COAL Chapter 3

Week 3
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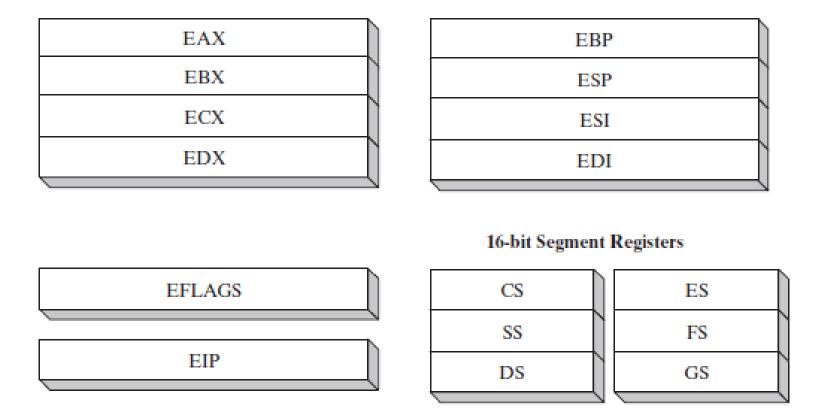
Basic Program Execution Registers

 Registers are high-speed storage locations directly inside the CPU, designed to be accessed at much higher speed than conventional memory

 There are eight general-purpose registers, six segment registers, a processor status flags register (EFLAGS), and an instruction pointer (EIP)

Figure 2-5 Basic Program Execution Registers.

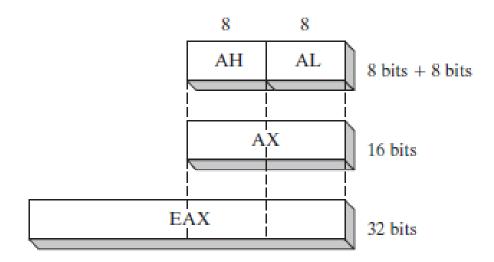
32-bit General-Purpose Registers



General-Purpose Registers:

The *general-purpose registers* are primarily used for arithmetic and data movement.

- As shown in Figure 2–6, the lower 16 bits of the EAX register can be referenced by the name AX
- Portions of some registers can be addressed as 8-bit values
 - For example, the AX register, has an 8-bit upper half named Figure 2-6 General-Purpose Registers.



32-Bit	16-Bit	8-Bit (High)	8-Bit (Low)
EAX	AX	AH	AL
EBX	BX	ВН	BL
ECX	CX	СН	CL
EDX	DX	DH	DL

The remaining general-purpose registers can only be accessed using 32-bit or 16-bit names, as shown in the following table:

32-Bit	16-Bit
ESI	SI
EDI	DI
EBP	BP
ESP	SP

Specialized Uses of general-purpose registers

Some general-purpose registers have specialized uses:

- EAX (accumulator) favored for arithmetic operations.
 - It is automatically used by multiplication and division instructions
- EBX (Base) Holds base address for procedures and variables
- ECX The CPU automatically uses ECX as a counter for looping operations
- EDX (Data) Used in multiplication and division operations

Index Registers

Index Registers contain the offsets for data and instructions.

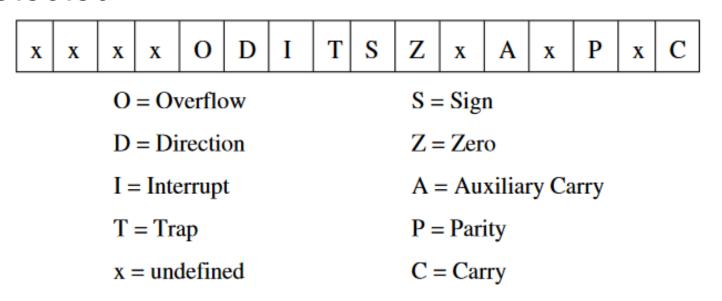
Offset- distance (in bytes) from the base address of the segment.

- ESP (extended stack pointer register) contains the offset for the top of the stack to addresses data on the stack (a system memory structure)
- ESI and EDI (extended source index and extended destination index) points to the source and destination string respectively in the string move instructions
- EBP is used to reference function parameters and local variables on the stack

EFLAGS Register:

The EFLAGS register consists of individual binary bits that control the operation of the CPU or reflect the outcome of some CPU operation.

- A flag is set when it equals 1; it is clear (or reset) when it equals 0.
- Programs can set individual bits in the EFLAGS register to control the CPU's operation
- For example: Interrupt when arithmetic overflow is detected



Flags

There are two types of flags: control flags (which determine how instructions are carried out) and status flags (which report on the results of operations.

