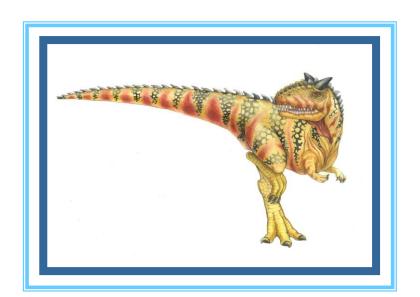
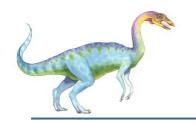
Chapter 4: Threads

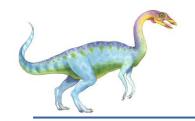




Chapter 4: Threads

- Overview
- Multithreading Models
- Thread Libraries
- Threading Issues
- Operating System Examples
- Windows XP Threads
- Linux Threads

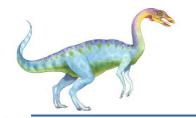




Objectives

- □ To introduce the notion of a thread a fundamental unit of CPU utilization that forms the basis of multithreaded computer systems
- □ To discuss the APIs for the Pthreads, Win32, and Java thread libraries
- To examine issues related to multithreaded programming

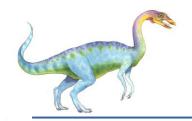




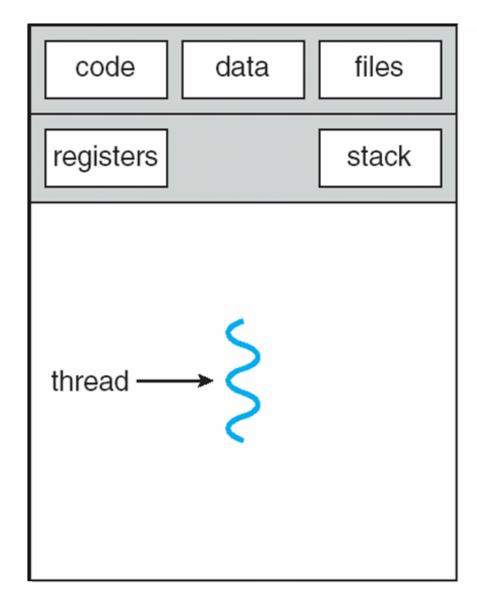
Motivation

- ☐ Threads run within application
- Multiple tasks with the application can be implemented by separate threads
 - Update display
 - Fetch data
 - Spell checking
 - Answer a network request
- Process creation is heavy-weight while thread creation is light-weight
- Can simplify code, increase efficiency
- Kernels are generally multithreaded

