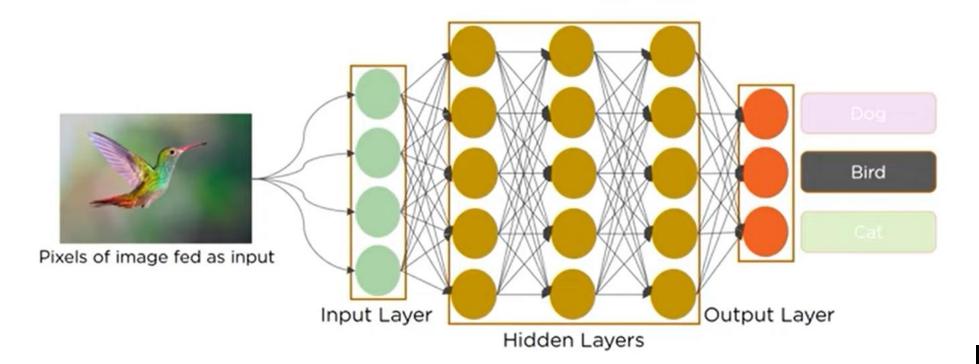
CNN

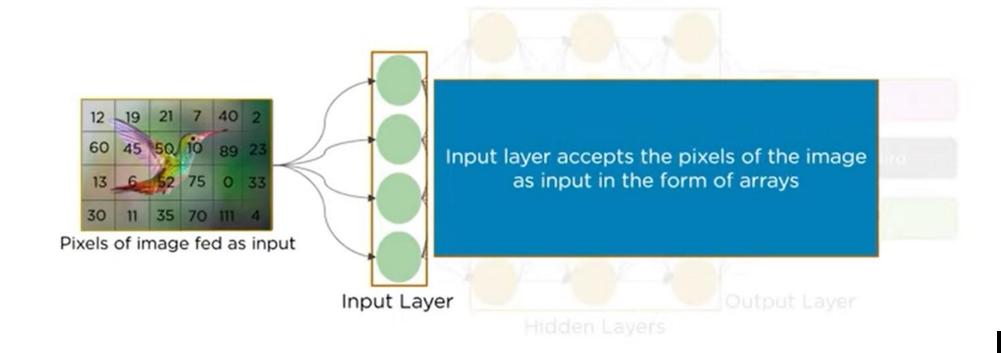
Zahoor Tanoli (PhD)
CUI Attock

Do you know how Deep Learning recognizes the objects in an image?

It does it using a Convolution Neural Network



Let's see how CNN identifies the image of a bird



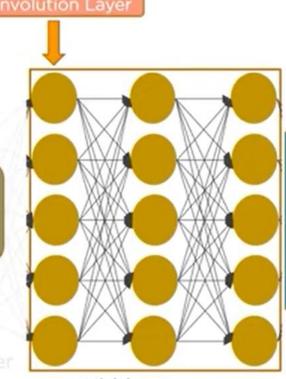
Let's see how CNN identifies the image of a bird



1	0	1
0	1	0
1	0	1

This layer uses a matrix filter and performs convolution operation to detect patterns in the image

Pixels of Image fed as input



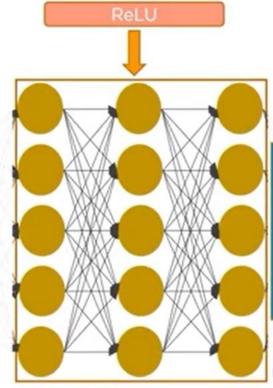
There are multiple hidden layers like Convolution layer, ReLU layer, Pooling layer, etc that perform feature extraction from the image

Output Layer

Let's see how CNN identifies the image of a bird

ReLU activation function is applied to the convolution layer to get a rectified feature map of the image

Pixels of image fed as inpu



There are multiple hidden layers like Convolution layer, ReLU layer, Pooling layer, etc that perform feature extraction from the image

