

1 **STLViz: C++ Visualized**

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3 ADVAIT PARMAR, ALEX YOSHIDA, and SIDHARTH BANKUPALLE, University of North Carolina at
4 Chapel Hill, USA
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6 C++ Standard Template Library (STL) containers are a challenge to debug, especially for programming beginners who might not be as
7 adept at understanding how data structures evolve at runtime, as existing debuggers expose low-level state textually but do little
8 to provide an intuition about operation-level semantics. To address this gap, we developed STLviz, a C++ visualization library that
9 integrates directly into user code and provides step-by-step, graphical visualizations of STL data structures and algorithms, including
10 support for forward and reverse stepping through operations. STLviz wraps standard library containers to capture operations and
11 displays their runtime state through an interactive graphical interface following the "overview, zoom, filter" framework [1] designed
12 to reduce cognitive load. Finally, to understand how STLviz could help novices debug C++ programs better, we evaluated our tool
13 through a small user study in which participants attempted to debug code with and without the tool. Our results suggest that STLviz
14 helps users better understand data-structure behaviour, reduces mental effort during debugging, and is particularly helpful for students
15 new to programming learn the skill.
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19 **1 Introduction**

20 Visually debugging C++ and learning data structures and basic algorithms in it remains a challenge today, especially
21 for beginners. Understanding how various operations change the state of a data structure is a cognitively demanding
22 task, particularly for learners who are still developing an intuition for how these structures evolve at runtime.
23

24 Visualizations are effective in learning algorithmic thinking and data-structure behaviour [2] [3], however, most
25 existing resources fall short of executing directly on top of a user's C++ code and providing visualizations to understand
26 the evolution of data structures used in the program. For example, Visualgo [4] is one such useful tool made for
27 pedagogical purposes, but it is browser-based. Alternatives such as GDB, LLDB and IDE-integrated tools exist and are
28 powerful tools, they let users peek into memory, not concepts. Such debuggers typically require substantial expertise to
29 use effectively, and even then primarily expose the underlying program state through text-based or breakpoint-driven
30 interfaces. They are invaluable to experienced programmers, but perhaps not so much to new developers. As a result,
31 novices often struggle, not with understanding what data a structure such as a binary tree might currently hold, but
32 how it got to its present state and why a particular bug emerged. This issue is especially pronounced with C++ Standard
33 Library (STL) data structures, where a lot of the intermediate steps involved in basic operations, like copy/move
34 operations, pointer invalidation and hash table/tree updates, are abstracted out and are difficult to follow even while
35 stepping through a program with a debugger.
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38 To address this gap, we present STLviz, a C++ visualization library that embeds directly into code and provides
39 step-through representations of standard library data structures. STLviz allows beginners to observe program behaviour
40 at a per-operation level (*e.g.* std::vector.push_back or std::stack.pop), helping them develop an intuition of how code
41 affects underlying containers. By integrating directly into the compilation and execution pipeline, STLviz aims to
42 reduce cognitive load on new programmers while being customized to the particular context in which data structures
43 are being used in their program.
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48 Authors' Contact Information: Advait Parmar, advaitp@cs.unc.edu; Alex Yoshida, alexander.yoshida@gmail.com; Sidharth Bankupalle, bankupal@cs.unc.
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50 edu, University of North Carolina at Chapel Hill, USA.
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53 2 Background

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 55
 Understanding how data structures and algorithms evolve at runtime is a key skill any competent programmer must
 56 possess in order to be adept at software engineering and develop effective debugging strategies. However, how
 57 programmers develop this understanding has undergone significant changes in recent years. Many students are now
 58 introduced to computer science through visual or high-level programming languages such as Scratch or Python, which
 59 abstract away key low-level details such as memory management, pointer semantics and object oriented programming
 60 (OOP) principles. While these languages are beneficial since they lower the barrier to entry, they often fail to teach
 61 the operational mechanisms that govern how data structures behave under the hood - semantics that are critical for
 62 mastering performance-oriented systems programming languages such as C++.