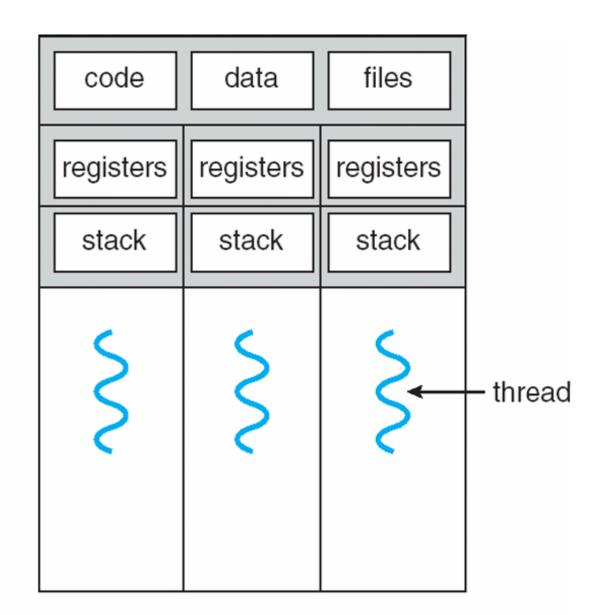




Single and Multithreaded Processes

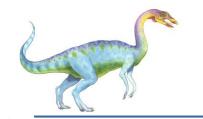


single-threaded process



multithreaded process

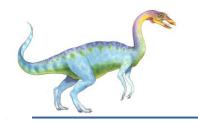




Benefits

- Responsiveness
- Resource Sharing
- Economy
- Scalability

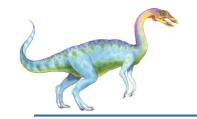




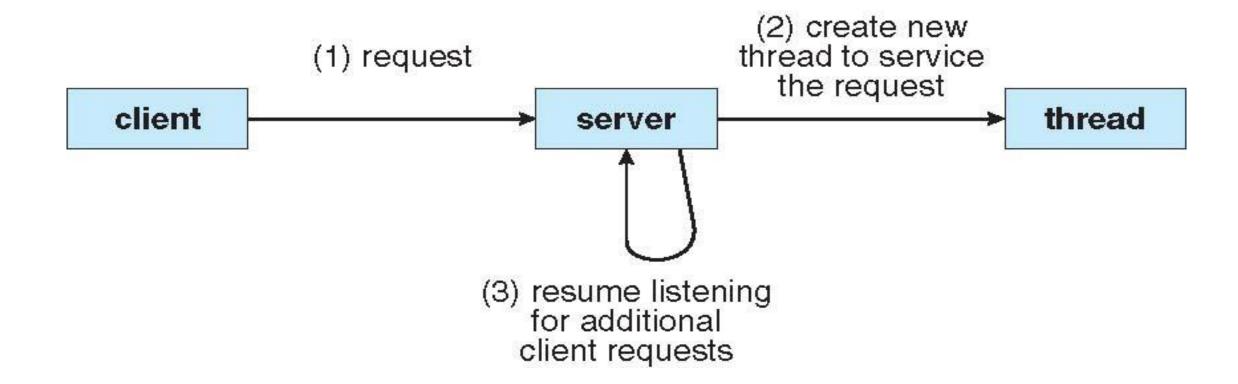
Multicore Programming

- □ Multicore systems putting pressure on programmers, challenges include:
 - Dividing activities
 - Balance
 - Data splitting
 - Data dependency
 - Testing and debugging

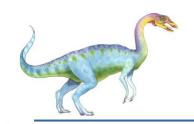




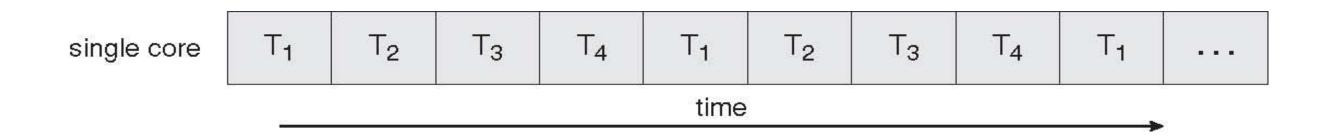
Multithreaded Server Architecture

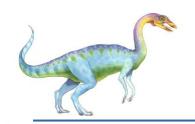




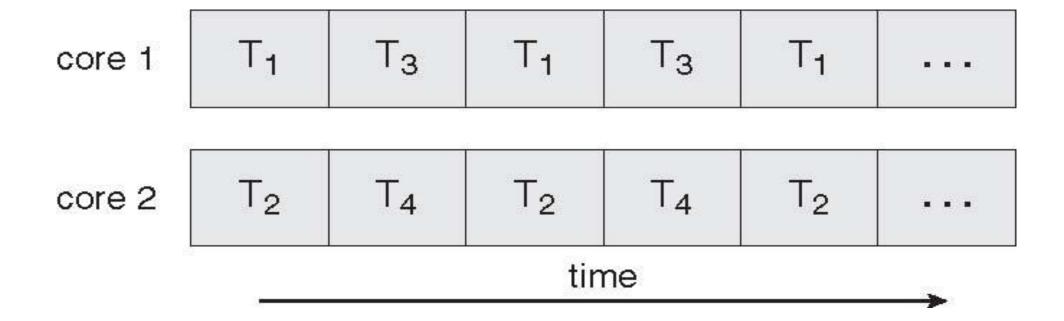


Concurrent Execution on a Single-core System

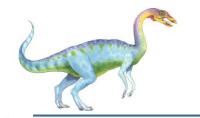




Parallel Execution on a Multicore System



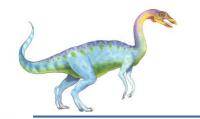




User Threads

- ☐ Thread management done by user-level threads library
- ☐ Three primary thread libraries:
 - POSIX Pthreads
 - Win32 threads
 - Java threads

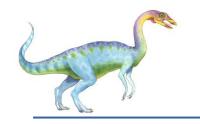




Kernel Threads

- Supported by the Kernel
- Examples
 - □ Windows XP/2000
 - Solaris
 - Linux
 - Tru64 UNIX
 - Mac OS X





