

Report for Embedded Systems Lecture's Project 1

Table Tennis

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Approch

1. There is a button to Reset the game.
2. There are 2 Users and a table for playing game.
3. Each user is a 32 bit path for move as up&down way.
4. For movement, users have a joystick. Users can move in their area by pulling their own joystick to up and down.
5. Users are placed as left and right. If left user pulls it's own joystick to left, then it will be ignored. If he/she pulls the joystick to right then it has a meaning and it will be described later. The same issue exist for Right user for pulling the joysick to right/left.
6. Table is 32 bitted 32 rows. Each bit is setted as 0 expect the ball. If the ball is on one of the bits, then it will be setted as 1.
7. The ball initially moves left/right. When it is at the corner of the row (0th or 32th bit) then it checks if user's position (as up-down) and its position (up-down) are matching. If it doesn't match, this means the game is over, don't allow any movement further. Otherwise the user it matches can return the ball to other direction. If matching user doesn't move it's joystick, then ball returns as the mirror return. This means: / goes \ -> goes <-, \ goes /. Otherwise, if joystick is pulled a side but it doesn't be ignored, then for left user pulling right-top means return / way and right direction, pulling just right means return – way and right, pulling right-down means return \ way and right direction. For right user, pulling left-up means \ way and left direction, pulling left means – way and left direction, pulling left-down means / way and left direction.
8. For moving of the ball is \ or /, it can reach the top of table. If it reaches, it should not drop away from table. For this issue, if it reaches the top or bottom, then it return as the mirror return and goes the same direction (left/right).
9. If game is over, then registers can not be updated. So there will be no movements further.

C CODE

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/**
    This is a template C code for the implementation of Table Tennis Game on
    Logisim.
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*/
int main(void)
{
    int[32][32] table;
    int[32]      U1 = {0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0} // 0 -> Top, 31 -> Bottom
    int[32]      U2 = {0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0,
0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0} // #####
    int          risk_left  = 0,
                risk_right = 0;
    int[3]       direction  = {0, 0, 0};
    int[2]       js_left_x  = {0, 0},
                js_left_y  = {0, 0},
                js_right_x  = {0, 0},
                js_right_y  = {0, 0};
    int          fin        = 0;
    int          start      = 0;
    int          upper_bound = 0,
                lower_bound = 0;

    do
    {
S0:    direction = {0, 0, 0};
        U1[16] = U1[17] = 1;
        U2[16] = U1[17] = 1;
        table[16][0] = 1;
        while(start);
        while(!fin)
        {
            if(start) goto S0;
            for(int i = 0; i < 32; ++i)
            {
                risk_left |= table[31][i];
                risk_right |= table[0][i];
            }

            if(risk_left)
            {
                int handle = 0;
                for(int i = 0; i < 32; ++i)
                    handle |= table[i][0] & U1[i]
                if(!handle)
                {

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while( !direction[0]
      && !direction[1]
      && !direction[2]
      && (
          !js_left_x[1] ||
          (!js_left_x[0] && js_left_x[1] && js_left_y[1] &&
!js_left_y[0]))
      );

if(js_left_x[1] & !js_left_x[0])
{
    if(js_left_y[0] & !js_left_y[1] & !U1[0])
    {
        for(i = 1; i < 31; ++i)
        {
            U1[i - 1] = U1[i];
            table[i - 1][0] = table[i][0];
        }
        U1[31] = 0;
        table[31][0] = 0;
    }
    else if(js_left_y[0] & js_left_y[1] & !U1[31])
    {
        for(i = 31; i > 0; --i)
        {
            U1[i] = U1[i - 1];
            table[i][0] = table[i - 1][0];
        }
        U1[0] = 0;
        table[0][0] = 0;
    }
}
else
{
    direction[2] = !direction[2];
    if( (js_left_y[1] && !js_left_y[0] && js_left_x[1] &&
!js_left_x[0]) ||
        !js_left_x[1]);
    else if(js_left_x[0] & js_left_x[1] & js_left_y[0] &
!js_left_y[1])
    {
        direction[0] = 1;
        direction[1] = 0;
    }
    else if(js_left_x[0] & js_left_x[1] & !js_left_y[0] &
js_left_y[1])
    {
        direction[0] = 1;
        direction[1] = 1;
    }
}

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        }
        else if(js_left_x[0] & js_left_x[1] & js_left_y[0] &
js_left_y[1])
        {
            direction[0] = 0;
            direction[1] = 1;
        }
    }
    else
        fin = 1;
}
else if(risk_right)
{
    int handle = 0;
    for(int i = 0; i < 32; ++i)
        handle |= table[i][31] & U1[i]
    if(!handle)
    {
        while( !direction[0]
            && !direction[1]
            && !direction[2]
            && (
                (js_right_x[0] & js_right_x[1]) ||
                (!js_right_x[0] &&
                    js_right_x[1] &&
                    js_right_y[1] &&
                    !js_right_y[0]))
            );
        if(js_right_x[1] & !js_right_x[0])
        {
            if(js_right_y[0] & !js_right_y[1] & !U2[0])
            {
                for(i = 1; i < 31; ++i)
                {
                    U2[i - 1] = U2[i];
                    table[i - 1][31] = table[i][31];
                }
                U1[31] = 0;
                table[31][31] = 0;
            }
            else if(js_right_y[0] & js_right_y[1] & !U2[31])
            {
                for(i = 31; i < 0; ++i)
                {
                    U2[i] = U2[i - 1];
                    table[i][31] = table[i - 1][31];
                }
                U2[0] = 0;
            }
        }
    }
}