Hidden Layers

Let's see how CNN identifies the image of a bird

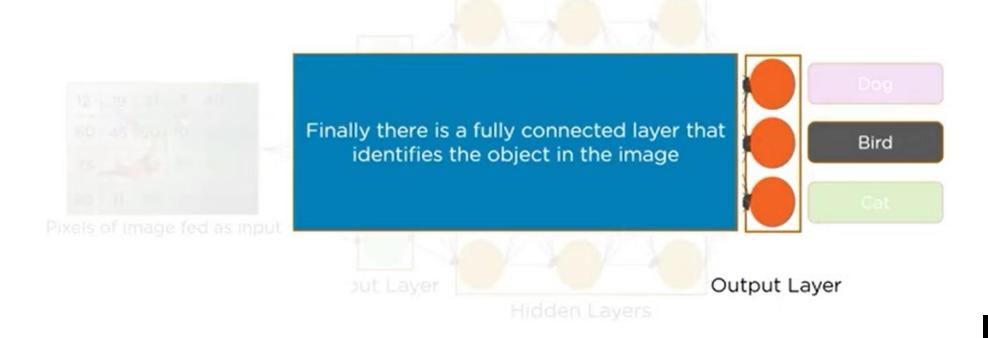
Pooling layer also uses multiple filters to detect edges, corners, eyes, feathers, beak, etc

Pixels of image fed as input

There are multiple hidden layers like Convolution layer, ReLU layer, Pooling layer, etc that perform feature extraction from the image

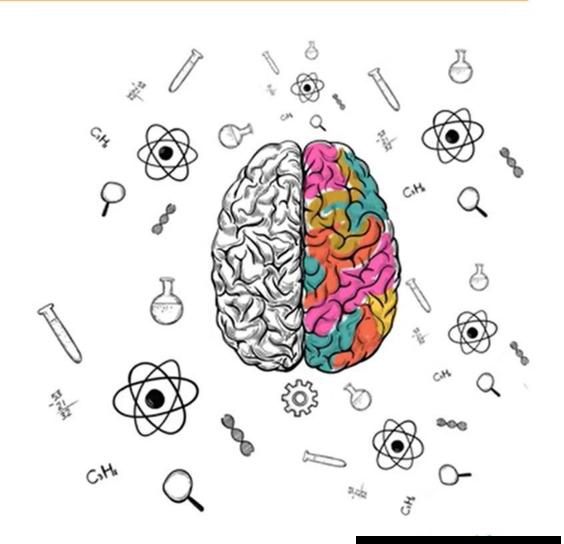
Hidden Layers

Let's see how CNN identifies the image of a bird

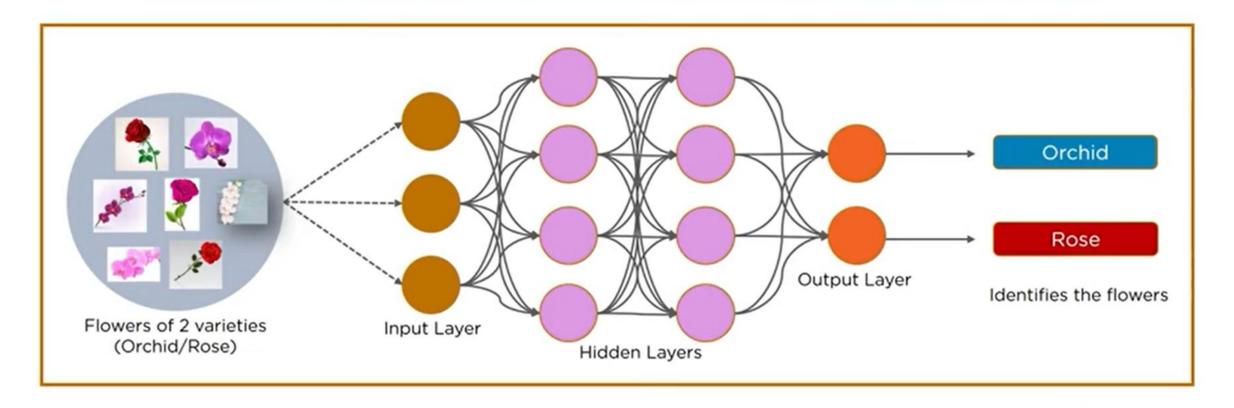


What's in it for you?