Control flags include:

- Direction Flag (DF) affects the direction of block data transfers (like long character string). 1 = up; 0 - down.
- Interrupt Flag (IF) determines whether interrupts can occur (whether hardware devices like the keyboard, disk drives, and system clock can get the CPU's attention to get their needs attended to.
- Trap Flag (TF) determines whether the CPU is halted after every instruction. Used for debugging purposes.

Status Flags

The Status flags reflect the outcomes of arithmetic and logical operations performed by

- Status Flags include:
 - Carry Flag (CF) set when the result of unsigned arithmetic is too large to fit in the destination. 1 = carry; 0 = no carry.
 - Overflow Flag (OF) set when the result of signed arithmetic is too large to fit in the destination. 1 = overflow; 0 = no overflow.
 - Sign Flag (SF) set when an arithmetic or logical operation generates a negative result. 1 = negative; 0 = positive.
 - Zero Flag (ZF) set when an arithmetic or logical operation generates a result of zero. Used primarily in jump and loop operations. 1 = zero; 0 = not zero.
 - Auxiliary Carry Flag set when an operation causes a carry from bit 3 to 4 or borrow (frombit 4 to 3). 1 = carry, 0 = no carry.
 - Parity- is set if the least-significant byte in the result contains an even number of 1 bits. It used to verify memory integrity.

Integer Constants

An *integer constant* (or integer literal) is made up of an optional leading sign, one or more digits, and an optional suffix character (called a *radix*) indicating the number's base:

$$[\{+|-\}]$$
 digits [radix]

Radix may be one of the following (uppercase or lowercase):

h	Hexadecimal	r	Encoded real
q/o	Octal	t	Decimal (alternate)
d	Decimal	У	Binary (alternate)
b	Binary		

If no radix is given, the integer constant is assumed to be decimal. Here are some examples using different radixes:

26	Decimal	420	Octal
26d	Decimal	1Ah	Hexadecimal
11010011b	Binary	0A3h	Hexadecimal
42q	Octal		

Integer Expressions

- An integer expression is a mathematical expression involving integer values and arithmetic operators
- The integer expression must evaluate to an integer, which can be stored in 32 bits (0 through FFFFFFFFh)

Table 3-1 Arithmetic Operators.

Operator	Name	Precedence Level
()	Parentheses	1
+, -	Unary plus, minus	2
*,/	Multiply, divide	3
MOD	Modulus	3
+, -	Add, subtract	4

Precedence refers to the implied order of operations when an expression contains two or more operators. The order of operations is shown for the following expressions:

The following are examples of valid expressions and their values:

Expression	Value
16/5	3
-(3 + 4) * (6 - 1)	-35
-3 + 4 * 6 - 1	20
25 mod 3	1

3.1.3 Real Number Constants

Real number constants are represented as decimal reals or encoded (hexadecimal) reals. A decimal real contains an optional sign followed by an integer, a decimal point, an optional integer that expresses a fraction, and an optional exponent:

```
[sign]integer.[integer][exponent]
```

Following are the syntax for the sign and exponent:

```
sign {+,-}
exponent E[{+,-}]integer
```

Following are examples of valid real number constants:

```
2.
+3.0
-44.2E+05
26.E5
```

At least one digit and a decimal point are required.

rVal1 REAL4 -1.2 rVal2 REAL8 3.2E-260 rVal3 REAL10 4.6E+4096 ShortArray REAL4 20 DUP(0.0)

Table 3-4 Standard Real Number Types.

Data Type	Significant Digits	Approximate Range
Short real	6	$1.18 \times 10^{-38} \text{ to } 3.40 \times 10^{38}$
Long real	15	2.23×10^{-308} to 1.79×10^{308}
Extended-precision real	19	3.37×10^{-4932} to 1.18×10^{4932}

3.1.4 Character Constants

A character constant is a single character enclosed in single or double quotes. MASM stores the value in memory as the character's binary ASCII code. Examples are

^{&#}x27;A'

[&]quot;d"

3.1.5 String Constants

A *string constant* is a sequence of characters (including spaces) enclosed in single or double quotes:

```
'ABC'
'X'
"Good night, Gracie"
'4096'
```

Embedded quotes are permitted when used in the manner shown by the following examples:

```
"This isn't a test"
'Say "Good night," Gracie'
```

3.1.6 Reserved Words

Reserved words have special meaning in MASM and can only be used in their correct context. There are different types of reserved words:

- Instruction mnemonics, such as MOV, ADD, and MUL
- · Register names
- Directives, which tell MASM how to assemble programs
- Attributes, which provide size and usage information for variables and operands. Examples are BYTE and WORD
- Operators, used in constant expressions
- Predefined symbols, such as @data, which return constant integer values at assembly time

3.1.7 Identifiers

An *identifier* is a programmer-chosen name. It might identify a variable, a constant, a procedure, or a code label. Keep the following in mind when creating identifiers:

- They may contain between 1 and 247 characters.
- They are not case sensitive.
- The first character must be a letter (A..Z, a..z), underscore (_), @ , ?, or \$. Subsequent characters may also be digits.
- An identifier cannot be the same as an assembler reserved word.