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        table[0][31] = 0;
    }
}
else
{
    direction[2] != direction[2];
    if( (js_right_y[1] && !js_right_y[0] && js_right_x[1]
&& !js_right_x[0]) ||
        (js_right_x[1] & js_right_x[1]));
    else if(!js_right_x[1] & js_left_y[0] &
!js_right_y[1])
    {
        direction[0] = 1;
        direction[1] = 0;
    }
    else if(!js_right_x[1] & !js_right_y[0] &
js_right_y[1])
    {
        direction[0] = 1;
        direction[1] = 1;
    }
    else if(!js_right_x[1] & js_right_y[0] &
js_right_y[1])
    {
        direction[0] = 0;
        direction[1] = 1;
    }
}
}
else
    fin = 1;
}
upper_bound = lower_bound = 0;
for(int i = 0; i < 32; ++i)
{
    upper_bound |= table[0][i];
    lower_bound |= table[31][i];
}
if(upper_bound || lower_bound)
{
    int temp = direction[0];
    direction[0] = direction[1];
    direction[1] = temp;
}
if(direction[2])
    if(direction[1])
        if(direction[0])            //
<<<<<<<<<<<<<<<<<<<-    111
        for(int i = 0; i < 32; ++i)

```

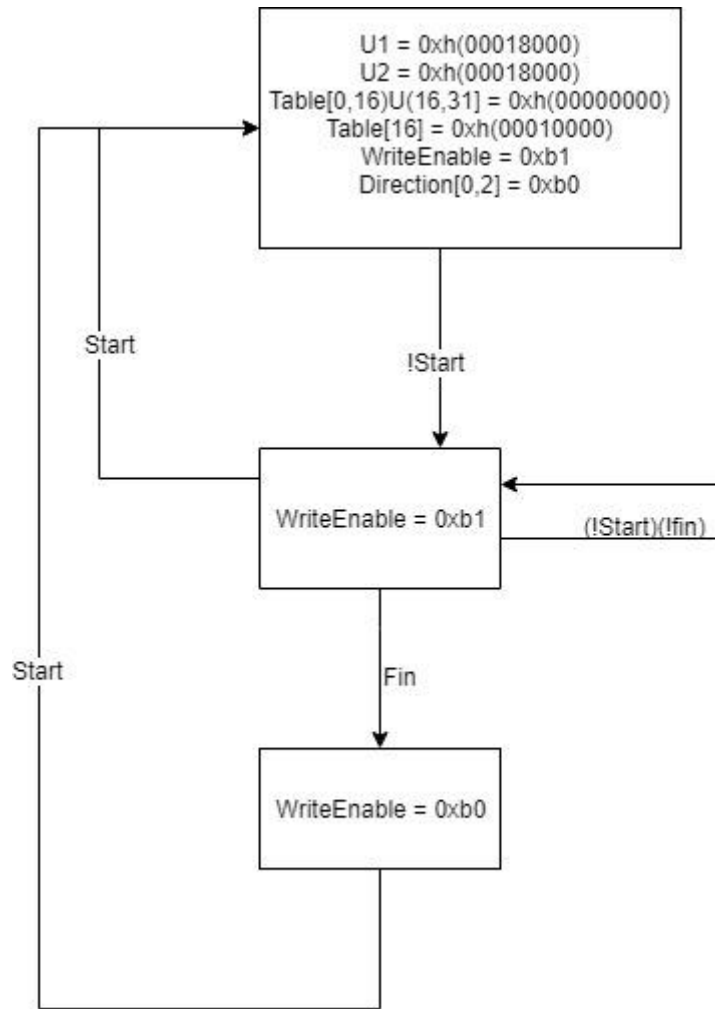
[illegible]

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    if (js_right_x[1] & !js_right_x[0])
    {
        if(js_right_y[0])
        {
            if(js_right_y[1])          // U2 >> 1
                for(int i = 0; i < 32; ++i)
                    if(i == 31)
                        U2[i] = U2[i];
                    else
                        U2[i] = U2[i - 1];
            else                          // U2 << 1
                for(int i = 0; i < 32; ++i)
                    if(i == 0)
                        U2[i] = U2[i];
                    else
                        U2[i] = U2[i + 1]
        }
    }
    if (js_left_x[1] & !js_left_x[0])
    {
        if(js_left_x[0])
        {
            if(js_left_x[1])
                for(int i = 0; i < 32; ++i)
                    if(i == 31)
                        U1[i] = U1[i];
                    else
                        U1[i] = U1[i - 1];
            else
                for(int i = 0; i < 32; ++i)
                    if(i == 0)
                        U1[i] = U1[i];
                    else
                        U1[i] = U1[i + 1]
        }
    }
}
while(!start);
} while(true);
}

```


FSM



SIMPLIFICATION

P_1	P_0	Start	Finish	N_2	N_1
0	0	0	X	0	1
0	0	1	X	0	0
0	1	0	0	0	1
0	1	0	1	1	1
0	1	1	X	0	0
1	1	0	X	1	1
1	1	1	X	0	0

N_1

$P_1 P_0$	Start	Finish
00	00	01
01	00	01
11	00	01
10	00	01

$$N_1 = \overline{P_0} \text{Start} \text{Finish} + P_1 P_0 \text{Start}$$

$$= \text{Start} P_0 (\text{Finish} + P_1)$$

N_0

$P_1 P_0$	Start	Finish
00	00	01
01	00	01
11	00	01
10	00	01

$$N_0 = \overline{P_2} \text{Start} + P_0 \text{Start}$$

$$= \text{Start} (\overline{P_2} + P_0)$$