- Introduction to CNN
- What is Convolution neural network?
- How CNN recognizes images?
- Layers in convolution neural network
- Use case implementation using CNN



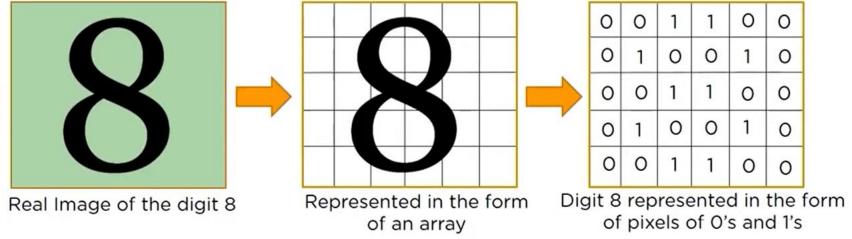
CNN is a feed forward neural network that is generally used to analyze visual images by processing data with grid like topology. A CNN is also known as a "ConvNet"



CNN is a feed forward neural network that is generally used to analyze visual images by processing data with grid like topology. A CNN is also known as a "ConvNet"

Convolution operation forms the basis of any Convolution Neural Network

In CNN, every image is represented in the form of arrays of pixel values

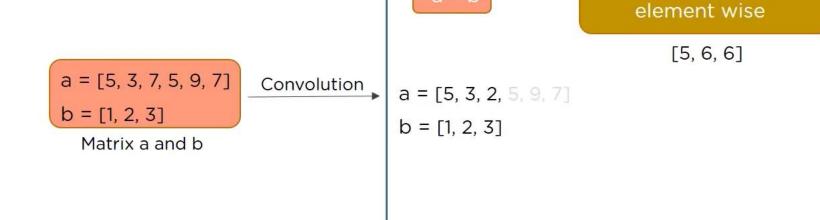


Let's understand the convolution operation using 2 matrices a and b of 1 dimension

a = [5, 3, 7, 5, 9, 7] b = [1, 2, 3] Matrix a and b a * b

Let's understand the convolution operation using 2 matrices a and b of 1 dimension

Multiply the arrays



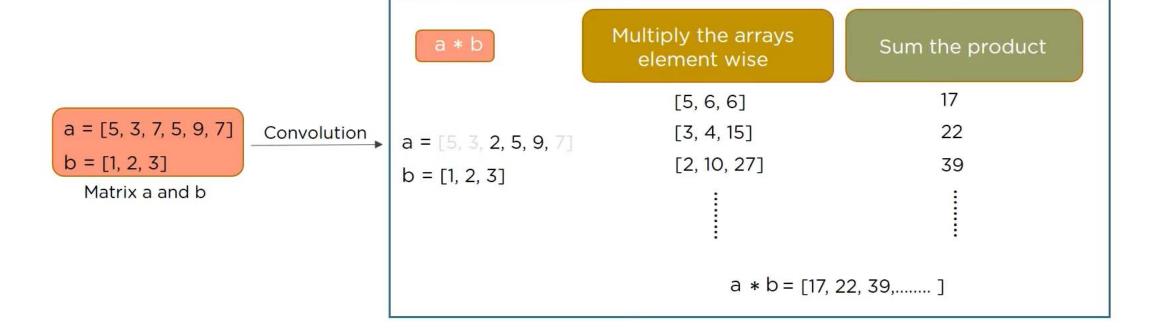
a * b = [17,]