The @ symbol is used extensively by the assembler as a prefix for predefined symbols, so avoid it in your own identifiers. Make identifier names descriptive and easy to understand. Here are some valid identifiers:

var1	Count	\$first
_main	MAX	open_file
myFile	xVal	_12345

3.1.8 Directives

A directive is a command embedded in the source code that is recognized and acted upon by the assembler. Directives do not execute at runtime. Directives can define variables, macros, and procedures. They can assign names to memory segments and perform many other housekeeping tasks related to the assembler. In MASM, directives are case insensitive. For example, it recognizes .data, .DATA, and .Data as equivalent.

The following example helps to show the difference between directives and instructions. The DWORD directive tells the assembler to reserve space in the program for a doubleword variable. The MOV instruction, on the other hand, executes at runtime, copying the contents of myVar to the EAX register:

```
myVar DWORD 26 ; DWORD directive mov eax, myVar ; MOV instruction
```

Defining Segments One important function of assembler directives is to define program sections, or segments. The .DATA directive identifies the area of a program containing variables:

```
.data
```

The .CODE directive identifies the area of a program containing executable instructions:

```
.code
```

The .STACK directive identifies the area of a program holding the runtime stack, setting its size:

```
.stack 100h
```

Directives

- Commands that are recognized and acted upon by the assembler
 - Not part of the Intel instruction set
 - Used to declare code, data areas, select memory model, declare procedures, etc.
 - not case sensitive
- Different assemblers have different directives
 - NASM not the same as MASM, for example

myVar DWORD 26; DWORD directive, set aside

; enough space for double word

Mov eax, myVar ; MOV instruction

3.1.9 Instructions

An instruction is a statement that becomes executable when a program is assembled. Instructions are translated by the assembler into machine language bytes, which are loaded and executed by the CPU at runtime. An instruction contains four basic parts:

- Label (optional)
- Instruction mnemonic (required)
- Operand(s) (usually required)
- Comment (optional)

This is the basic syntax:

```
[label:] mnemonic [operands] [;comment]
```

Instructions

- An instruction is a statement that becomes executable when a program is assembled.
- Assembled into machine code by assembler
- Executed at runtime by the CPU
- We use the Intel IA-32 instruction set
- An instruction contains:
 - Label (optional)
 - Mnemonic (required)
 - Operand (depends on the instruction)
 - Comment (optional)
- Basic syntax
 - [label:] mnemonic [operands] [; comment]

Label

A *label* is an identifier that acts as a place marker for instructions and data. A label placed just before an instruction implies the instruction's address. Similarly, a label placed just before a variable implies the variable's address.

Data Labels A data label identifies the location of a variable, providing a convenient way to reference the variable in code. The following, for example, defines a variable named count:

```
count DWORD 100
```

The assembler assigns a numeric address to each label. It is possible to define multiple data items following a label. In the following example, array defines the location of the first number (1024). The other numbers following in memory immediately afterward:

```
array DWORD 1024, 2048
DWORD 4096, 8192
```

Code Labels A label in the code area of a program (where instructions are located) must end with a colon (:) character. Code labels are used as targets of jumping and looping instructions. For example, the following JMP (jump) instruction transfers control to the location marked by the label named target, creating a loop:

```
target:

mov ax,bx
...
jmp target
```

A code label can share the same line with an instruction, or it can be on a line by itself:

```
L1: mov ax,bx
L2:
```

3.1.10 The NOP (No Operation) Instruction

The safest (and the most useless) instruction you can write is called NOP (no operation). It takes up 1 byte of program storage and doesn't do any work. It is sometimes used by compilers and assemblers to align code to even-address boundaries. In the following example, the first MOV instruction generates three machine code bytes. The NOP instruction aligns the address of the third instruction to a doubleword boundary (even multiple of 4):

```
00000000 66 8B C3 mov ax,bx
00000003 90 nop ; align next instruction
00000004 8B D1 mov edx,ecx
```

x86 processors are designed to load code and data more quickly from even doubleword addresses.

