

# Typicality Algorithm for Partial Trace Estimation

Robert Chen, Kevin Li, Skai Nzeuton, Yilu Pan, Yixin Wang

NYU Courant Institute of Mathematical Science

May 5th, 2023



## Background Introduction

- ▶ Study of quantum systems has gained significant attention due to its potential applications in quantum computing, quantum communication, and quantum sensing
- ▶ These systems are described by density matrices, which provide a comprehensive description of the quantum state of a system
- ▶ When we have a composite quantum system described by a density matrix, we often want to study the properties of one of its subsystems without considering the rest

## What is Partial Trace?

- Partial trace is a mathematical operation used to obtain the reduced density matrix from the density matrix of a larger composite system.

$$\begin{bmatrix} a_{00} & a_{01} & a_{02} & a_{03} \\ a_{10} & a_{11} & a_{12} & a_{13} \\ a_{20} & a_{21} & a_{22} & a_{23} \\ a_{30} & a_{31} & a_{32} & a_{33} \end{bmatrix} \xrightarrow{Tr_2} \begin{bmatrix} Tr \begin{bmatrix} a_{00} & a_{01} \\ a_{10} & a_{11} \end{bmatrix} & Tr \begin{bmatrix} a_{02} & a_{03} \\ a_{12} & a_{13} \end{bmatrix} \\ Tr \begin{bmatrix} a_{20} & a_{21} \\ a_{30} & a_{31} \end{bmatrix} & Tr \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} \end{bmatrix} \\
 = \begin{bmatrix} a_{00} + a_{11} & a_{02} + a_{13} \\ a_{20} + a_{31} & a_{22} + a_{33} \end{bmatrix}$$

**Tr<sub>2</sub>**

**Figure 1:** *Partial Trace Example*

# Computation and Storage Cost

- ▶ If we have an explicit representation of a matrix  $A$ , computing the partial trace of  $A$  is simple.
- ▶ What if  $A$  is a complicated matrix function?

$$Eg : A = \exp(-H/t)$$

- ▶ When the size of  $H$  is  $2^{20} * 2^{20}$  or even greater, the cost to compute and/or store  $A$  is too expensive.
- ▶ Hence a cheaper, faster algorithm is required.

## A Stochastic Partial Trace Estimator

- Essential of setting up:

$$\text{tr}(M) = \mathbb{E}[\mathbf{v}^T M \mathbf{v}], \quad \text{tr}^m(M) \approx \frac{1}{m} \sum_{i=1}^m \mathbf{v}^T M \mathbf{v}$$

where  $\mathbf{v}$  is a random vector with independent and identically distributed entries having a standard normal distribution.

- Extend this property to partial trace:

$$\begin{bmatrix} \text{tr}(A_{1,1}) & \text{tr}(A_{1,2}) & \cdots & \text{tr}(A_{1,a}) \\ \text{tr}(A_{2,1}) & \text{tr}(A_{2,2}) & \cdots & \text{tr}(A_{2,a}) \\ \vdots & \vdots & \ddots & \vdots \\ \text{tr}(A_{a,1}) & \text{tr}(A_{a,2}) & \cdots & \text{tr}(A_{a,a}) \end{bmatrix} = \mathbb{E} \begin{bmatrix} \mathbf{v}^T A_{1,1} \mathbf{v} & \mathbf{v}^T A_{1,2} \mathbf{v} & \cdots & \mathbf{v}^T A_{1,a} \mathbf{v} \\ \mathbf{v}^T A_{2,1} \mathbf{v} & \mathbf{v}^T A_{2,2} \mathbf{v} & \cdots & \mathbf{v}^T A_{2,a} \mathbf{v} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{v}^T A_{a,1} \mathbf{v} & \mathbf{v}^T A_{a,2} \mathbf{v} & \cdots & \mathbf{v}^T A_{a,a} \mathbf{v} \end{bmatrix}$$

- However, introducing randomness will definitely lead to a potentially large variance of the estimator.

## A Variance Reduce Algorithm

- ▶ Notice the following property of partial trace:

$$\text{tr}_b(A) = \text{tr}_b(\tilde{A}) + \text{tr}_b(A - \tilde{A}).$$

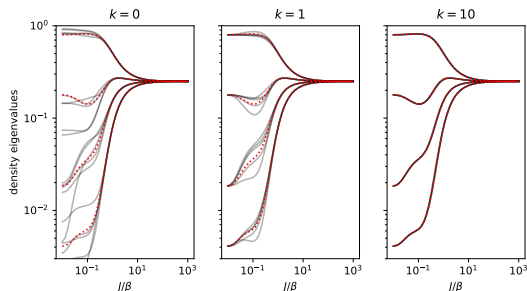
- ▶ We can compute the trace of  $\tilde{A}$  explicitly, and use the stochastic partial trace estimator we developed earlier to estimate  $\text{tr}_b(A - \tilde{A})$ , ie:

$$\text{tr}_b(\mathbf{A}) \approx \text{tr}_b(\tilde{A}) + \text{tr}_b^m(A - \tilde{A}).$$

- ▶  $\tilde{A}$  should be chosen so that  $\text{tr}_b^m(A - \tilde{A})$  produces a relatively smaller variance.
- ▶ Generalize  $A = \exp(-H/t)$  to any arbitrary matrix function  $A = f(H)$  using Krylov Subspace Method, which uses matrix polynomial functions to approximate  $A$ .

# Numerical Experiments

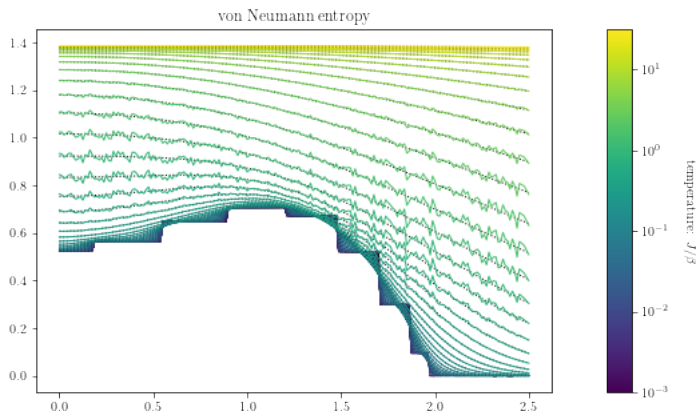
$$\rho^*(\beta) := \frac{\text{tr}_b(\exp(-\beta H))}{\text{tr}(\text{tr}_b(\exp(-\beta H)))}, \beta = \frac{1}{t}$$
$$\tilde{A} := QQ^T AQQ^T, Q \in \mathbb{R}^{d_A \times k}$$



**Figure 2:** comparison of  $k = 0$ ,  $k = 1$ , and  $k = 10$

# Adaptive Point Estimation

- Our blackbox function generates the graph below:



- To estimate the points at which the function changes, use binary search method with sample points.



# Supercomputer

- ▶ To study the performance of different quantum systems, we will conduct numerical experiments on the NYU Greene Supercomputer.
- ▶ The problem is well-suited for parallel computing:
- ▶ Inputs are independent of each other without the need to exchange information.

## Q & A

Any Questions?