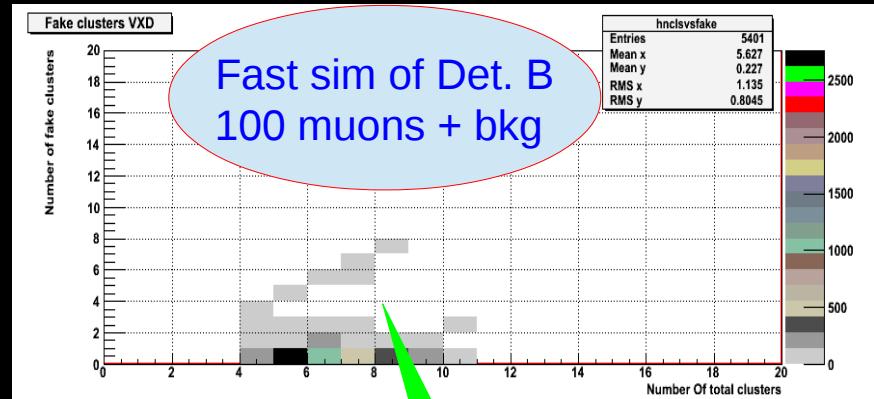


Det. D = Acquires data in variable 1 ns time gate

Effects of background Hits on Physics



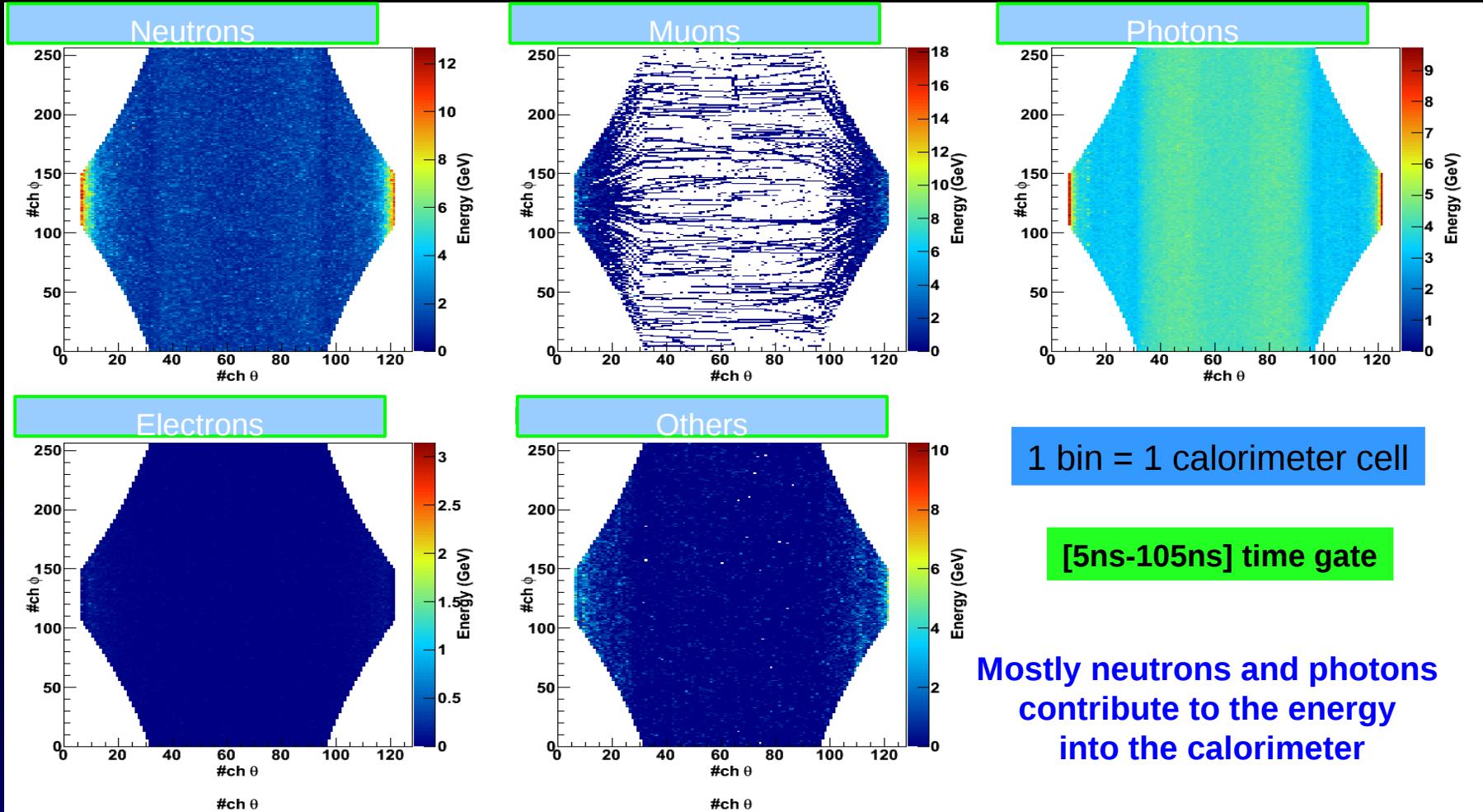
no fake cluster



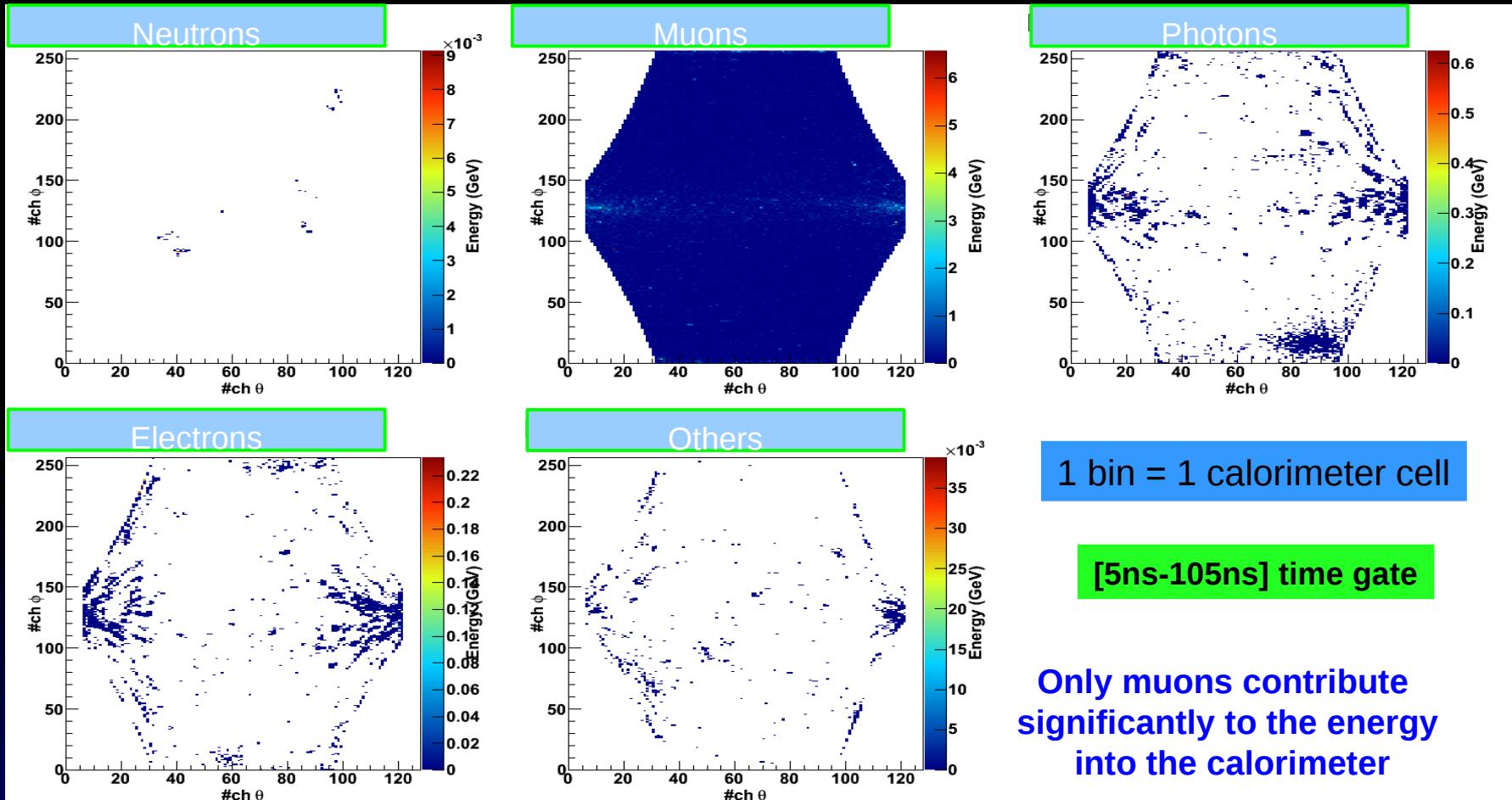