Multithreading Models

- Many-to-One
- One-to-One
- Many-to-Many

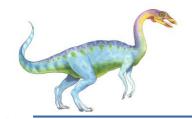




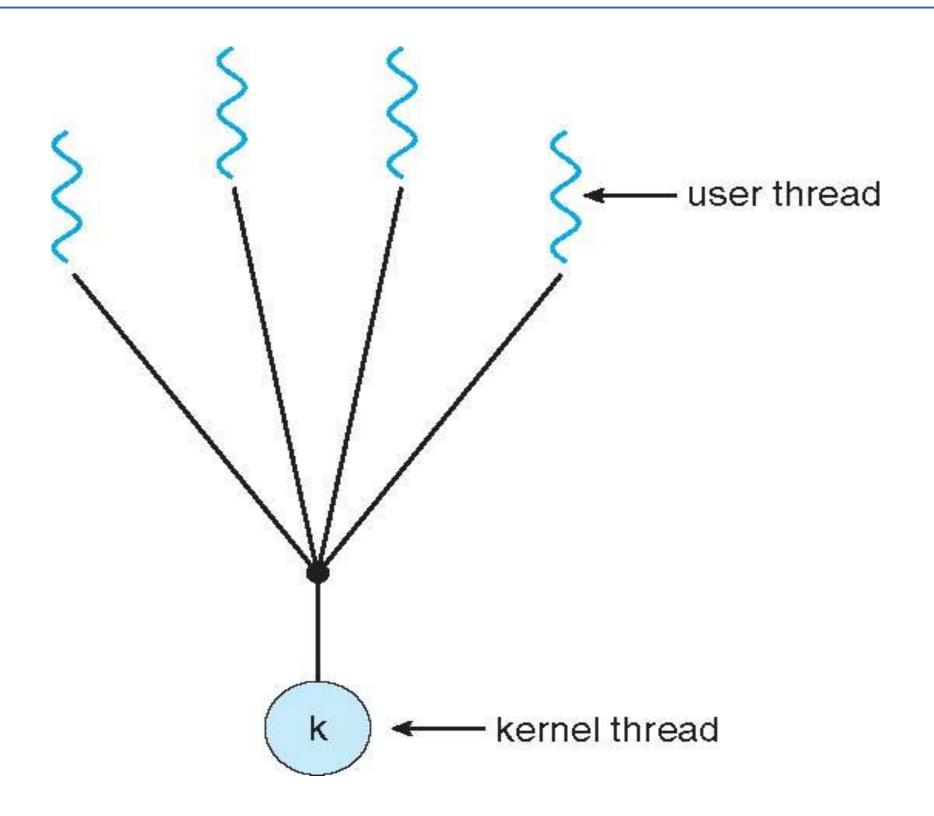
Many-to-One

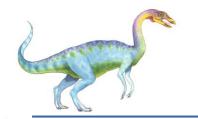
- Many user-level threads mapped to single kernel thread
- Examples:
 - Solaris Green Threads
 - GNU Portable Threads





