

## Indirect Network Troubleshooting with The Chase



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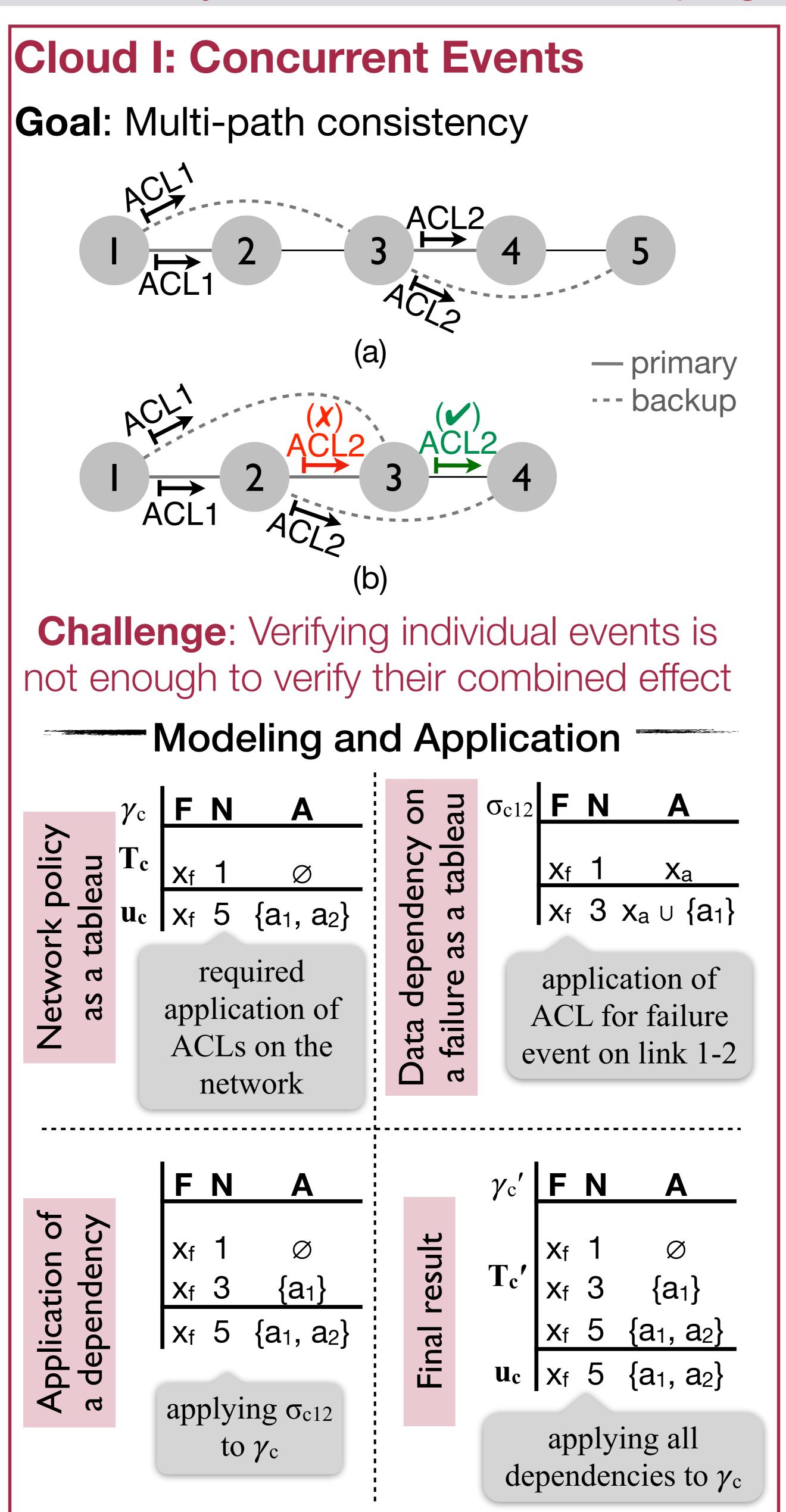
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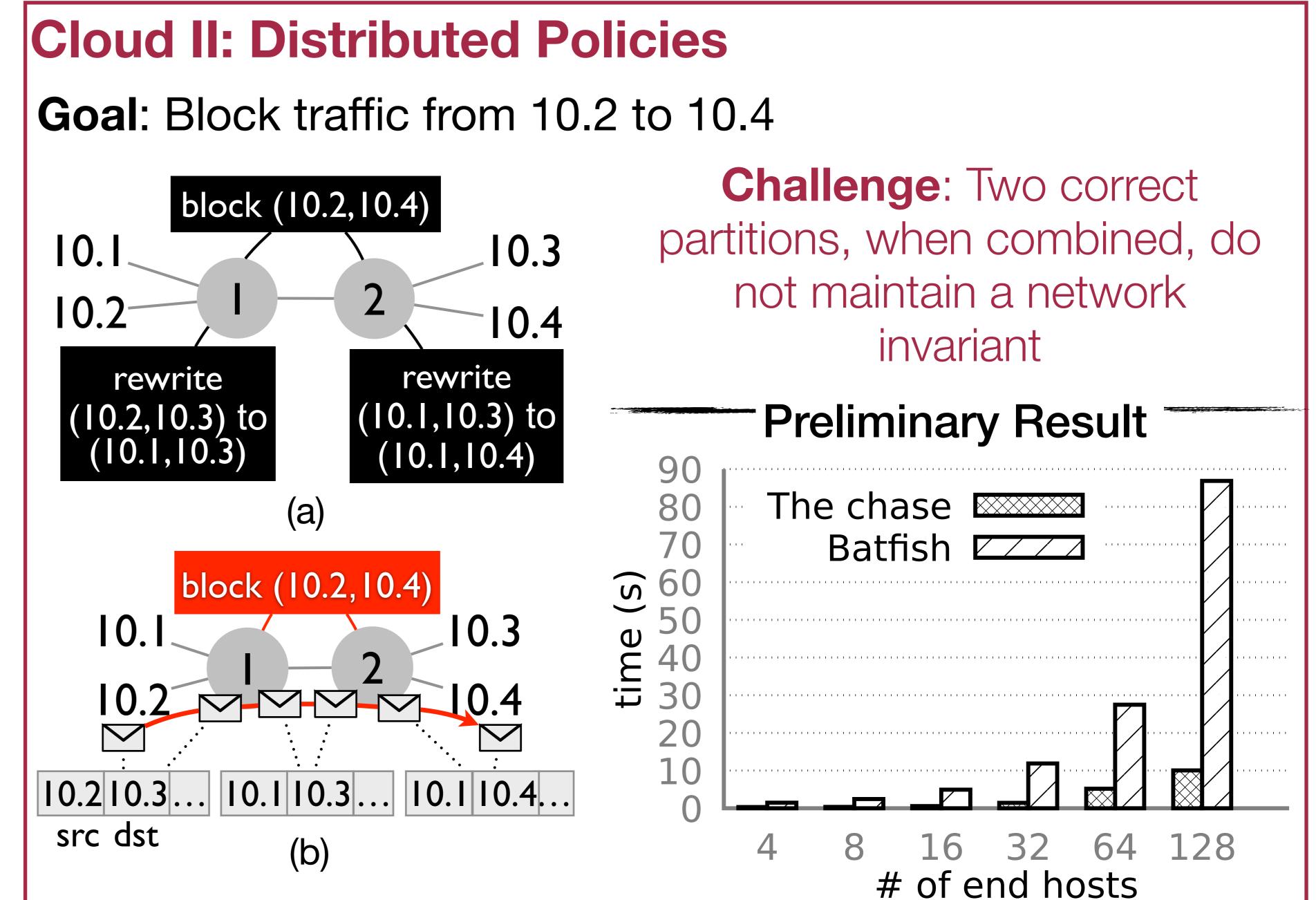
## Two clouds obscuring network verification