Sum the product

17

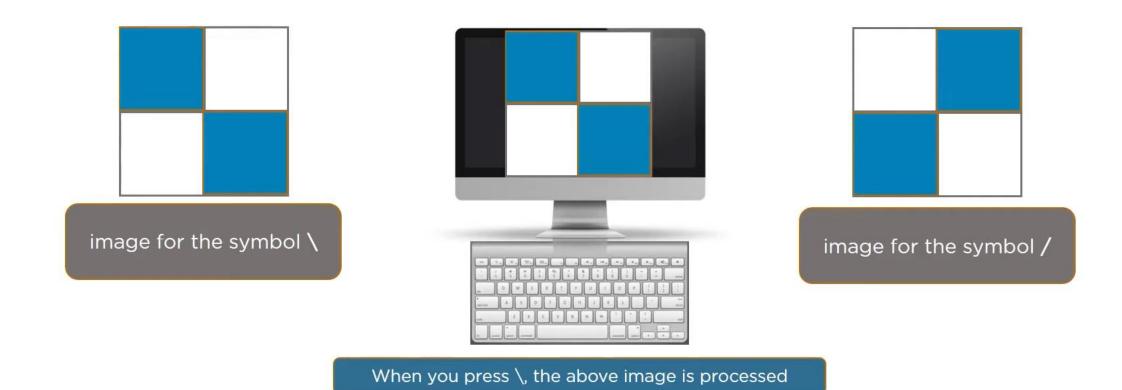
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Let's understand the convolution operation using 2 matrices a and b of 1 dimension



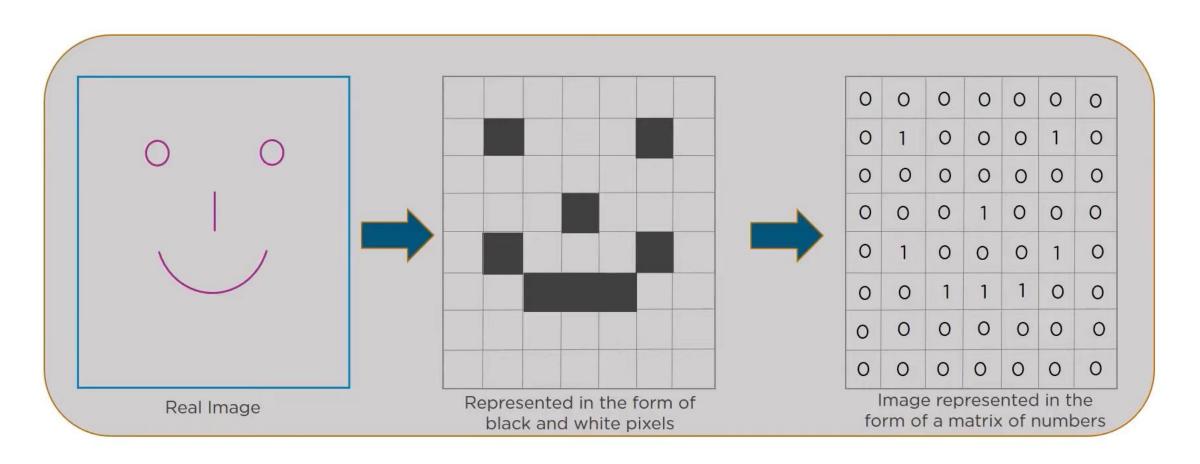
How CNN recognizes images?

Consider the following 2 images:

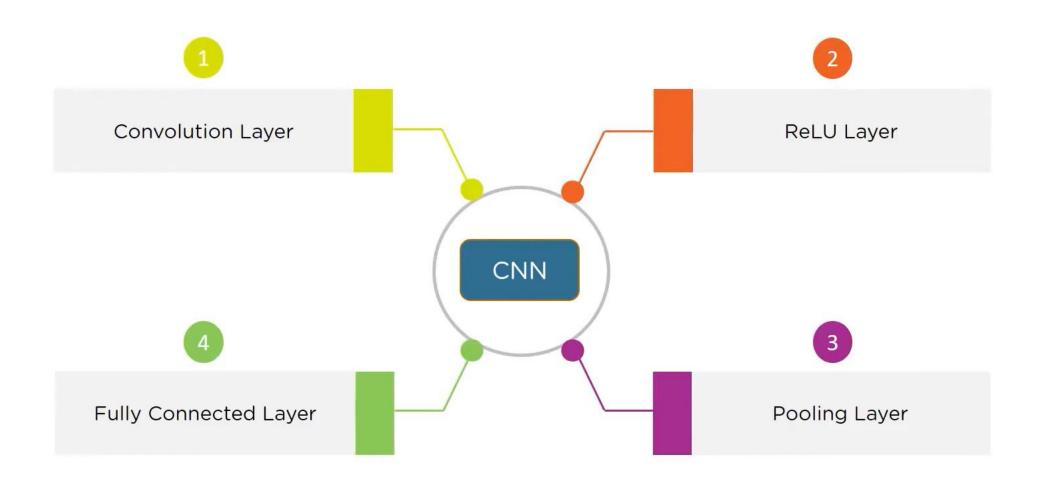


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How CNN recognizes images?