Many-to-One Model

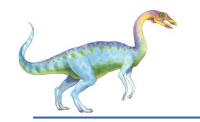




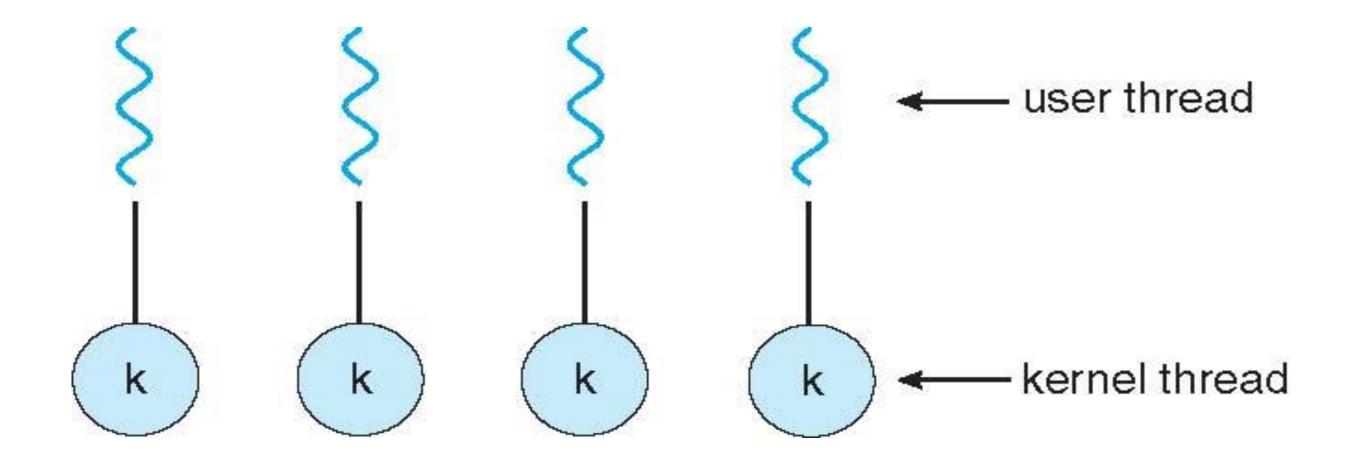
One-to-One

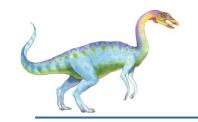
- Each user-level thread maps to kernel thread
- Examples
 - □ Windows NT/XP/2000
 - Linux
 - Solaris 9 and later





One-to-one Model

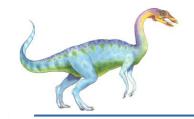




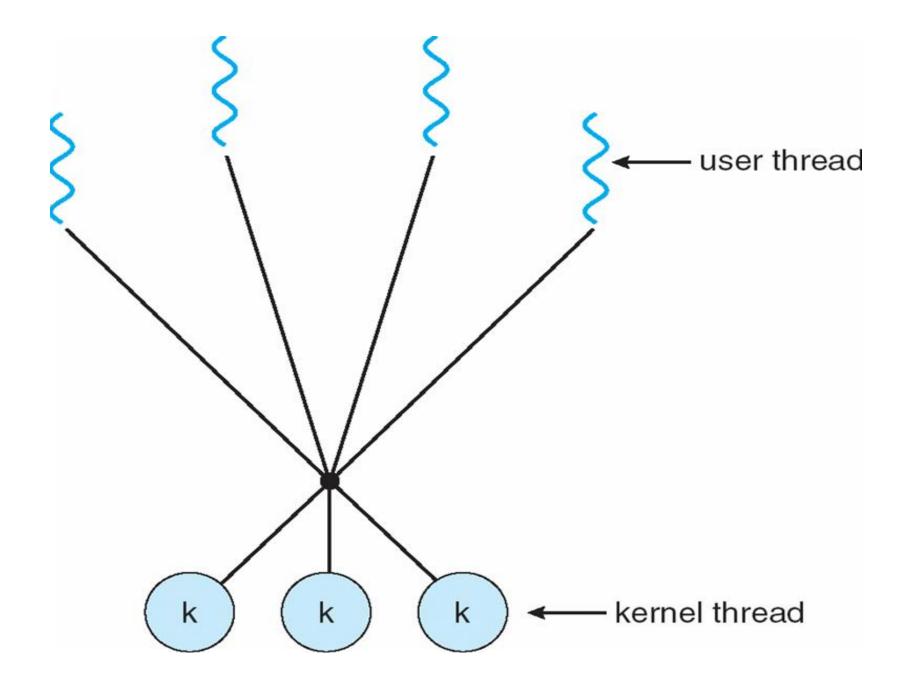
Many-to-Many Model

- Allows many user level threads to be mapped to many kernel threads
- Allows the operating system to create a sufficient number of kernel threads
- Solaris prior to version 9
- □ Windows NT/2000 with the *ThreadFiber* package

