## EN2550: Assignment 03 on Object Counting on a Conveyor Belt

## **Connected Component Analysis**

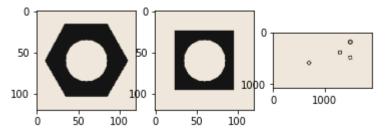
In this part, we will generate an indexed image representing connected components in conveyor\_f101.png image. Notice that, as there are three square nuts and one hexagonal nut in the image, there will be five connected components (backgound will be assigned the label 0).

1. Open the hexnut\_template.png, squarenut\_template.png and conveyor\_f100.png and display. This is done for you.

```
import cv2 as cv
import numpy as np
import matplotlib.pyplot as plt

hexnut_template = cv.imread('hexnut_template.png', cv.IMREAD_COLOR)
squarenut_template = cv.imread('squarenut_template.png', cv.IMREAD_COLOR)
conveyor_f100 = cv.imread('conveyor_f100.png', cv.IMREAD_COLOR)

fig, ax = plt. subplots(1,3)
ax[0].imshow(cv.cvtColor(hexnut_template, cv.COLOR_RGB2BGR))
ax[1].imshow(cv.cvtColor(squarenut_template, cv.COLOR_RGB2BGR))
ax[2].imshow(cv.cvtColor(conveyor_f100, cv.COLOR_RGB2BGR))
plt.show()
```



1. Convert the images to grayscale and apply Otsu's thresholding to obtain the binarized image. Do this for both the templates and belt images. See <a href="https://docs.opencv.org/master/d7/d4d/tutorial\_py\_thresholding.html">https://docs.opencv.org/master/d7/d4d/tutorial\_py\_thresholding.html</a> for a guide. State the threshold value (automatically) selected in the operation. Display the output images.

```
In [ ]: # Your code here.
```

1. Carry out morphological closing to remove small holes inside the foreground. Use a  $3\times 3$  kernel. See https://docs.opencv.org/master/d9/d61/tutorial\_py\_morphological\_ops.html for a guide.

```
In [ ]: # Your code here.
```

1. Connected components analysis: apply the connectedComponentsWithStats function (see

https://docs.opencv.org/4.5.5/d3/dc0/group\_imgproc\_shape.html#ga107a78bf7cd25dec05fb² and display the outputs as colormapped images. Answer the following questions

- How many connected components are detected in each image?
- What are the statistics? Interpret these statistics.
- What are the centroids?

For the hexnut template, you should get the object area in pixel as approximately 4728.

```
In []: # Your code here.
```

1. Contour analysis: Use findContours function to retrieve the *extreme outer* contours. (see https://docs.opencv.org/4.5.2/d4/d73/tutorial\_py\_contours\_begin.html for help and https://docs.opencv.org/4.5.2/d3/dc0/group\_imgproc\_shape.html#gadf1ad6a0b82947fa1fe3c for information.

Display these contours. You should see something like the following:

```
extreme_outer_contours
```

## **Detecting Objects on a Synthetic Conveyor**

In this section, we will use the synthetic conveyor.mp4 sequence to count the two types of nuts.

1. Open the sequence and play it using the code below.

```
In []: cv.namedWindow('Conveyor', cv.WINDOW_NORMAL)
    cap = cv.VideoCapture('conveyor.mp4')
    f = 0
    frame = []
    while cap.isOpened():
        ret, frame = cap.read()
        if not ret:
            print("Can't receive frame (stream end?). Exiting.")
            break

    f += 1
        text = 'Frame:' + str(f)
        cv.putText(frame,text , (100, 100), cv.FONT_HERSHEY_COMPLEX, 1, (0,250,0), 1, cv.l
        cv.imshow('Conveyor', frame)

    if cv.waitKey(1) == ord('q'):
```

```
break
cap.release()
cv.destroyAllWindows()

In []: # Your code here.
```

- Count the number of matching hexagonal nuts in conveyor\_f100.png. You can use matchCountours function as shown in https://docs.opencv.org/4.5.2/d5/d45/tutorial\_py\_contours\_more\_functions.html to match contours in each frame with that in th template.
- 1. Count the number of objects that were conveyed along the conveyor belt: Display the count in the current frame and total count upto the current frame in the output video. Please compress your video (using Handbreak or otherwise) before uploading. It would be good to experiment first with the two adjacent frames conveyor\_f100.png and conveyor\_f101.png. In order to disregard partially appearing nuts, consider comparing the contour area in addition to using the matchCountours function.

```
In []: # Yor code here.

# Writing the video

frame_array = []
    shape = (1080, 1920, 3)

# Your code here

out = cv.VideoWriter('./conveyor_result_indexno.mp4',cv.VideoWriter_fourcc(*'h264'), 3

for i in range(len(frame_array)):
    cv.imshow('Frame', frame_array[i])
    if cv.waitKey(1) == ord('q'):
        break
    out.write(frame_array[i])

out.release()
    cv.destroyAllWindows()
```