< 5% of tracks
have > 1 fake cluster

Effects on track parameter resolution are unaffected by background

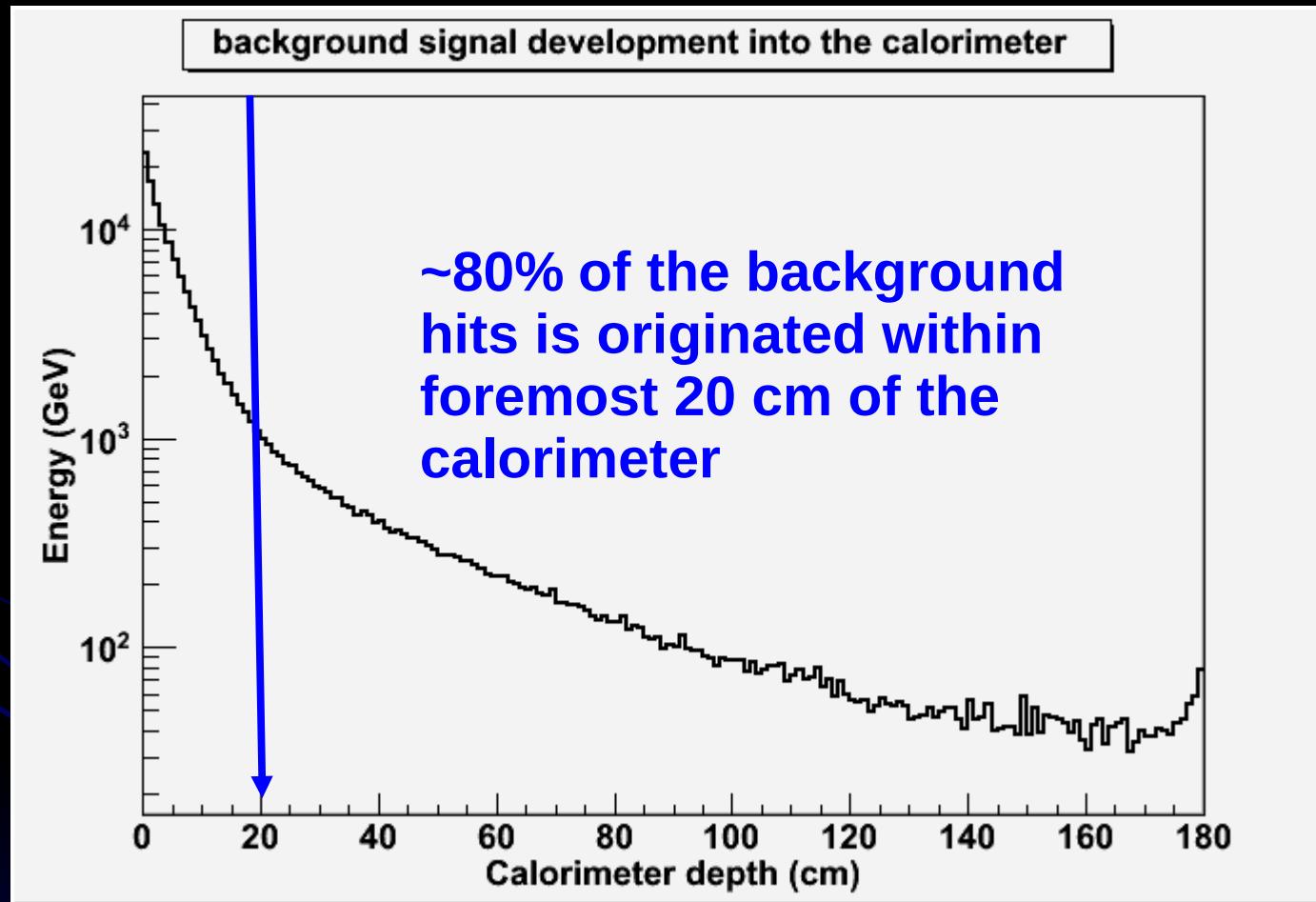
Background in the calorimeter for different particle species originating within 25 m from IP