- Cloud I: Concurrent Events
- failures and changes are common in networks
- Cloud II: Distributed Policies
- global invariants are ensured using policies in different parts of the network
- Problem Formulation:
- I: Temporal Decision Problem: Does a policy still hold under different network environments (e.g. failures)?
- II: Spatial Decision Problem: Do local policies (under different network partitions) imply a network-wide invariant?

## Indirect Troubleshooting

- Solves an implication problem
- decides if known facts about the network imply some unknown property
- natively supports reasoning about concurrent events (link failures) and distributed policies
- a unifying implementation with the chase
- The chase: Tests implications among data dependencies in databases
- a unifying database primitive (denoted, chase( $\gamma$ ,  $\sigma$ )) denotes the impact of applying the premise  $\sigma$  to the conclusion  $\gamma$
- premise and conclusion represented as tableaux
- premise could be policies verified by existing verification tools directly





## **Future Possibilities**

- Networks are hard to reason about
- grow without a premeditated plan
- different parts often managed
   by different departments
- The chase provides a flexible framework to reason with disparate network views

is new policy  $\sigma_v$  redundant (impossible)?  $\Rightarrow$  chase( $\sigma_v$ ,  $\Sigma$ ) = T( $\bot$ )?

is policy  $\sigma_i$  unaffected when a new error  $\epsilon_1$  is detected?  $\Rightarrow$  chase( $\sigma_i$ ,  $\{\epsilon_1, \Sigma\}$ ) =  $\sigma_i$ ?

is detected failure  $\epsilon_1$  a sure symptom of  $\sigma_i$ ?  $\Rightarrow$  chase( $\sigma_i$ ,  $\{\epsilon_1, \Sigma\}$ ) =  $\bot$ ?

is remote  $\epsilon_2$  bound to occur if  $\epsilon_1$  is detected?  $\Rightarrow$  chase( $\epsilon_2$ ,  $\{\epsilon_1, \Sigma\}$ ) = T?

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