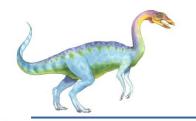




Many-to-Many Model







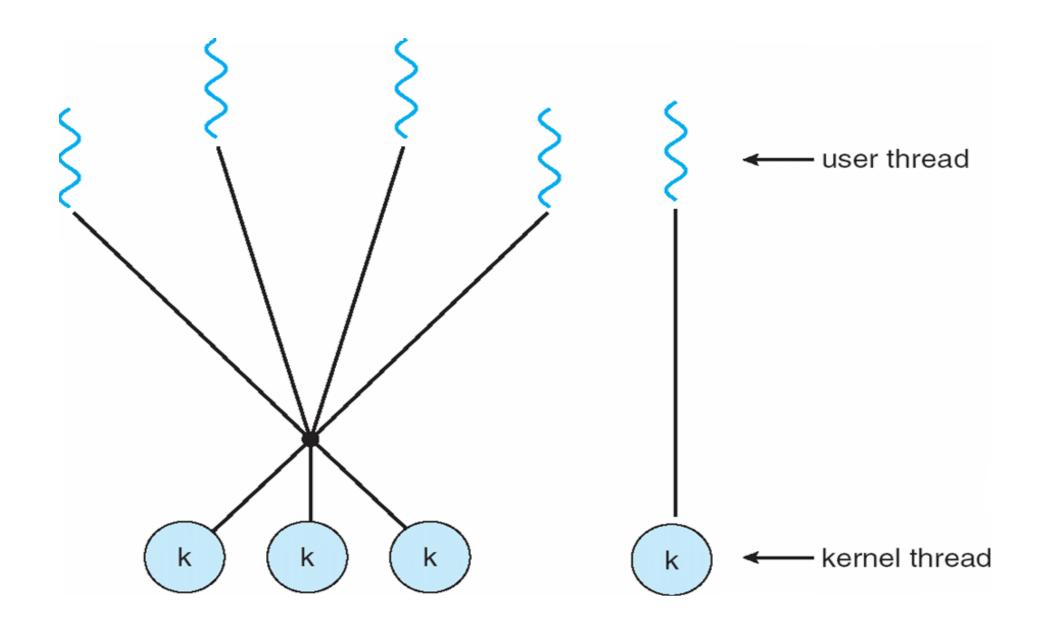
Two-level Model

- □ Similar to M:M, except that it allows a user thread to be **bound** to kernel thread
- Examples
 - IRIX
 - HP-UX
 - Tru64 UNIX
 - Solaris 8 and earlier

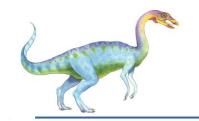




Two-level Model







Thread Libraries

- ☐ Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS

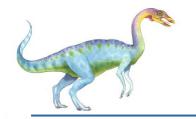




Pthreads

- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- □ API specifies behavior of the thread library, implementation is up to development of the library
- □ Common in UNIX operating systems (Solaris, Linux, Mac OS X)

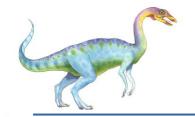




Pthreads Example

```
#include <pthread.h>
#include <stdio.h>
int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* the thread */
int main(int argc, char *argv[])
  pthread_t tid; /* the thread identifier */
  pthread_attr_t attr; /* set of thread attributes */
  if (argc != 2) {
     fprintf(stderr, "usage: a.out <integer value>\n");
     return -1:
  if (atoi(argv[1]) < 0) {
     fprintf(stderr, "%d must be >= 0\n", atoi(argv[1]));
     return -1:
```





Pthreads Example (Cont.)

```
/* get the default attributes */
  pthread_attr_init(&attr);
  /* create the thread */
  pthread_create(&tid,&attr,runner,argv[1]);
  /* wait for the thread to exit */
  pthread_join(tid,NULL);
  printf("sum = %d\n",sum);
/* The thread will begin control in this function */
void *runner(void *param)
  int i, upper = atoi(param);
  sum = 0:
  for (i = 1; i <= upper; i++)
     sum += i;
  pthread_exit(0);
```

Figure 4.9 Multithreaded C program using the Pthreads API.





```
#include <windows.h>
#include <stdio.h>
DWORD Sum; /* data is shared by the thread(s) */
/* the thread runs in this separate function */
DWORD WINAPI Summation(LPV0ID Param)
  DWORD Upper = *(DWORD*)Param;
  for (DWORD i = 0; i <= Upper; i++)
     Sum += i:
  return 0:
int main(int argc, char *argv[])
  DWORD ThreadId;
  HANDLE ThreadHandle;
  int Param:
  /* perform some basic error checking */
  if (argc != 2) {
     fprintf(stderr, "An integer parameter is required\n");
     return -1:
  Param = atoi(argv[1]);
  if (Param < 0) {
     fprintf(stderr, "An integer >= 0 is required\n");
     return -1:
```

Win32 API Multithreaded C Program (Cont.)

```
// create the thread
ThreadHandle = CreateThread(
  NULL, // default security attributes
  // default stack size
  Summation, // thread function
  &Param, // parameter to thread function
  0, // default creation flags
  &ThreadId); // returns the thread identifier
if (ThreadHandle != NULL) {
  // now wait for the thread to finish
  WaitForSingleObject(ThreadHandle, INFINITE);
  // close the thread handle
  CloseHandle(ThreadHandle);
  printf("sum = %d\n",Sum);
```

Figure 4.10 Multithreaded C program using the Win32 API.