Background in the calorimeter for different particle species originating beyond 25 m from IP



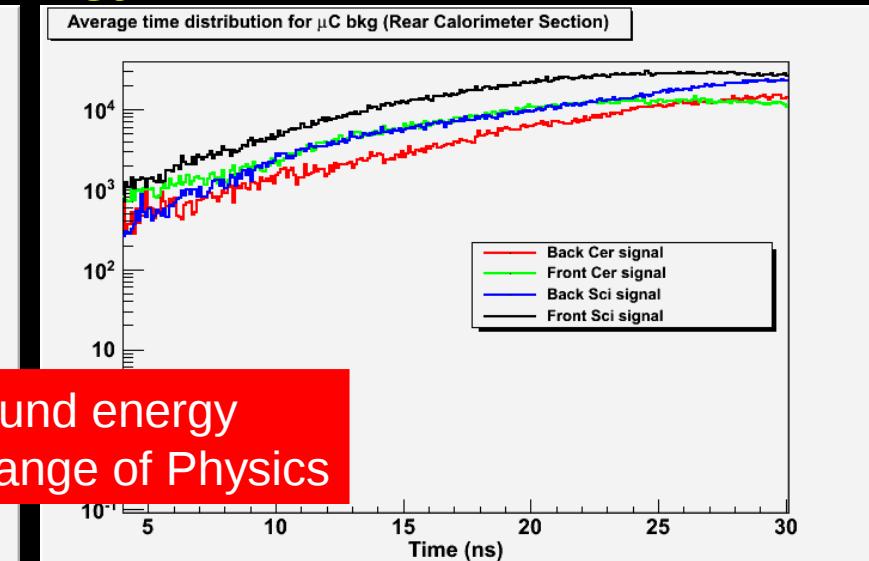
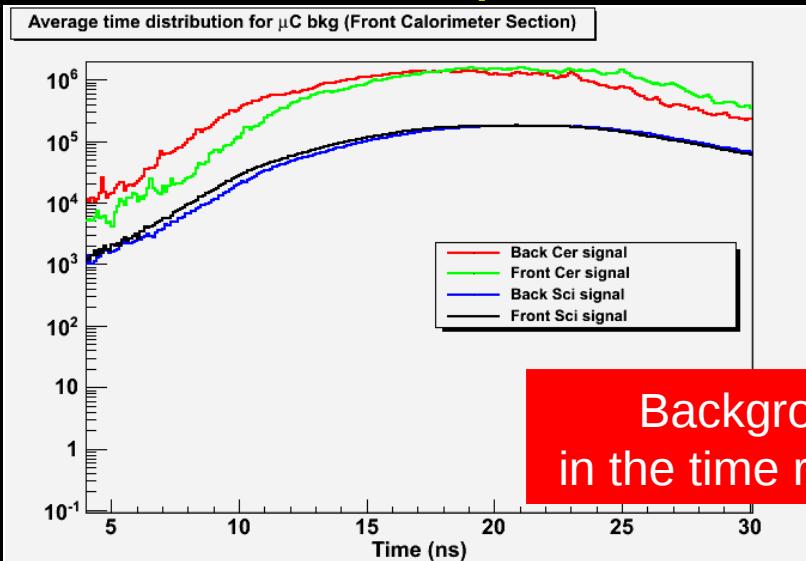
Longitudinal energy deposition produced in the calorimeter



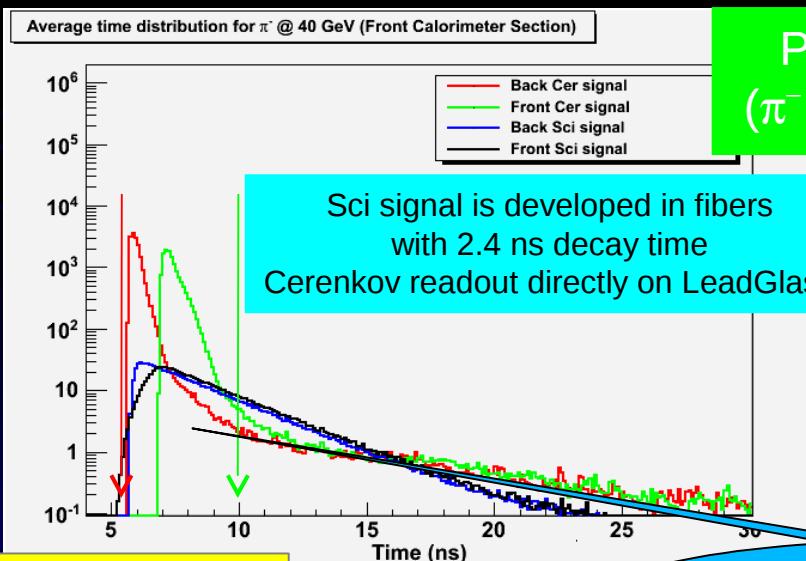
Time Distribution of MuonCollider background and IP particles energy in Calorimeter

Front Section

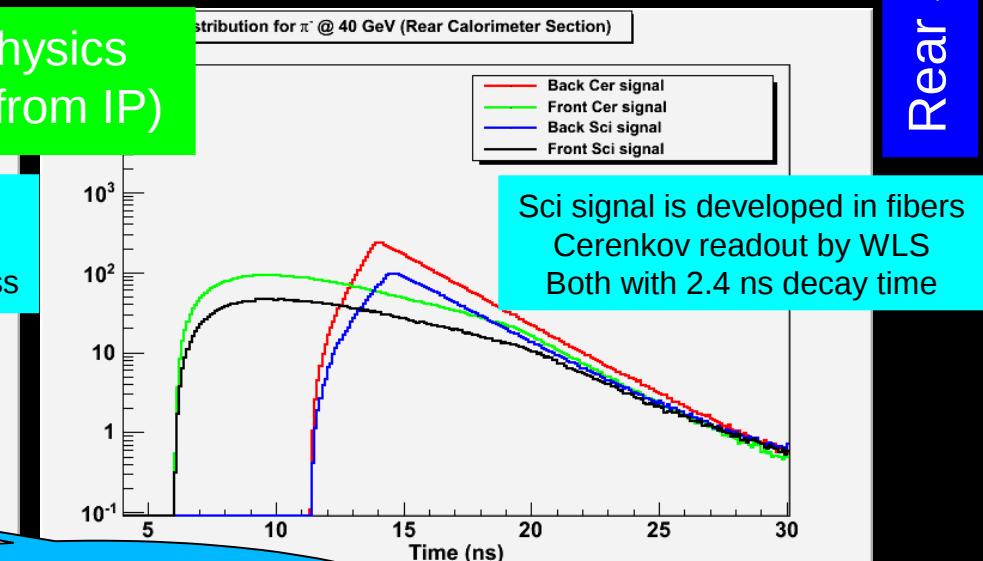
Rear Section



Background energy
in the time range of Physics



Physics
(π^- from IP)