63
 64 While C++ retains and builds on the core concepts of C, the introduction of the Standard Template Library (STL)
 65 added a rich layer of abstraction over common data structures. In C, programmers are forced to directly work with
 66 raw memory, pointers and manually managed arrays; for example, in C, if a function is passed an array, it does not
 67 know what the size of the array being passed is and thus, the size has to be passed as well. On the other hand, C++ STL
 68 containers like std::vector, std::stack, std::array, encapsulate both data and metadata, exposing useful APIs such as size(),
 69 empty(), push_back() while hiding the underlying memory management. While this significantly reduces the hassle
 70 and verbosity of code that needs to be written, it also makes it a challenge for students to connect high-level container
 71 operations to the low-level behaviours that actually dictate performance and correctness, further motivating the need
 72 for runtime visualizers.
 73
 74
 75

76 3 Prior Work

77

78

79 Several works such as Simonák[5] and Li et al.[6] have proposed frameworks to better integrate visualization into
 80 computer science pedagogy, and others like Bende [7] and Koschke[8] present evidence to suggest visualization is
 81 immensely beneficial to students and experienced programmers alike. Building on this, Shneiderman[1] establishes that
 82 effective visual debugging tools follow an "overview, zoom, filter, details-on-demand" paradigm to allow users to easily
 83 switch between a global context and specific state updates. These works help underscore the importance of tools that,
 84 instead of just displaying static snapshots, reveal how operations reshape program state over time.

85
 86 Unfortunately, existing tools fall short of achieving this goal in the context of C++. The GNU Debugger (GDB)
 87 remains the de facto standard for low-level debugging, while the Low-Level Debugger (LLDB) is another powerful
 88 alternative. However, such debuggers operate at the level of breakpoints, stack frames or assembly instructions, not
 89 operations. Moreover, as argued by Romero et al.[9], text-based debuggers impose substantial cognitive load: users must
 90 mentally simulate data-structure evolution for textual trace output. While GDB and LLDB support extensions such
 91 as reverse stepping and pretty printing, they still require expertise in order to be used effectively and do not provide
 92 continuous, operation-level visualizations of STL containers.
 93
 94

95 More visual approaches, such as the GNU Data Display Debugger (DDD)[10] (fig. 1), attempted to address these
 96 limitations by layering a graphical interface atop the GDB. However, this too suffers from several drawbacks: it is
 97 restricted to UNIX environments, the user interface (UI) is fairly dated and its visualizations are limited by what can
 98 be inferred from external inspection of an executing binary. These shortcomings make it ill-suited for educational
 99 use. Modern IDEs provide partial improvements: Microsoft's Natvis and CLion visualizers allow structured, rule-based
 100 visualization of custom C++ types but they are fundamentally tied to the IDEs that offer these tools.
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106   0: data_ptrs
107     12: data_ptrs
108       0x804ab78 0x804ab90 0x804ab98 0x804ab00
109     13: data_ptrs
110       0x804ab78 0x804ab80 0x804ab88 0x804abc0
111     Display *()
112     New Display
113     Hide All
114     Rotate
115     Set Value...
116     Undisplay
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Rotating an Array

Fig. 1. Debugging with GNU DDD

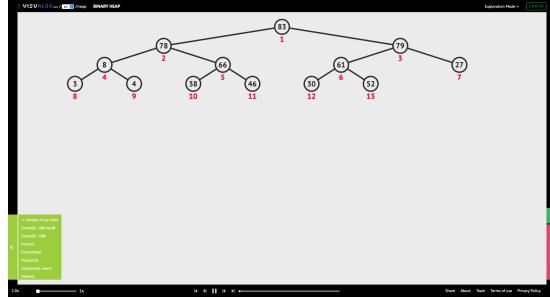


Fig. 2. Binary heap visualized on VisuAlgo.

Outside of debugger-based tools, one of the most well-suited visualization tools for pedagogical purposes is VisuAlgo[4] (fig. 2), developed by Steven Halim at NUS. It is a website-based interactive tool that lets students input data and perform operations on textbook data structures and see standard algorithms (e.g. bubble sort) in action. VisuAlgo presents strong educational value, especially for beginners, and is one of the inspirations for our project. Yet, it has the fundamental limitation of only visualizing illustrative examples, not a user's actual code.

4 Design

4.1 Goals

As discussed in section 3, the use of data visualizations in C++ debugging is still relatively niche, with terminal-based visualization being more prevalent, such as GDB pretty printers. GNU DDD is currently the only general solution for C++ UI-based runtime data visualization, but it has a few limitations inherent in its design that we hope to address with our visualizer.