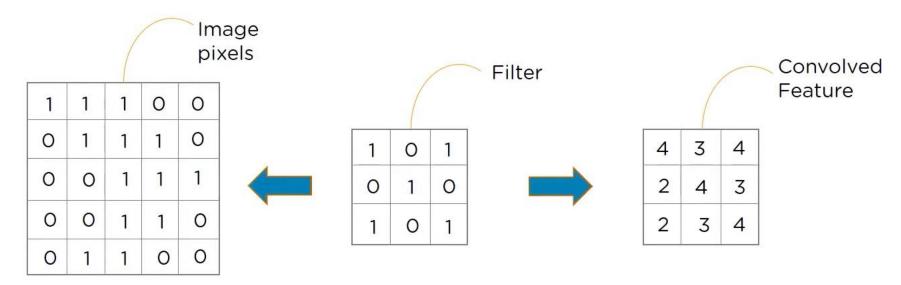
Layers in Convolution Neural Network



A Convolution Layer has a number of filters that perform convolution operation

Every image is considered as a matrix of pixel values.

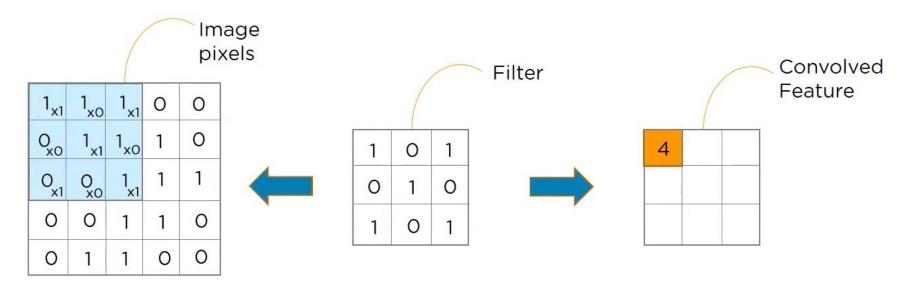
Consider the following 5*5 image whose pixel values are only 0 and 1



A Convolution Layer has a number of filters that perform convolution operation

Every image is considered as a matrix of pixel values.

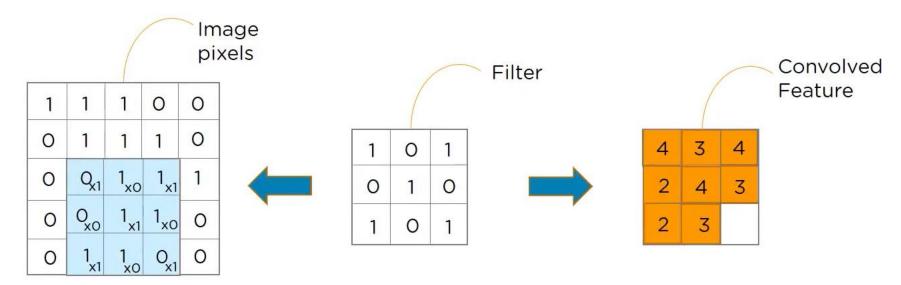
Consider the following 5*5 image whose pixel values are only 0 and 1



A Convolution Layer has a number of filters that perform convolution operation

Every image is considered as a matrix of pixel values.