V. Di Benedetto

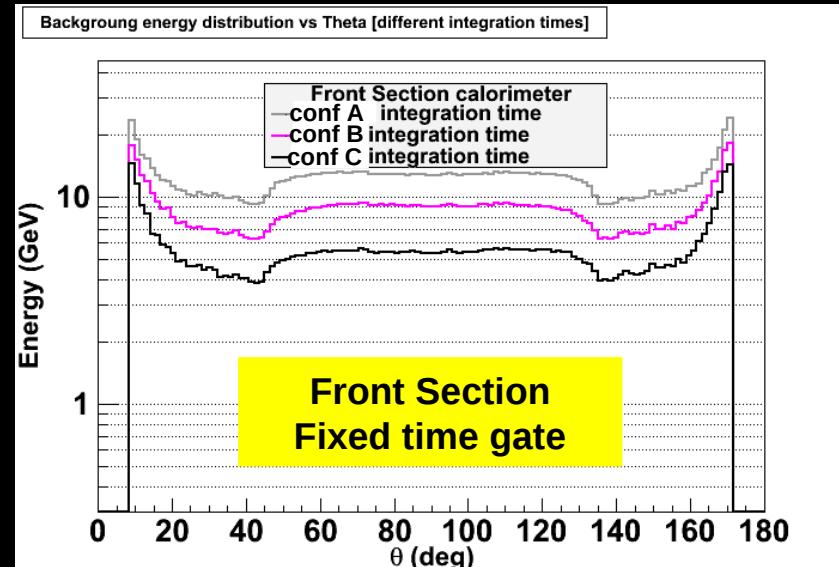
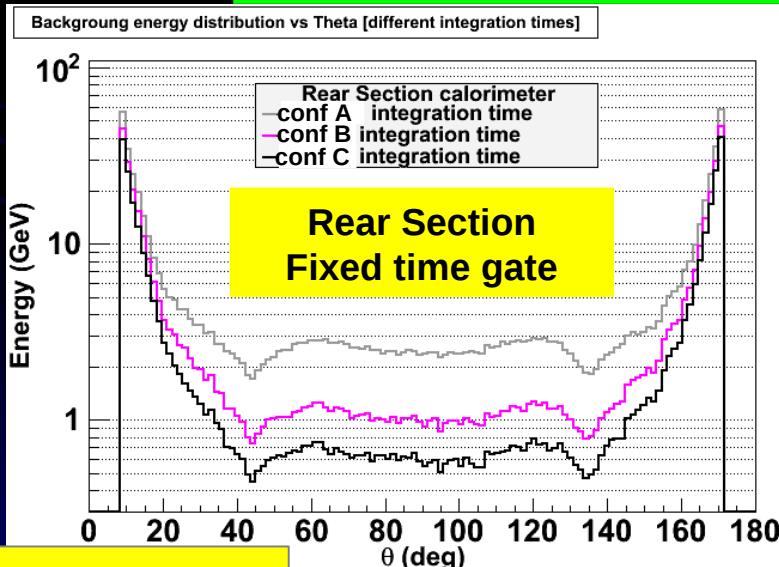
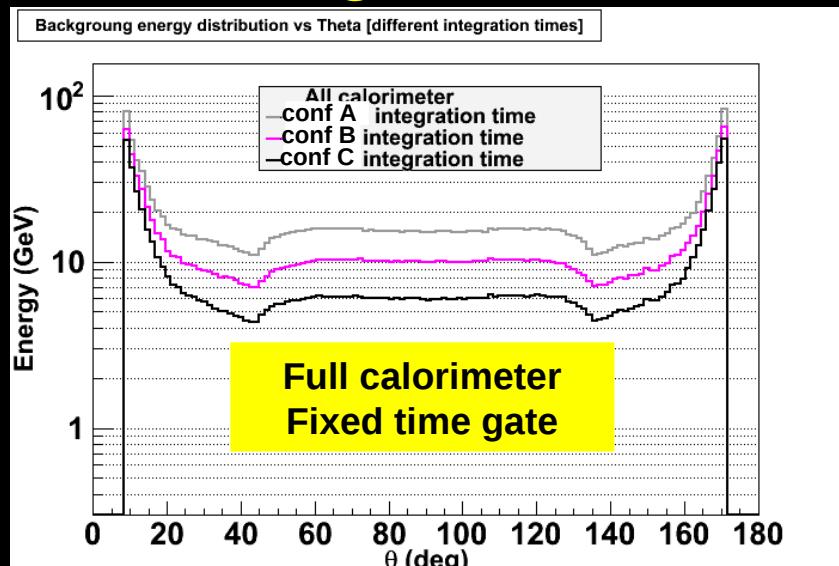
Most of physics occurs
between 5 and 10 ns

Angular distribution of background in Calorimeter for different integration time gates