While GNU DDD is capable of displaying more complex data such as graphs and 3D models, it is tied to Unix platforms and suffers from its age. GNU DDD was first released in 1995 and feature development stopped in early 2009 with few updates to the original design. Additionally, while GNU DDD operates on the binary executable through GDB, integrating the visualizer directly in the source code may allow for more flexible, easier, and platform-agnostic extendibility, as well as opening the door to interfaces to the visualizer within the code itself.

Modern alternatives to DDD do exist, but are primarily tied to a particular IDE, such as GDB visualizers for GDB and CLion.

With this context in mind, the primary goals of our design are threefold:

- (1) Modernize the core debugging utility of GNU DDD and GDB by implementing their features within a lightweight C++ library with an ergonomic UI.
- (2) Facilitate cross-platform support with minimal development effort.
- (3) Evaluate the capabilities and limitations of this approach by visualizing the runtime state of C++ standard library objects.

4.2 User Interface

The user interface (UI) of our program can be broken into two sections: the code interface and the visualizer interface.

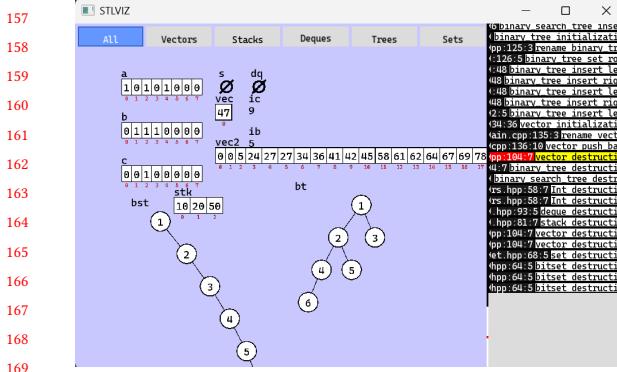


Fig. 3. STLviz’s visualizer interface, with data display on the left/center, tabs on the top, and operations list on the right.

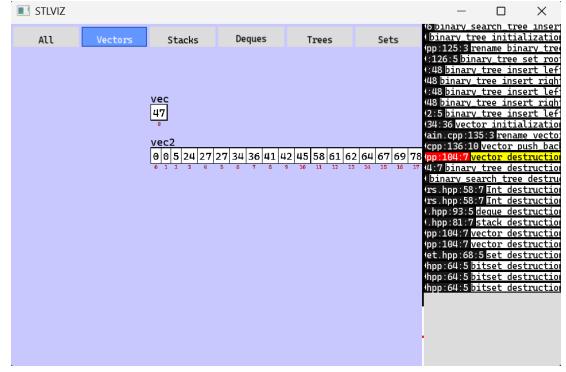


Fig. 4. STLviz’s visualizer interface with only vector objects shown using a tab filter.

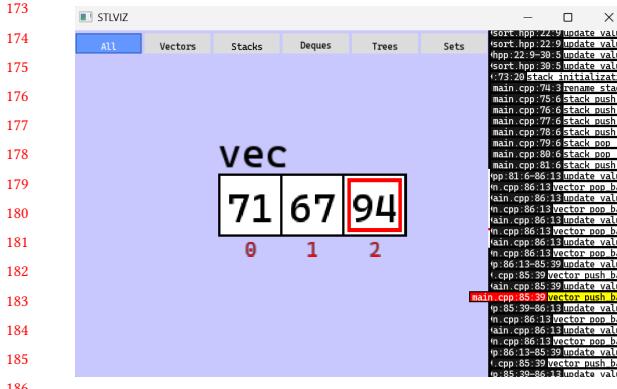


Fig. 5. STLviz’s visualizer interface zoomed in on a particular object. The current operation is also highlighted.

