# HUGGING FACE ACCELERATE: MAKING DEVICE-AGNOSTIC ML TRAINING AND INFERENCE EASY AT SCALE

### WHO AM I?

- Zachary Mueller
- Technical Lead for the Accelerate project
- Maintain the transformers Trainer
- API design geek



- A training framework
- An inference framework
- A command-line interface

### A TRAINING FRAMEWORK

- Powered by PyTorch
- Change a few lines of code, gain device and hardwareagnostic capabilities
- Low-code, with minimal magic aimed at easy hackability and use without high-level abstractions
- We handle the intracies so you don't have to

### A TRAINING FRAMEWORK

- Support for any hardware-accelerator on the market:
  - CPU, GPU, TPU, XPU, NPU, MLU
- Automatic mixed-precision training *safely* in whatever fashion you may choose:
  - FP16, BF16, FP8 (through either TransformerEngine or MS-AMP)
- Automatic and efficient gradient accumulation
- Support for quantization through bitsandbytes
- Support your favorite experiment trackers (aim, clearml, comet\_ml, dvc-lite, ml-flow, tensorboard, wandb)
- Easy to configure plugin or YAML-level API for setting up advanced frameworks like FSDP, DeepSpeed, and Megatron-LM

### **LOW-CODE**

- Biggest friction with "wrapper" libraries is control of your code
- By being minimally intrusive, your code just "works" while still giving you complete control

```
import torch
     import torch.nn.functional as F
     from datasets import load_dataset
     model = torch.nn.Transformer().to(device)
    optimizer = torch.optim.Adam(model.parameters())
    dataset = load_dataset('my_dataset')
13
     data = torch.utils.data.DataLoader(dataset, shuffle=True)
14
     model.train()
     for epoch in range(10):
         for source, targets in dataloader:
              source, targets = source.to(device), targets.to(device)
             optimizer.zero_grad()
             output = model(source)
             loss = F.cross_entropy(output, targets)
             optimizer.step()
```

### EASY TO INTEGRATE

- Due to the low-code nature, it's trivial to integrate into existing PyTorch frameworks:
  - 1. Create an Accelerator

```
import torch
     import torch.nn.functional as F
     from datasets import load_dataset
     device = 'cpu'
     model = torch.nn.Transformer().to(device)
    optimizer = torch.optim.Adam(model.parameters())
    dataset = load_dataset('my_dataset')
     data = torch.utils.data.DataLoader(dataset, shuffle=True)
13
     model.train()
     for epoch in range (10):
         for source, targets in dataloader:
              source, targets = source.to(device), targets.to(device)
             optimizer.zero_grad()
             output = model(source)
             loss = F.cross_entropy(output, targets)
             loss.backward()
             optimizer.step()
```

### **EASY TO INTEGRATE**

- Due to the low-code nature, it's trivial to integrate into existing PyTorch frameworks:
  - 2. Wrap your PyTorch objects with accelerator.prepare and remove device-placements

```
import torch
     import torch.nn.functional as F
     from datasets import load_dataset
     from accelerate import Accelerator
     accelerator = Accelerator()
    model = torch.nn.Transformer().to(device)
    optimizer = torch.optim.Adam(model.parameters())
     dataset = load_dataset('my_dataset')
12
     data = torch.utils.data.DataLoader(dataset, shuffle=True)
13
14
     model.train()
     for epoch in range(10):
17
         for source, targets in dataloader:
              source, targets = source.to(device), targets.to(device)
             optimizer.zero_grad()
             output = model(source)
             loss = F.cross_entropy(output, targets)
23
             loss.backward()
             optimizer.step()
```

### EASY TO INTEGRATE

- Due to the low-code nature, it's trivial to integrate into existing PyTorch frameworks:
  - 3. Use accelerator.backward for the backward pass