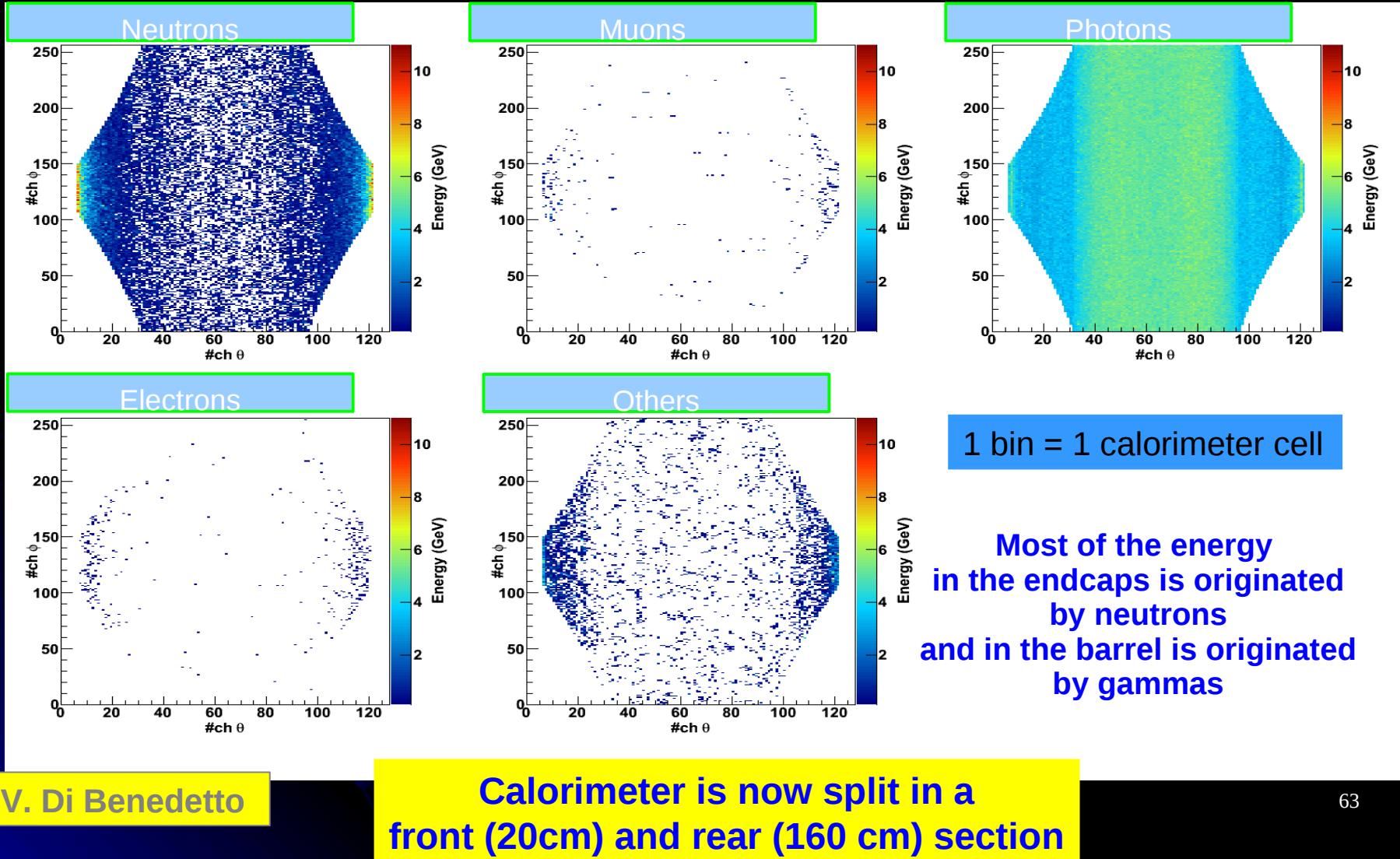
Integration time gate for each section

	Front Section		Rear Section	
	Scint	Cer	Scint	Cer
conf A	100 ns	100 ns	100 ns	100 ns
conf B	20 ns	15 ns	25 ns	25 ns
conf C	15 ns	6 ns	22 ns	22 ns

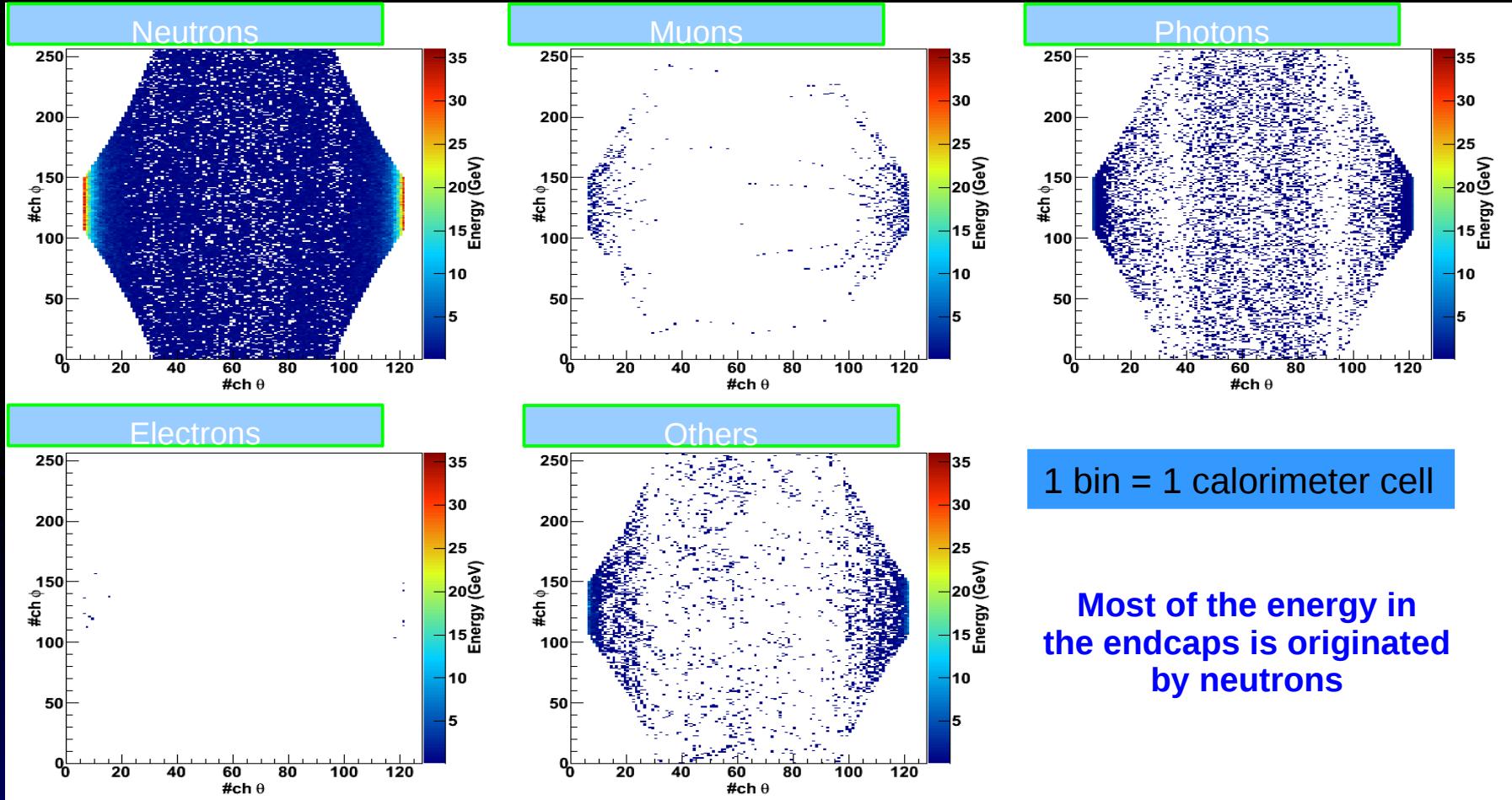
1 entry = $\langle 1 \text{ cell} \rangle|_{\varphi}$