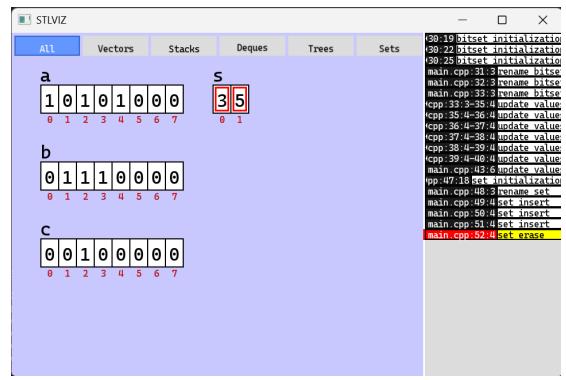


Fig. 6. STLviz’s visualizer interface zoomed in on a particular object. The current operation is also highlighted.

4.2.1 Code Interface. The code interface allows the user to hook the visualizer into the source-code of the program. It includes a programming interface that aims to be as minimal as possible to reduce the user code needed to enable the visualizer.

In order to utilize this interface, the user must include the header file `stlviz.hpp`.

- **Wrapper Classes:** To enable visualization for a standard library class, we require the user to replace `std::` with `vstd::`. For example, `std::vector<int>` would become `vstd::vector<int>`. Primitives within these classes are handled innately, but for visualizing standalone primitives, the user can replace the primitive class with `vstd::<Type>` (e.g. `vstd::Int` for `int`). These wrapper classes allow us to intercept and communicate method calls to the visualizer, so that the underlying standard library class can be represented in the visualizer. Many wrapper classes can be modeled with the same internal object (e.g. `vobj::List`). Currently, we have implemented the following wrapper classes represented by `vstd::List<T>`: `vstd::vector<T>`, `vstd::deque<T>`, `vstd::stack<T>`, `vstd::bitset<T>`, `vstd::set<T>`.
- **Supplementary Structures:** In addition to wrapper classes, we provide a few data structures and algorithms not present in the C++ standard library to showcase the extensibility of STLviz as functional library. These include

- 209 visualizations of sorting algorithms (insertion, selection, merge, quick) and two binary tree data structures
 210 (`vstd::binary_tree` and `vstd::binary_search_tree`).
 211
- 212 • Helper Macros: In the future we hope to redefine these in a cleaner manner, as introducing macros can cause
 213 issues with name collisions. However for now we provide the following supplemental macros to enhance
 214 visualization.
 - 215 – `DEF(X)` - assigns variable X the name X in the visualizer.
 - 216 – `DEFN(X, NAME)` - assigns variable X the name NAME in the visualizer.
 - 217 – `SNAP` - trigger a value update check at the current location, useful for capturing value changes with better
 218 granularity between operations.
 - 219 – `MAIN_DONE` - prevents the visualizer from closing after main returns by blocking on the last `vstd` object
 220 destructor.

223
 224 4.2.2 *Visualizer Interface*. The visualizer interface is the graphical user interface (GUI) that visualizes the program
 225 state and allows the user to navigate through the runtime of the program.
 226

227 4.3 Operations

228 One of the main features developers utilize in debugging is the ability to inspect the program state at different points
 229 in the lifetime in the program. In GDB, this is done through providing the ability to step through the program at the
 230 assembly level, with commands to step over function calls to get source-code level stepping. Alongside forward stepping,
 231 GDB also provides reverse execution, which is a feature that allows developers to step backwards through instructions
 232 to examine prior program states. GDB does this by applying instructions in reverse on GDB's model of the program
 233 state rather than modifying the program state directly.
 234

235 Since our goal is to visualize standard library objects, the smallest step we need to support is a single function call
 236 within a standard library class. We denote these as "operations", with each step progressing the program state by one
 237 operation. To facilitate both forward and reverse execution, STLViz models the program state with internal objects,
 238 and maintains an operations list with a pointer to the current visualized operation. To jump between points in time,
 239 the internal state provides the ability to step forward and backwards one operation. Whenever the program state is
 240 advanced, an operation is added to the list rather than updating the internal state directly.
 241

242 As shown in figure 3, these operations are displayed in the GUI, with the location in the source code supplied by the
 243 file name, line number, and offset in the line. The user is able to quickly navigate to arbitrary operations via clicking
 244 and scrolling, which is translated internally to a sequence of forward or backwards steps.
 245

246 4.4 Data Display

247 The core feature of our visualizer is the ability to display the program state in a visual manner. Instead of integrating a
 248 more rigid UI to display data, we implemented a more dynamic interface where elements can be moved and the view
 249 can be panned and zoomed. In this regard, our design follows the Visual Information Seeking Mantra of "Overview first,
 250 zoom and filter, then details-on-demand" [1], which organizes features into the following task list:
 251