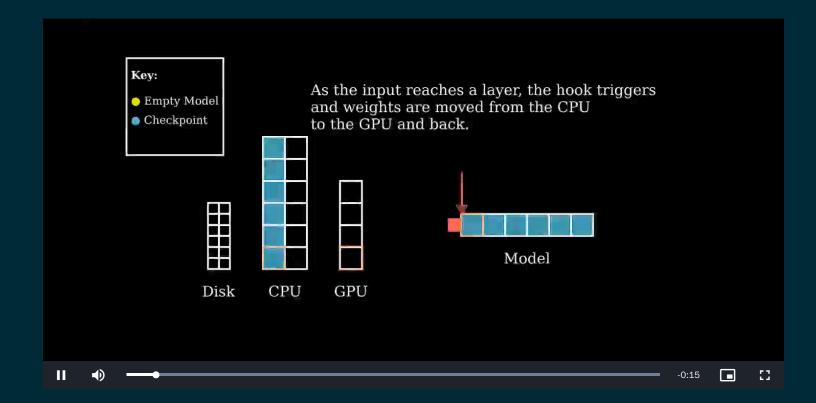
```
import torch
     import torch.nn.functional as F
     from datasets import load_dataset
     from accelerate import Accelerator
    accelerator = Accelerator()
     model = torch.nn.Transformer().to(device)
     optimizer = torch.optim.Adam(model.parameters())
     dataset = load_dataset('my_dataset')
     data = torch.utils.data.DataLoader(dataset, shuffle=True)
13
     model, optimizer, dataloader = accelerator.prepare(model, optimizer, dataloader
     model.train()
     for epoch in range (10):
         for source, targets in dataloader:
              source, targets = source.to(device), targets.to(device)
             optimizer.zero_grad()
             output = model(source)
             loss = F.cross_entropy(output, targets)
             optimizer.step()
```

### **BUT WHAT ABOUT INFERENCE?**

- Accelerate is not just for training, and has helped make the GPU-Poor take control of the narrative
- Using tools like Big Model Inference, users with tiny compute can run large models locally
- Started with the boom of stable diffusion, and now has scaled to having the ability to run huge LLMs locally with a single graphics card

### **HOW DOES IT WORK?**

- PyTorch introduced device="meta"
- Accelerate introduced device\_map="auto"



### A CLI INTERFACE

- accelerate config
  - Configure the environment
- accelerate launch
  - How to run your script

### LAUNCHING DISTRIBUTED TRAINING IS HARD

```
1 python script.py
```

VS.

```
1 torchrun --nnodes=1 --nproc_per_node=2 script.py
```

VS.

```
1 deepspeed --num_gpus=2 script.py
```

How can we make this better?

#### accelerate launch

```
1 accelerate launch script.py
```

```
1 accelerate launch --multi_gpu --num_processes 2 script.py
```

```
1 accelerate launch \
2   --multi_gpu \
3   --use_deepspeed \
4   --num_processes 2 \
5   script.py
```

#### accelerate config

- Rely on config. yaml files
- Choose to either running accelerate config or write your own:

```
ddp_config.yaml

1 compute_environment: LOCAL_MACHINE
2 distributed_type: MULTI_GPU
3 main_training_function: main
4 mixed_precision: bf16
5 num_machines: 1
6 num_processes: 8
```

```
fsdp_config.yaml

1 compute_environment: LOCAL_MACHINE
2 distributed_type: FSDP
3 fsdp_config:
4 fsdp_auto_wrap_policy: TRANSFORMER_BASED_WRA
5 fsdp_backward_prefetch: BACKWARD_PRE
6 fsdp_cpu_ram_efficient_loading: true
7 fsdp_forward_prefetch: false
8 fsdp_offload_params: false
9 fsdp_sharding_strategy: FULL_SHARD
10 fsdp_state_dict_type: SHARDED_STATE_DICT
11 fsdp_sync_module_states: true
12 fsdp_use_orig_params: false
13 main_training_function: main
14 mixed_precision: bf16
15 num_machines: 1
16 num_processes: 8
```