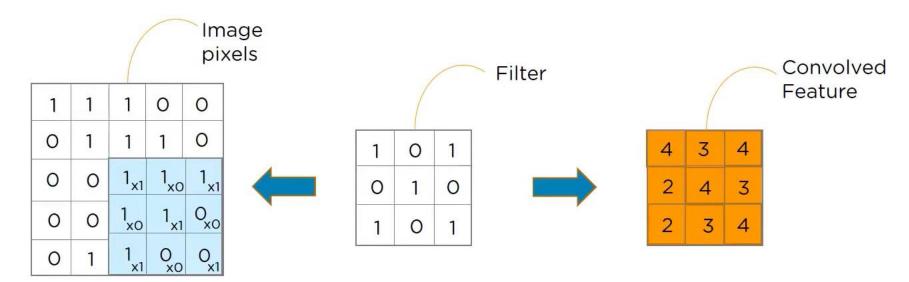
Consider the following 5*5 image whose pixel values are only 0 and 1

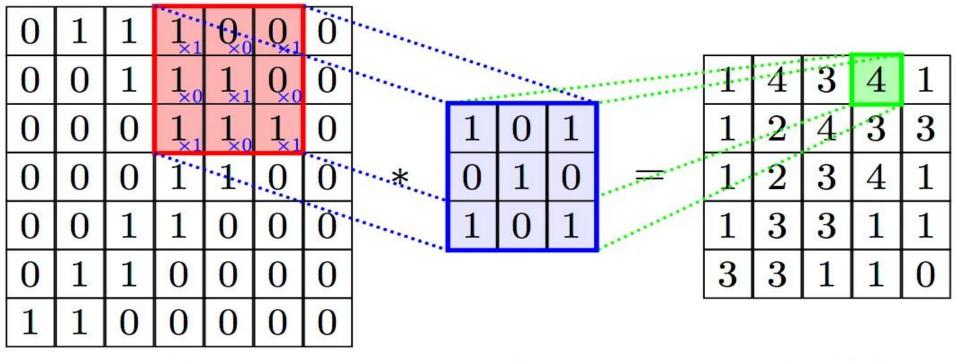


A Convolution Layer has a number of filters that perform convolution operation

Every image is considered as a matrix of pixel values.

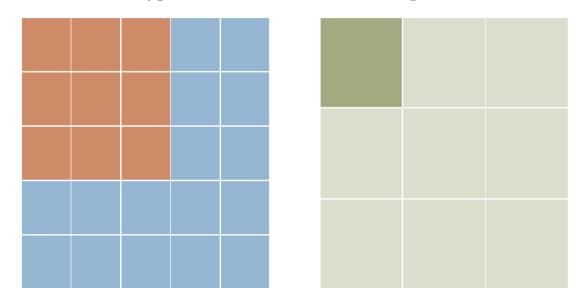
Consider the following 5*5 image whose pixel values are only 0 and 1