- 252 • Overview - The data display showcases an overview of the current program state by displaying the names of
 253 objects, their associated data, and what data has been modified by the current operation.
 254

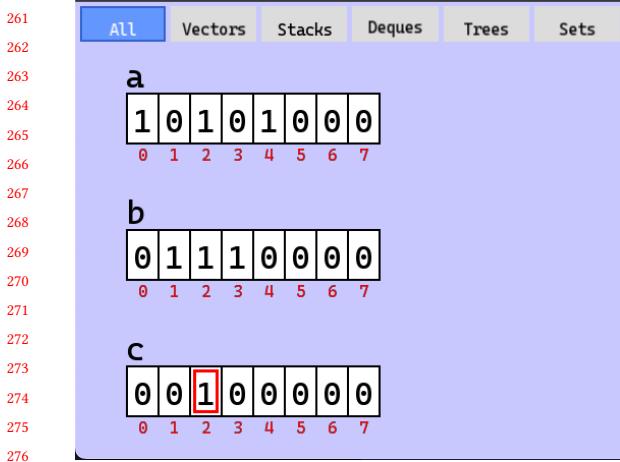


Fig. 7. STLviz's visualizer interface, with colorblind mode off

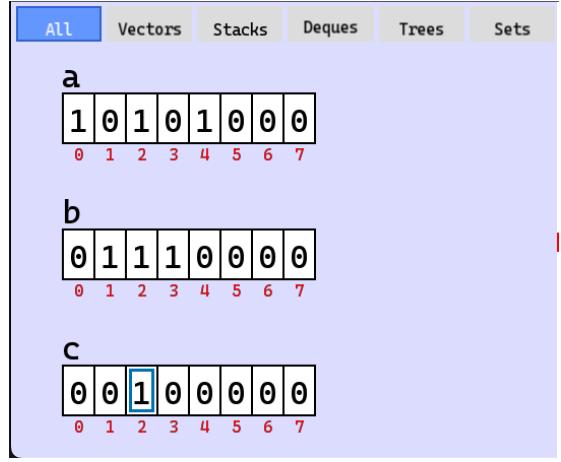


Fig. 8. STLviz's visualizer interface, with colorblind mode on.

- Zoom - The user can zoom the data view in and out using the scroll wheel, which is done relative to the mouse pointer. Alongside zoom, the user can pan around using mouse dragging to focus in on particular object easily. Figure 5 showcases this feature.
- Filter - The user can select tabs to display only a certain type of object, such as all `vstd::vector` objects. Figure 4 showcases this feature. Additionally, the ability to reposition objects by dragging them around with the mouse pointer also allows for spatial isolation of key objects. In the future, better filters and search would make this feature even more useful.
- Relate - By default, objects are positioned near similar types of objects, and the user can freely reposition objects around to organize them in a more cohesive manner. Additionally, data within objects are organized in a meaningful manner, either by rank/index for list structures, or a classic representation of trees for tree structures. Figure 3 showcases how both list and tree data structures are displayed, and figure 6 shows the default organization of structures.
- History - The operations list and ability to step forward and backwards through operations allows the user to view the program state over the entire history of the program's lifetime.
- Extract - This aspect is currently lacking in our implementation. In the future, adding the ability to export the current program state into other formats would address this aspect.

305 4.5 Accessibility

306 To address concerns with colorblind accessibility, we implemented a colorblind mode that can be toggled by pressing 'C' 307 (fig. 7, fig. 8). Although still very incomplete, this mode aims to adjust the color palette to use primarily value and 308 shading instead of color. The base UI also doesn't rely heavily on color differentiation for usability. 309

310 In the future, other accessibility features such as changes to font style/size can be added relatively easily. 311

312

313 4.6 Dependencies

314 In order to implement such design, we needed to choose suitable dependencies that handled some of the lower-level
315 details. We decided to use SFML 3.0.2, a low-level cross-platform graphics library, for rendering the visualizer and UI.
316 The advantage of utilizing a raw graphics engine rather than a UI framework is that it allows for maximal flexibility
317 in our UI design in exchange for the lack of pre-built elements. We also chose SFML over SDL2, another low-level
318 cross-platform graphics library, due to having more prior experience in it. However, porting to SDL2 in the future
319 should not be a major hurdle as most of the development effort doesn't involve the graphics engine.
320