Background energy distribution per tower Calorimeter Front Section “conf C”



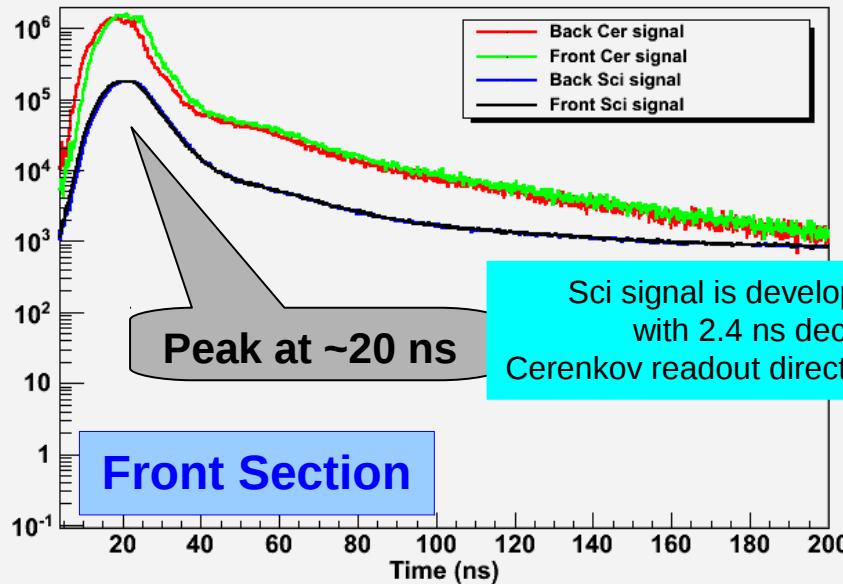
Background energy distribution per tower Calorimeter Rear Section with “conf C”



Most of the energy in
the endcaps is originated
by neutrons

Time Distribution of MuonCollider background energy in Calorimeter

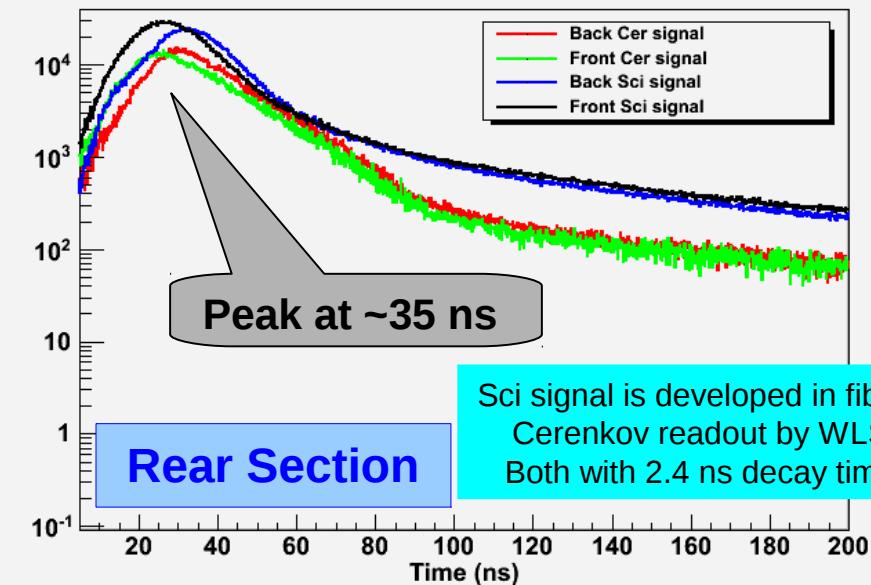
Average time distribution for μ C bkg (Front Calorimeter Section)



Calorimeter is now split in a front (20cm) and rear (160 cm) section

Light propagation in fibers and lead glass is implemented in ILCroot

Average time distribution for μ C bkg (Rear Calorimeter Section)



Sci signal is developed in fibers
Cerenkov readout by WLS
Both with 2.4 ns decay time

Preliminary Physics Studies

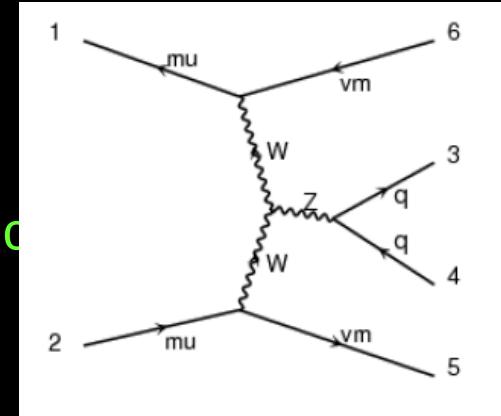
- Production of a single Z^0 in a fusion process:

$$\mu^+ \mu^- \rightarrow \nu_\mu \bar{\nu}_\mu + Z^0 \rightarrow \nu_\mu \bar{\nu}_\mu q \bar{q}$$

- How well can the invariant mass of the Z^0 be reconstructed from its decay into two jets?
- In particular, could the Z^0 be distinguished from a W^\pm decaying into two jets in the process