Java Threads

- Java threads are managed by the JVM
- ☐ Typically implemented using the threads model provided by underlying OS
- Java threads may be created by:
 - Extending Thread class
 - Implementing the Runnable interface





Java Multithreaded Program

```
class Sum
  private int sum;
  public int getSum() {
   return sum;
  public void setSum(int sum) {
   this.sum = sum;
class Summation implements Runnable
  private int upper;
  private Sum sumValue;
  public Summation(int upper, Sum sumValue) {
   this.upper = upper;
   this.sumValue = sumValue;
  public void run() {
   int sum = 0;
   for (int i = 0; i <= upper; i++)
      sum += i;
   sumValue.setSum(sum):
```



Java Multithreaded Program (Cont.)

```
public class Driver
  public static void main(String[] args) {
   if (args.length > 0) {
     if (Integer.parseInt(args[0]) < 0)
      System.err.println(args[0] + * must be >= 0.*);
     else {
      // create the object to be shared
      Sum sumObject = new Sum();
      int upper = Integer.parseInt(args[0]);
      Thread thrd - new Thread(new Summation(upper, sumObject)):
      thrd.start():
      try {
         thrd.join();
         System.out.println
                 ("The sum of "+upper+" is "+sumObject.getSum());
       catch (InterruptedException ie) { }
    else.
     System.err.println("Usage: Summation <integer value>"); }
```

Figure 4.11 Java program for the summation of a non-negative integer.

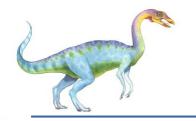




Threading Issues

- Semantics of fork() and exec() system calls
- □ Thread cancellation of target thread
 - Asynchronous or deferred
- Signal handling
 - Synchronous and asynchronous

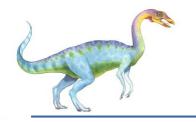




Threading Issues (Cont.)

- □ Thread pools
- □ Thread-specific data
 - Create Facility needed for data private to thread
- □ Scheduler activations

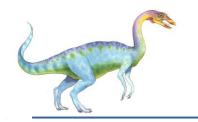




Semantics of fork() and exec()

Does **fork()** duplicate only the calling thread or all threads?

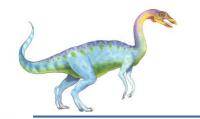




Thread Cancellation

- Terminating a thread before it has finished
- □ Two general approaches:
 - Asynchronous cancellation terminates the target thread immediately.
 - Deferred cancellation allows the target thread to periodically check if it should be cancelled.

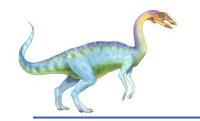




Signal Handling

- Signals are used in UNIX systems to notify a process that a particular event has occurred.
- A **signal handler** is used to process signals
 - Signal is generated by particular event
 - Signal is delivered to a process
 - Signal is handled
- Options:
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals for the process

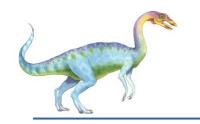




Thread Pools

- Create a number of threads in a pool where they await work
- Advantages:
 - Usually slightly faster to service a request with an existing thread than create a new thread
 - Allows the number of threads in the application(s) to be bound to the size of the pool

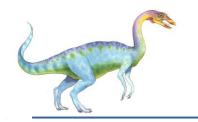




Thread Specific Data

- Allows each thread to have its own copy of data
- □ Useful when you do not have control over the thread creation process (i.e., when using a thread pool)

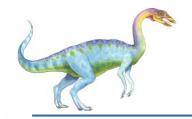




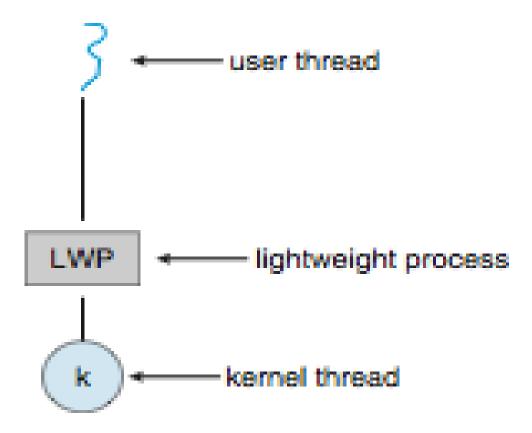
Scheduler Activations

- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- Scheduler activations provide upcalls a communication mechanism from the kernel to the thread library
- ☐ This communication allows an application to maintain the correct number kernel threads