321 To provide a stable starting point for our implementation, we forked the open-source CMake SFML Project Template
322 [11]. This provides a cross-platform build pipeline and continuous integration workflows for building SFML projects
323 with CMake.
324

325 The rest of our implementation is contained within STLViz itself, which is built as a CMake-based library. Currently
326 we require building STLViz from source to include it in other programs. However, once a stable release is completed,
327 we can distribute it as a pre-compiled library via standard package managers.
328

329 4.7 Implementation

330 The source code for STLViz is available on GitHub at <https://github.com/mugicha101/stlviz>. This section provides a
331 brief overview of the implementation of STLViz. Basic C++ knowledge is assumed.
332

333 The visualizer interface and internal model is represented in a Model View Controller (MVC) design pattern, with
334 the core MVC being under namespace vcore and the internal model objects being under vobj. The wrapper classes
335 themselves are under namespace vstd, and sync their internal states to the internal model by adding operations to the
336 internal operations list whenever a function is called. These operations are able to apply and undo the data updates of
337 the function call on the internal model objects.
338

339 To handle value updates outside of operations, before an operation is carried out, the internal model compares its
340 latest values with the values of the wrapper class objects to determine if any values have been changed. If so, a value
341 update operation is added to the list.
342

343 After an operation is carried out, the visualizer handles GUI events until the next operation is needed to prevent the
344 program state from advancing.
345

346 Static objects are used to initialize the visualizer without needing explicit user code. However, the user must specify
347 the end of main with MAIN_DONE to prevent the program from terminating the visualizer after main returns.
348

349 Each wrapper class object and visualized primitive are represented by a subclass of vobj::Display, and are organized
350 in a hierarchical manner to facilitate nested structures.
351

352 5 Evaluation

353 5.1 Study Design

354 To evaluate how well STLViz performed, we conducted a user study where users were asked to debug six c++ programs.
355 A within-subjects design was used, wherein participants were asked to debug three problems with the help of STLViz
356 and three problem without its assistance. A total of n=3 participants were recruited for the study, all of them being
357 Computer Science students that the authors personally knew, with varying degree of experience. Two of the participants
358 were post graduate students and the third one was a sophomore at UNC. While we had hoped to have more participants,
359 we were unable to find the target audience (participants who had some familiarity with programming and C++, but
360

361

not well versed in it). All three had varying debugging preferences, namely using print statements, dry runs, and breakpoints respectively.

All studies were conducted online (via zoom or discord), with one of the authors walking the participant through the procedure. VSCode was the IDE used in all three cases. The entire study took about one hour per participant. Before starting the study, we asked the participants to fill a background questionnaire, which gauged their familiarity with programming, C++, debugging, and their preferences towards debugging methods. Then, the participants were guided to set up the STLviz directory. The users were then given a tutorial of STLviz, wherein a sample program was used to demonstrate the various features they could use to help them debug.

After the participants felt familiar enough with STLviz, they were asked to solve the six problems as directed by the author. For each problem, the participant was first shown the problem statement and a sample input/output pair. Depending on whether they were using STLviz or not, the participant would either run the program for STLviz, or swap over to the buggy code file, which counted as the start time for the time it took them to solve that particular problem. Modification of the original code was allowed, as was using other debugging methods alongside STLviz (only one participant used print statements along with STLviz, no other debugging methods were used in conjunction with STLviz otherwise). The participants were asked to elucidate their thought process (as long as it didn't hinder them) which was taken into account for our qualitative analysis. The time to completion was when they identified the correct error and the program output matched with the expected output.

Throughout the experiment, quantitative and qualitative data was collected. The quantitative data included three metrics for comparison, Task completion time and self-reported difficulty scale (1-10) (Found in table 1 for each problem, along with a post-study likert questionnaire, shown in Table 2).

Qualitative data in the form of semi-structured interviews were collected as well. The types of questions ranged from specific (which features of STLviz did you find most/least effective?) to open-ended (Overall thoughts on STLviz). This gave insights as to how they felt about STLviz as a whole as well as technical, immediately applicable feedback regarding specific features.