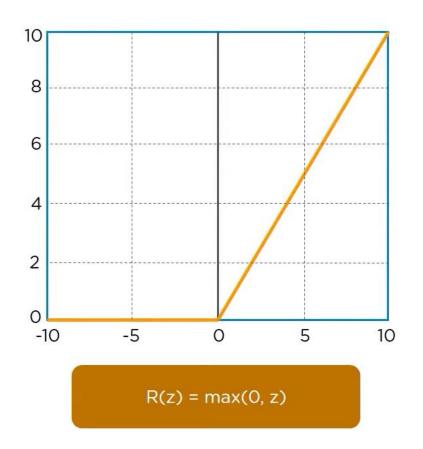
I K I * K

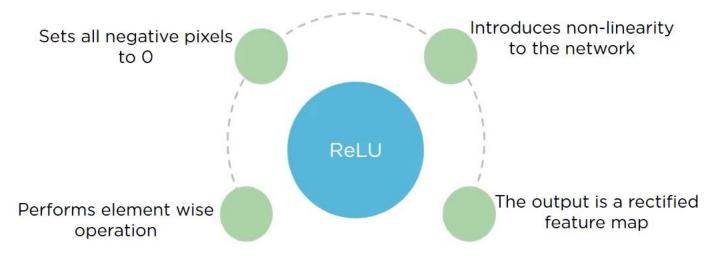
Type: conv - Stride: 1 Padding: 0



ReLU Layer

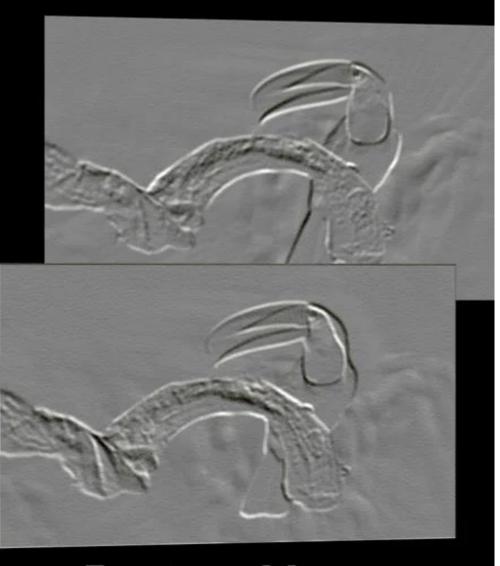
Once the feature maps are extracted, the next step is to move them to a ReLU layer





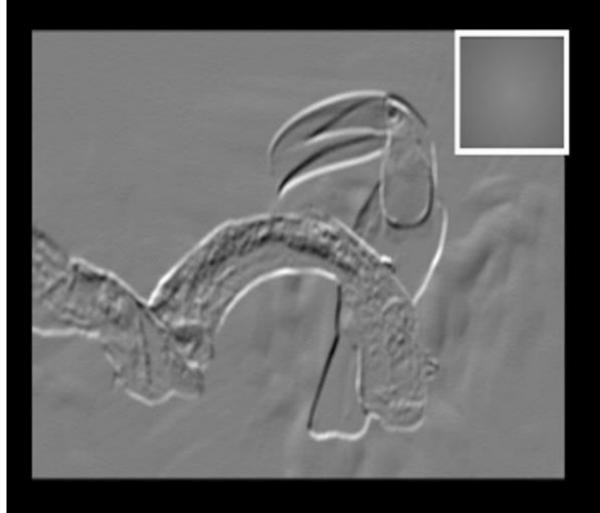






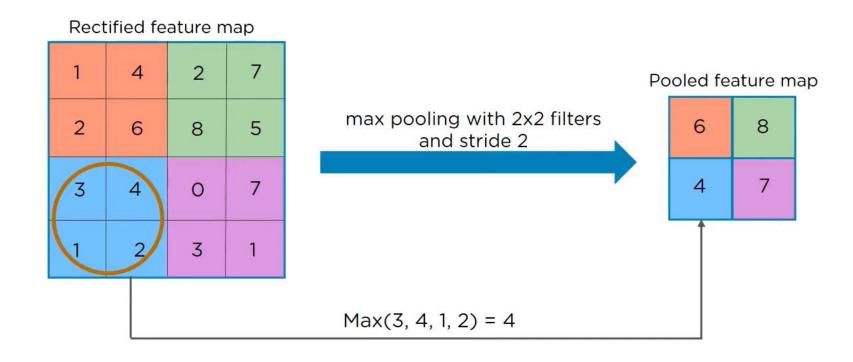
Feature Map

Input Feature Map



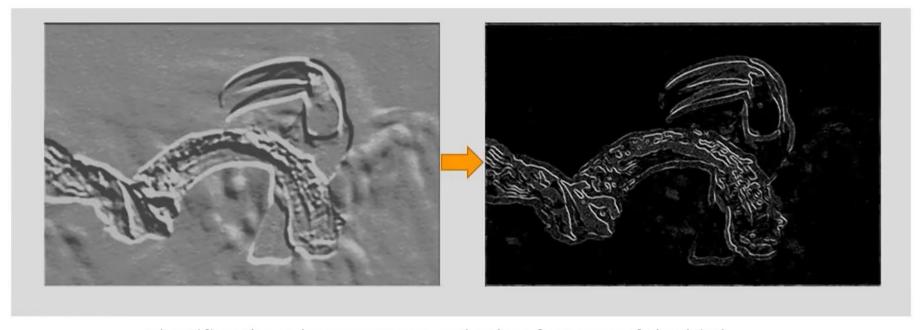
Pooling Layer

The rectified feature map now goes through a pooling layer. Pooling is a down-sampling operation that reduces the dimensionality of the feature map.



