How to run the program?

- 1. In your IDE, activate "onebyzero_env" virtual environment to avoid "module not found" errors. (If you don't follow this, you might need to install missing packages in your local environment.)
- 2. Open the jupyter notebook file named "solution.ipynb".
- This notebook has three sections:
 - a. INPUTS: Here you have to provide:
 - i. the correct path for order data and driver data csv
 files
 - ii. Set "one_driver_one_order_bool". When this is set to True, we are solving the variation 1 of the problem. When this is set to False, we are solving the variation 2 of the problem.
 - iii. The path of the output file containing the final routes and driver-order assignments are also set according to the above boolean variable.
 - b. DATA PREPARATION: This part prepares input data in the required format to be consumed by ortools routing engine.
 - c. SOLVE: This part calls the main function to model the problem and run the routing engine. Also, this will publish the output in a .txt file.

How are the results produced?

This problem has been solved using google ortools routing engine.

First data preparation is done.

- 1. Distance Matrix: We created the distance matrix for the problem using geodesics.
- 2. Index locations by dividing them into pickup locations and drop locations.
- 3. Set resources like demands, order counts for all nodes.
- 4. Set time windows for all nodes.

Steps followed are:

- a. Create nodes for locations.
- b. Set vehicle start and end nodes.
- c. Set travel costs for the routes.
- d. Apply constraints:
 - i. Pickup and Delivery constraints
 - ii. Capacity constraints
 - iii. One order at a time constraint (in variation 1)
 - iv. Soft Time Window constraints with penalty
- e. Set solution search parameters.
- f. Search for the solution.
- g. Parse the solution to get all routes, driver order assignments and route metrics.

h. Dump the output file in .txt format.

About program files:

<u>solution.ipynb</u>: Main solution notebook which needs to be run by the end user.

<u>input.py</u>: This reads data from given paths and does basic data sanity checks.

<u>distance_matrix.py</u>: This calculates distance matrix using geodesics and caches it for reusability.

<u>data.py</u>: Main data processing file which prepares everything to become suitable for consumption by ortools.

<u>manager.py</u>: This initiates the ortools routing engine and sets the index manager.

<u>solver.py</u>: This sets the search parameters for the routing engine.

<u>solution_reader.py</u>: This reads and parses the solution in required format.

<u>model.py</u>: This is the main file which calls and combines above files to dump the final solution as a text file.