5.2 Results

Table 1. Self-Reported Difficulty Ratings (1-10 scale). Tasks solved with STLviz are marked with *.

Task	P1	P2	P3
num_smaller (kth largest)	7*	6*	8
max_subarr (Kadane's)	6	2	3*
max_path (tree longest path)	4*	2*	7
nearest_higher (next higher element)	3	3	3*
sum_queries (prefix sum)	1*	1*	4
intersect_arrays (array overlap)	1	1	1*

Since three is a statistically insignificant participant count, we mainly focus our discussion on the qualitative aspect of the user study. We first talk about the specifics, then move onto to a broader analysis.

5.2.1 Most effective Features. Reverse Execution (ability to move backwards in operations), intuitive visual representation of data structures, as well as clear variable tracking and updates were the most liked features.

Table 2. Post-Study Likert Scale Responses (7-point scale: 1 = Strongly Disagree, 7 = Strongly Agree)

Question	P1	P2	P3	Mean
Q1: STLviz's UI is intuitive to use	6	5	6	5.67
Q2: STLviz's UI is overwhelming	1	2	2	1.67
Q3: STLviz is effective for debugging small programs	7	5	7	6.33
Q4: I have practiced solving these types of problems	5	6	2	4.33
Q5: STLviz reduced the mental load required to debug	6	4	6	5.33
Q6: I found debugging with STLviz easier than without	5	2	7	4.67
Q7: STLviz has potential for more features than text-based debuggers	4	4	6	4.67
Q8: I regularly use text-based debuggers (like gdb)	3	1	6	3.33
Q9: I regularly use visual debuggers	1	1	1	1.00
Q10: I can see myself using visual debuggers regularly in the future	5	5	4	4.67

5.2.2 *Least effective Features.* Tab filters, operation line visualization (right side of the screen). There were also some navigation challenges, with some data structures overlapping others.

5.2.3 *Desired Features.* There were multiple features which the participants expressed would make STLviz more effective. Custom filters for user specified objects. In a similar thought, another student asked for custom variable tracking(like in gdb). They also suggested some quality of life features. For example, One of the participants asked for a snap-to-area as potential feature, as zoom in and zoom out speeds were quite high, which could lead users to lose track of where they were on the screen. Another feature they requested for was directly going to the output at the start.

5.2.4 *Best Use Cases.* All participants well that this tool would be effective for beginners to visualize different data structures and help them learn better, as well as debug more effectively, especially in a more algorithmic problem-solving context. Some also felt that this would be much more useful with complex data structures like binary trees.

5.3 Discussion

There are some great insights to be had from this study. It was unanimously observed that STLviz had a learning curve, which could increase performance with more practice with the application. The more experienced participants were less likely to adopt this visualizer since existing methods seemed more intuitive to them, however, the third participant (sophomore) preferred STLviz instead of existing methods. As represented with the Likert scores, for the given task set, most participants found that STLviz's UI was intuitive to use and not overwhelming. They also found STLviz effective for debugging smaller problems while simultaneously reducing the mental load required. The largest variance in response was whether they preferred STLviz or their usual debugging method, wherein both the graduates preferred either using their pre-existing debugging method or remaining neutral, whereas the student leaned more towards preferring STLviz.

These qualitative results support the claim that STLviz is much more suited to be used by beginner or intermediate level programmers to help visualize complex data structures effectively, which was its intended use case. This study also shows that debugging is not simply seeing the data structures at a singular point of time, but also visualizing how the data transforms across operation and understanding the overall flow at a higher level(reverse execution being an effective feature points to this), while still maintaining the ability to scrutinize each operation thoroughly (variable tracking).

469 **5.4 Limitations**

470
 471 While this work was conducted fairly well, it does have some limitations we would like to acknowledge. The most
 472 significant limitation is the small sample size of participants for the user study. This limitation does not allow us to
 473 draw statistically significant conclusions about quantitative data which would give us better insight as to how STLVis
 474 performed across the board.

475
 476 The scope of the problems presented in the user study was limited. This study focused more on the debugging aspect
 477 for smaller programs, however, its validity for larger programs or building a program instead is unknown. This is
 478 highlighted by the fact that participants did not feel the tab filter was effective, as most programs focused on only
 479 one data structure, obviating the tab filter. A larger study with multiple data structures might have produced different
 480 results.