$$\mu^+ \mu^- \rightarrow \mu^- \bar{\nu}_\mu + W^\pm$$

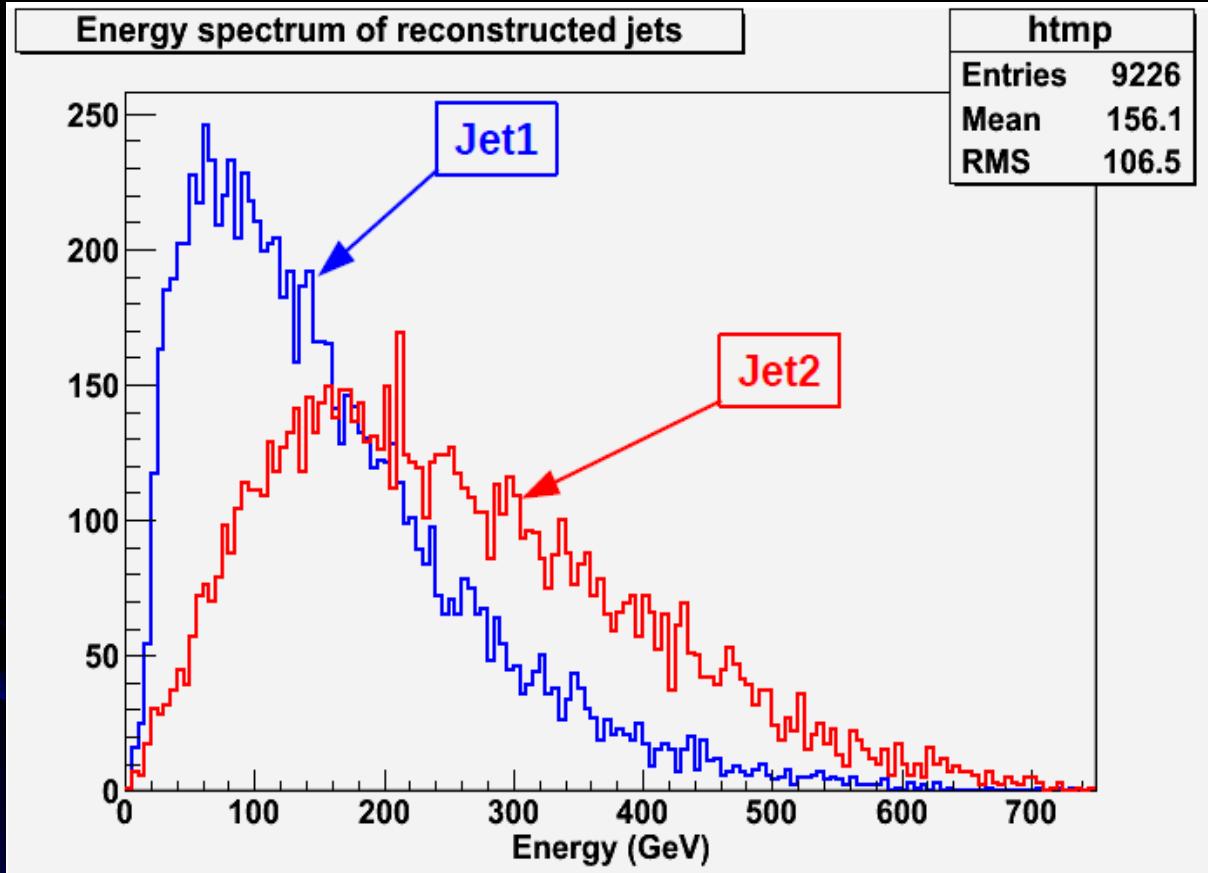
- if the forward μ^- is not tagged?
- Madgraph and MARS15 as event generators (sig & bkg)
- ADRIANO calorimeter used in this study
- Recursive jet finder (from ILC studies)
- Full simulation, digitization and reconstruction**



$\mu^+ \mu^- \rightarrow \nu_\mu \bar{\nu}_\mu Z^0 @1.5\text{TeV}$
↓ jet, jet

Jet's are originated by light quarks (u,d,s)

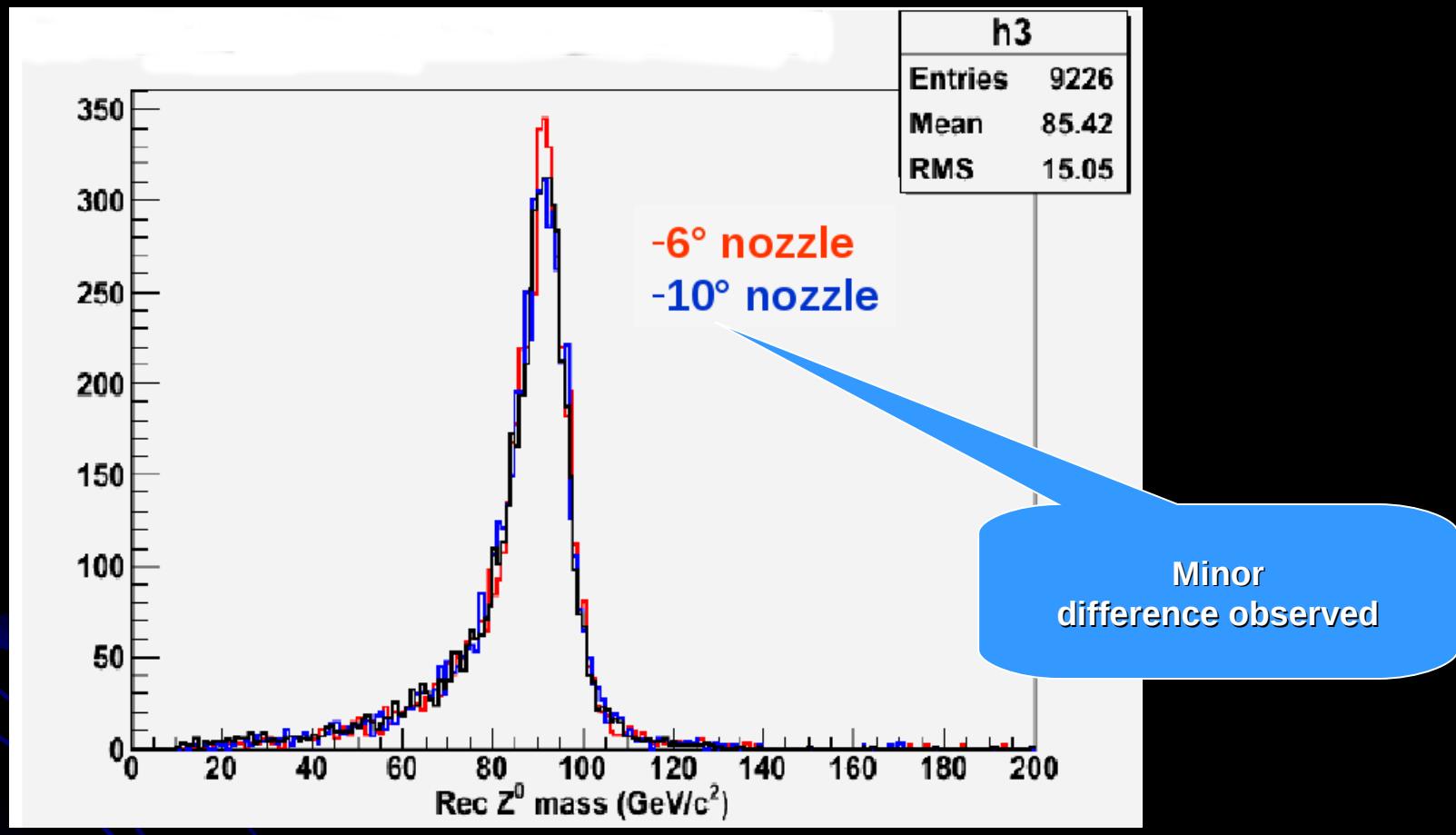
Jets Reconstruction



Jet finder algorithm

- Divide jet in 2 non-overlapping regions:
 - Core: region of the calorimeter with nearby clusters
 - Outliers: isolated clusters
- Identify the core energy:
 - using calorimetric informations
- Identify the jet axis:
 - using infos from the tracking systems
- Reconstruct Outliers individually using:
 - trackers if calo and trackers have match clusters
 - Calo for neutral outliers
- Recursive algorythm