Labels

- Act as place markers
 - marks the address (offset) of code and data
- Follow identifier rules
- Data label
 - must be unique
 - example: myArray (not followed by colon)
 - count DWORD 100
- Code label
 - target of jump and loop instructions
 - example: L1: (followed by colon)

Mnemonics and Operands

- Instruction Mnemonics
 - memory aid
 - examples: MOV, ADD, SUB, MUL, INC, DEC
- Operands

constant96

constant expression2 + 4

registereax

memory (data label) count

Constants and constant expressions are often called immediate values

Instruction Format Examples

No operands

– stc ; set Carry flag

One operand

– inc eax ; register

– inc myByte ; memory

Two operands

add ebx, ecx ; register, register

sub myByte, 25 ; memory, constant

add eax, 36 * 25 ; register, constant-expression

```
TITLE Add and Subtract
                                   (AddSub.asm)
; This program adds and subtracts 32-bit integers.
INCLUDE Irvine32.inc
   .code
   main PROC
       mov eax, 10000h
                                  : EAX = 10000h
       add eax, 40000h
                                  ; EAX = 50000h
       sub eax, 20000h
                                  : EAX = 30000h
       call DumpRegs
                                  ; display registers
```

exit main ENDP END main TITLE Add and Subtract

(AddSub.asm)

The TITLE directive marks the entire line as a comment. You can put anything you want on this line.

; This program adds and subtracts 32-bit integers.

All text to the right of a semicolon is ignored by the assembler, so we use it for comments.

INCLUDE Irvine32.inc

The INCLUDE directive copies necessary definitions and setup information from a text file named *Irvine32.inc*, located in the assembler's INCLUDE directory. (The file is described in Chapter 5.)

```
.code
```

The .code directive marks the beginning of the *code segment*, where all executable statements in a program are located.

```
main PROC
```

The PROC directive identifies the beginning of a procedure. The name chosen for the only procedure in our program is main.

```
mov eax, 10000h ; EAX = 10000h
```

The MOV instruction moves (copies) the integer 10000h to the EAX register. The first operand (EAX) is called the *destination operand*, and the second operand is called the *source operand*. The comment on the right side shows the expected new value in the EAX register.

```
add eax, 40000h ; EAX = 50000h
```

The ADD instruction adds 40000h to the EAX register. The comment shows the expected new value in EAX.

```
sub eax, 20000h ; EAX = 30000h
```

The SUB instruction subtracts 20000h from the EAX register.

```
call DumpRegs ; display registers
```

The CALL statement calls a procedure that displays the current values of the CPU registers. This can be a useful way to verify that a program is working correctly.

```
exit
main ENDP
```

The exit statement (indirectly) calls a predefined MS-Windows function that halts the program. The ENDP directive marks the end of the main procedure. Note that exit is not a MASM keyword; instead, it's a macro command defined in the *Irvine32.inc* include file that provides a simple way to end a program.

```
END main
```

The END directive marks the last line of the program to be assembled. It identifies the name of the program's *startup* procedure (the procedure that starts the program execution).

Program Output The following is a snapshot of the program's output, generated by the call to DumpRegs:

```
EAX=00030000 EBX=7FFDF000 ECX=00000101 EDX=FFFFFFFF ESI=000000000 EDI=00000000 EBP=0012FFF0 ESP=0012FFC4 EIP=00401024 EFL=00000206 CF=0 SF=0 ZF=0 OF=0 AF=0 PF=1
```

3.4.1 Intrinsic Data Types

MASM defines *intrinsic data types*, each of which describes a set of values that can be assigned to variables and expressions of the given type. The essential characteristic of each type is its size in bits: 8, 16, 32, 48, 64, and 80. Other characteristics (such as signed, pointer, or floating-point) are optional and are mainly for the benefit of programmers who want to be reminded about the type of data held in the variable. A variable declared as DWORD, for example, logically holds an unsigned 32-bit integer. In fact, it could hold a signed 32-bit integer, a 32-bit single precision real, or a 32-bit pointer. The assembler is not case sensitive, so a directive such as DWORD can be written as **dword**, **Dword**, **dWord**, and so on.

Table 3-2 Intrinsic Data Types.

Туре	Usage
BYTE	8-bit unsigned integer. B stands for byte
SBYTE	8-bit signed integer. S stands for signed
WORD	16-bit unsigned integer (can also be a Near pointer in real-address mode)
SWORD	16-bit signed integer
DWORD	32-bit unsigned integer (can also be a Near pointer in protected mode). D stands for double
SDWORD	32-bit signed integer. SD stands for signed double
FWORD	48-bit integer (Far pointer in protected mode)
QWORD	64-bit integer. Q stands for quad
TBYTE	80-bit (10-byte) integer. T stands for Ten-byte
REAL4	32-bit (4-byte) IEEE short real
REAL8	64-bit (8-byte) IEEE long real
REAL10	80-bit (10-byte) IEEE extended real

```
.data
promptUse byte "Enter two integers: ", O
results byte "Result is: ", 0
.code
main proc
mov esi, offset array
mov ecx, int_count
11:
mov edx, offset promptUser
call writestring
call readint
mov [esi],eax
add eax, [esi]
add esi, type dword
loop 11
```

mov edx, offset results call writestring call writeint exit main endp end main