481
 482 While sufficient for the pilot study, the scope of the data structures supported needs to increase to allow for more
 483 widespread future usage.

484
 485 **6 Future Work**

486
 487 There are numerous features still needed before our proof-of-concept implementation can compete with the features of
 488 other debuggers.

489
 490 **6.1 Standard Library Coverage**

491
 492 Our wrapper classes only cover a small portion of the standard library. Ideally, we would wrap every standard library
 493 data-structure and algorithm. However, this is a monumental task especially considering how much the standard library
 494 changes between versions, so the ability to support most commonly used ones completely would likely be sufficient.

495
 496 **6.2 Nested Data Structure Support**

497
 498 The internal model of the program state was designed with nested structures in mind, but some advanced template
 499 meta-programming challenges would need to be resolved in order to add support for nested structures.

500
 501 **6.3 Limitations with Source Location**

502
 503 C++'s source location feature is very limiting due to being done through default parameters. Operator overloading
 504 prohibits the use of default parameters, and adding default parameters makes wrapping methods with existing default
 505 values challenging. Trying to integrate this feature is a challenge due to ambiguous function resolution, and this source
 506 location field is visible to the user. There's not much we can do to address this limitation other than push for a feature
 507 akin to Rust's track caller attribute being introduced into the C++ standard. An alternative approach to this would be
 508 to extend the C++ preprocessor to insert these source locations, but aside from development effort that would add a
 509 further dependency the user needs to consider when including our library.

510
 511 **6.4 Tracking Value Updates**

512
 513 Due to C++'s unrestricted memory access model, it is difficult to intercept data updates in a precise manner. STLVis
 514 tries to get around this by scanning the entire internal state for changes in values before every operation. This approach
 515 is very limited in granularity, but we see no ways to improve this currently without significant tradeoffs to usability.

521 **6.5 Recursion**

522 Currently the visualizer does not take recursion into consideration, due to currently lacking the capability to capture the
 523 call stack. With further design, it may be possible to implement this without burdening the user excessively. This would
 524 further benefit the debugging capabilities, as displaying the program state at all levels of the call stack can be difficult
 525 with traditional logging. Structures such as call trees could also be integrated into the UI, similar to the operations list.
 526

527 **6.6 User Structure Support**

528 Currently, there is no way to display user-defined structs/classes. One way to implement this would be to provide some
 529 code interface to allow the user to hook their structures into the visualizer's internal model. We could take inspiration
 530 from GDB pretty printers and add Python bindings to our visualizer in order to allow the user to specify their own
 531 visualization, however this would likely require an overhaul of the internals of our visualizer.
 532

533 **6.7 Failure Handling**

534 Currently, our visualizer and program run in the same thread. Thus, whenever the program terminates unexpectedly, so
 535 does the GUI, which makes it hard for the user to determine where in the code the program fails. A straightforward fix
 536 for this would be to launch the visualizer and main program in a separate processes, which would require implementing
 537 a cross-platform inter-process communication channel between the program and the visualizer.
 538

539 **7 Conclusion**

540 In conclusion, this work developed STLViz, a C++ STL data visualizer with real time visualizations, supporting features
 541 such as reverse execution and a host of data structures such as vectors, sets, stacks, deques, binary trees, and binary
 542 search trees. A user study was conducted to evaluate the efficacy of STLViz, which found the UI to be intuitive to use,
 543 not overwhelming, and that STLViz was effective in debugging smaller programs. Most participants envisioned this
 544 being used in a more academic context to facilitate learning.

545 While this work has its limitations and is far from a complete product, STLViz demonstrates the potential of visual
 546 debugging for reducing cognitive load in understanding programs. Future work would include higher coverage of the
 547 standard library, addressing gaps in modeling capabilities such as nested structures and high-granularity value update
 548 operations, adding advanced filtering features and call trees, general polishing to the UI, conducting a broader user
 549 study to gain deeper insights into how STLViz performs, and changing UI elements like the filter tabs or operation list.
 550 On the evaluation front, a larger user study would also provide better insight into the effectiveness of such visualizers.
 551

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