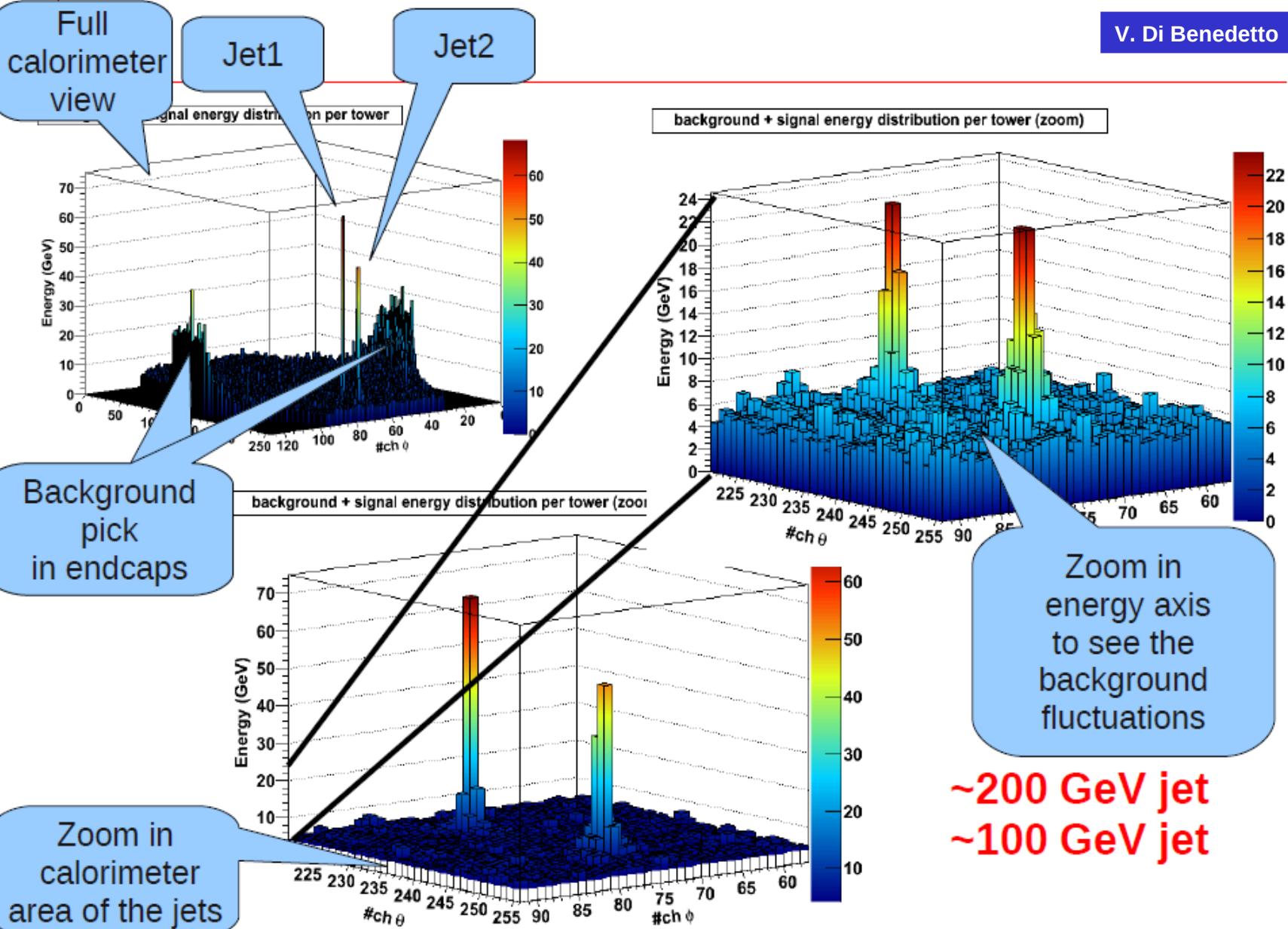
Z^0 Mass with Different Nozzles



Fully reconstructed
 Z^0 mass (bin=1 GeV)
No cuts applied
No leakage corrections

Merging Signal + Background

V. Di Benedetto



Baseline Detector for Muon Collider Studies
Timing Is The Key
Strategies To Reduce Clusters In The Tracking System
Produced By The Machine Background
Reconstructed Background Tracks
(from Kalman filter)
Dual-Readout Projective Calorimeter
Why MuC Detector R&D Is Important
But Do Not Forget Software
Conclusions
Backup slides
Introduction
Muon Collider Parameters
Sources of Background and Dynamic Heat Load
Background Suppression
10° Nozzle
ILCroot: root Infrastructure for Large Colliders
Simulation steps in ILCroot:
 Tracking system
Fast simulation and/or fast digitization also available in ILCroot for tracking system
Digitization and Clusterization
 of Si Detectors in ILCroot:
 a description of the algorithms available for detailed tracking simulation and studies
Technologies Implemented
SDigitization in Pixel Detector
(production of summable digits)
SDigitization in Pixels (2)
Digitization in Pixels
Clusterization in Pixel Detector
Parameters used for the pixel tracking detectors in current MuX studies
Clusterization in Strip Detector
SDigitization in Strips Detector
SDigitization in Strips (2)
The Parameters for the Strips
Track Fitting in ILCRoot
Kalman Filter (classic)
Parallel Kalman Filter
VXD Standalone Tracking
Effect of the 10° nozzle
Physics vs Background in Det. B:
 A strategy to disentangle reconstructed tracks from IP
Physics vs Background in Det. D:
 A strategy to disentangle reconstructed tracks from IP
Reconstructed Background Tracks
(from Kalman filter) after 2 and IP cuts
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Background in the calorimeter for different particle species originating within 25 m from IP
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