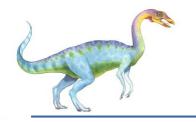




Lightweight Processes







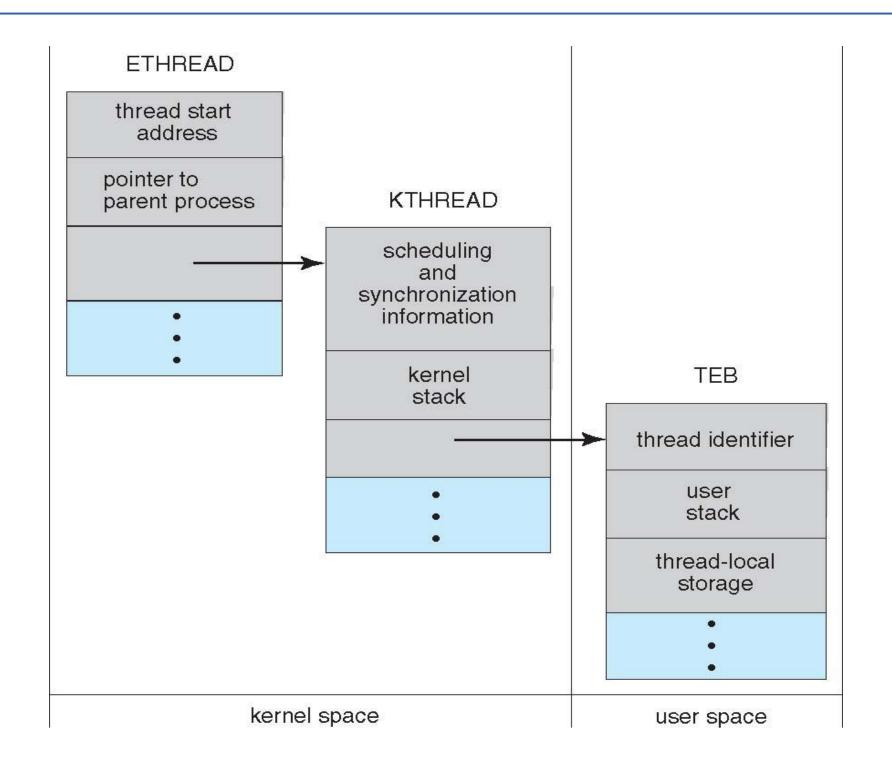
Operating System Examples

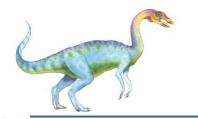
- Windows XP Threads
- Linux Thread





Windows XP Threads Data Structures

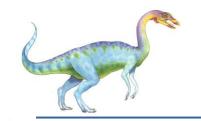




Windows XP Threads

- □ Implements the one-to-one mapping, kernel-level
- Each thread contains
 - A thread id
 - Register set
 - Separate user and kernel stacks
 - Private data storage area
- ☐ The register set, stacks, and private storage area are known as the **context** of the threads
- ☐ The primary data structures of a thread include:
 - ETHREAD (executive thread block)
 - KTHREAD (kernel thread block)
 - TEB (thread environment block)

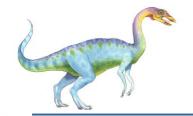




Linux Threads

- □ Linux refers to them as *tasks* rather than *threads*
- ☐ Thread creation is done through clone() system call
- clone() allows a child task to share the address space of the parent task (process)
- struct task_struct points to process data structures (shared or unique)





Linux Threads

- fork() and clone() system calls
- Doesn't distinguish between process and thread
 - □ Uses term *task* rather than thread
- clone() takes options to determine sharing on process create
- struct task_struct points to process data structures (shared or unique)

flag	meaning
CLONE_FS	File-system information is shared.
CLONE_VM	The same memory space is shared.
CLONE_SIGHAND	Signal handlers are shared.
CLONE_FILES	The set of open files is shared.



End of Chapter 4