Pooling Layer

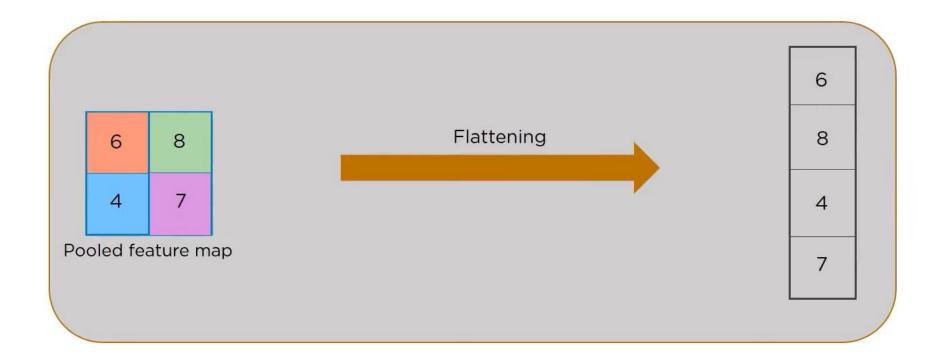
Pooling layer uses different filters to identify different parts of the image like edges, corners, body, feathers, eyes, beak, etc.



Identifies the edges, corners and other features of the bird

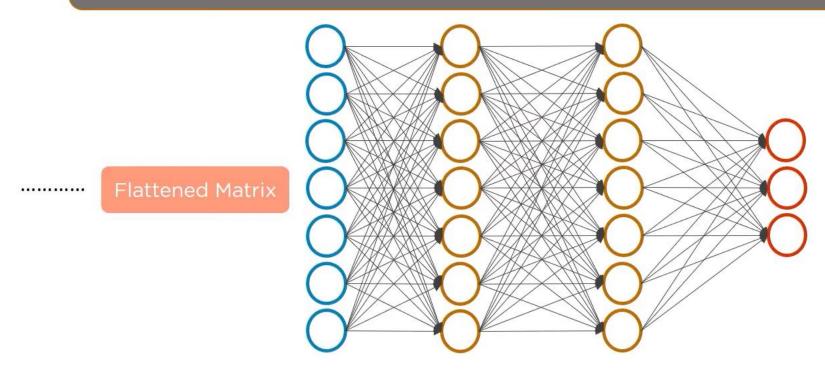
Flattening

Flattening is the process of converting all the resultant 2 dimensional arrays from pooled feature map into a single long continuous linear vector.



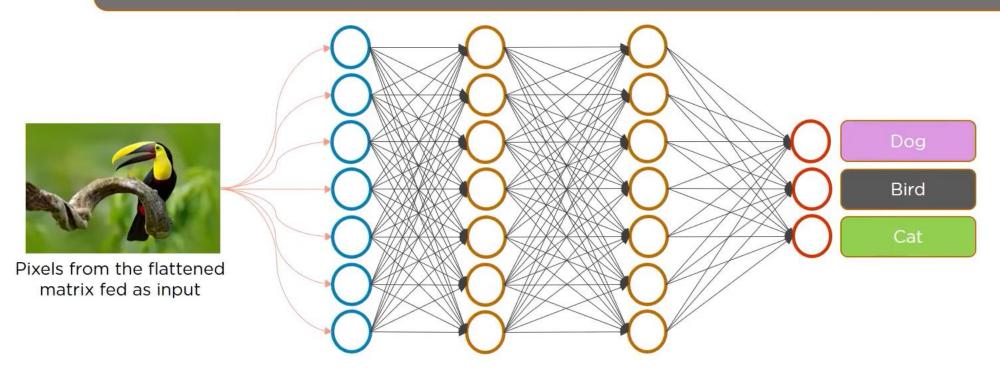
Fully Connected Layer

The Flattened matrix from the pooling layer is fed as input to the Fully Connected Layer to classify the image



Fully Connected Layer

The Flattened matrix from the pooling layer is fed as input to the Fully Connected Layer to classify the image



Fully Connected Layer

Lets see the entire process how CNN recognizes a bird