# NOW THAT YOU'RE UP TO SPEED, WHAT'S NEW?

# WE'VE HAD A BUSY LAST YEAR, AND SO HAS THE ML COMMUNITY!

### **NEW TRAINING TECHNIQUES**

- Quantization has taken the field by storm
- New ideas such as FSDP + QLoRA to train huge models on tiny compute!
- New precision backends as we train natively on smaller precision
- Optimizing futher how much we can push on a single machine through efficient RAM and timing techniques

### LARGER COMPUTE LANDSCAPE

- As we search for alternatives to NVIDIA, new compilers rise:
  - XPU (Intel)
  - NPU (Intel)
  - MLU (Cambricon)

All of which are supported by 🤗 Accelerate

### **LOWER ABSTRACTIONS**

- While the Accelerator was great, needed better abstractions focused on controlling behaviors
- Introduced the Partial State

```
1 from accelerate import PartialState
2
3 if PartialState().is_main_process:
4  # Run on only 1 device
5
6 with PartialState().main_process_first:
7  # Useful for dataset processing
8
9 # Device-agnostic without the bulk of the `Accelerator`
10 device = PartialState().device
```

### FASTER AND BETTER INFERENCE ALTERNATIVES

- Pippy gives us efficient pipeline-parallelism in distributed environments to increase throughput while keeping a simple torch-bound API
- Rather than having to wait for each GPU, every GPU can be busy in parallel

```
1 import torch
2 from transformers import AutoModelForSequenceClassification
3
4 from accelerate import PartialState, prepare_pippy
5
6 model = AutoModelForSequenceClassification.from_pretrained("gpt2")
7 model.eval()
8
9 input = torch.randint(
10 low=0,
11 high=model.config.vocab_size,
12 size=(2, 1024), # bs x seq_len
13 device="cpu",
14 )
15
16 model = prepare_pippy(model, split_points="auto", example_args=(input, 17)
18 with torch.no_grad():
19 output = model(input)
```

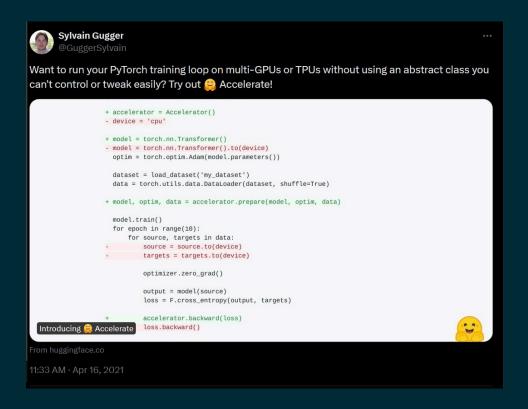
# ADOPTION: ACCELERATE IN THE ECOSYSTEM

### **ACCELERATE IN THE ECOSYSTEM**

- Many of the frameworks you use daily already rely on Accelerate!
  - Nearly all of <a></a>
  - axolotl
  - fastai
  - FastChat
  - lucidrains
  - kornia

### ACCELERATE IN THE ECOSYSTEM

• Started as a way to isolate out distributed code on TPU and DistributedDataParallelism



### **ACCELERATE IN THE ECOSYSTEM**

 Now is the backbone of some of the largest PyTorch training frameworks in the ecosystem



## WHAT'S NEXT?

### ELEVATING THE COMMUNITY

- Now that more advanced training techniques are reachable (FSDP, DeepSpeed, etc), we need to focus on educating the community on how to use it best
- Goes beyond how to use the Trainer or Accelerator, but how to use what where
- Keep Accelerate as a tool for the community to utilize when new techniques come out and play with, to push new ideas to scale quickly

### 1.0.0: SOON!

- Tried and battle-tested by over 7M users/month
- As we've been stable for over a year now, we're near ready to release 1.0.0

### THANKS FOR JOINING!

- Accelerate documentation
- Launching distributed code
- Distributed code and Jupyter Notebooks
- Migrating to 
   Accelerate easily
- Big Model Inference tutorial
- DeepSpeed and 
   Accelerate
- Fully Sharded Data Parallelism and 🤗 Accelerate
- FSDP vs DeepSpeed In-Depth